```
In []: import pandas as pd
    import numpy as np
    from sklearn.datasets import load_iris
    from sklearn.model_selection import train_test_split
    from sklearn.tree import DecisionTreeClassifier,plot_tree
    from sklearn.metrics import accuracy_score,classification_report,confusion_matri
    import matplotlib.pyplot as plt
In []: X,y=load_iris(return_X_y=True)
    print(X)
    print(y)
```

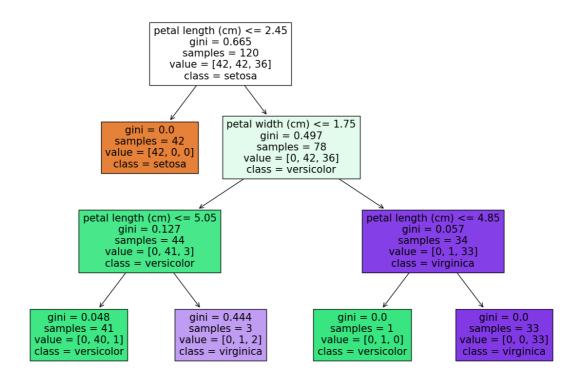
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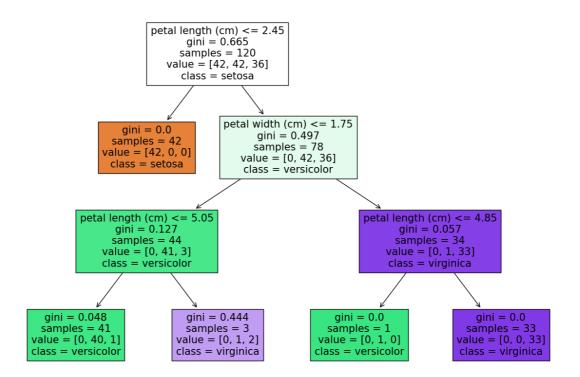
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      2 2]
In [ ]: x_train,x_test,y_train,y_test=train_test_split(X,y,test_size=0.2,random_state=33
In [ ]: cl=DecisionTreeClassifier()
      cl.fit(x_train,y_train)
      print("Accuracy",cl.score(x_test,y_test))
      y_pred=cl.predict(x_test)
      print(confusion_matrix(y_test,y_pred))
      Accuracy 0.866666666666667
      [[ 8 0 0]
       [080]
       [ 0 4 10]]
In [ ]: iris=load_iris()
      fig = plt.figure(figsize=(15,10))
      _ = plot_tree(cl,
                     feature_names=iris.feature_names,
                     class_names=iris.target_names,
                     filled=True)
```



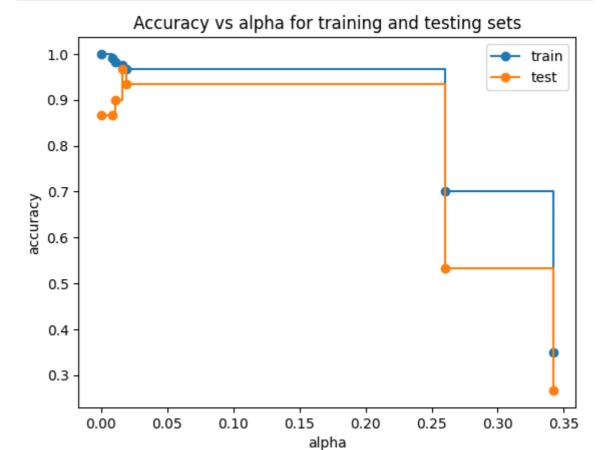
Pre-Pruning



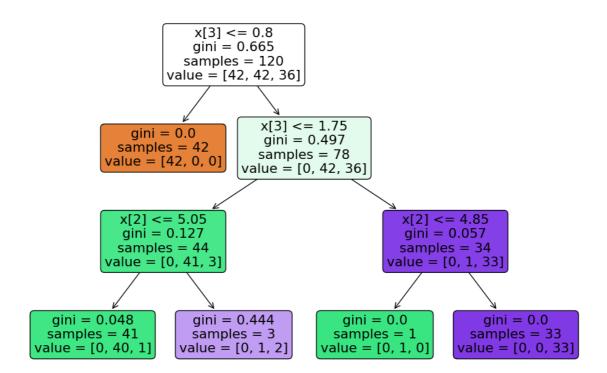
Post Pruning

```
In [ ]: path=cl.cost_complexity_pruning_path(x_train,y_train)
        ccp_alphas,impurities=path.ccp_alphas,path.impurities
        print("ccp alpha wil give list of values :\n",ccp_alphas)
        print("Impurities in Decision Tree :\n",impurities)
        ccp alpha wil give list of values :
                     0.00813008 0.01111111 0.01617647 0.01921964 0.26030954
         0.34192308]
        Impurities in Decision Tree :
                     0.01626016 0.02737127 0.04354774 0.06276738 0.32307692
         0.665
In [ ]: clfs=[]
        for ccp_alpha in ccp_alphas:
            clf=DecisionTreeClassifier(random_state=23,ccp_alpha=ccp_alpha)
            clf.fit(x train,y train)
            clfs.append(clf)
        print("Last node in Decision Tree is {} and ccp alpha for last node is {}".forma
        Last node in Decision Tree is DecisionTreeClassifier(ccp_alpha=0.34192307692307
        71, random_state=23) and ccp_alpha for last node is 0.3419230769230771
In [ ]: train_scores = [clf.score(x_train, y_train) for clf in clfs]
        test_scores = [clf.score(x_test, y_test) for clf in clfs]
        fig, ax = plt.subplots()
        ax.set_xlabel("alpha")
        ax.set ylabel("accuracy")
        ax.set_title("Accuracy vs alpha for training and testing sets")
        ax.plot(ccp_alphas, train_scores, marker='o', label="train",drawstyle="steps-pos
        ax.plot(ccp_alphas, test_scores, marker='o', label="test",drawstyle="steps-post"
```

ax.legend()
plt.show()



```
In [ ]: from sklearn import tree
    clf=DecisionTreeClassifier(random_state=0,ccp_alpha=0.015)
    clf.fit(x_train,y_train)
    plt.figure(figsize=(12,8))
    tree.plot_tree(clf,rounded=True,filled=True)
    plt.show()
```



```
In [ ]: import numpy as np
        from collections import Counter
        from sklearn.datasets import load_iris
        from sklearn.model_selection import train_test_split
        from sklearn.metrics import confusion_matrix
In [ ]: class Node:
            Helper class which implements a single tree node.
            def __init__(self, feature=None, threshold=None, data_left=None, data_right=
                self.feature = feature
                self.threshold = threshold
                self.data_left = data_left
                self.data right = data right
                self.gain = gain
                self.value = value
        class DecisionTree:
            Class which implements a decision tree classifier algorithm.
            def __init__(self, min_samples_split=2, max_depth=5):
                self.min samples split = min samples split
                self.max_depth = max_depth
                self.root = None
            @staticmethod
            def _entropy(s):
                Helper function, calculates entropy from an array of integer values.
                 :param s: list
                 :return: float, entropy value
                # Convert to integers to avoid runtime errors
                counts = np.bincount(np.array(s, dtype=np.int64))
                # Probabilities of each class label
                percentages = counts / len(s)
                # Caclulate entropy
                entropy = 0
                for pct in percentages:
                    if pct > 0:
                         entropy += pct * np.log2(pct)
                return -entropy
            def _information_gain(self, parent, left_child, right_child):
                Helper function, calculates information gain from a parent and two child
                :param parent: list, the parent node
                 :param left_child: list, left child of a parent
                :param right_child: list, right child of a parent
                 :return: float, information gain
                num_left = len(left_child) / len(parent)
```

num_right = len(right_child) / len(parent)

```
# One-liner which implements the previously discussed formula
    return self._entropy(parent) - (num_left * self._entropy(left_child) + r
def _best_split(self, X, y):
   Helper function, calculates the best split for given features and target
    :param X: np.array, features
    :param y: np.array or list, target
    :return: dict
    best_split = {}
    best_info_gain = -1
    n_rows, n_cols = X.shape
    # For every dataset feature
   for f_idx in range(n_cols):
       X curr = X[:, f idx]
        # For every unique value of that feature
        for threshold in np.unique(X_curr):
            # Construct a dataset and split it to the left and right parts
            # Left part includes records lower or equal to the threshold
            # Right part includes records higher than the threshold
            df = np.concatenate((X, y.reshape(1, -1).T), axis=1)
            df_left = np.array([row for row in df if row[f_idx] <= threshold</pre>
            df_right = np.array([row for row in df if row[f_idx] > threshold
            # Do the calculation only if there's data in both subsets
            if len(df left) > 0 and len(df right) > 0:
                # Obtain the value of the target variable for subsets
                y = df[:, -1]
                y_left = df_left[:, -1]
                y_right = df_right[:, -1]
                # Caclulate the information gain and save the split paramete
                # if the current split if better then the previous best
                gain = self._information_gain(y, y_left, y_right)
                if gain > best_info_gain:
                    best_split = {
                        'feature_index': f_idx,
                        'threshold': threshold,
                        'df_left': df_left,
                        'df_right': df_right,
                        'gain': gain
                    best_info_gain = gain
    return best split
def _build(self, X, y, depth=0):
   Helper recursive function, used to build a decision tree from the input
    :param X: np.array, features
    :param y: np.array or list, target
    :param depth: current depth of a tree, used as a stopping criteria
    :return: Node
    n_rows, n_cols = X.shape
```

```
# Check to see if a node should be leaf node
    if n_rows >= self.min_samples_split and depth <= self.max_depth:</pre>
        # Get the best split
        best = self._best_split(X, y)
        # If the split isn't pure
        if best['gain'] > 0:
            # Build a tree on the left
            left = self._build(
                X=best['df_left'][:, :-1],
                y=best['df_left'][:, -1],
                depth=depth + 1
            right = self._build(
                X=best['df_right'][:, :-1],
                y=best['df_right'][:, -1],
                depth=depth + 1
            return Node(
                feature=best['feature index'],
                threshold=best['threshold'],
                data_left=left,
                data_right=right,
                gain=best['gain']
    # Leaf node - value is the most common target value
    return Node(
        value=Counter(y).most_common(1)[0][0]
def fit(self, X, y):
    Function used to train a decision tree classifier model.
    :param X: np.array, features
    :param y: np.array or list, target
    :return: None
    # Call a recursive function to build the tree
    self.root = self._build(X, y)
def predict(self, x, tree):
    Helper recursive function, used to predict a single instance (tree trave
    :param x: single observation
    :param tree: built tree
    :return: float, predicted class
    # Leaf node
    if tree.value != None:
        return tree.value
    feature_value = x[tree.feature]
    # Go to the Left
    if feature_value <= tree.threshold:</pre>
        return self._predict(x=x, tree=tree.data_left)
    # Go to the right
    if feature_value > tree.threshold:
        return self._predict(x=x, tree=tree.data_right)
```

```
In [ ]: iris = load_iris()
      X = iris['data']
      y = iris['target']
      X_train, X_test, y_train, y_test = train_test_split(X, y, test_size=0.2, random_
      model=DecisionTree()
      model.fit(X_train,y_train)
      y_pred=model.predict(X_test)
      print("Test Results:",y_test)
      print("Predicted Results: ",y_pred)
      # print(np.concatenate((np.array(y_test).reshape(len(y_test),1),np.array(y_pred)
      print("Confusion Matrix\n",confusion_matrix(y_test,y_pred))
      Predicted Results: [1.0, 0.0, 2.0, 1.0, 1.0, 0.0, 1.0, 2.0, 1.0, 2.0, 0.
      2.0, 0.0, 0.0]
      Confusion Matrix
       [[10 0 0]
       [0 9 0]
       [0 0 11]]
```