



Chapter 12: Physical Storage Systems

Database System Concepts, 7th Ed.

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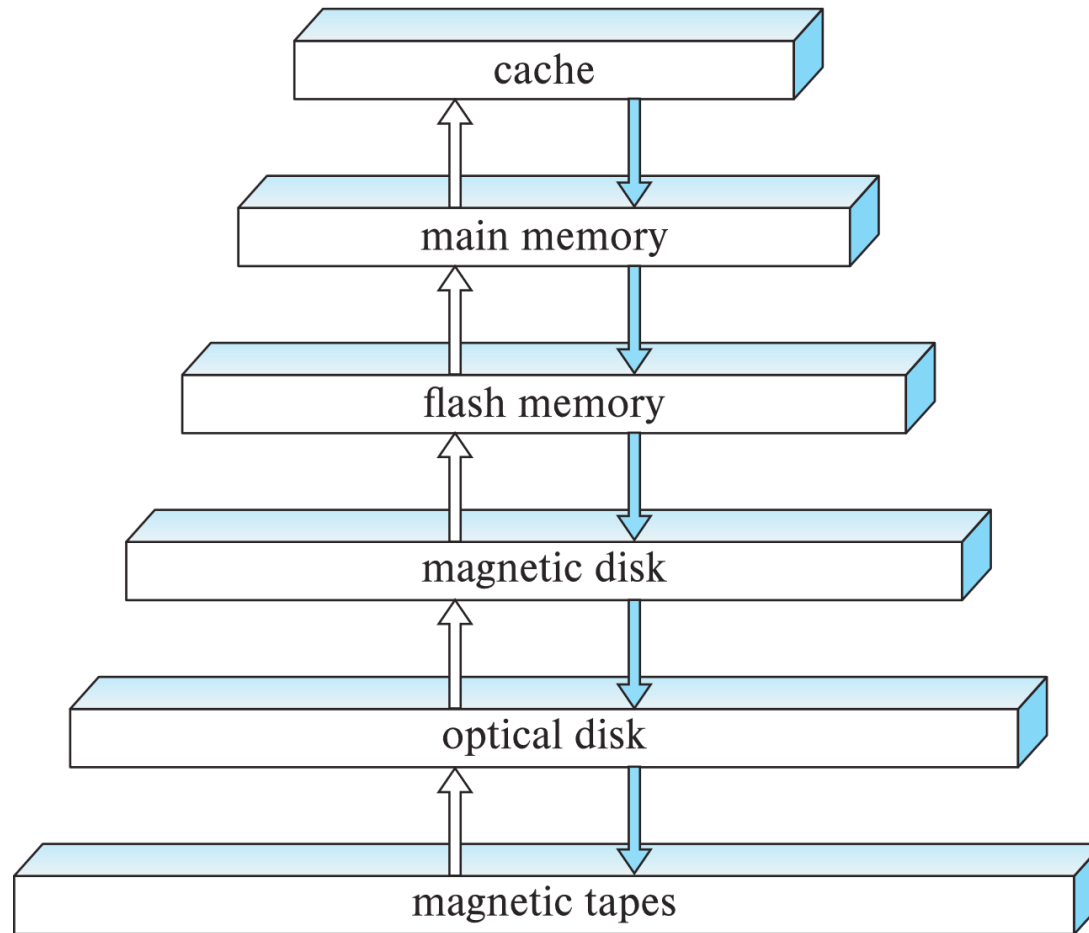


Classification of Physical Storage Media

- Can differentiate storage into:
 - **volatile storage:** loses contents when power is switched off
 - **non-volatile storage:**
 - ▶ Contents persist even when power is switched off.
 - ▶ Includes secondary and tertiary storage, as well as batter-backed up main-memory.
- Factors affecting choice of storage media include
 - Speed with which data can be accessed
 - Cost per unit of data
 - Reliability



Storage Hierarchy



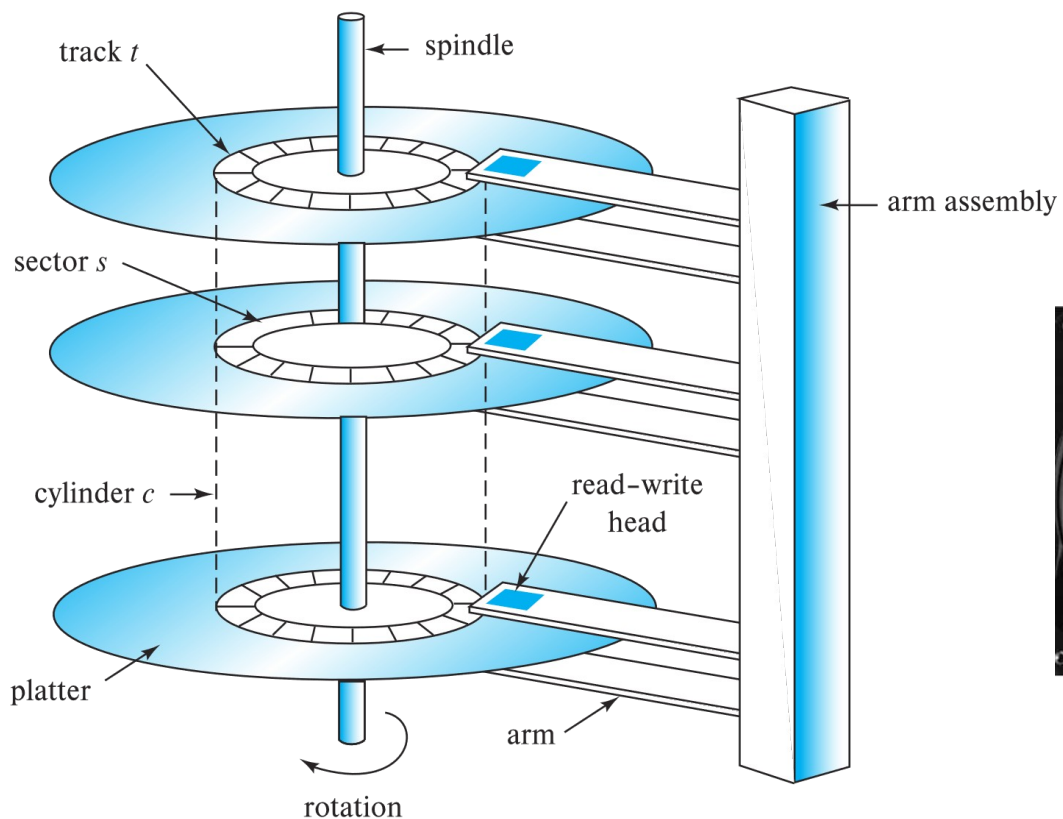


Storage Hierarchy (Cont.)

- **primary storage:** Fastest media but volatile (cache, main memory).
- **secondary storage:** next level in hierarchy, non-volatile, moderately fast access time
 - Also called **on-line storage**
 - E.g., flash memory, magnetic disks
- **tertiary storage:** lowest level in hierarchy, non-volatile, slow access time
 - also called **off-line storage** and used for **archival storage**
 - e.g., magnetic tape, optical storage
 - Magnetic tape
 - Sequential access, 1 to 12 TB capacity
 - A few drives with many tapes
 - Juke boxes with petabytes (1000's of TB) of storage



Magnetic Hard Disk Mechanism



Schematic diagram of magnetic disk drive

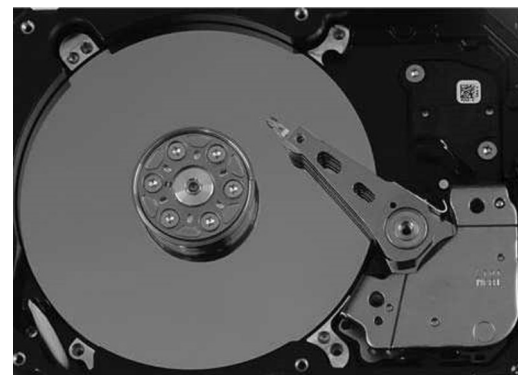


Photo of magnetic disk drive



Magnetic Disks

- **Read-write head**
- Surface of platter divided into circular **tracks**
 - Over 50K-100K tracks per platter on typical hard disks
- Each track is divided into **sectors**.
 - A sector is the smallest unit of data that can be read or written.
 - Sector size typically 512 bytes
 - Typical sectors per track: 500 to 1000 (on inner tracks) to 1000 to 2000 (on outer tracks)
- To read/write a sector
 - disk arm swings to position head on right track
 - platter spins continually; data is read/written as sector passes under head
- Head-disk assemblies
 - multiple disk platters on a single spindle (1 to 5 usually)
 - one head per platter, mounted on a common arm.
- **Cylinder** i consists of i^{th} track of all the platters



Magnetic Disks (Cont.)

- **Disk controller** – interfaces between the computer system and the disk drive hardware.
 - accepts high-level commands to read or write a sector
 - initiates actions such as moving the disk arm to the right track and actually reading or writing the data
 - Computes and attaches **checksums** to each sector to verify that data is read back correctly
 - If data is corrupted, with very high probability stored checksum won't match recomputed checksum
 - Ensures successful writing by reading back sector after writing it
 - Performs **remapping of bad sectors**



Performance Measures of Disks

- **Access time** – the time it takes from when a read or write request is issued to when data transfer begins. Consists of:
 - **Seek time** – time it takes to reposition the arm over the correct track.
 - ▶ Average seek time is $1/2$ the worst case seek time.
 - Would be $1/3$ if all tracks had the same number of sectors, and we ignore the time to start and stop arm movement
 - ▶ 4 to 10 milliseconds on typical disks
 - **Rotational latency** – time it takes for the sector to be accessed to appear under the head.
 - ▶ 4 to 11 milliseconds on typical disks (5400 to 15000 r.p.m.)
 - ▶ Average latency is $1/2$ of the above latency.
 - Overall latency is 5 to 20 msec depending on disk model
- **Data-transfer rate** – the rate at which data can be retrieved from or stored to the disk.
 - 25 to 200 MB per second max rate, lower for inner tracks



Performance Measures (Cont.)

- **Disk block** is a logical unit for storage allocation and retrieval
 - 4 to 16 kilobytes typically
 - Smaller blocks: more transfers from disk
 - Larger blocks: more space wasted due to partially filled blocks
- **Sequential access pattern**
 - Successive requests are for successive disk blocks
 - Disk seek required only for first block
- **Random access pattern**
 - Successive requests are for blocks that can be anywhere on disk
 - Each access requires a seek
 - Transfer rates are low since a lot of time is wasted in seeks
- **I/O operations per second (IOPS)**
 - Number of random block reads that a disk can support per second
 - 50 to 200 IOPS on current generation magnetic disks



Performance Measures (Cont.)

- **Mean time to failure (MTTF)** – the average time the disk is expected to run continuously without any failure.
 - Typically 3 to 5 years
 - Probability of failure of new disks is quite low, corresponding to a “theoretical MTTF” of 500,000 to 1,200,000 hours for a new disk
 - E.g., an MTTF of 1,200,000 hours for a new disk means that given 1000 relatively new disks, on an average one will fail every 1200 hours
 - MTTF decreases as disk ages



Flash Storage

- NOR flash vs NAND flash
- NAND flash
 - used widely for storage, cheaper than NOR flash
 - requires page-at-a-time read (page: 512 bytes to 4 KB)
 - 20 to 100 microseconds for a page read
 - Not much difference between sequential and random read
 - Page can only be written once
 - Must be erased to allow rewrite
- **Solid state disks**
 - Use standard block-oriented disk interfaces, but store data on multiple flash storage devices internally
 - Transfer rate of up to 500 MB/sec using SATA, and up to 3 GB/sec using NVMe PCIe



Storage Class Memory

- 3D-XPoint memory technology pioneered by Intel
- Available as Intel Optane
 - SSD interface shipped from 2017
 - Allows lower latency than flash SSDs
 - Non-volatile memory interface announced in 2018
 - Supports direct access to words, at speeds comparable to main-memory speeds



RAID

■ RAID: Redundant Arrays of Independent Disks

- disk organization techniques that manage a large numbers of disks, providing a view of a single disk of
 - ▶ **high capacity** and **high speed** by using multiple disks in parallel,
 - ▶ **high reliability** by storing data redundantly, so that data can be recovered even if a disk fails

■ The chance that some disk out of a set of N disks will fail is much higher than the chance that a specific single disk will fail.

- E.g., a system with 100 disks, each with MTTF of 100,000 hours (approx. 11 years), will have a system MTTF of 1000 hours (approx. 41 days)
- Techniques for using redundancy to avoid data loss are critical with large numbers of disks



Improvement of Reliability via Redundancy

- **Redundancy** – store extra information that can be used to rebuild information lost in a disk failure
- E.g., **Mirroring** (or **shadowing**)
 - Duplicate every disk. Logical disk consists of two physical disks.
 - Every write is carried out on both disks
 - ▶ Reads can take place from either disk
 - If one disk in a pair fails, data still available in the other
 - ▶ Data loss would occur only if a disk fails, and its mirror disk also fails before the system is repaired
 - Probability of combined event is very small
 - ⌚ Except for dependent failure modes such as fire or building collapse or electrical power surges
- **Mean time to data loss** depends on mean time to failure, and **mean time to repair**
 - E.g., MTTF of 100,000 hours, mean time to repair of 10 hours gives mean time to data loss of 500×10^6 hours (or 57,000 years) for a mirrored pair of disks (ignoring dependent failure modes)



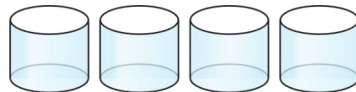
Improvement in Performance via Parallelism

- Two main goals of parallelism in a disk system:
 1. Load balance multiple small accesses to increase throughput
 2. Parallelize large accesses to reduce response time.
- Improve transfer rate by striping data across multiple disks.
- **Bit-level striping** – split the bits of each byte across multiple disks
 - In an array of eight disks, write bit i of each byte to disk i .
 - Each access can read data at eight times the rate of a single disk.
 - But seek/access time worse than for a single disk
 - ▶ Bit level striping is not used much any more
- **Block-level striping** – with n disks, block i of a file goes to disk $(i \bmod n) + 1$
 - Requests for different blocks can run in parallel if the blocks reside on different disks
 - A request for a long sequence of blocks can utilize all disks in parallel

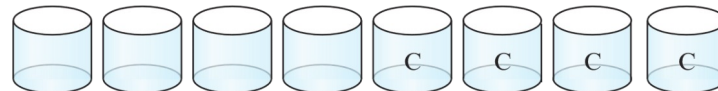


RAID Levels

- Schemes to provide redundancy at lower cost by using disk striping combined with parity bits
 - Different RAID organizations, or RAID levels, have differing cost, performance and reliability characteristics
- **RAID Level 0: Block striping; non-redundant.**
 - Used in high-performance applications where data loss is not critical.
- **RAID Level 1: Mirrored disks with block striping**
 - Offers best write performance.
 - Popular for applications such as storing log files in a database system.



(a) RAID 0: nonredundant striping



(b) RAID 1: mirrored disks



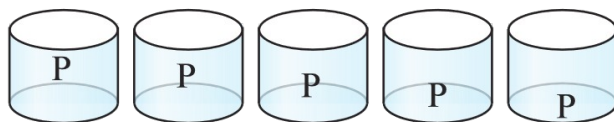
RAID Levels (Cont.)

- **Parity blocks:** Parity block j stores XOR of bits from block j of each disk
 - When writing data to a block j , parity block j must also be computed and written to disk
 - ▶ Can be done by using old parity block, old value of current block and new value of current block (2 block reads + 2 block writes)
 - ▶ Or by recomputing the parity value using the new values of blocks corresponding to the parity block
 - More efficient for writing large amounts of data sequentially
 - To recover data for a block, compute XOR of bits from all other blocks in the set including the parity block



RAID Levels (Cont.)

- **RAID Level 5: Block-Interleaved Distributed Parity;** partitions data and parity among all $N + 1$ disks, rather than storing data in N disks and parity in 1 disk.
 - E.g., with 5 disks, parity block for n th set of blocks is stored on disk $(n \bmod 5) + 1$, with the data blocks stored on the other 4 disks.



(c) RAID 5: block-interleaved distributed parity

P0	0	1	2	3
4	P1	5	6	7
8	9	P2	10	11
12	13	14	P3	15
16	17	18	19	P4



Choice of RAID Level

- Factors in choosing RAID level
 - Monetary cost
 - Performance: Number of I/O operations per second, and bandwidth during normal operation
 - Performance during failure
 - Performance during rebuild of failed disk
 - ▶ Including time taken to rebuild failed disk
- RAID 0 is used only when data safety is not important
 - E.g., data can be recovered quickly from other sources



Hardware Issues

- **Software RAID:** RAID implementations done entirely in software, with no special hardware support
- **Hardware RAID:** RAID implementations with special hardware
 - Use non-volatile RAM to record writes that are being executed
 - Beware: power failure during write can result in corrupted disk
 - ▶ E.g., failure after writing one block but before writing the second in a mirrored system
 - ▶ Such corrupted data must be detected when power is restored
 - Recovery from corruption is similar to recovery from failed disk
 - NV-RAM helps to efficiently detect potentially corrupted blocks
 - ⌚ Otherwise all blocks of disk must be read and compared with mirror/parity block



End of Chapter 12