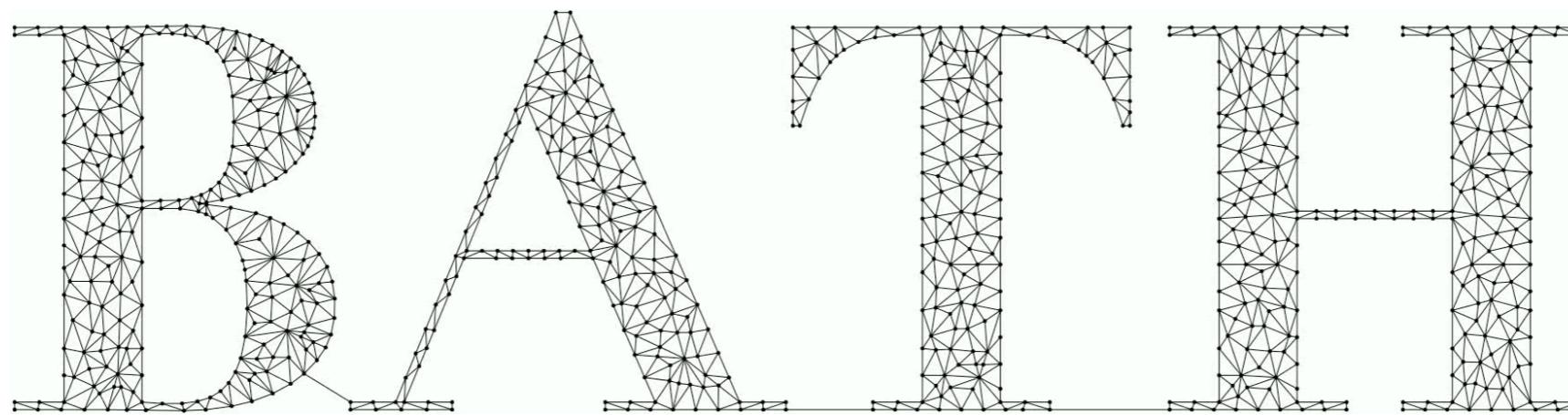


To contract/ or to delete— that is the question



Gecia Bravo-Hermsdorff

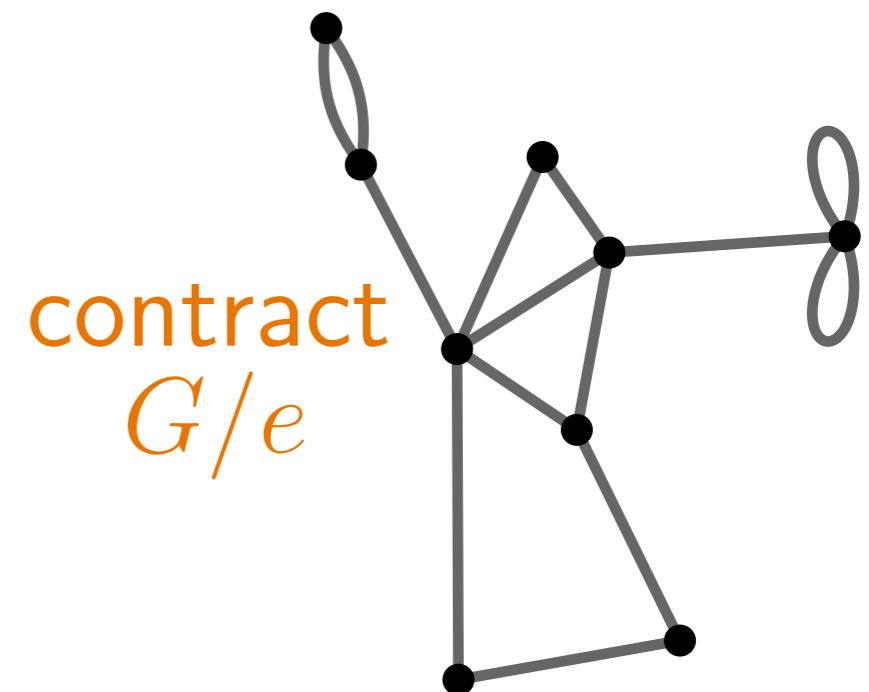
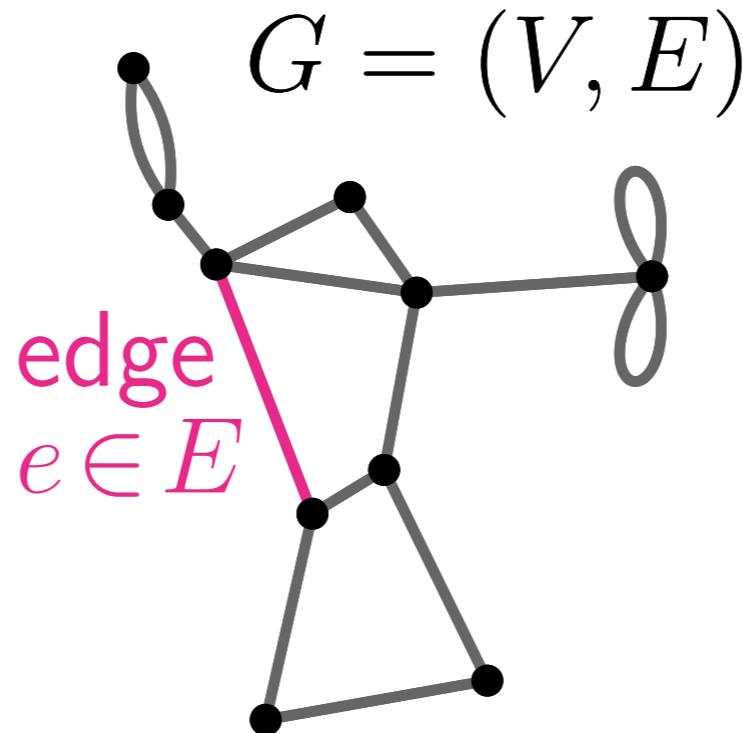
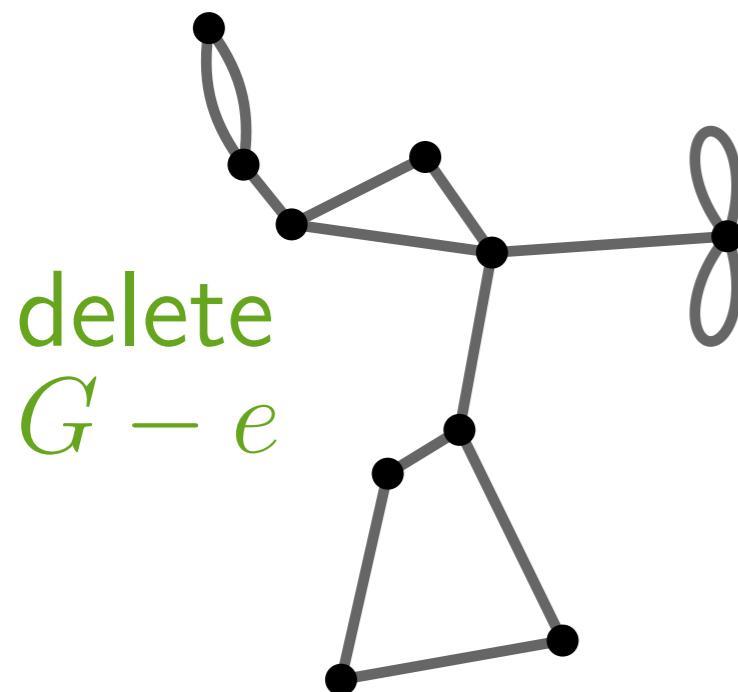
joint work with Lee M. Gunderson



UNIVERSITY OF
BATH

Thirteenth Meeting of the
Southern Logic Seminar

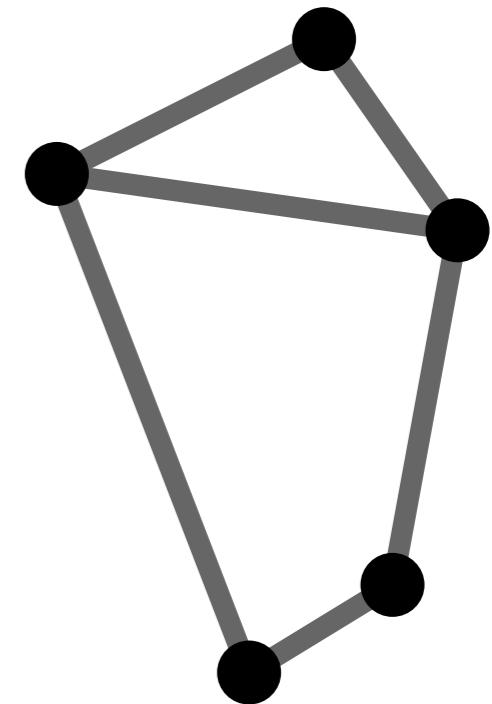
Deletion–Contraction / Example



Two Tantalizing Graph Invariants

Laplacian (spectrum)

$$0 \leq 1.38 \leq 2.38 \leq 3.62 \leq 4.62$$

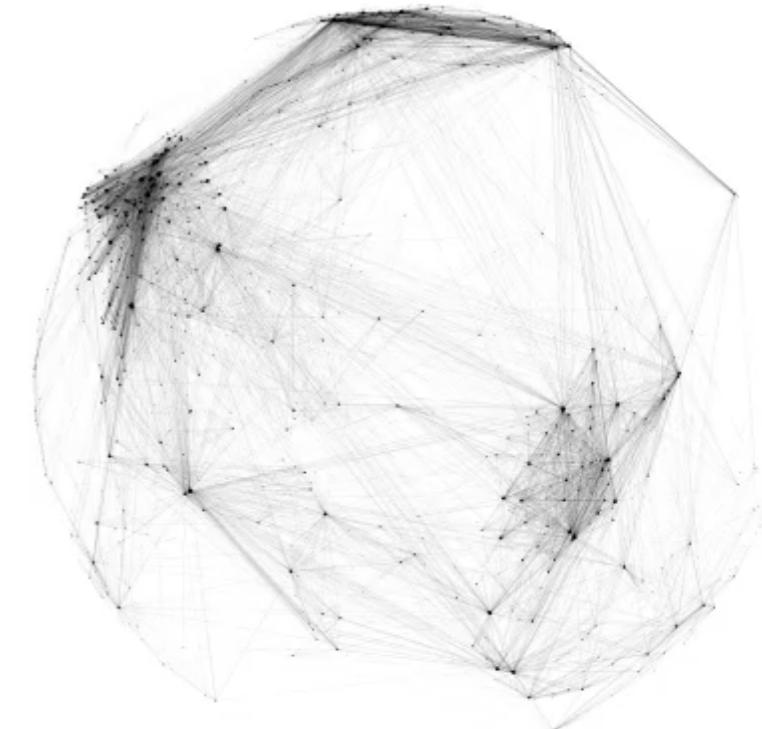
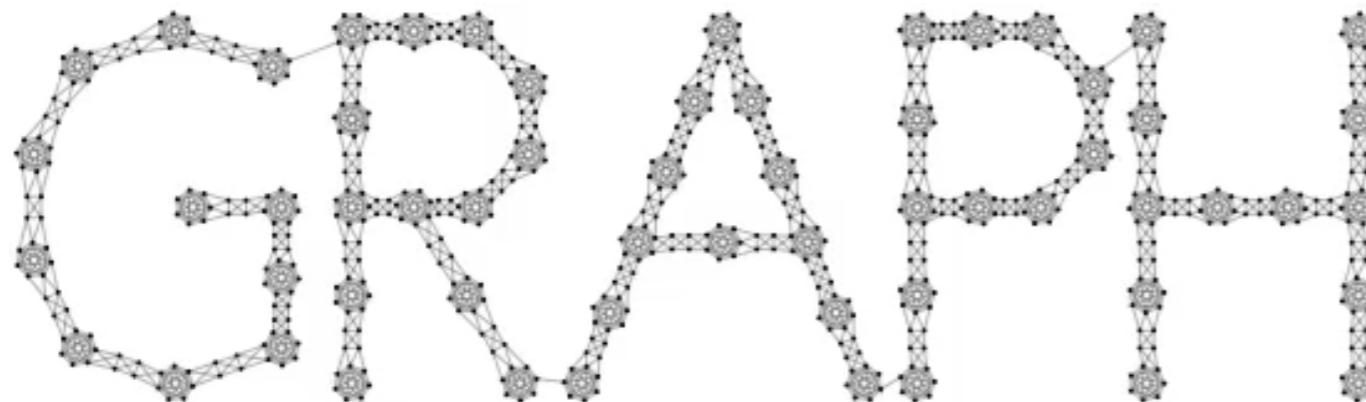


Tutte (polynomial)

$$x + y + 2x^2 + 2xy + y^2 + 2x^3 + x^2y + x^4$$

Two Tantalizing Graph Invariants

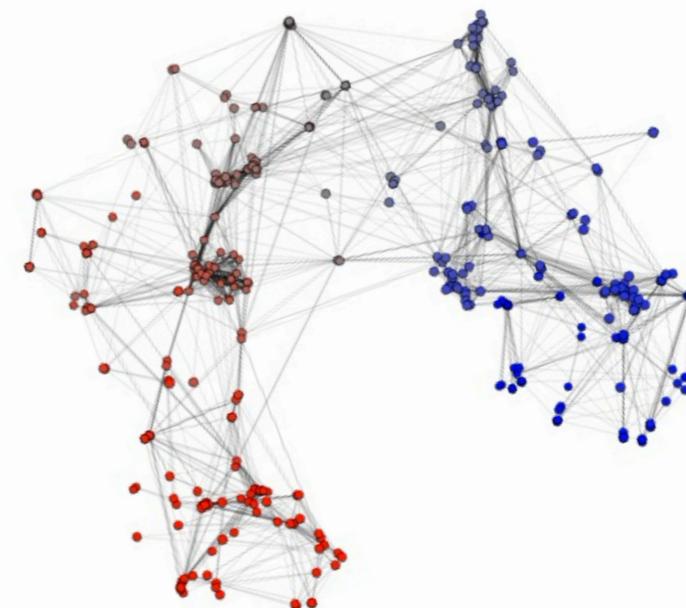
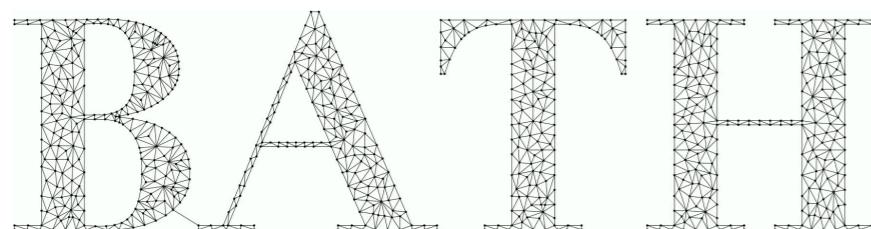
Laplacian (spectrum)



G. B-H & L. Gunderson. *NeurIPS*, 2019.

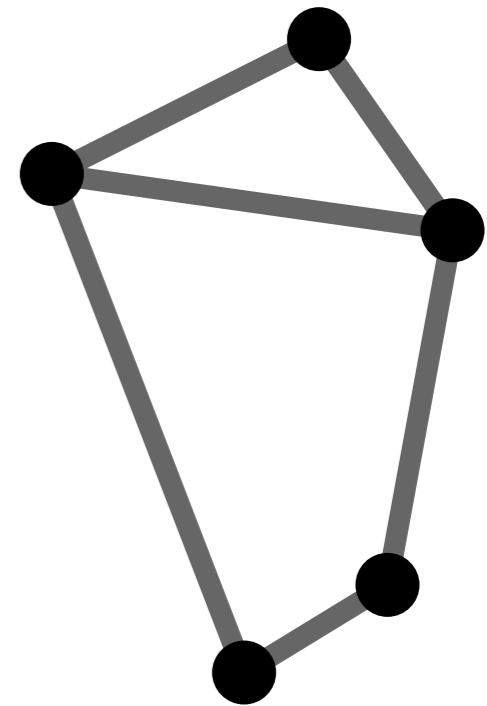
A unifying framework for spectrum-preserving graph sparsification and coarsening.

Tutte (polynomial)



Laplacian (spectrum)

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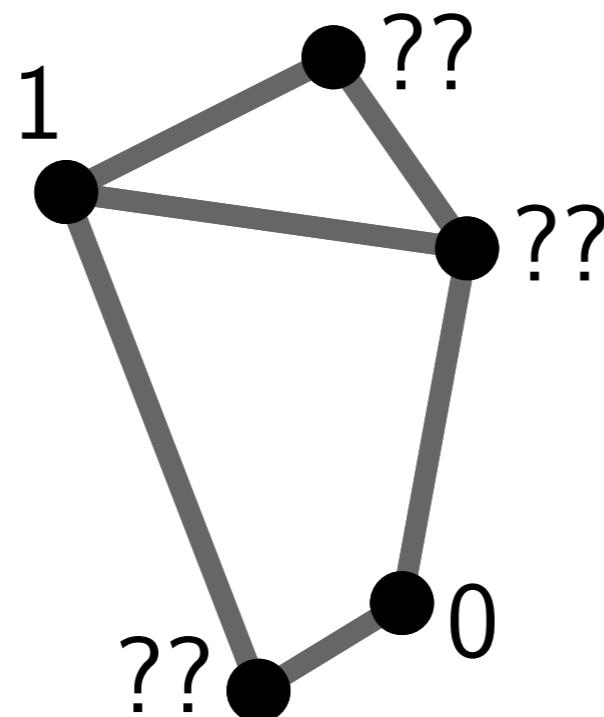
How to interpolate on graphs

Want: a function assigning a scalar to each vertex

$$x_i \in \mathbb{R} \quad \forall i \in V$$

Problem: only know f unction on some *Fixed* subset

$$x_i = f_i \quad \forall i \in F$$



How to interpolate on graphs

Solution: “be the average of your neighbors”

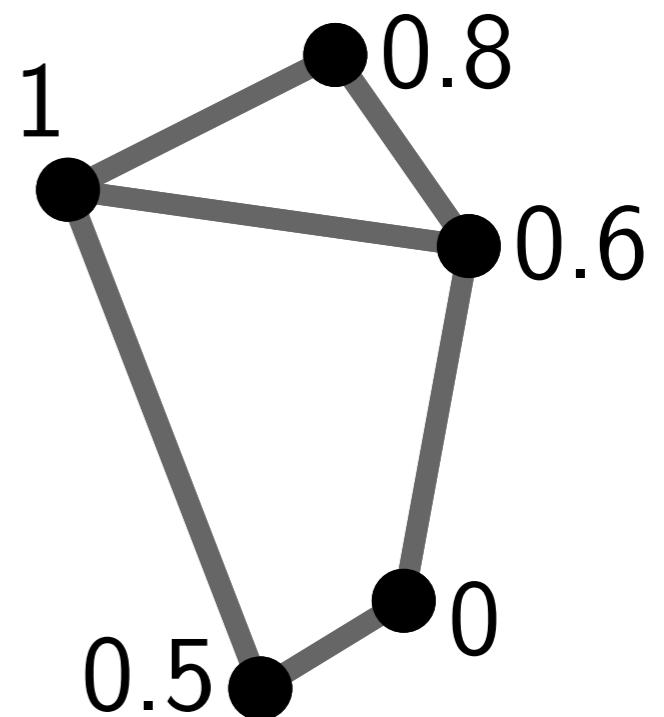
or

“minimize squared differences between neighbors”

$$x_i = \frac{1}{|N(i)|} \sum_{j \in N(i)} x_j$$

or

$$\operatorname{argmin}_{\mathbf{x}} \sum_{(i,j) \in E} (x_i - x_j)^2$$



How to interpolate on graphs

Solution: “be the average of your neighbors”
or

“minimize squared differences between neighbors”

$$x_i = \frac{1}{|N(i)|} \sum_{j \in N(i)} x_j \quad L \cdot x = 0$$
$$L = D - A$$

or

$$\operatorname{argmin}_{(i,j) \in E} (x_i - x_j)^2 \quad \operatorname{argmin}_L x^\top L x$$
$$L = B^\top B$$

How to interpolate on graphs

Solution: “be the average of your neighbors”
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$$x_i = \frac{1}{|N(i)|} \sum_{j \in N(i)} x_j \quad L \cdot x = 0$$
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$$L = B^\top B$$

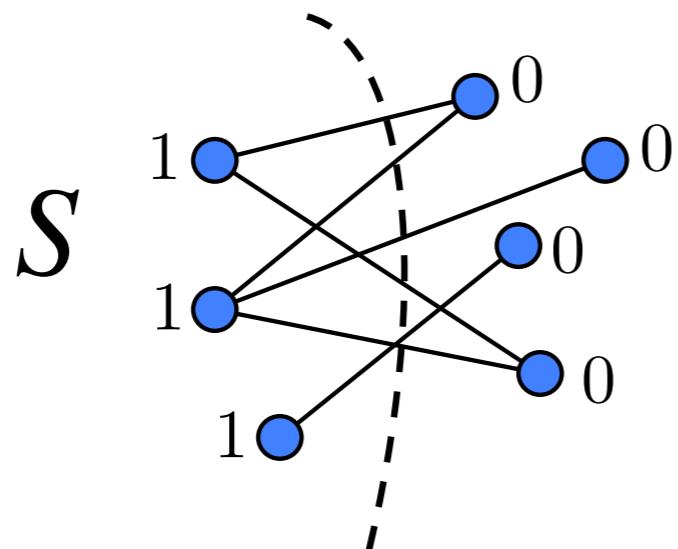
$$L = \sum_{k=1}^n \lambda_k \mathbf{v}_k \mathbf{v}_k^\top \quad \lambda_1 = 0 < \lambda_2 \leq \dots \leq \lambda_n$$

How to interpolate on graphs

Solution: “be the average of your neighbors”

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“minimize squared differences between neighbors”



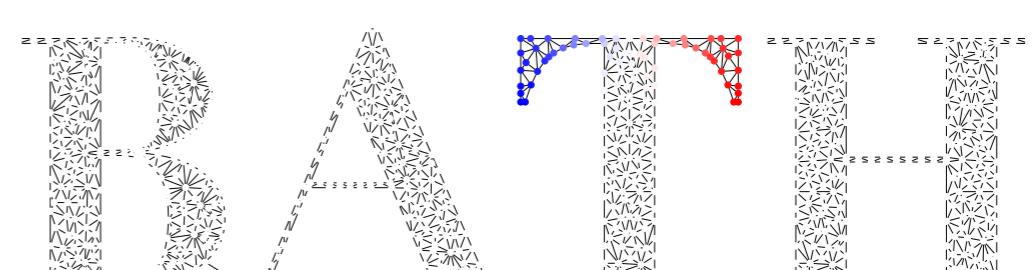
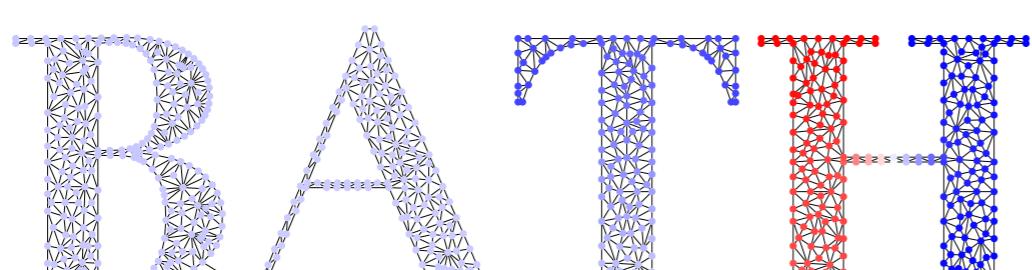
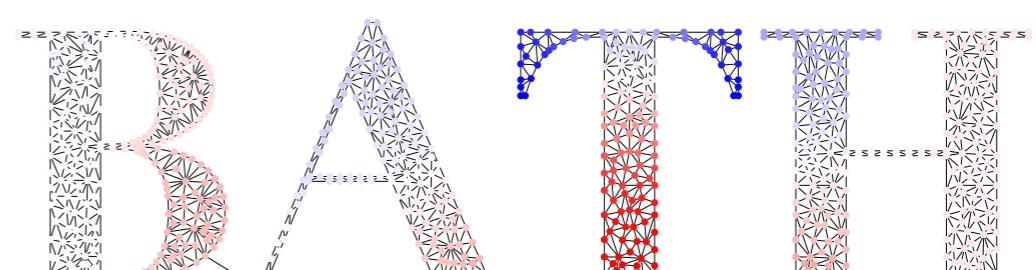
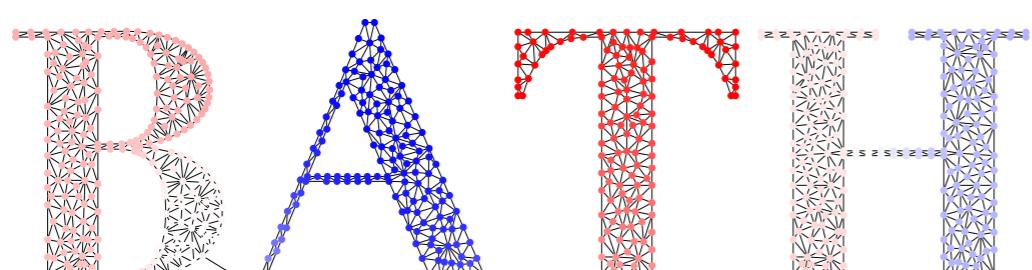
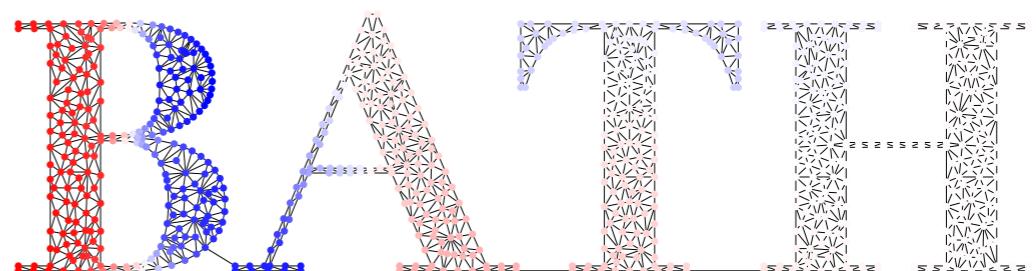
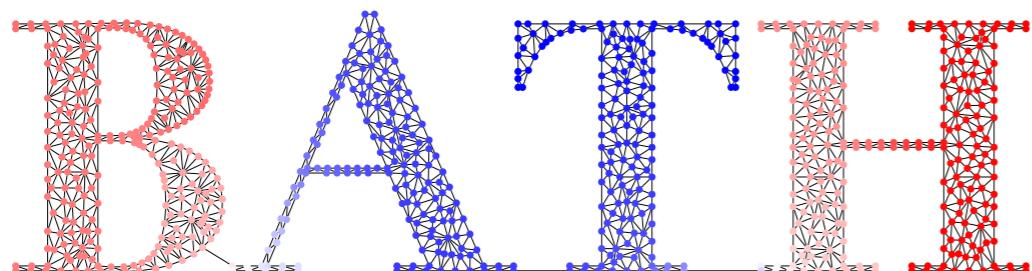
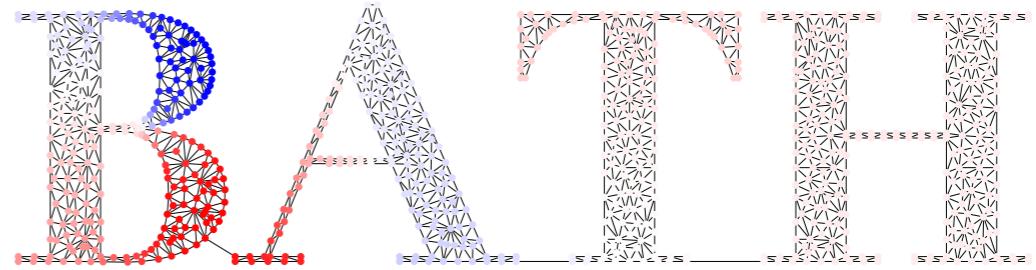
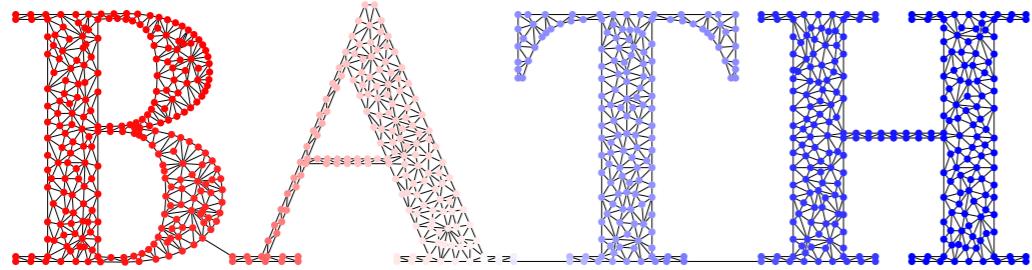
$$\begin{aligned} L \cdot x &= 0 \\ L &= D - A \end{aligned}$$

$$\operatorname{argmin}_{\mathbf{x}} \sum_{(i,j) \in E} (x_i - x_j)^2$$

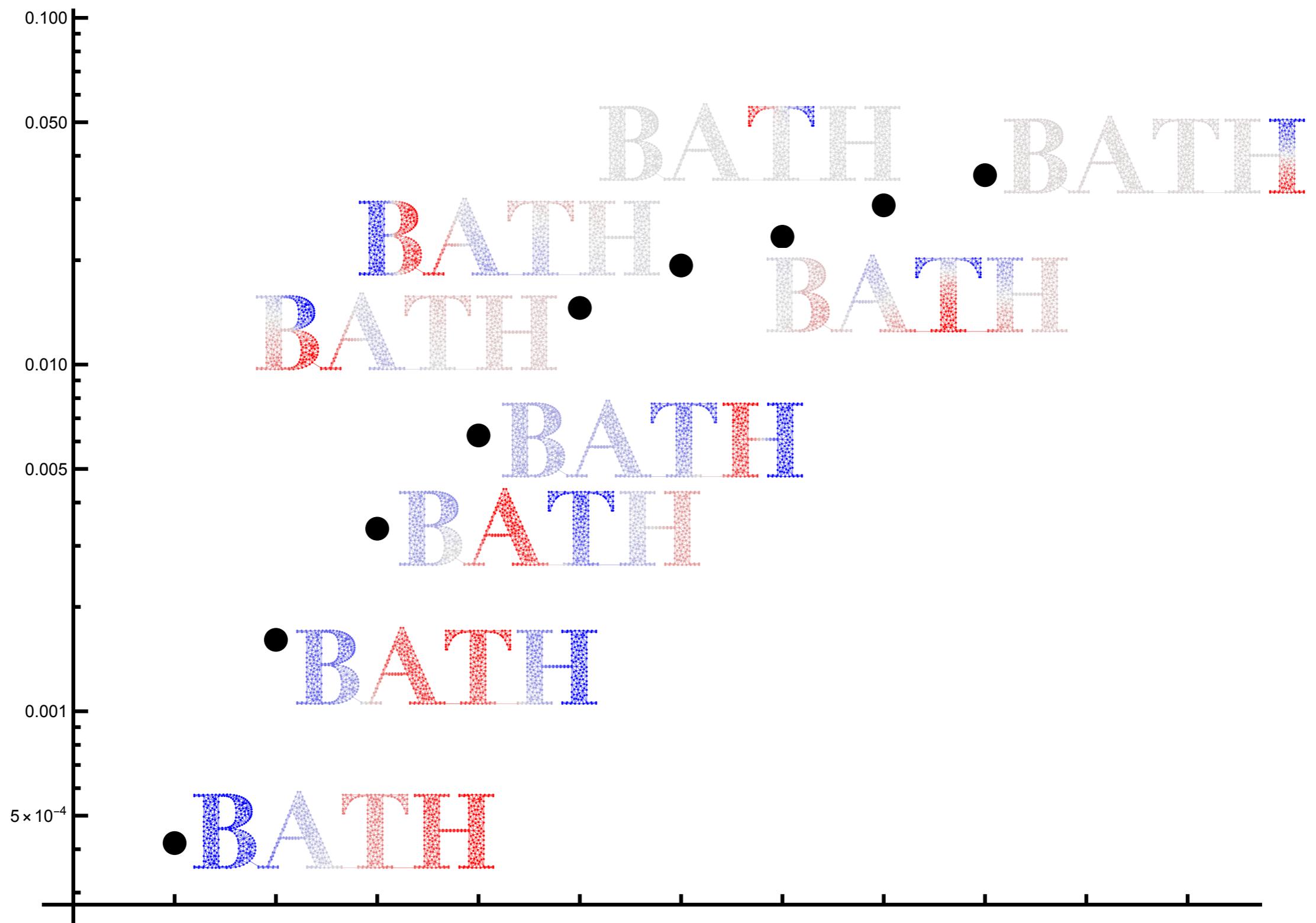
$$\begin{aligned} \operatorname{argmin}_{\mathbf{x}} \mathbf{x}^\top L \mathbf{x} \\ L = B^\top B \end{aligned}$$

$$L = \sum_{k=1}^n \lambda_k \mathbf{v}_k \mathbf{v}_k^\top \quad \lambda_1 = 0 < \lambda_2 \leq \dots \leq \lambda_n$$

“Hearing” the shape of a (Bath) Graph



“Hearing” the shape of a (Bath) Graph



Kirchhoff's Matrix-Tree Theorem

$$\prod_{i=2}^{|V|} \lambda_i = (\# \text{ of spanning trees}) \times (\# \text{ of vertices})$$

**Effective resistance (distance)
between nodes u and v is:**

$$\Omega_{uv} := (\delta_u - \delta_v)^\top L^\dagger (\delta_u - \delta_v)$$

where δ is a unit indicator vector

Effective resistance (distance) between nodes u and v is:

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The effective resistance has multiple interpretations:

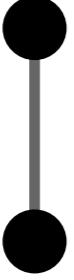
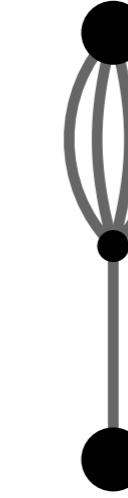
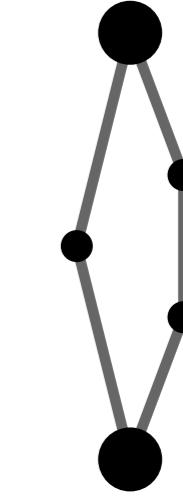
The fraction of spanning trees containing the edge (u, v) .

As a network of resistors, the (reciprocal of the) current resulting from a unit of voltage between u and v .

The resulting difference in voltage between u and v when passing a unit of current through the network.

The expected number of steps for a random walker to get from u to v then back to u (divided by $2|E|$).

Effective resistance (distance)

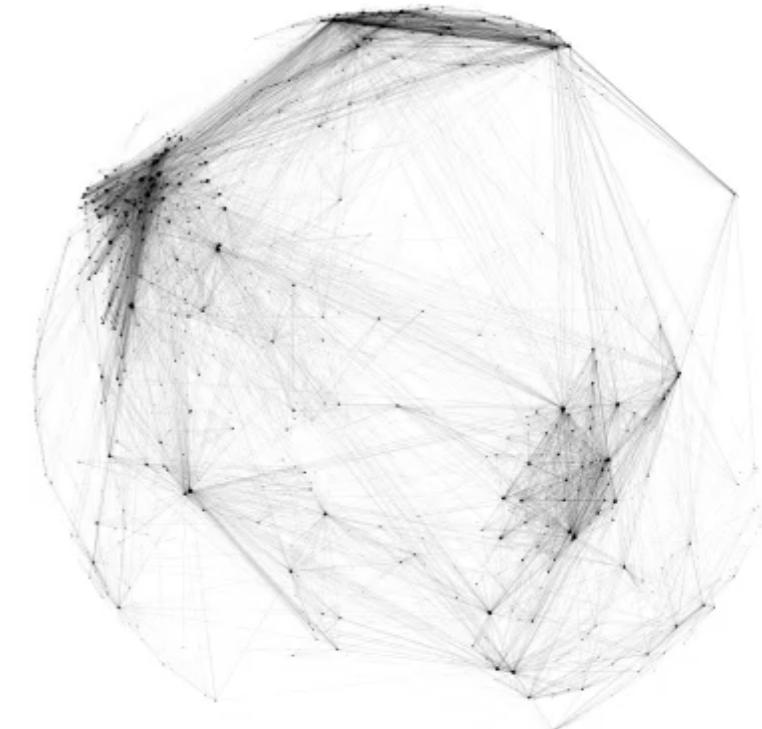
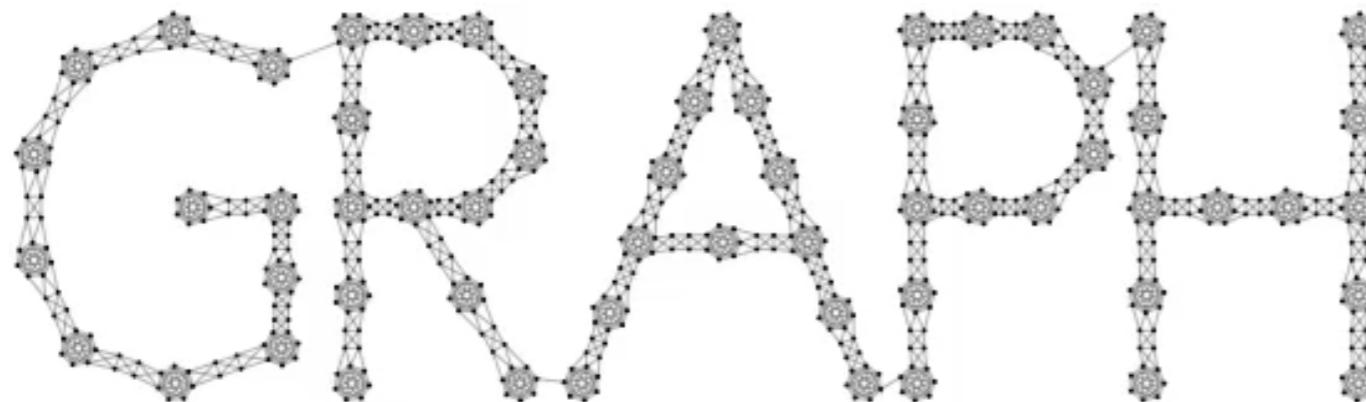
					
shortest path	1	2	1	2	2
effective resistance	1	2	0.5	$1 + \frac{1}{4}$	$\left(\frac{1}{2} + \frac{1}{3}\right)^{-1}$

series \longrightarrow sum resistances

parallel \longrightarrow sum reciprocals

Two Tantalizing Graph Invariants

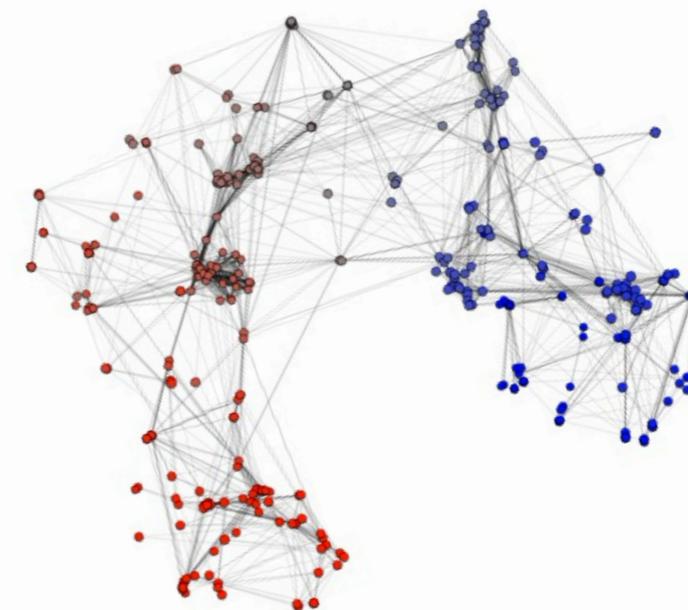
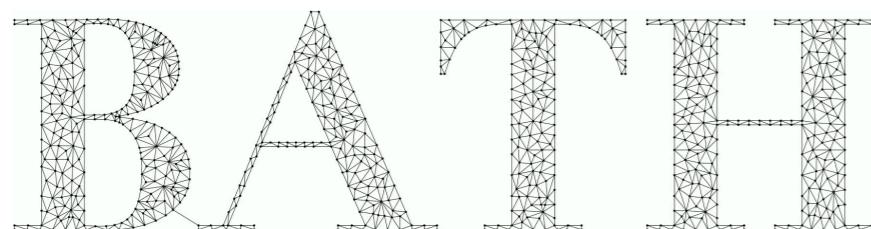
Laplacian (spectrum)



G. B-H & L. Gunderson. *NeurIPS*, 2019.

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Tutte (polynomial)



Algorithms for reducing a graph while preserving global structure

Spielman et. al (\sim 2010)

edge deletion–

Laplacian quadratic form

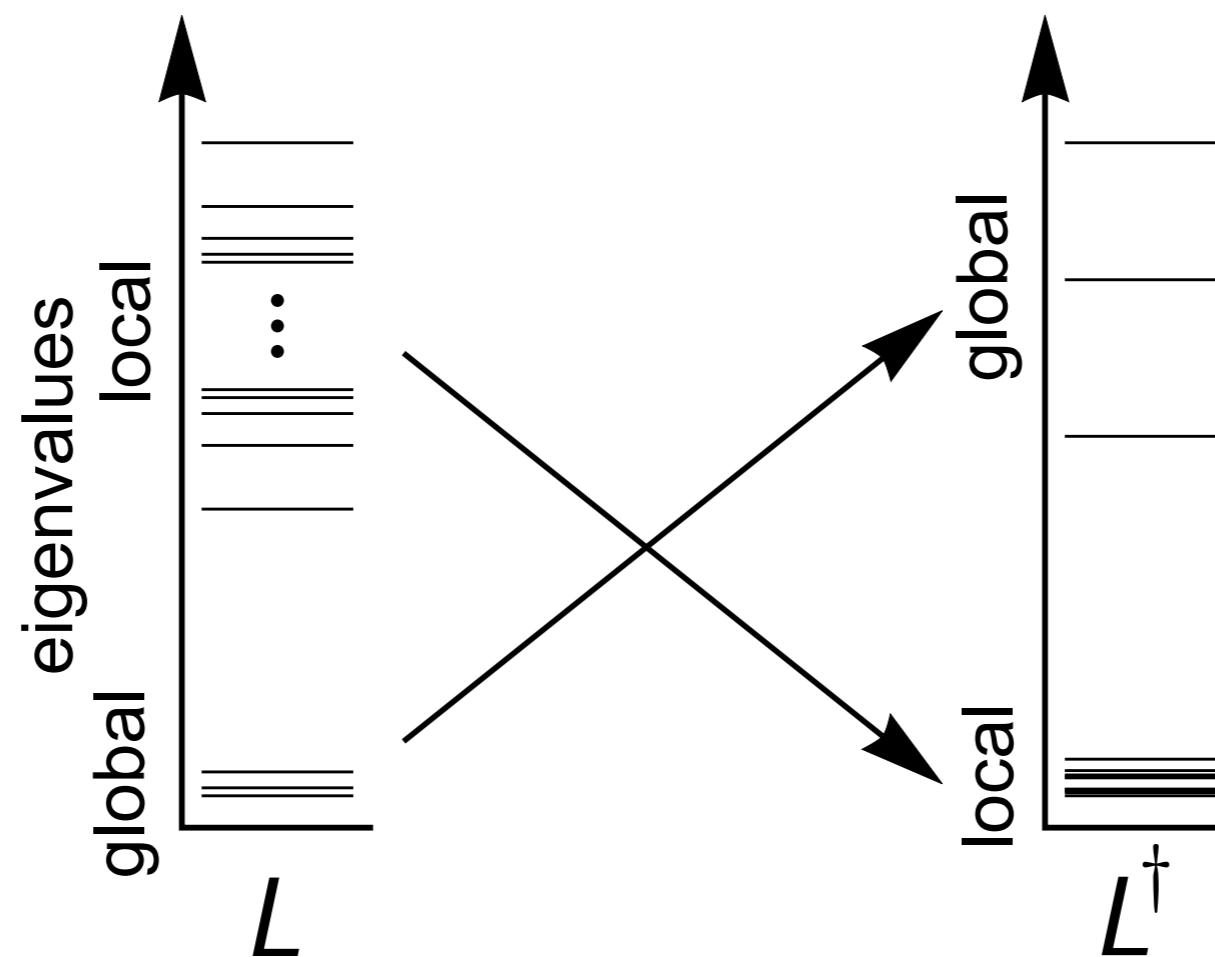
Our algorithm (2019)

edge deletion– and edge contraction/

Laplacian pseudoinverse

Probabilistically preserving the pseudoinverse

Want: $\mathbb{E}[\tilde{L}^\dagger] = L^\dagger$



$$LL^\dagger = L^\dagger L = \mathbf{1} - \frac{1}{|V|} \mathbf{v}_1 \mathbf{v}_1^\top$$

$$L^\dagger = \sum_{k=2}^n \frac{1}{\lambda_k} \mathbf{v}_k \mathbf{v}_k^\top$$

Probabilistically preserving the pseudoinverse

Want: $\mathbb{E}[\tilde{\mathbf{L}}^\dagger] = \mathbf{L}^\dagger$

Change the weight of edge $e = (u, v)$ by Δw :

$$\tilde{\mathbf{L}} = \mathbf{L} + \Delta w \mathbf{b}\mathbf{b}^\top$$

$$(b_i)_{i \in V} = \begin{cases} +1 & \text{if } i = u \\ -1 & \text{if } i = v \\ 0 & \text{otherwise} \end{cases}$$

Probabilistically preserving the pseudoinverse

$$\text{Want: } \mathbb{E}[\tilde{\mathbf{L}}^\dagger] = \mathbf{L}^\dagger$$

Change the weight of edge $e = (u, v)$ by Δw :

$$\tilde{\mathbf{L}} = \mathbf{L} + \Delta w \mathbf{b} \mathbf{b}^\top$$

$$(\mathbf{b}_i)_{i \in V} = \begin{cases} +1 & \text{if } i = u \\ -1 & \text{if } i = v \\ 0 & \text{otherwise} \end{cases}$$

$$\tilde{\mathbf{L}}^\dagger = \mathbf{L}^\dagger - \underbrace{\frac{\Delta w}{1 + \Delta w \mathbf{b}^\top \mathbf{L}^\dagger \mathbf{b}}}_{\text{scalar function of } \Delta w} \times \underbrace{\mathbf{L}^\dagger \mathbf{b} \mathbf{b}^\top \mathbf{L}^\dagger}_{\text{constant matrix}}$$

Probabilistically preserving the pseudoinverse

Change in L^\dagger $\propto \frac{-\Delta w}{\underbrace{1 + \Delta w \Omega}_{\text{scalar function of } \Delta w}}$

$$\Omega = \underbrace{\mathbf{b}^\top L^\dagger \mathbf{b}}_{\text{effective resistance}}$$

Deleting an edge:

$$\begin{aligned}\Delta w &\rightarrow -1 \\ \frac{-\Delta w}{1 + \Delta w \Omega} &\rightarrow \frac{1}{1 - \Omega}\end{aligned}$$

Contracting an edge:

$$\begin{aligned}\Delta w &\rightarrow +\infty \\ \frac{-\Delta w}{1 + \Delta w \Omega} &\rightarrow -\frac{1}{\Omega}\end{aligned}$$

To preserve $\mathbb{E}[L^\dagger]$:

delete with probability $1 - \Omega$
contract with probability Ω

Algorithms for reducing a graph while preserving global structure

Spielman et. al (\sim 2010)

edge deletion–

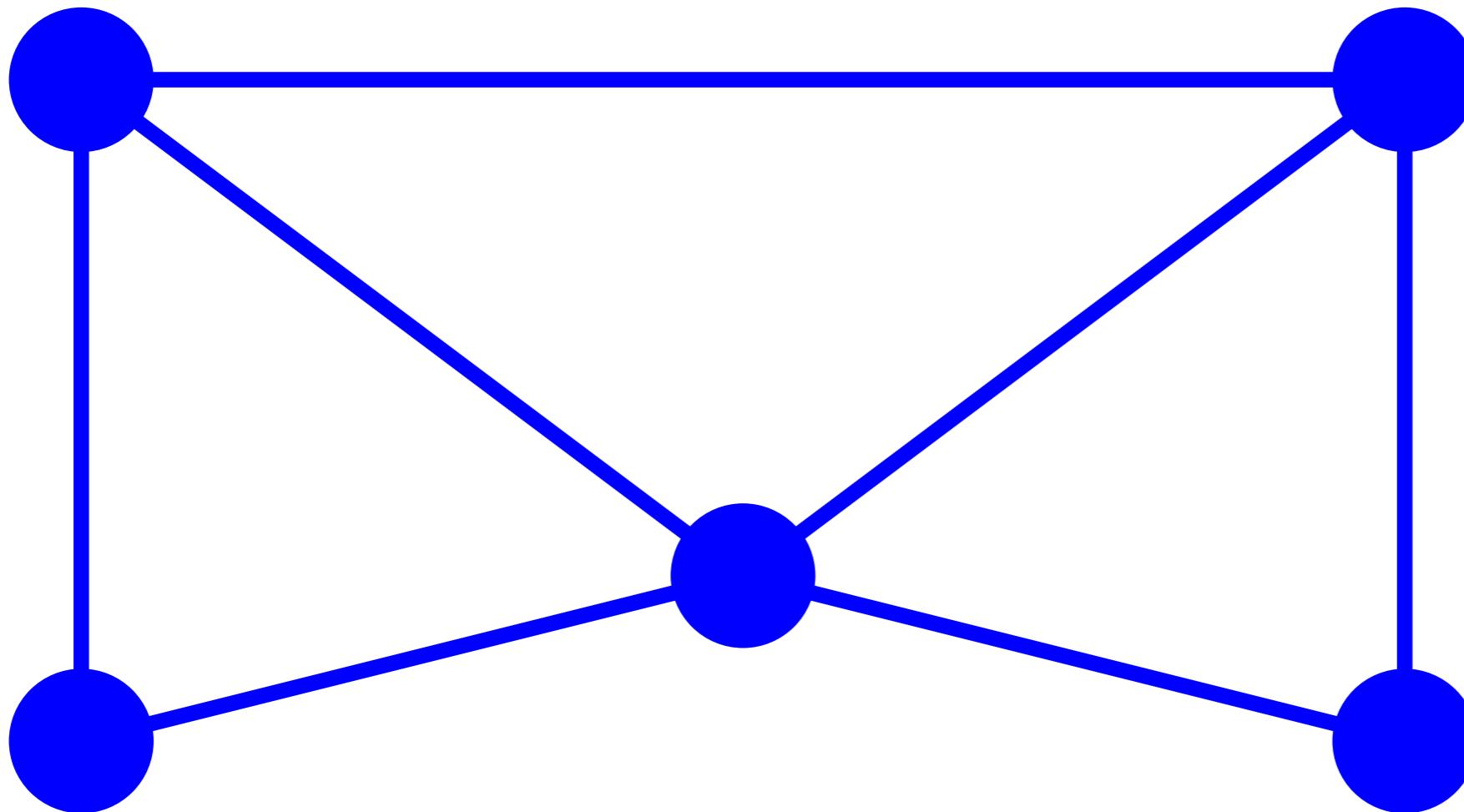
Laplacian quadratic form

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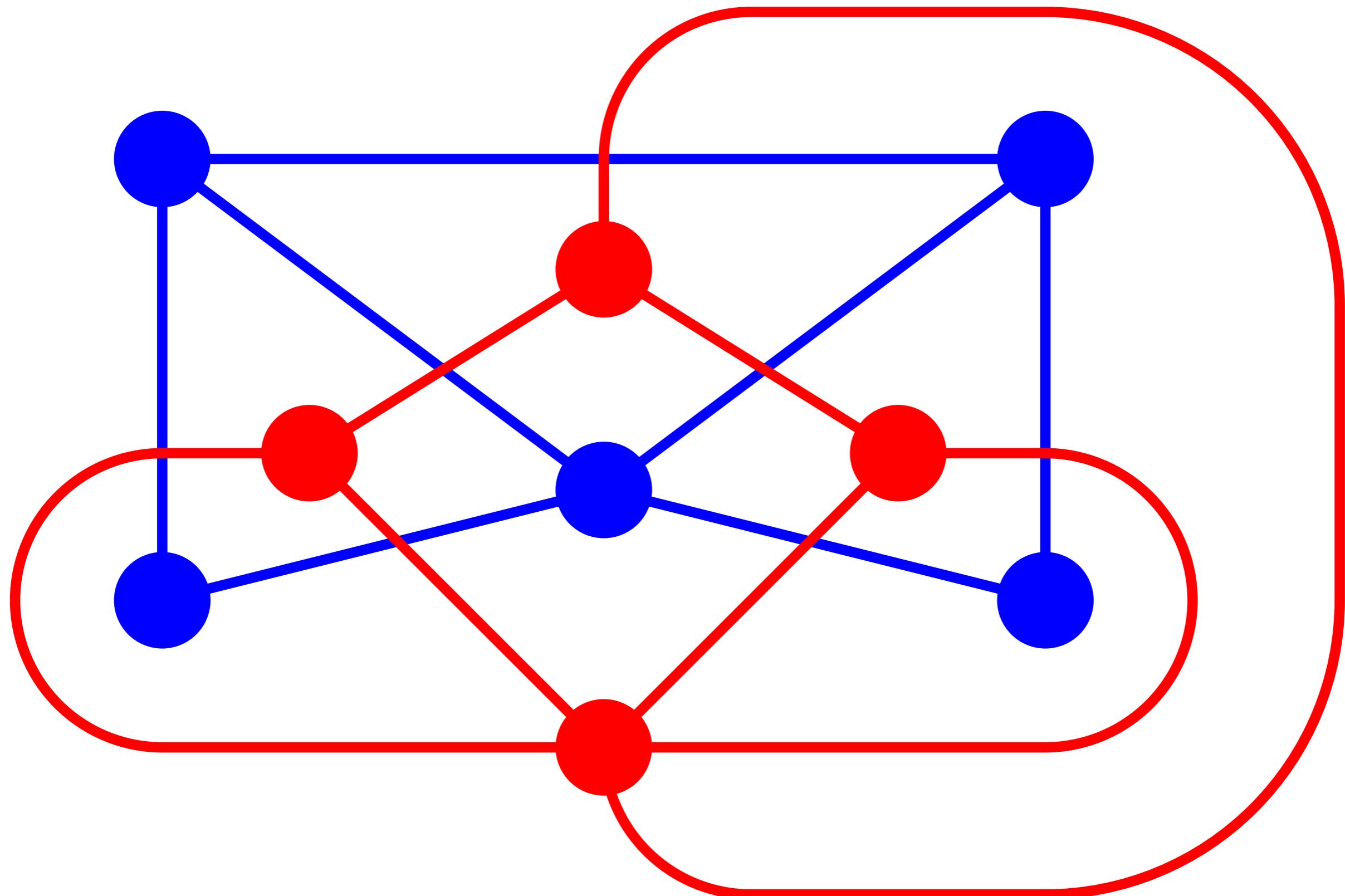
edge deletion– and edge contraction/

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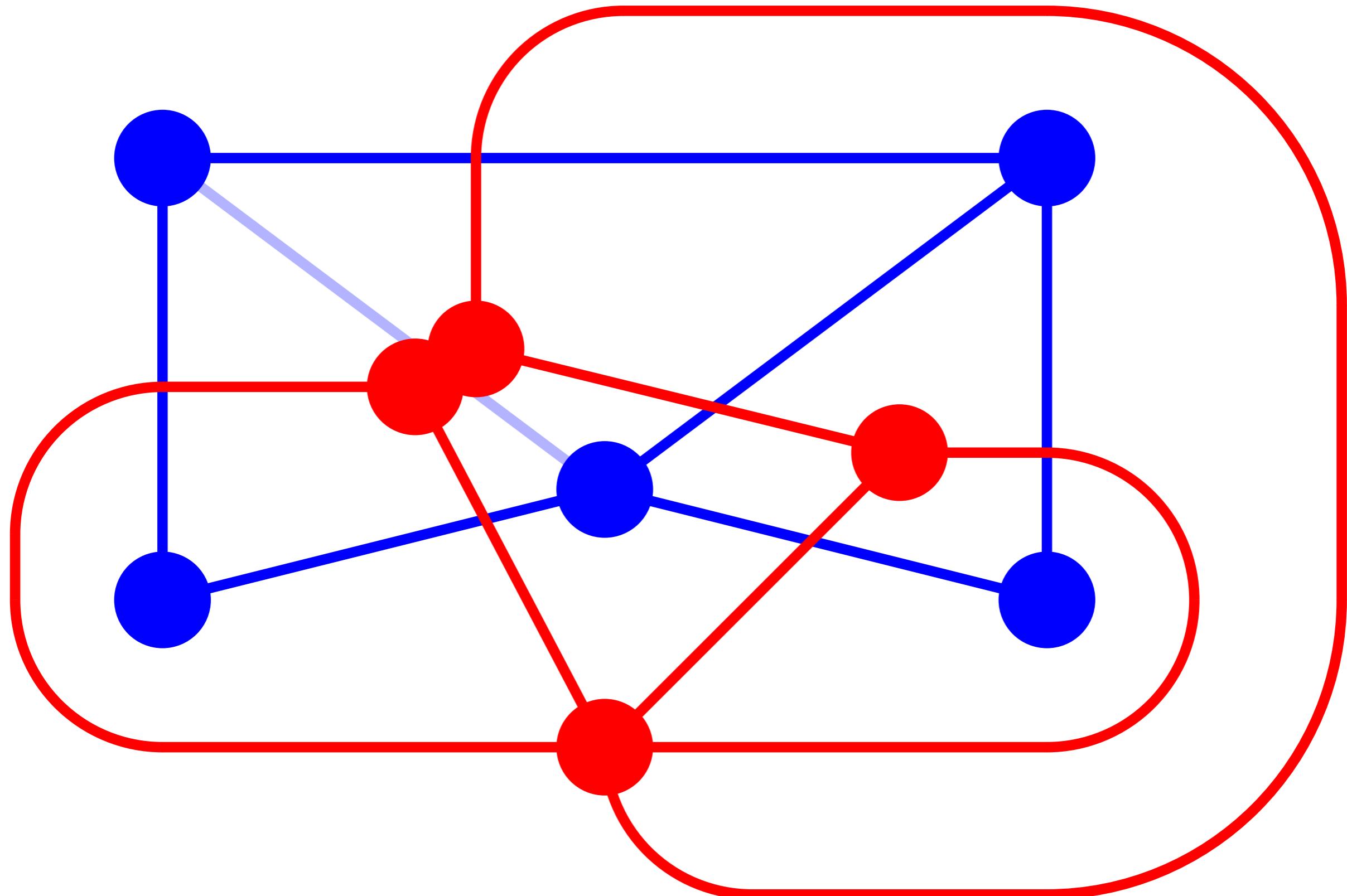
Deletion–Contraction/Duality



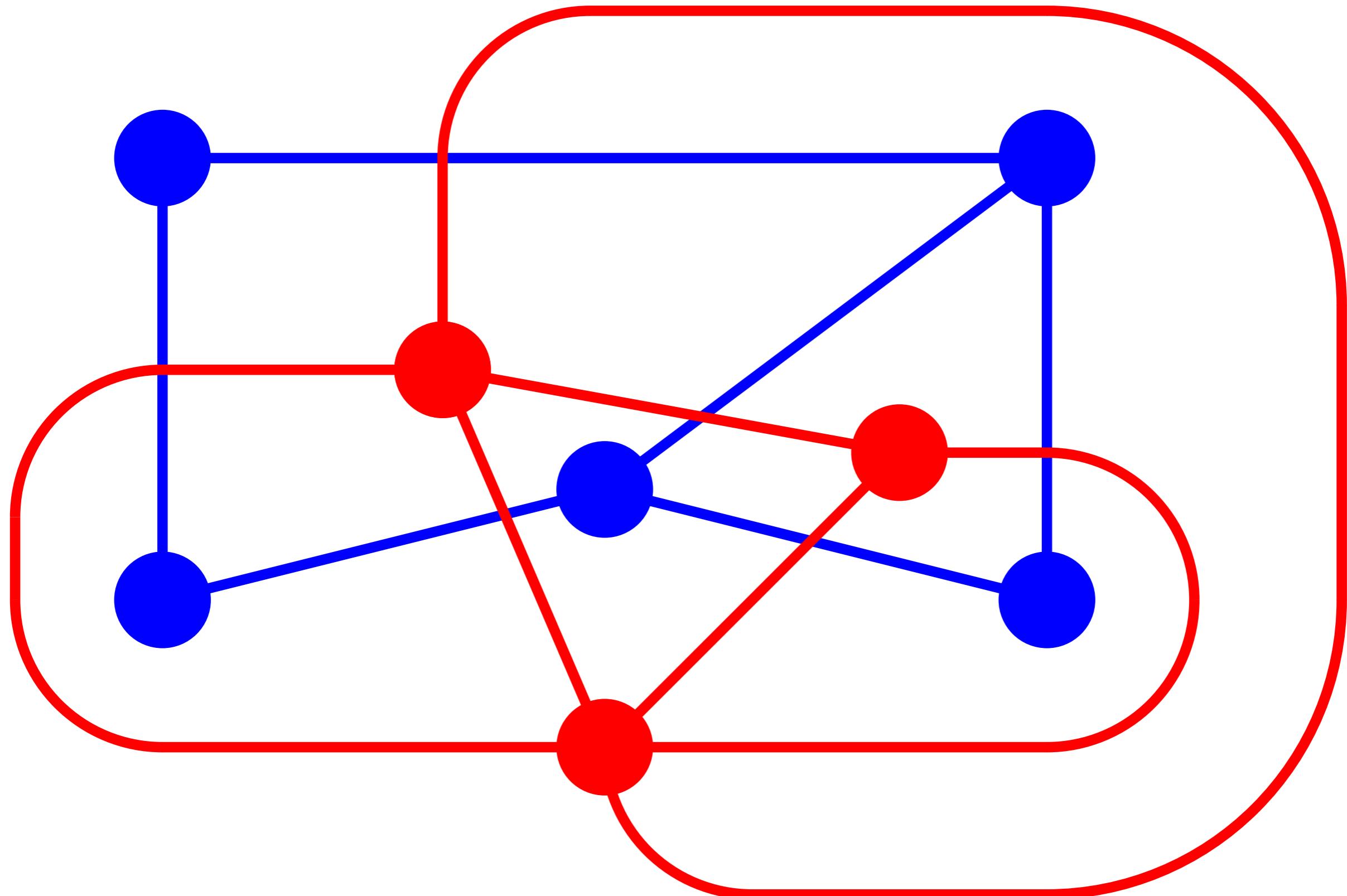
Deletion–Contraction/Duality

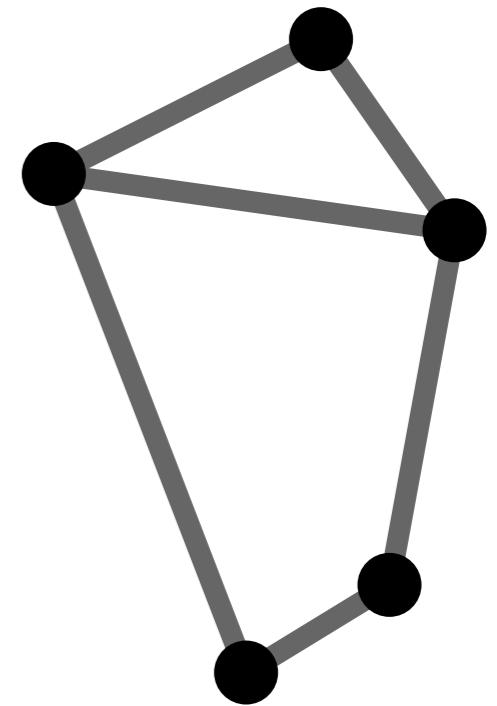


Deletion–Contraction/Duality



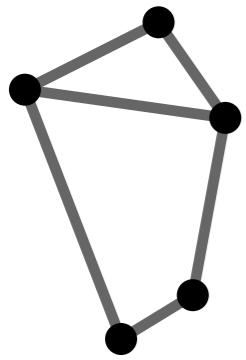
Deletion–Contraction/Duality





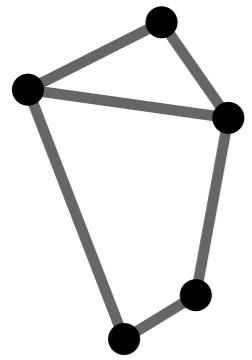
Tutte (polynomial)

$$x + y + 2x^2 + 2xy + y^2 + 2x^3 + x^2y + x^4$$

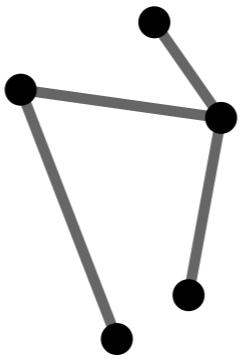


all edges

$$T(x, y) = x + 2x^2 + 2x^3 + x^4 + y + 2xy + x^2y + y^2$$



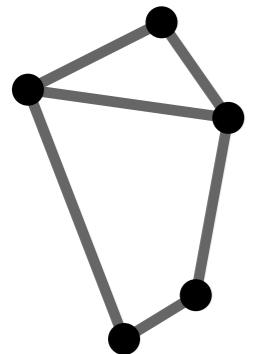
all edges



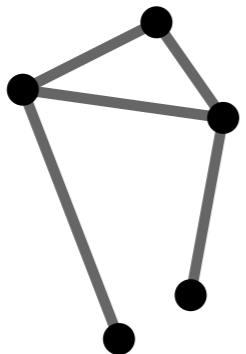
spanning
tree

$$T(x, y) = x + 2x^2 + 2x^3 + x^4 + y + 2xy + x^2y + y^2$$

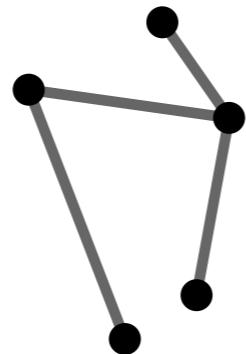
$$T(1, 1) = 11 \quad \text{spanning trees}$$



all edges



spanning
connected
subgraph

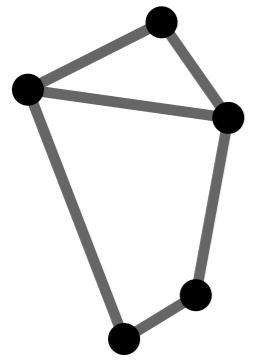


spanning
tree

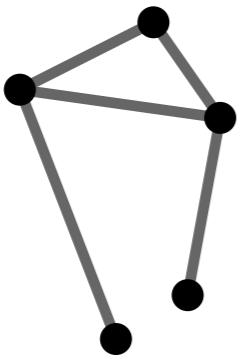
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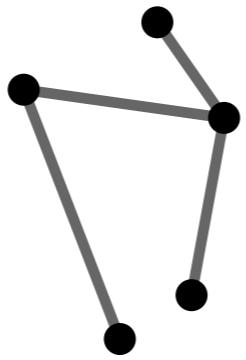
$$T(1, 2) = 18 \quad \text{spanning connected subgraphs}$$



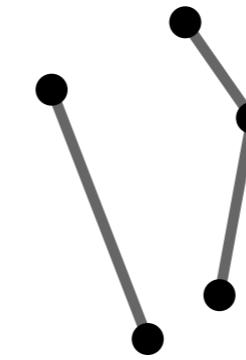
all edges



spanning
connected
subgraph



spanning
tree



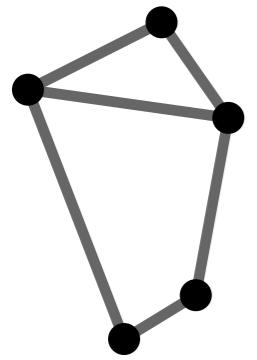
forest

$$T(x, y) = x + 2x^2 + 2x^3 + x^4 + y + 2xy + x^2y + y^2$$

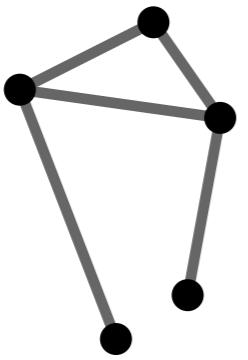
$$T(1, 1) = 11 \quad \text{spanning trees}$$

$$T(1, 2) = 18 \quad \text{spanning connected subgraphs}$$

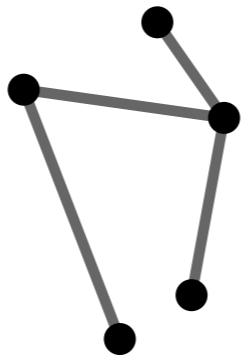
$$T(2, 1) = 52 \quad \text{forests}$$



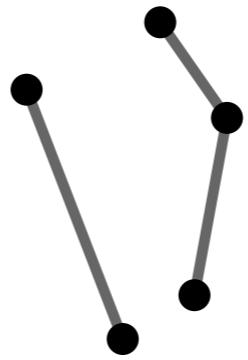
all edges



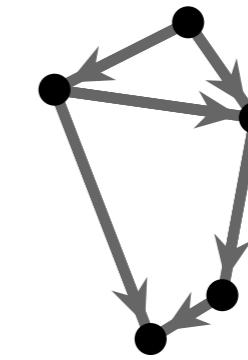
spanning
connected
subgraph



spanning
tree



forest



acyclic
orientation

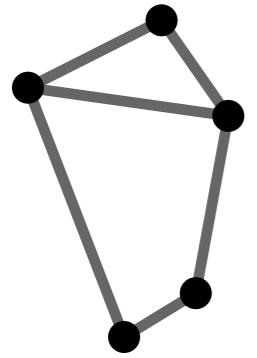
$$T(x, y) = x + 2x^2 + 2x^3 + x^4 + y + 2xy + x^2y + y^2$$

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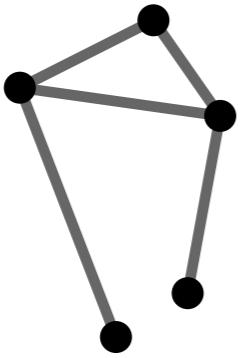
$$T(1, 2) = 18 \quad \text{spanning connected subgraphs}$$

$$T(2, 1) = 52 \quad \text{forests}$$

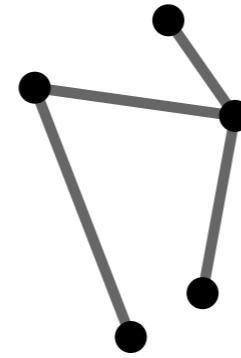
$$T(2, 0) = 42 \quad \text{acyclic orientations}$$



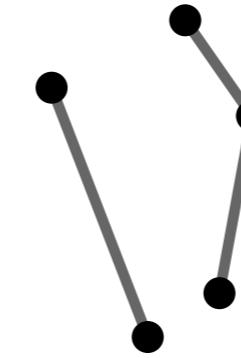
all edges



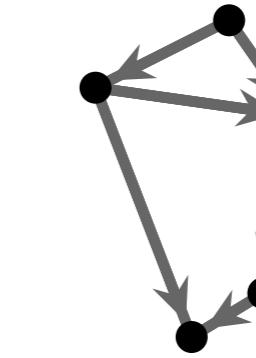
spanning
connected
subgraph



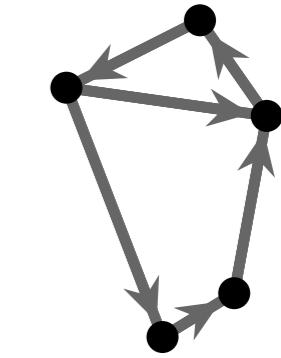
spanning
tree



forest



acyclic
orientation



strongly
connected
orientation

$$T(x, y) = x + 2x^2 + 2x^3 + x^4 + y + 2xy + x^2y + y^2$$

$$T(1, 1) = 11 \quad \text{spanning trees}$$

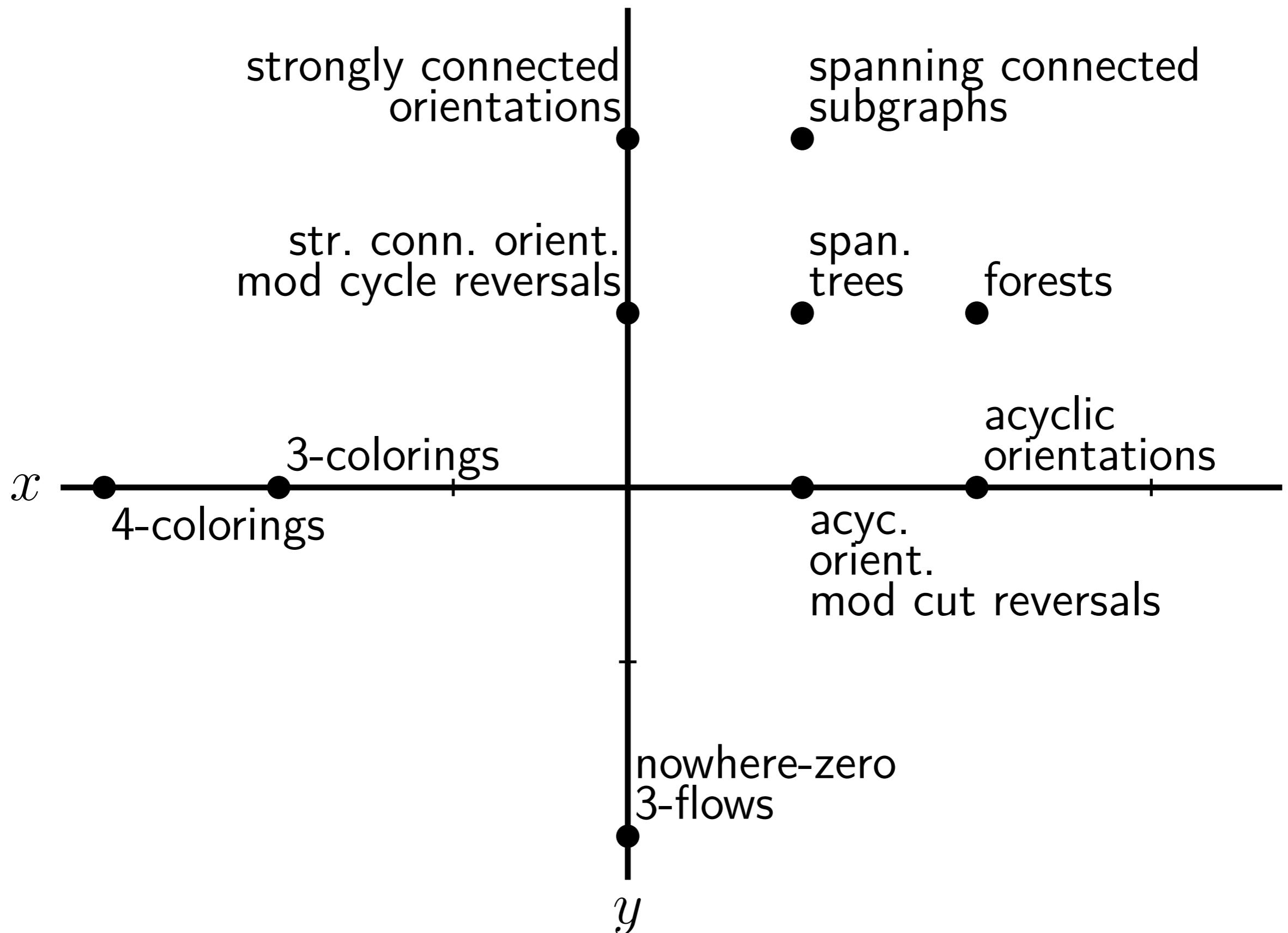
$$T(1, 2) = 18 \quad \text{spanning connected subgraphs}$$

$$T(2, 1) = 52 \quad \text{forests}$$

$$T(2, 0) = 42 \quad \text{acyclic orientations}$$

$$T(0, 2) = 6 \quad \text{strongly connected orientations}$$

Tutte–Grothendieck invariants



Specializations of the Tutte polynomial

polynomial	curve of $T[G](x, y)$
chromatic	x -axis
flow	y -axis
reliability	line $x = 1$
Jones	curve $xy = 1$
q -state Potts model	$(x - 1)(y - 1) = q$

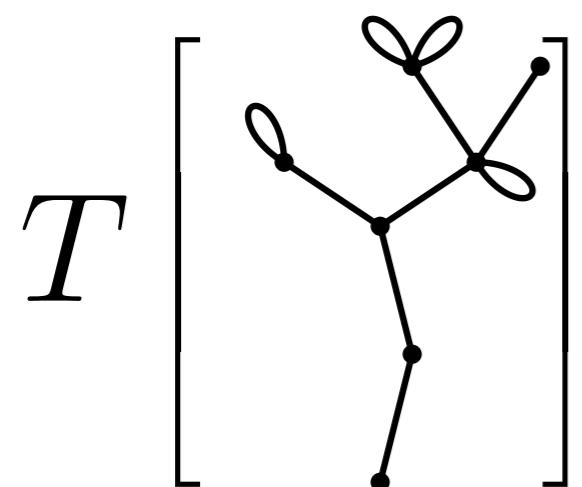
Def. the **Tutte polynomial** of a graph is:

Tutte's deletion and contraction recurrence

Def. the **Tutte polynomial** of a graph is:

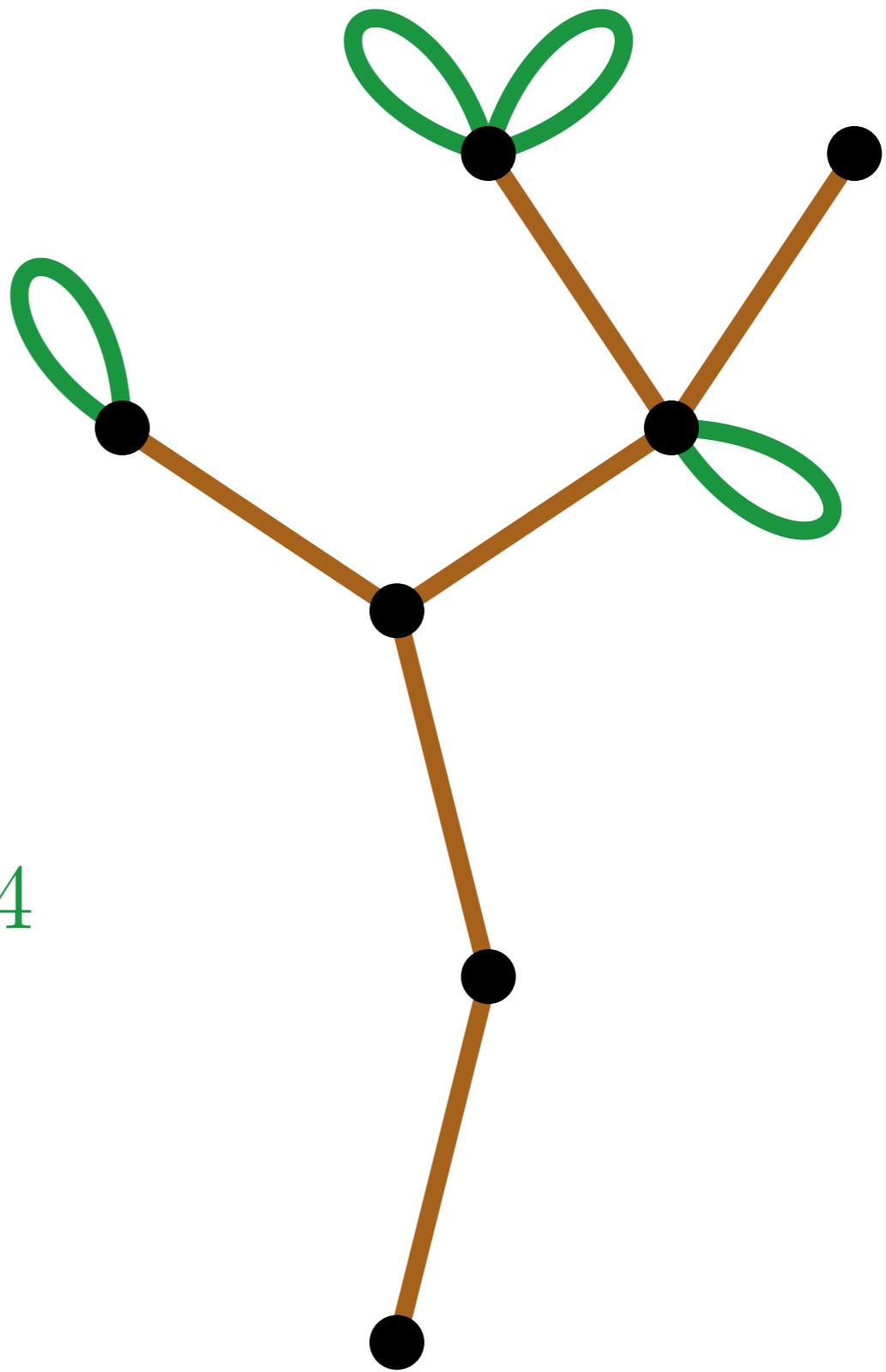
$$T[G](x, y) = \begin{cases} T[G - e] + T[G/e] & \text{if } e \text{ is an} \\ & \text{"ordinary" edge} \\ x^b y^l & \text{if } G \text{ consists of exactly} \\ & b \text{ bridges and } l \text{ self-loops} \end{cases}$$

Monomials are “loopy trees”

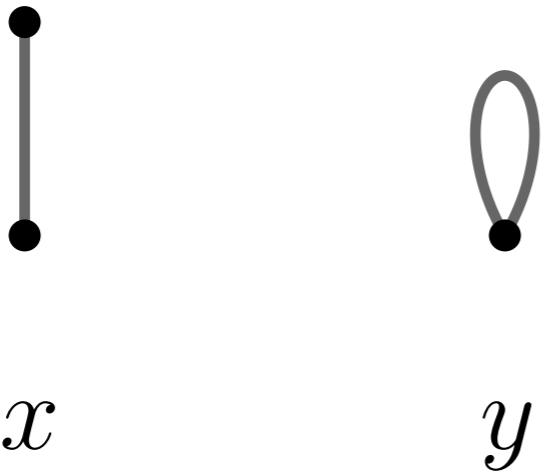


=

$$x^6 y^4$$



Hands-on Tutte evaluation



Hands-on Tutte evaluation

$$\begin{array}{ccc} \text{Diagram } x & + & \text{Diagram } y \\ \text{A vertical edge connecting two black dots} & & \text{A loop consisting of two curved edges meeting at a single black dot} \\ x & & y \end{array} = \text{Diagram } x + y$$

The diagram illustrates the addition of two graphs, x and y , resulting in $x + y$. Graph x is a single vertical edge connecting two black dots. Graph y is a loop consisting of two curved edges meeting at a single black dot. The sum $x + y$ is a graph where the two black dots from x and y are connected by a single curved edge, forming a loop.

Hands-on Tutte evaluation

 x  y  $x + y$  $x^2 + 2xy + y^2$

Hands-on Tutte evaluation



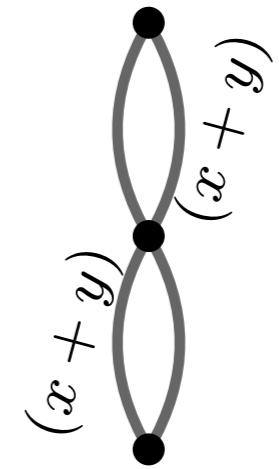
x



y



$x + y$



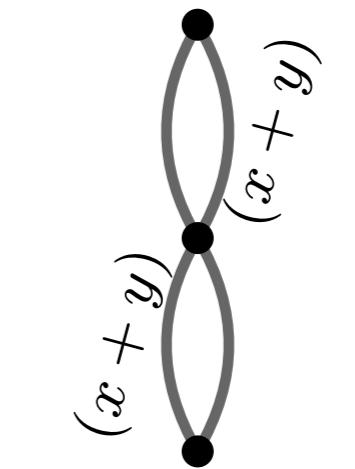
$x^2 + 2xy + y^2$

Hands-on Tutte evaluation

$$x$$

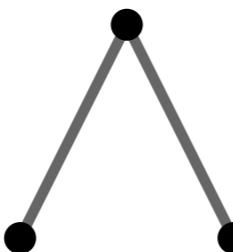

$$y$$


$$x + y$$


$$(x+y)^2$$




 $=$



 $+$

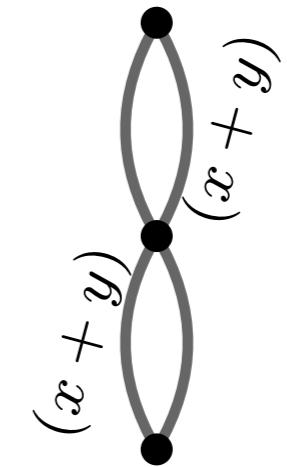


Hands-on Tutte evaluation

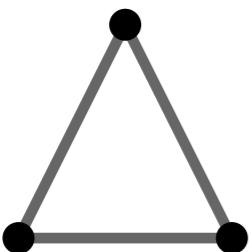

$$x$$


$$y$$


$$x + y$$


$$(x + y)$$

$$x^2 + 2xy + y^2$$



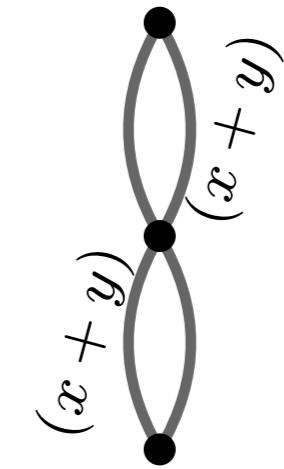
$$x^2 + x + y$$

Hands-on Tutte evaluation

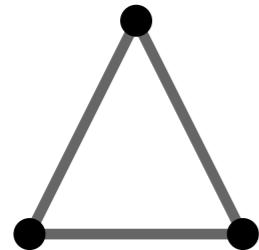
$$x$$

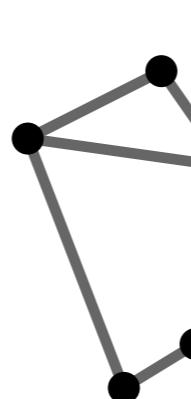

$$y$$


$$x + y$$

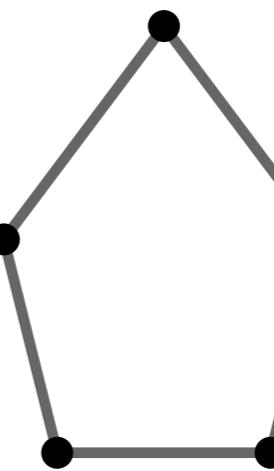

$$(x+y)^2$$


$$x^2 + 2xy + y^2$$

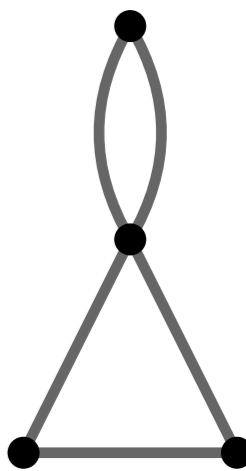
$$x^2 + x + y$$




 $=$



 $+$

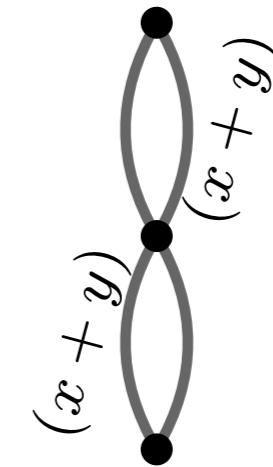


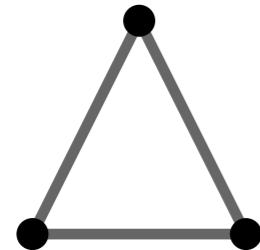
Hands-on Tutte evaluation

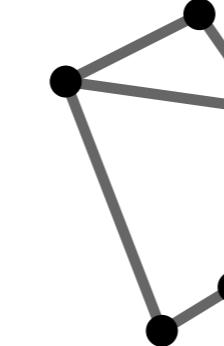
$$x$$


$$y$$

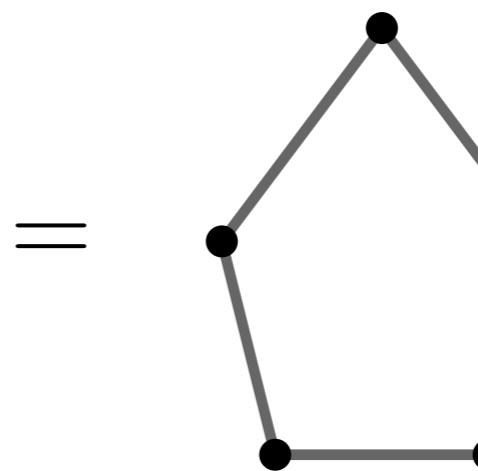

$$x + y$$

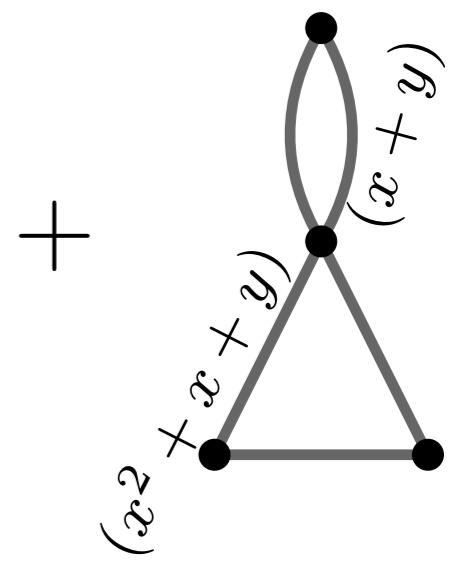

$$(x+y)$$


$$x^2 + x + y$$




 $=$

$$x^4 + x^3 + x^2 + x + y$$


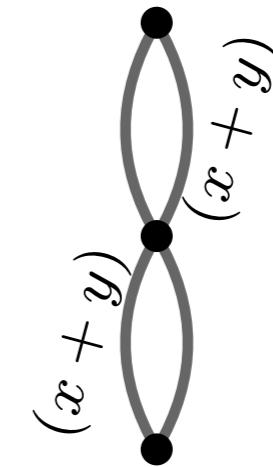
$$+$$

$$(x^2 + x + y)$$

Hands-on Tutte evaluation

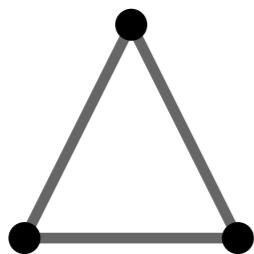

$$x$$


$$y$$

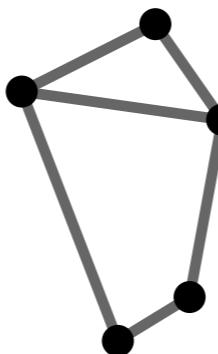

$$x + y$$


$$(x+y)$$

$$x^2 + 2xy + y^2$$



$$x^2 + x + y$$



$$x^4 + x^3 + x^2 + x + y + (x^2 + x + y)(x + y)$$

Def. For a connected graph $G = (V, E)$,
the **Tutte polynomial** is:

$$T[G](x, y) = \sum_{S \in E} = (x - 1)^{\text{corank}(S)}(y - 1)^{\text{nullity}(S)}$$

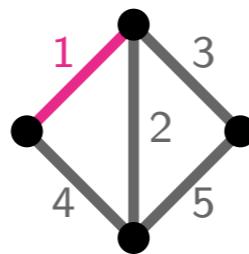
$\text{corank}(S) = \# \text{ edges}$ needed to **add** to
get a **connected** subgraph.

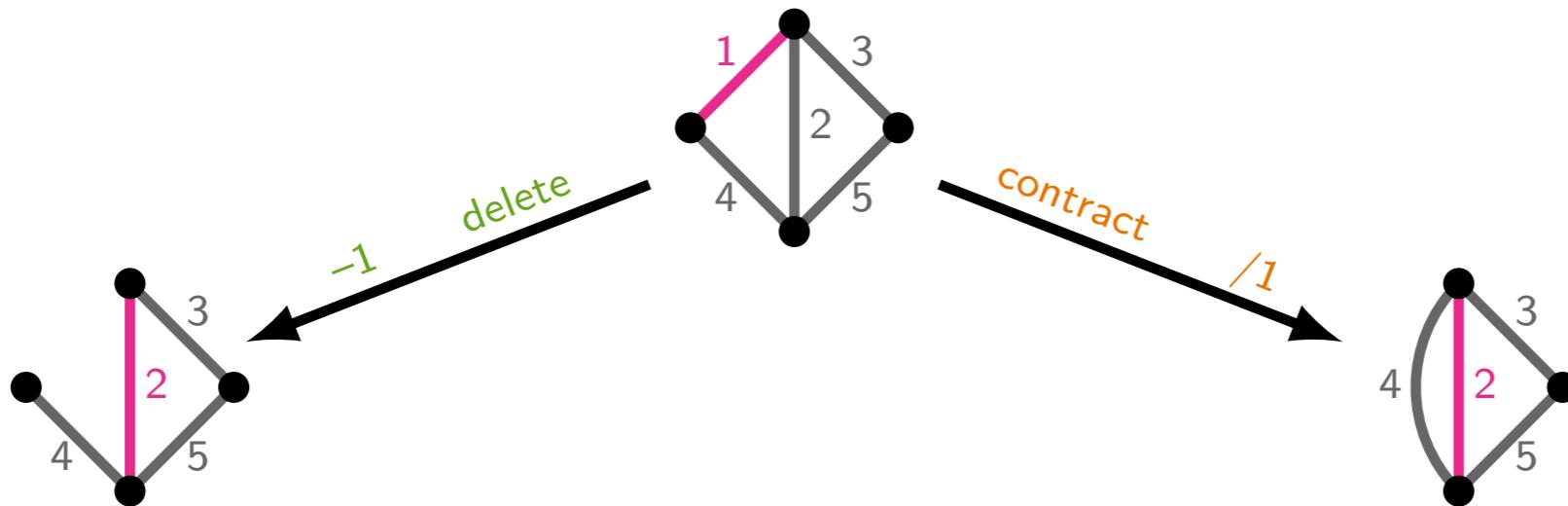
$\text{nullity}(S) = \# \text{ edges}$ needed to **delete** to
get an **acyclic** subgraph.

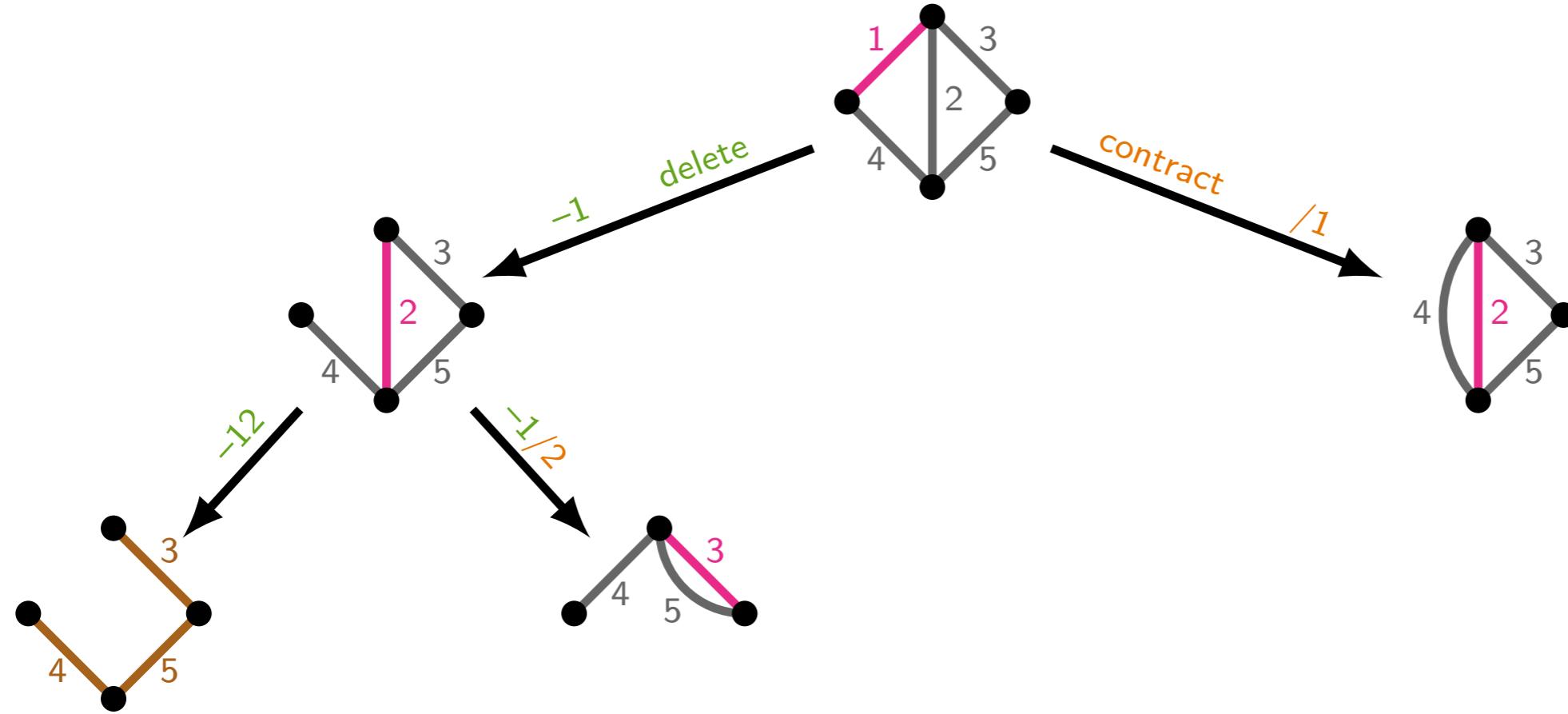
Tutte's deletion and contraction recurrence

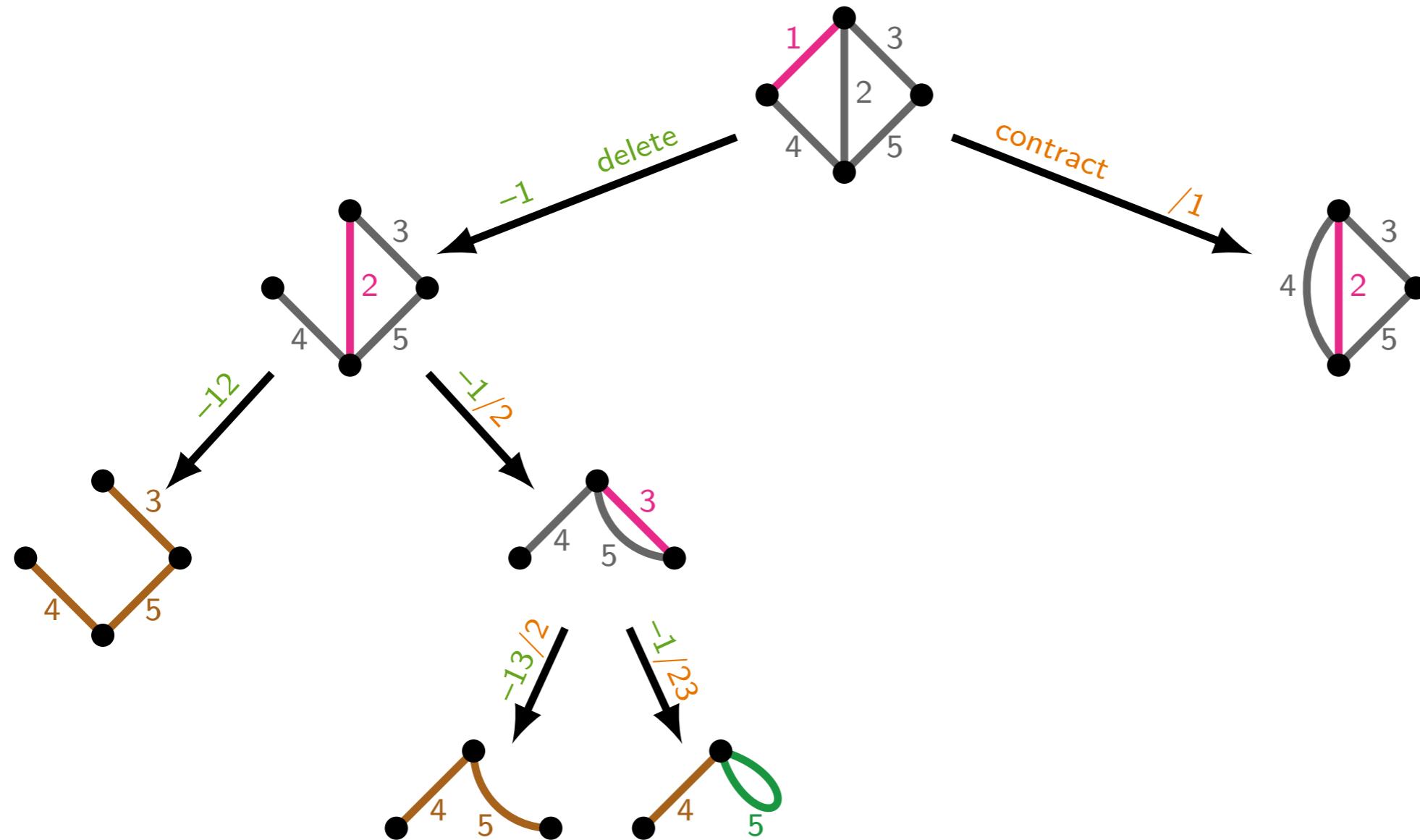
Def. the **Tutte polynomial** of a graph is:

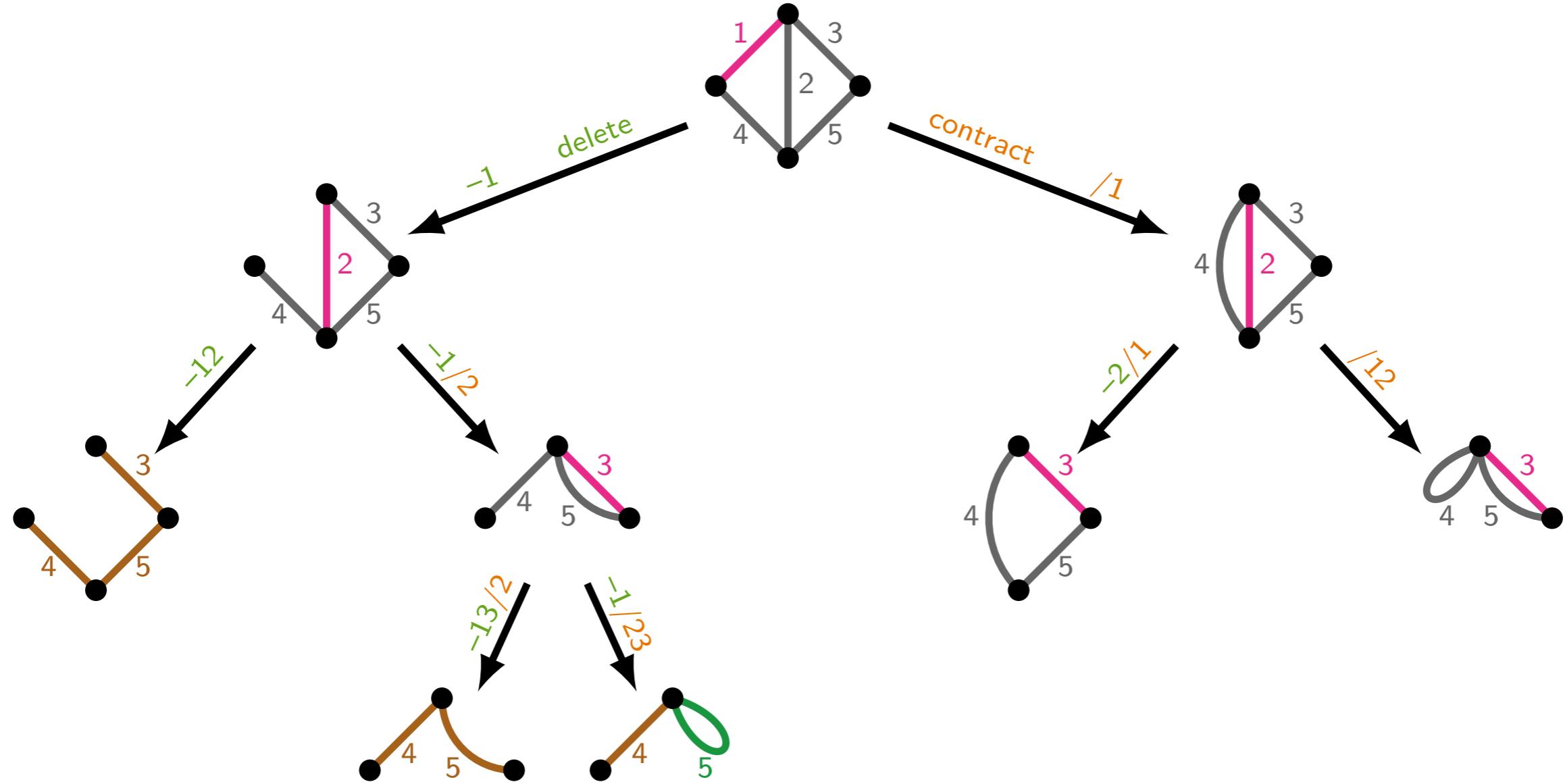
$$T[G](x, y) = \begin{cases} T[G - e] + T[G/e] & \text{if } e \text{ is an} \\ & \text{"ordinary" edge} \\ x^b y^l & \text{if } G \text{ consists of exactly} \\ & b \text{ bridges and } l \text{ self-loops} \end{cases}$$

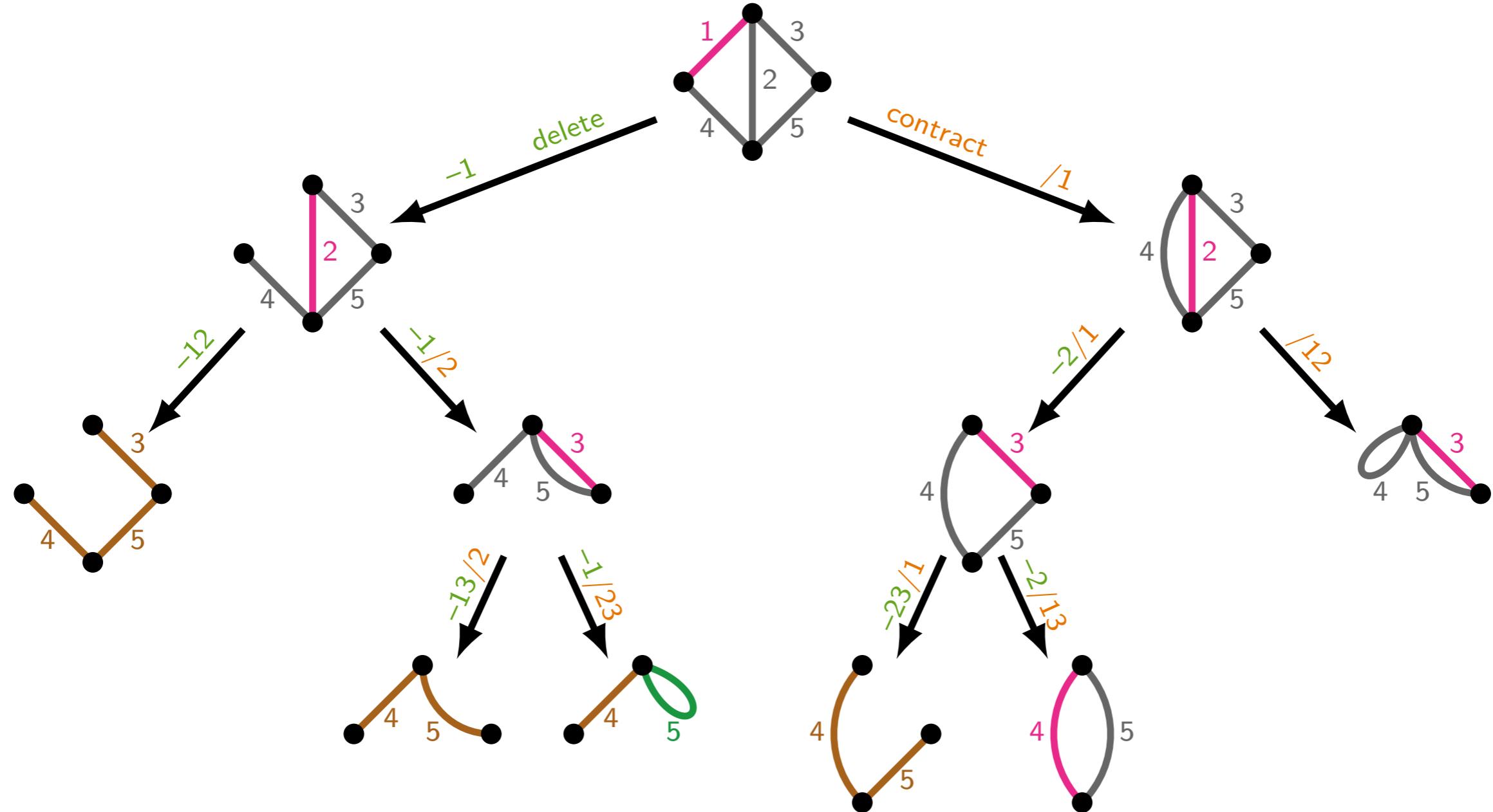


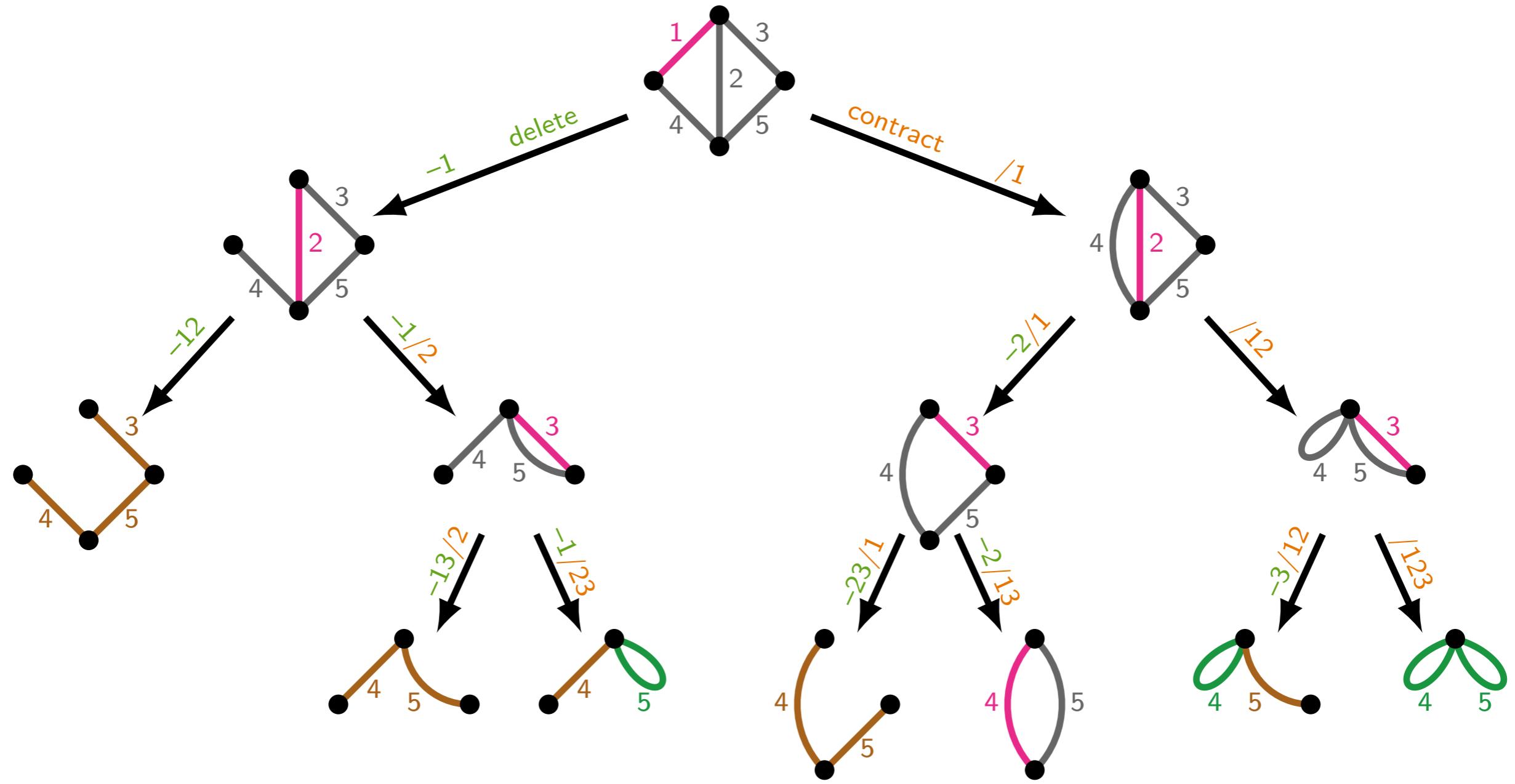


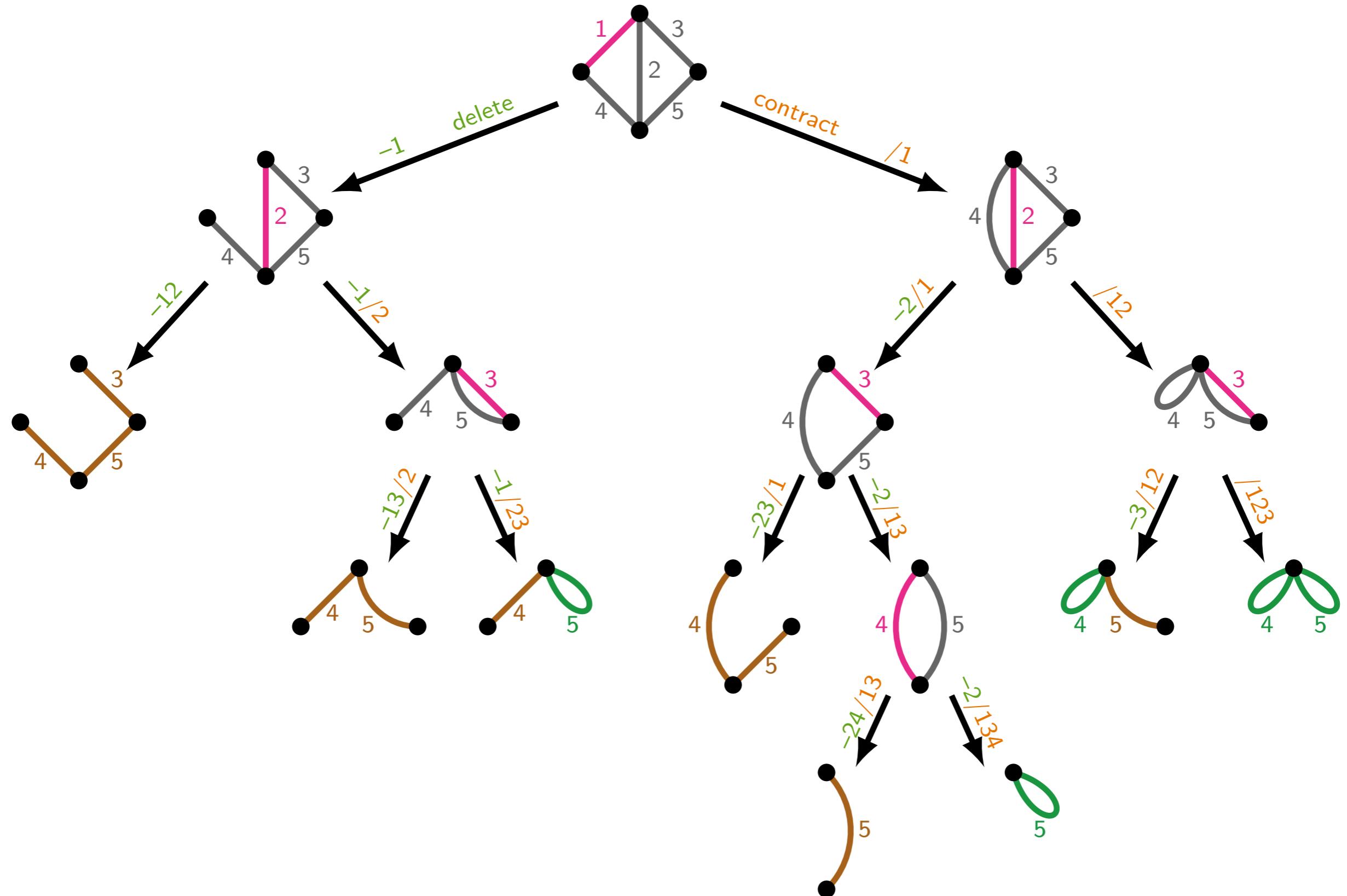


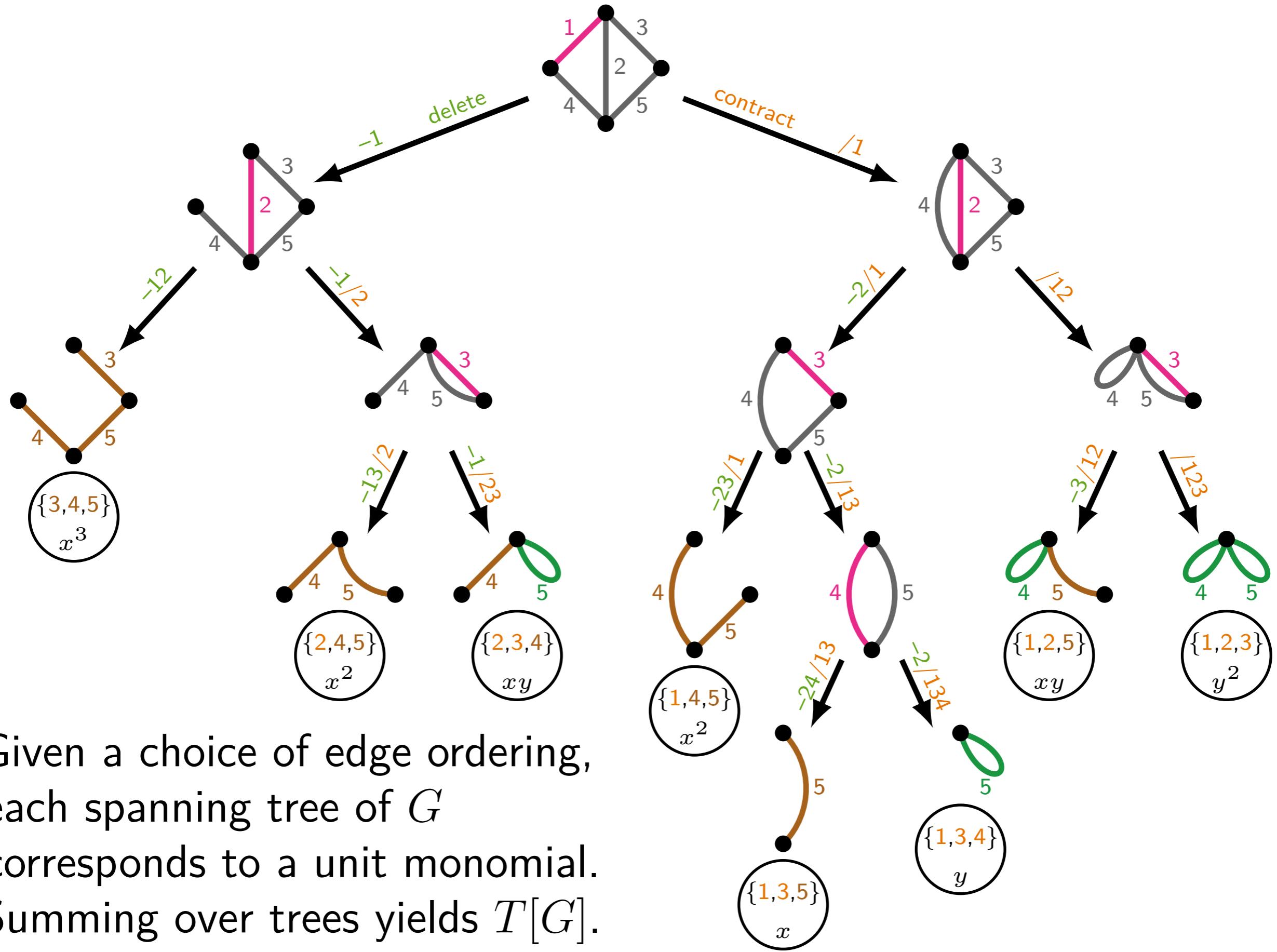




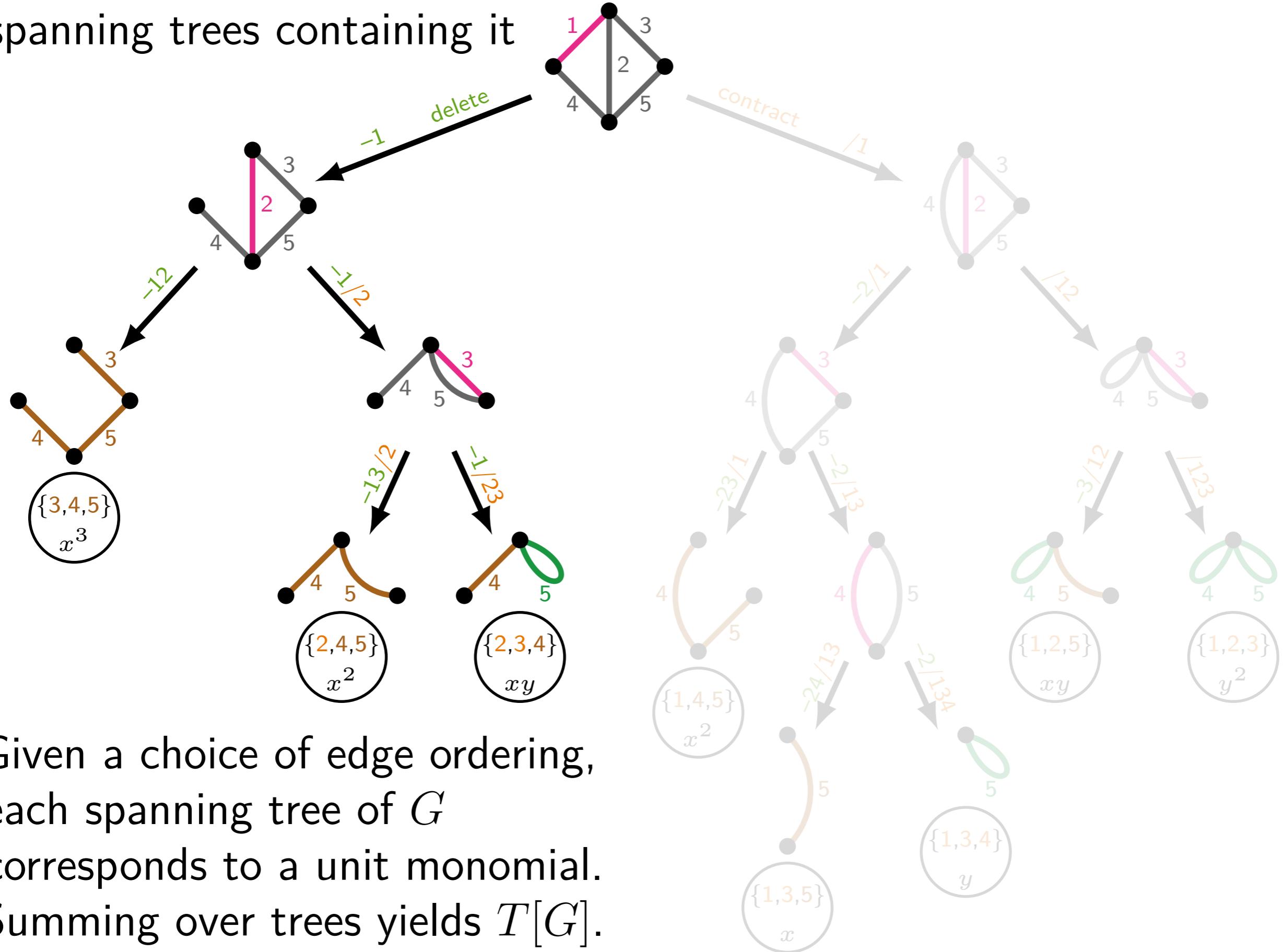




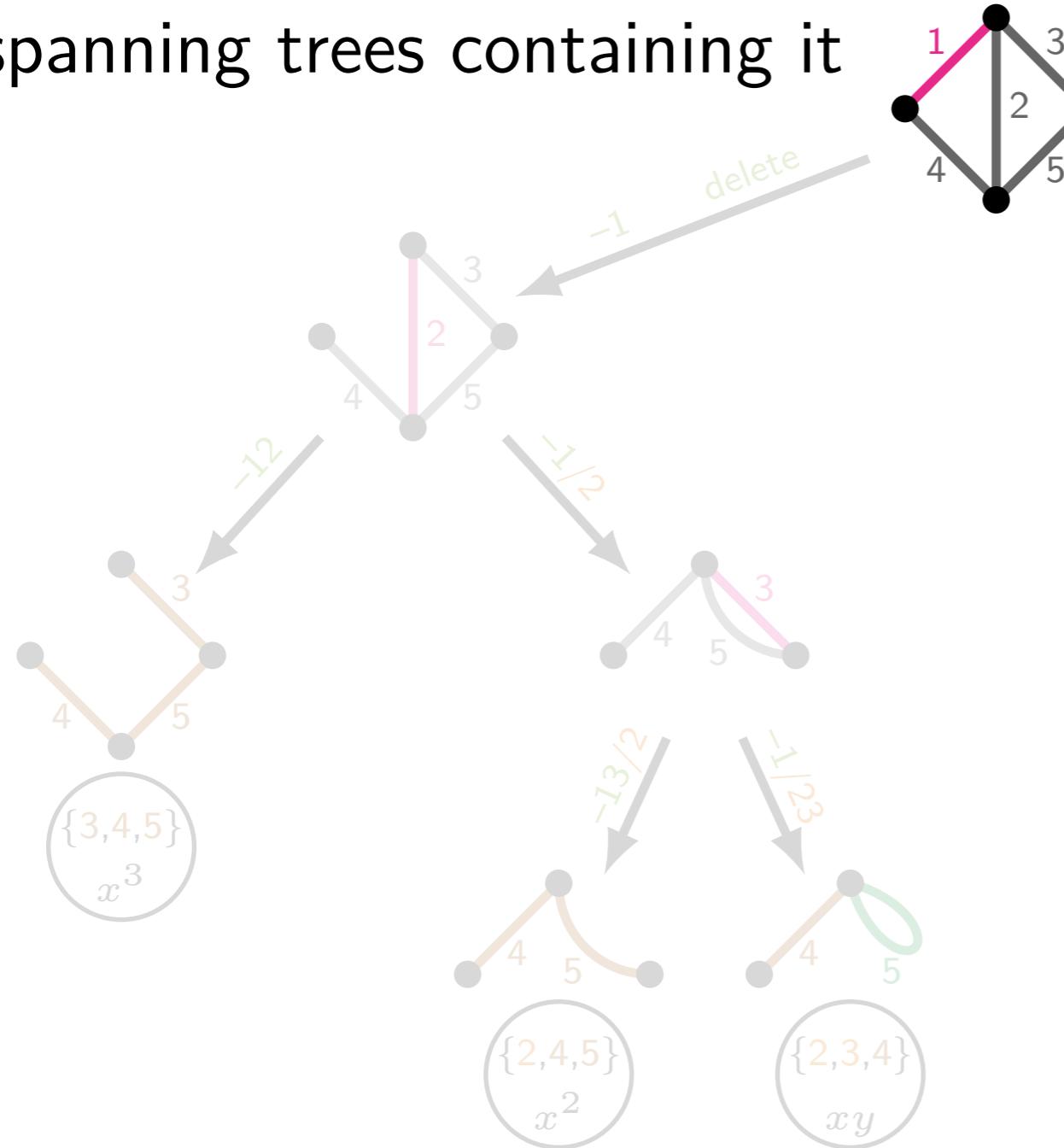




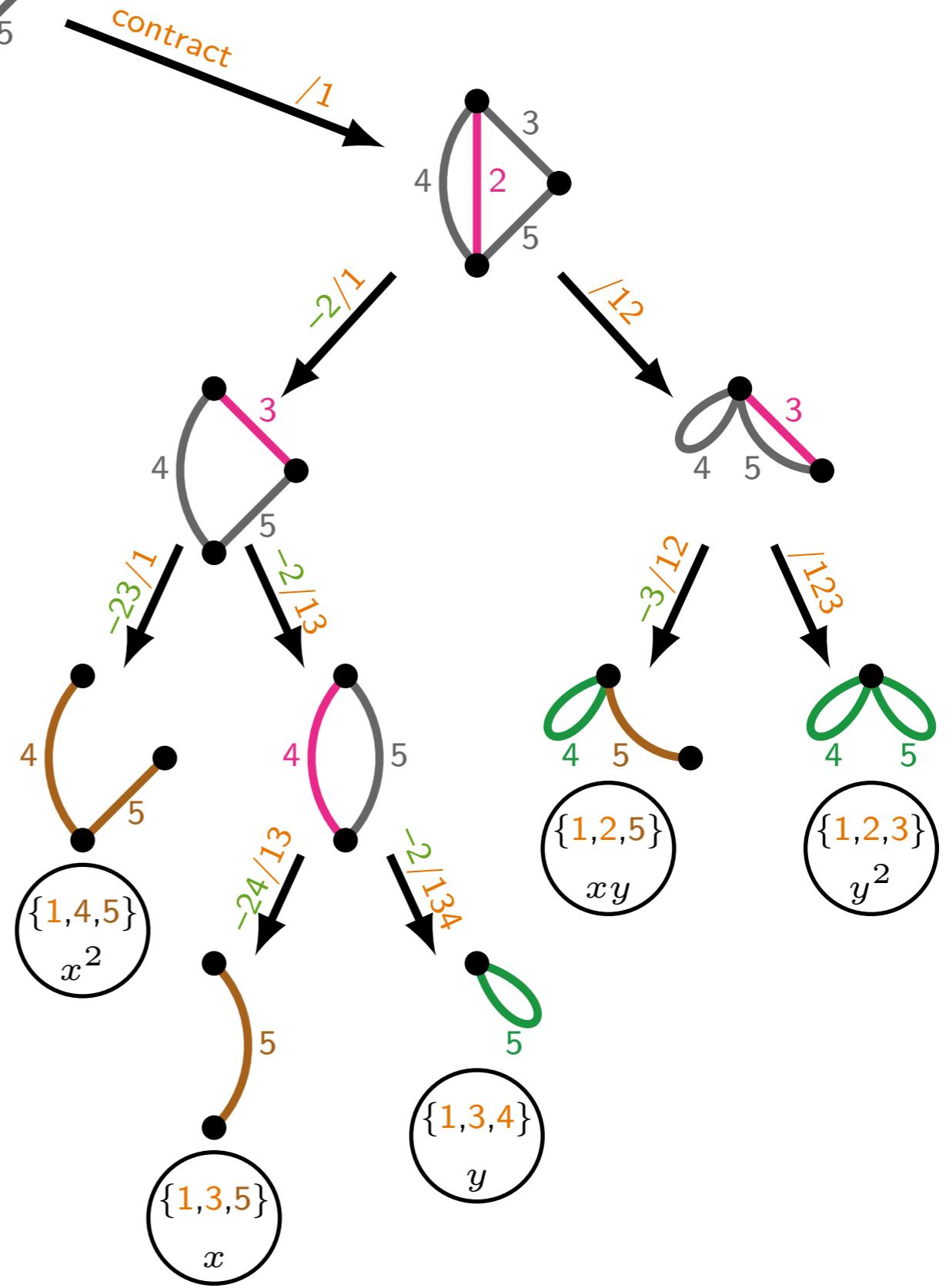
Deleting an edge **removes** the spanning trees containing it



Deleting an edge **removes** the spanning trees containing it



Contracting an edge keeps **only** the spanning trees containing it

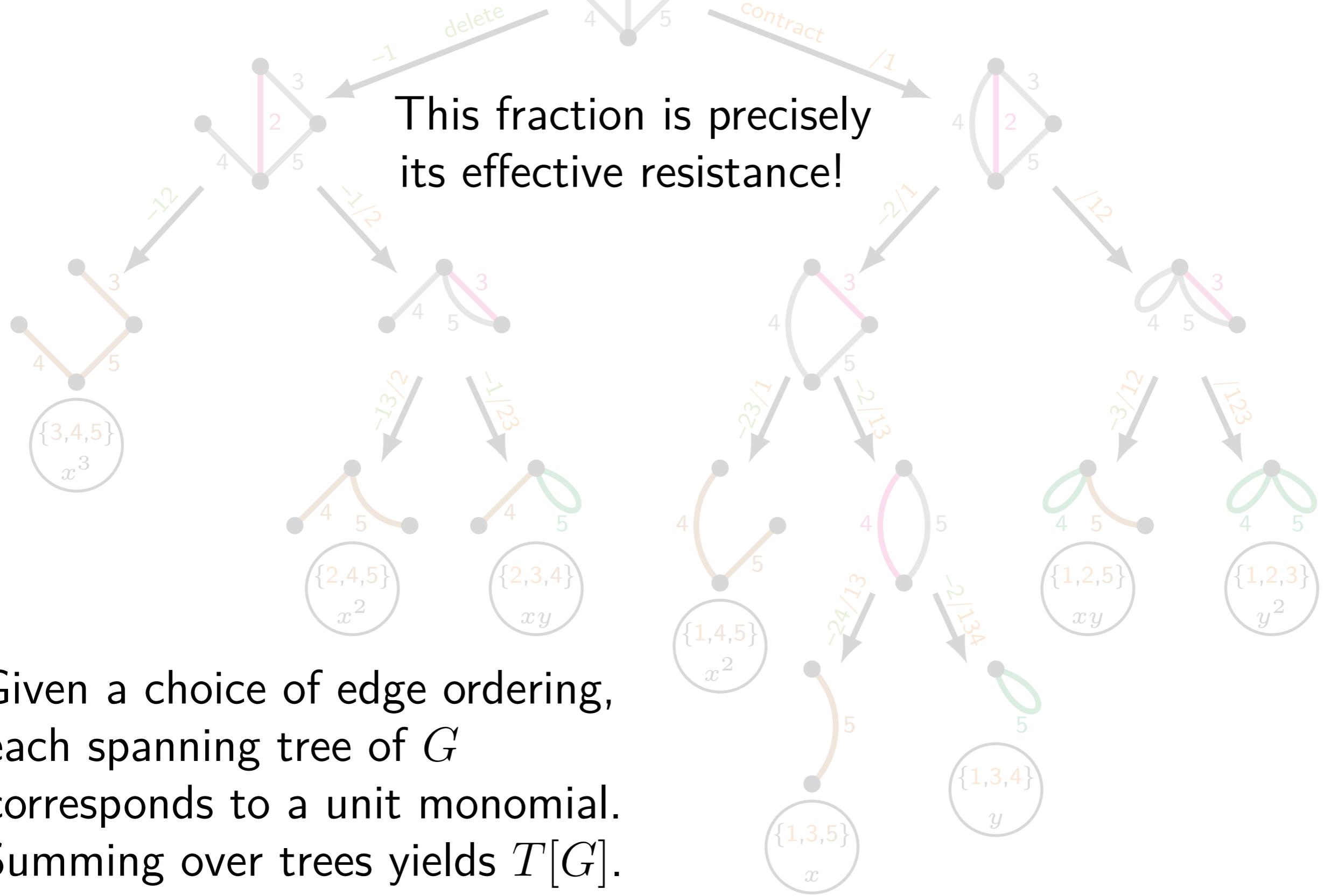


Given a choice of edge ordering,
each spanning tree of G
corresponds to a unit monomial.
Summing over trees yields $T[G]$.

Deleting an edge **removes** the spanning trees containing it

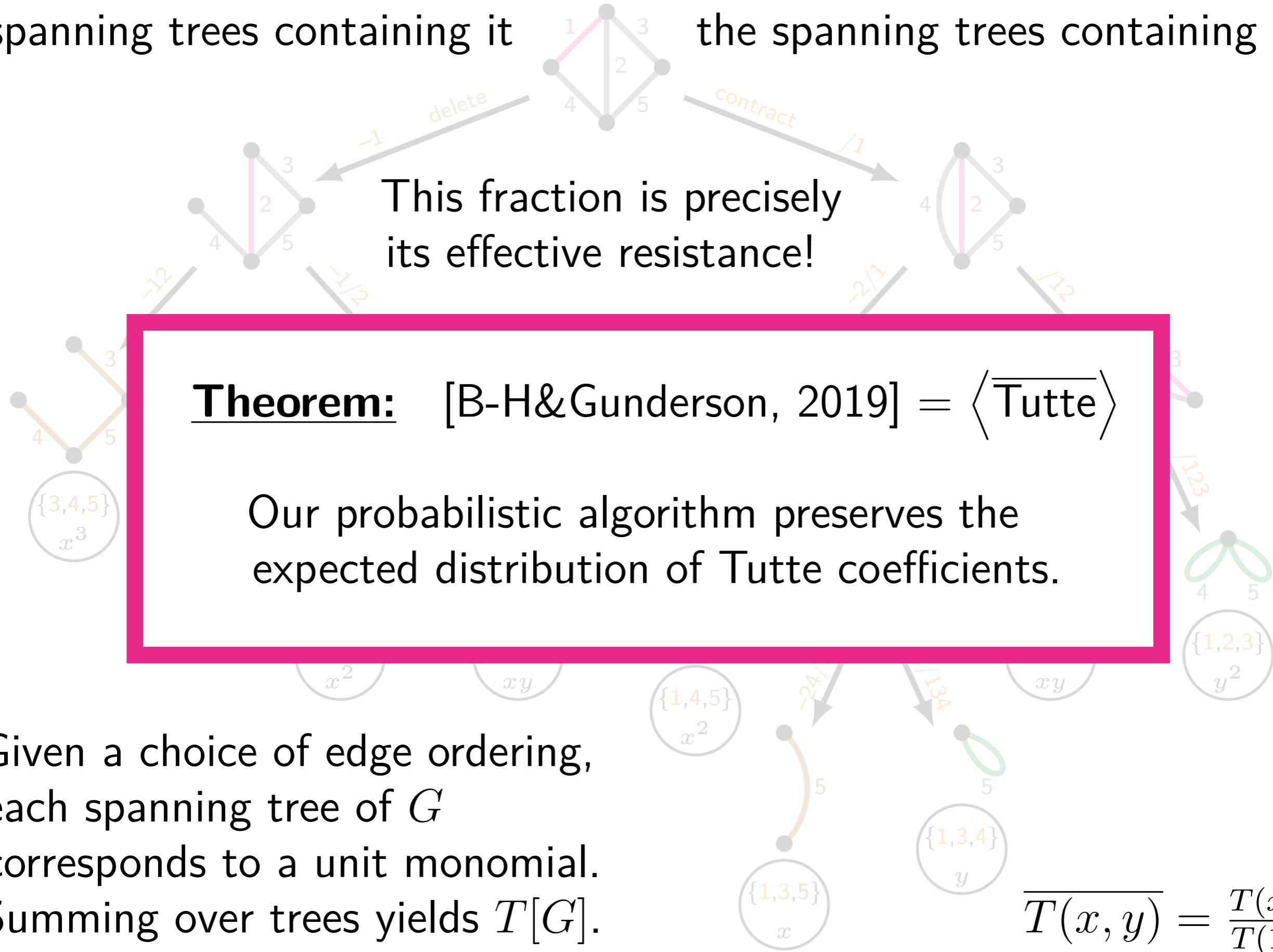


Contracting an edge keeps **only** the spanning trees containing it



Deleting an edge **removes** the spanning trees containing it

Contracting an edge keeps **only** the spanning trees containing it



Some Platonic Solids

Tetrahedron: $x^3 + 3x^2 + 4xy + 2x + y^3 + 3y^2 + 2y$

Cube: $x^7 + 5x^6 + 15x^5 + 6x^4y + 29x^4 + 24x^3y \dots$

Octahedron: $y^7 + 5y^6 + 15y^5 + 6y^4x + 29y^4 + 24y^3x \dots$

$$T[G](x, y) = T[G^\star](y, x)$$

Specializations of the Tutte polynomial

polynomial	curve of $T[G](x, y)$
chromatic	x -axis
flow	y -axis
reliability	line $x = 1$
Jones	curve $xy = 1$
q -state Potts model	$(x - 1)(y - 1) = q$

Flows

Assign direction to every edge in the graph G

A **nowhere-zero k -flow** assigns a flow value $f(e)$ from $\mathbb{Z}_k - \{0\}$ to every edge e of G such that, at every vertex, Kirchoff's current law holds, ie

flow in = flow out

- If G has a nowhere-zero k -flow, then G has no bridge edges.
- A bridgeless (ie, two-connected) planar graph G has a nowhere-zero k -flow iff its dual G^* is k -colorable.

Flow conjectures

Conjecture (Tutte, 1954)

There is a fixed number t such that every two-connected graph has a nowhere-zero t -flow.

Theorem (Jaeger, 1975)

Every two-connected graph has a nowhere-zero 8-flow.

Flow conjectures

Conjecture (Tutte, 1954)

Every two-connected graph has
a nowhere-zero 5-flow.

Tutte also conjectured that if, in addition,
 G doesn't have Petersen graph as minor,
then G has a nowhere-zero 4-flow.

Theorem (Seymour, 1981)

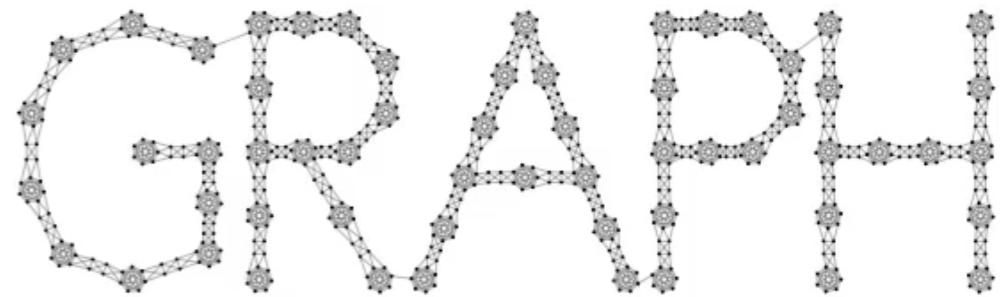
Every two-connected graph has
a nowhere-zero 6-flow.

Selected references



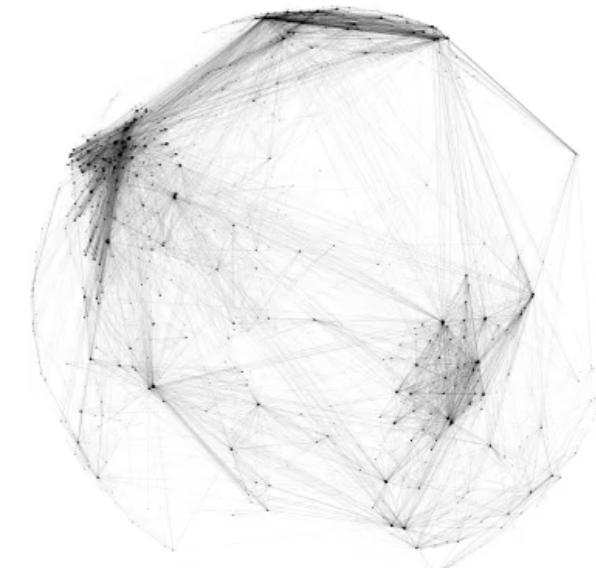
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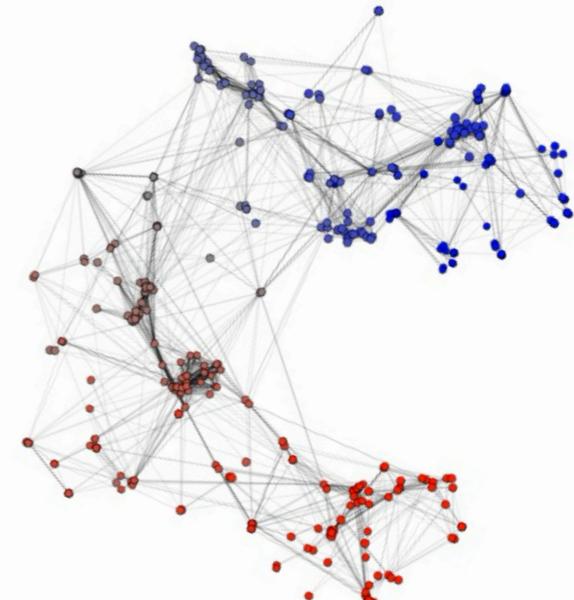
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Number 11. Oxford University Press.

extra slides

Deletion and contraction recurrence II

$$T[G](x, y) = \begin{cases} 1 & \text{if } G \text{ has no edges} \\ xT[G/e] & \text{if } e \text{ is a bridge} \\ yT[G - e] & \text{if } e \text{ is a self-loop} \\ T[G - e] + T[G/e] & \text{if } e \text{ is neither} \end{cases}$$

Merino-Welsh conjecture

$$\max\{T[G](2,0), T[G](0,2)\} \geq T[G](1,1)$$

