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LAB1 – BER

## Code Snips

First generate random data and save it in data vector, then calculate the signal power which is the Expectations of  $E(x^2)$ , then generate SNR range in decibel (dB) and in linear scale, then create two vectors of length  $N$  to hold the received sequence which will be the original data + noise, then the received bits is the sampled bits after adding the noise.

```
clc; clear;

% Number of bits
N=1e6;

% Generate random binary data vector (sent signal)
data = randi([0,1],1,N);

% Calculate transmitted signal power =E(x^2)
sigPower = mean(data.^2);

% SNR range in dB
SNRdB_range = -20:2:20;

% Convert SNR to linear scale
SNR=db2pow(SNRdB_range);

% Initialize error count
errorNUM=0;

RecievedSequence = zeros(size(data));
RecievedBits = zeros(size(data));
BER = zeros(size(SNRdB_range));
thresholdVal = 0.5;
```

Here we loop on the whole data sequence with the length of the SNR range, first we get the signal noise from the relation  $noise = \frac{1}{\sqrt{SNR}} * randn$  then it will be divided by the sqrt power since it's normalized power, then we will add the noise to the original data, then we will loop to all of the data sequence to check the bit value with the specified threshold to reconstruct the signal, then we will XOR the original data sequence with the reconstructed sequence to check the changed bits as the XOR will give in case of the flipped bits then we will count the flipped bits to count them up to calculate the BER.

```
for k=1:length(SNRdB_range)
    % Add noise based on SNR
    % Dividing by the sqrt of power since its normalized power
    noise=((1/sqrt(SNR(k)))*randn(1,N)*sqrt(sigPower));

    % Received signal with noise
    RecievedSequence = data+noise;

    for i=1:N
        %define the threshold value
        if RecievedSequence(i)<thresholdVal
            RecievedBits(i) = 0;
        else
            RecievedBits(i) = 1;
        end
    end

    %compare original bit with the recieved one
    Rx=xor(data,RecievedBits);

    % Count Number of Errored bits
    for j=1:N
        if (Rx(j)==1)
            errorNUM = errorNUM+1;
        end
    end

    BER(k) = errorNUM ./ N;
    errorNUM=0;
end
```

***Then finally we will display the BER graph and the signal power.***

```
% Plot BER curve
figure;
semilogy(SNRdB_range, BER, 'x-k', 'Color', 'b', 'LineWidth', 1);
xlabel('SNR (dB)'); ylabel('Bit Error Rate (BER)');
title('Bit Error Rate vs. SNR');

% Calculation of transmitted signal power
disp(['Transmitted Signal Power: ' num2str(sigPower)]);

% Find SNR where the system is nearly without error
[min_BER, min_BER_index] = min(BER);
SNR_nearly_without_error = SNRdB_range(min_BER_index);
disp(['SNR where the system is nearly without error: ' num2str(SNR_nearly_without_error) ' dB']);
```

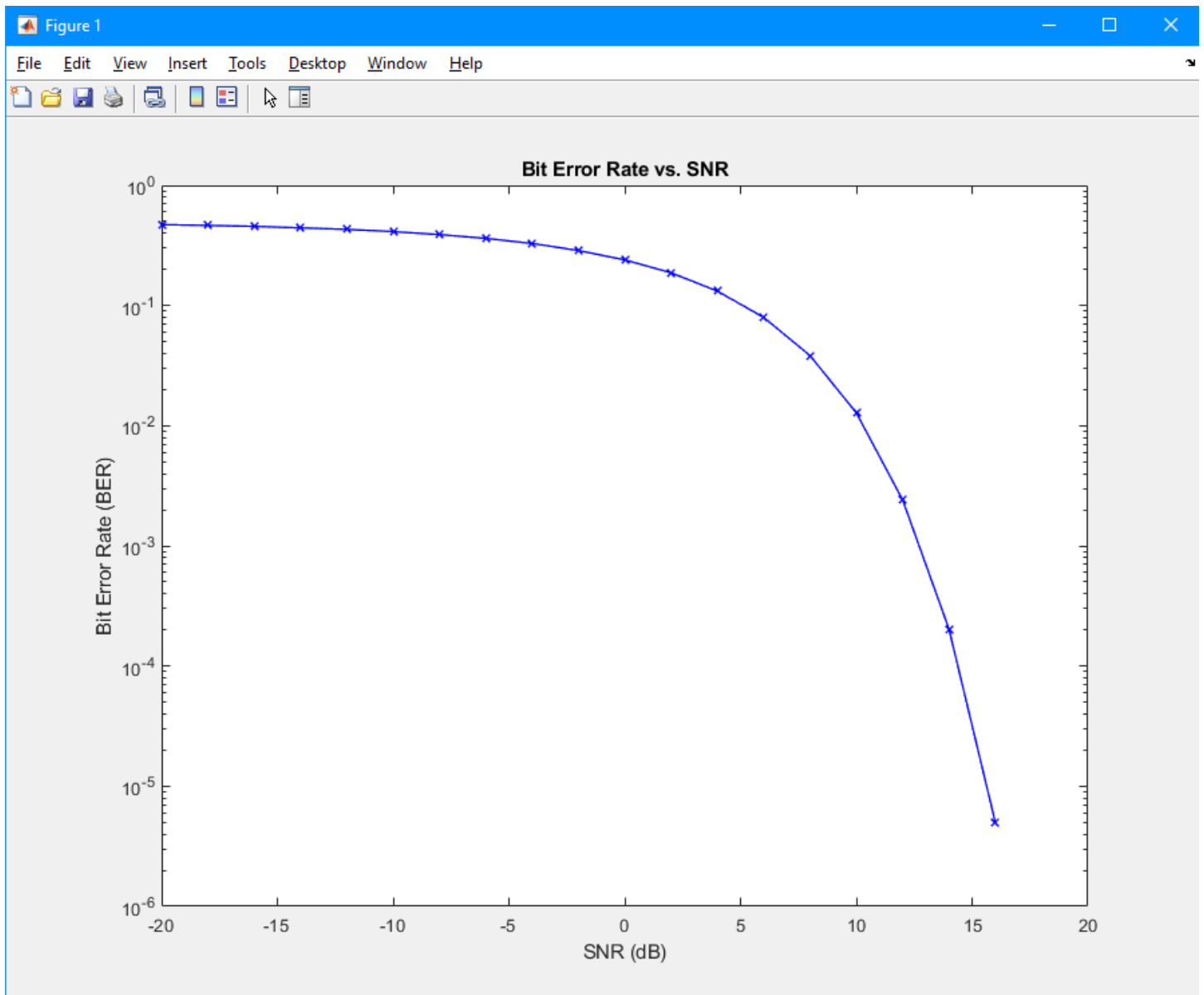
### Command Window

Transmitted Signal Power: 0.49994

SNR where the system is nearly without error: 16 dB

 >> |

## The Final BER Graph



### ***Comment on equation (1) for the reason of dividing by the root of SNR.***

The division by the square root of SNR in equation (1) is a common practice in signal processing and communication systems, this operation assumes that the noise in the system follows a Gaussian (normal) distribution. by doing this we ensure scaling the noise to account for the SNR. This normalization ensures that the noise term is appropriately adjusted according to the SNR, allowing for a consistent representation of the signal and noise relationship. So, dividing by the square root of SNR can be considered a form of normalization.

### ***At which SNR value the BER value is almost zero for a given frame ?***

The specific SNR value at which the BER is "almost zero" depends on various factors, including the modulation scheme, coding techniques, and the characteristics of the communication channel. Different systems and scenarios may have different requirements for an acceptable level of BER. For digital communication systems, a common metric is the Shannon Limit, which provides a theoretical upper bound on the achievable data rate for a given bandwidth and SNR. Approaching the Shannon Limit often implies very low BER values. In Our Example Frame the BER approaches zero at 16 dB and still zero at higher values.