

Simple if beautiful...
...but is it useful?

Robin Delabays

robin.delabays@hevs.ch

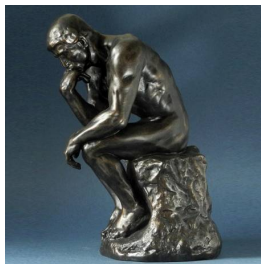
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- ▶ aesthetic;
- ▶ ...



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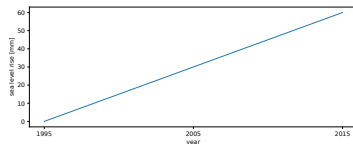
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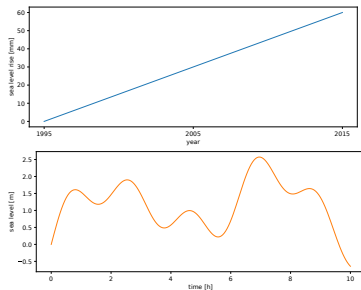
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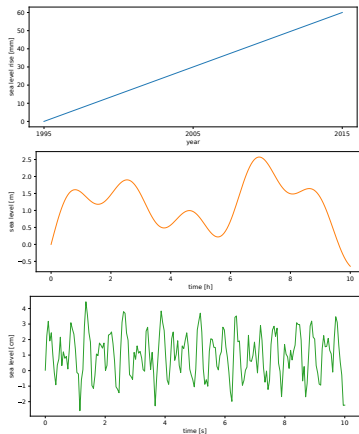
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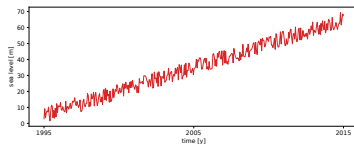
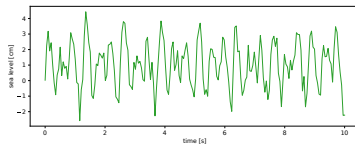
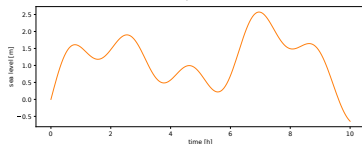
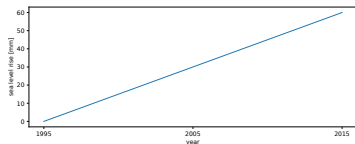
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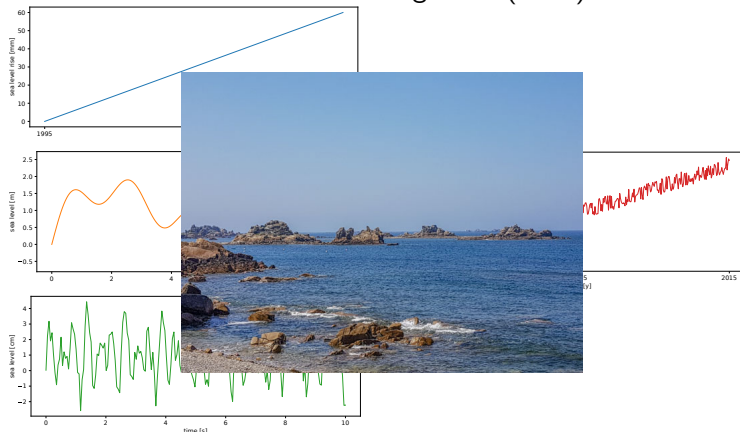
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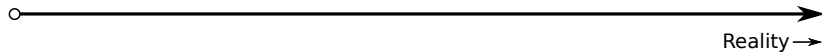
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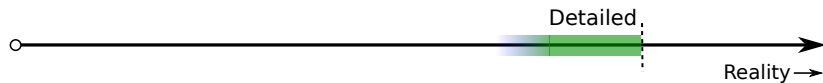


Accuracy range



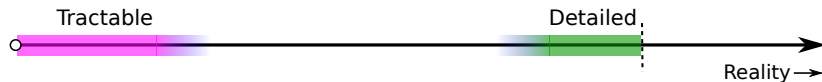
Accuracy range

- Focused research;



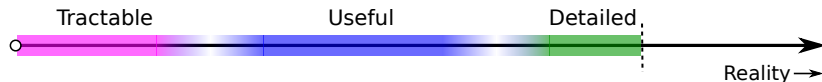
Accuracy range

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Accuracy range

- ▶ Focused research;
- ▶ Analytical results;
- ▶ Operation.



The Power Flow Equations (1)

Power flow in AC grid:

- ▶ Apparent, active, and reactive power: $S = P + iQ$;
- ▶ Complex voltage, amplitude, and phase: $E = Ve^{i\theta}$;
- ▶ Admittance, conductance, and susceptance: $y = g + ib$.

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Then the power balance at j :

$$S_j = \sum_{k \neq j} S_{jk} = \sum_{k \neq j} E_j y_{jk}^* (E_j^* - E_k^*) = \sum_k E_j E_k^* Y_{jk}^*$$

The Power Flow Equations (2)

Using:

- ▶ $S_j = P_j + iQ_j;$
- ▶ $Y_{jk} = G_{jk} + iB_{jk};$
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$$P_j = \sum_k V_j V_k [B_{jk} \sin(\theta_j - \theta_k) + G_{jk} \cos(\theta_j - \theta_k)]$$

$$Q_j = \sum_k V_j V_k [G_{jk} \sin(\theta_j - \theta_k) - B_{jk} \cos(\theta_j - \theta_k)] .$$

The Swing Dynamics

Voltage phase dynamics at each point j :

$$\begin{aligned} m_j \ddot{\theta}_j + d_j \dot{\theta}_j &= P_j^{\text{mec}} - P_j^{\text{el}} \\ &= P_j^{\text{mec}} - \sum_k V_j V_k [B_{jk} \sin(\theta_j - \theta_k) + G_{jk} \cos(\theta_j - \theta_k)] . \end{aligned}$$

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But these equations are hard to solve/integrate!

\Rightarrow numerics

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So what do we do?

Simplifying assumptions

In high voltage power grids:

- ▶ Conductance is small compared to susceptance $\implies G \approx 0$;
- ▶ Phase differences are small $\implies \cos(\theta_j - \theta_k) \approx 1$;
- ▶ Voltage amplitudes are almost constant $\implies V_j \approx cte$.

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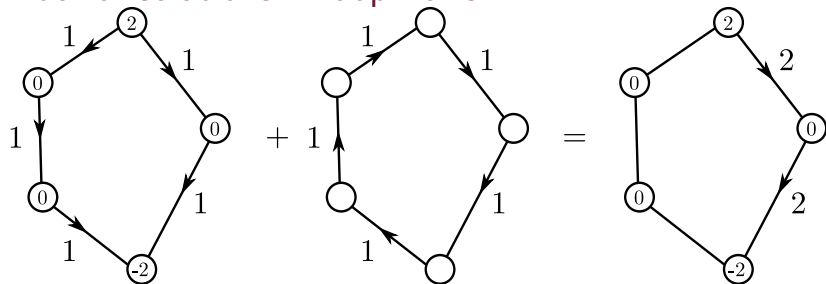
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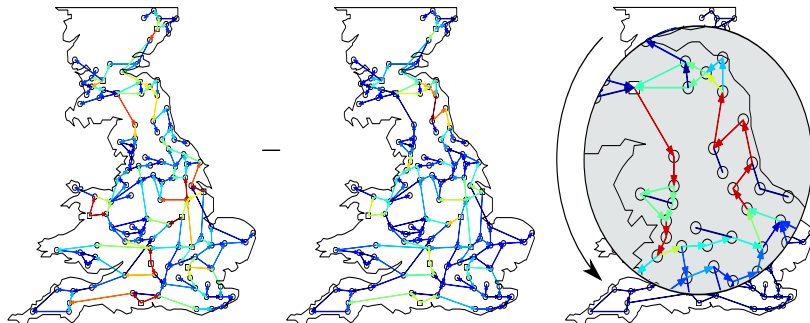
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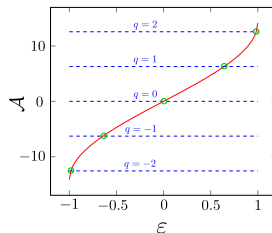
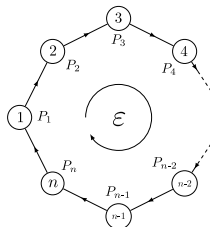
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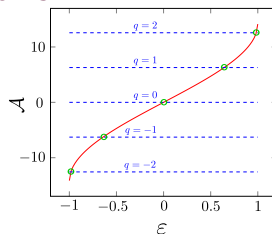
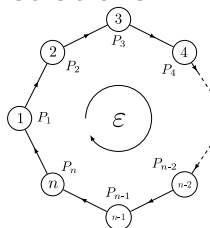


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$$q = \frac{1}{2\pi} \sum_{j=1}^{n_k} |\theta_j - \theta_{j+1}|_{2\pi} \in \mathbb{Z}.$$

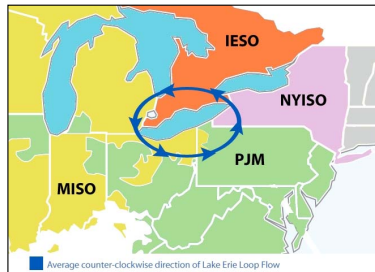
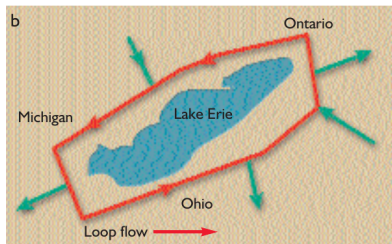
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$$\mathcal{N} \leq \prod_{k=1}^c [2 \cdot \text{Int}(n_k/4) + 1].$$

Number of solutions - Lake Erie loop flow



E. J. Lerner, *Industrial Physicist* **9** (2003).

S. G. Whitley, *Technical Report; New York Independent System Operator* (2008).

Performance measures

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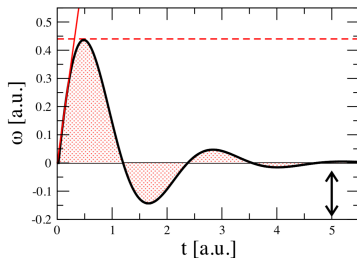
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3. Compute:

$$\|x_i\|_p = \frac{1}{T} \left[\int_0^T |x_i(t)|^p dt \right]^{1/p}.$$



A few concepts of graph theory

A **graph** is a set of **vertices/nodes** $V = \{1, \dots, n\}$ and a set of **edges/lines** $E \subset V \times V$, which are pairs of vertices.

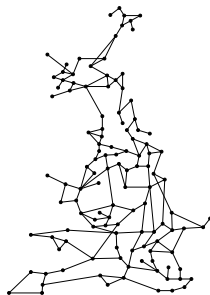
Its **Laplacian matrix**,

$$L_{ij} = \begin{cases} d_i, & \text{if } i = j, \\ -1, & \text{if } (i, j) \in E, \\ 0, & \text{otherwise,} \end{cases}$$

with eigenvalues $0 = \lambda_1 < \lambda_2 \leq \dots \leq \lambda_n$.

The **Kirchhoff indices**

$$Kf_1 = n \sum_{j \geq 2} \frac{1}{\lambda_j}, \quad Kf_2 = n \sum_{j \geq 2} \frac{1}{\lambda_j^2}, \quad Kf_m = n \sum_{j \geq 2} \frac{1}{\lambda_j^m}.$$



Example

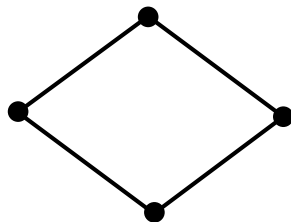
$$V = \{1, 2, 3, 4\}$$

$$E = \{(1, 2), (1, 4), (2, 3), (3, 4)\}$$

$$L = \begin{pmatrix} 2 & -1 & 0 & -1 \\ -1 & 2 & -1 & 0 \\ 0 & -1 & 2 & -1 \\ -1 & 0 & -1 & 2 \end{pmatrix}$$

$$Kf_1 = 5,$$

$$Kf_2 = 2.25.$$



Quadratic performance measures

Considering $\delta\theta_i$ (resp. $\delta\omega_i$) and $\|\dots\|_2$ gives additional losses (resp. primary control effort):

M. Tyloo, T. Coletta, and P. Jacquod, *Phys. Rev. Lett.* **120** (2018).

M. Tyloo and P. Jacquod, *Phys. Rev. E* **100** (2019).

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For short perturbations,

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and for long perturbations,

$$\mathcal{P}_1 \sim Kf_2$$

$$\mathcal{P}_2 \sim Kf_1.$$

M. Tyloo, T. Coletta, and P. Jacquod, *Phys. Rev. Lett.* **120** (2018).

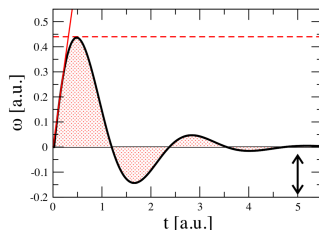
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RoCoF under line contingency

Considering $\delta\dot{\omega}_i$ and $\|\dots\|_\infty$ gives the Rate of Change of Frequency.

After line (i,j) is lost,

$$\max_{k,t} |\delta\dot{\omega}_k| = |\delta\dot{\omega}_i(0^+)|.$$



Concluding remark

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We aim now at refining our model, i.e., drop some simplifications.

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