

# Primitive Data Types

*“Elementary Elements”*

Prerequisite: None

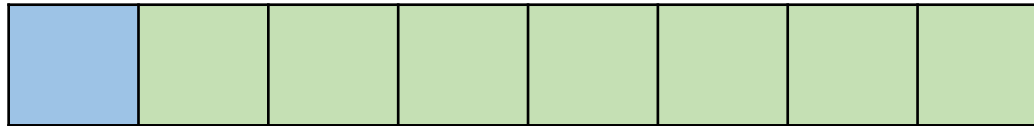
Md. Saidul Hoque Anik  
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# Primitive Data Types

- Char
  - Integer
  - Float
  - Double
- 
- Array
  - Multidimensional Array

# char Data Type

8 bit



1 sign bit

7 bit data

-128 to 127

Code	Char	Code	Char	Code	Char	Code	Char
0128	€	0160		0192	À	0224	à
0129	–	0161	¡	0193	Á	0225	á
0130	,	0162	¢	0194	Â	0226	â
0131	ƒ	0163	£	0195	Ã	0227	ã
0132	„	0164	¤	0196	Ä	0228	ä
0133	...	0165	¥	0197	Å	0229	å
0134	†	0166	¦	0198	Æ	0230	æ
0135	‡	0167	§	0199	Ç	0231	ç
0136	^	0168	¨	0200	È	0232	è
0137	‰	0169	©	0201	É	0233	é
0138	–	0170	ª	0202	Ê	0234	ê
0139	<	0171	«	0203	Ë	0235	ë
0140	Œ	0172	¬	0204	Ì	0236	ì
0141	–	0173	-	0205	Í	0237	í
0142	–	0174	®	0206	Î	0238	î
0143	–	0175	¯	0207	Ï	0239	ï
0144	–	0176	°	0208	Ð	0240	ð

# char Range

8 bit



8 bit data =  $2^8 = 256$  characters

Code	Char	Code	Char	Code	Char	Code	Char
0128	€	0160		0192	À	0224	à
0129	–	0161	¡	0193	Á	0225	á
0130	, ’	0162	¢	0194	Â	0226	â
0131	¸	0163	£	0195	Ã	0227	ã
0132	”	0164	¤	0196	Ä	0228	ä
0133	…	0165	¥	0197	Å	0229	å
0134	†	0166		0198	Æ	0230	æ
0135	‡	0167	§	0199	Ç	0231	ç
0136	^	0168	¨	0200	È	0232	è
0137	‰	0169	©	0201	É	0233	é
0138	—	0170	ª	0202	Ê	0234	ê
0139	<	0171	«	0203	Ë	0235	ë
0140	œ	0172	¬	0204	Ì	0236	ì
0141	—	0173	•	0205	Í	0237	í
0142	—	0174	®	0206	Î	0238	î
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# Memory Allocation for int

16 or 32 bit



1 sign bit

15 bit data



1 sign bit

31 bit data

# Memory Allocation for int

16 bit or 32 bit

16 bit range = -32,767 to 32,767



1 sign bit

15 bit data

32 bit range = -2,14,74,83,647 to 2,14,74,83,647

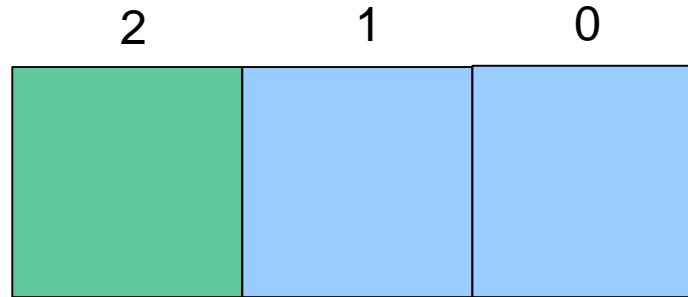


1 sign bit

31 bit data

# Where does this range come from?

Suppose int occupies only 3 bits

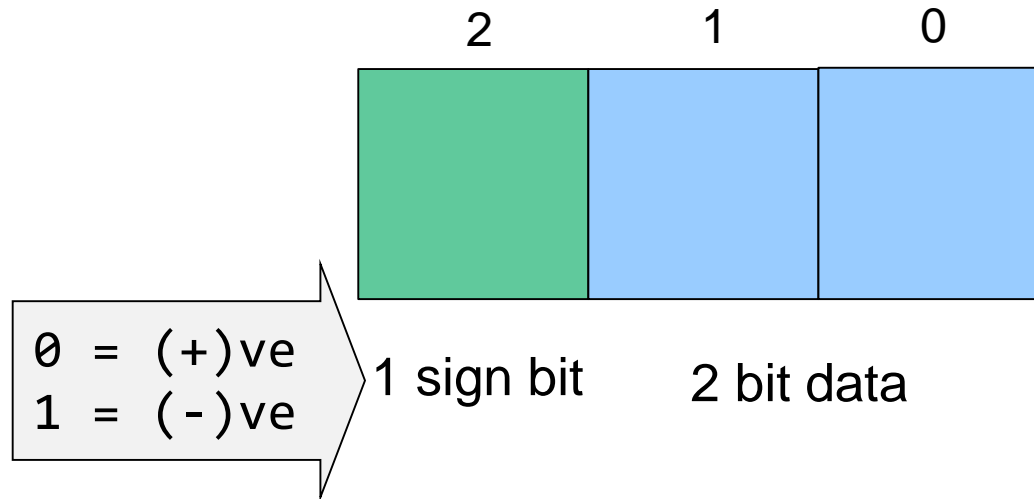


1 sign bit

2 bit data

# Where does this range come from?

Suppose int occupies only 3 bits





# Understanding 2s complement

How to perform 2s complement

1. Take binary representation 101
2. Take 1s complement (Invert all bits) 010
3. Add 1 011

# Representing signed numbers

Suppose int occupies only 3 bits

0 00	+0
------	----

0 01	+1
------	----

0 10	+2
------	----

0 11	+3
------	----

# Representing signed numbers

Suppose int occupies only 3 bits

1 00

1 01

1 10

1 11

# Representing signed numbers

Suppose int occupies only 3 bits

1 00	-4
------	----

1 01	-3
------	----

1 10	-2
------	----

1 11	-1
------	----

# Representing signed numbers

Suppose int occupies only 3 bits

Binary	Decimal
0 00	+0
0 01	+1
0 10	+2
0 11	+3
1 00	-4
1 01	-3
1 10	-2
1 11	-1

3 bit =  $2^3 = 8$  numbers

When 2s complement is used:

4 positive : 0, 1, 2, 3

4 negative: -1, -2, -3, -4

# Reviewing the ranges

Data-type	Size in bits	Range
int	16 or 32	-32,767 to 32,767
char	8	-127 to 127

# Recap

Why do we use 2s complement instead of just flipping the sign bit?

# Recap

Why do we use 2s complement instead of just flipping the sign bit?

Because otherwise it would produce minus zero (-0)



# Recap

How do we calculate the range of `int`? Suppose the size is 16 bit

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$$\frac{65536}{2} = 32768$$

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So largest negative number = -32768

Largest positive number =  $32768 - 1 = 32767$

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How do we calculate the range of int? Suppose the size is 16 bit

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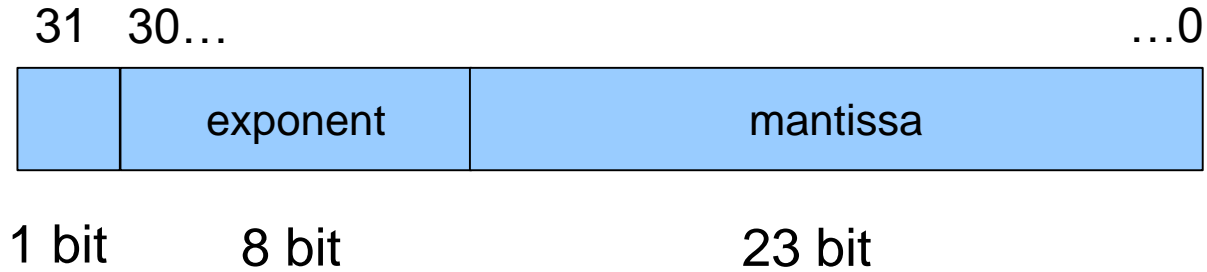
So largest negative number = -32768

Largest positive number =  $32768 - 1 = 32767$

So the range of 16 bit int is from -32768 to 32767

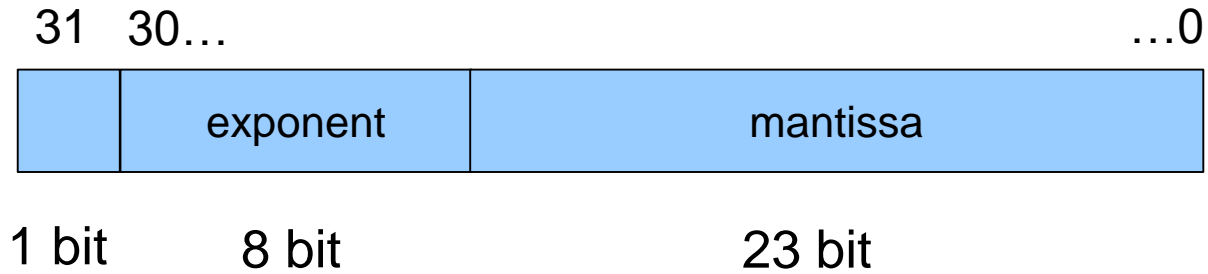
# Memory Allocation of float

32 bit memory



# Memory Allocation of float

IEEE-754 floating-point standard

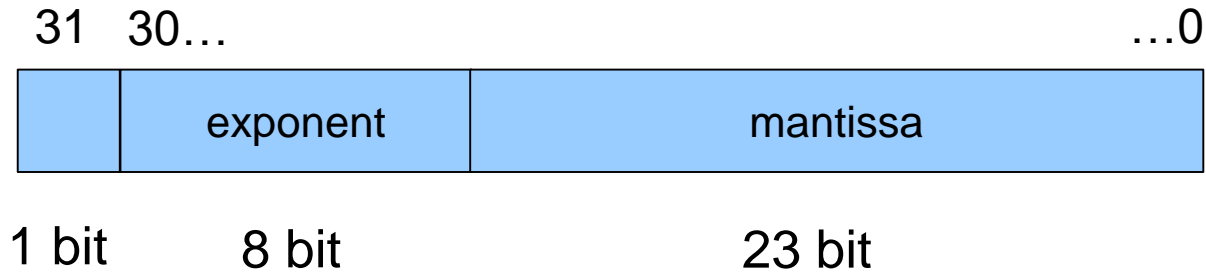


Suppose we have to store 10.375



# Memory Allocation of float

IEEE-754 floating-point standard

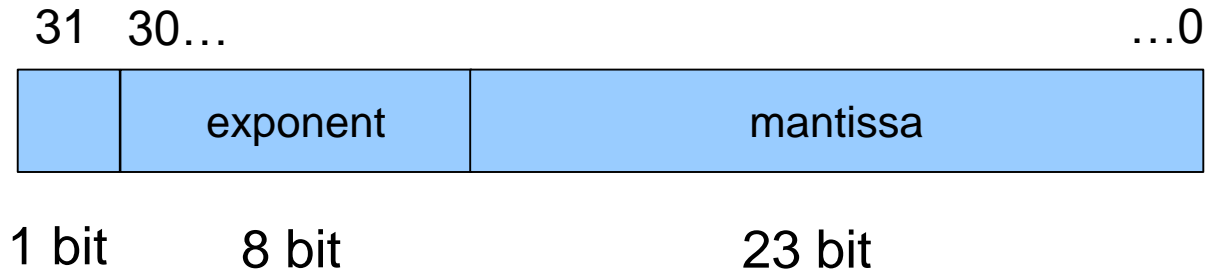


Suppose we have to store 10.375

1. Convert to Binary (=1010.011)

# Memory Allocation of float

## IEEE-754 floating-point standard



Suppose we have to store 10.375

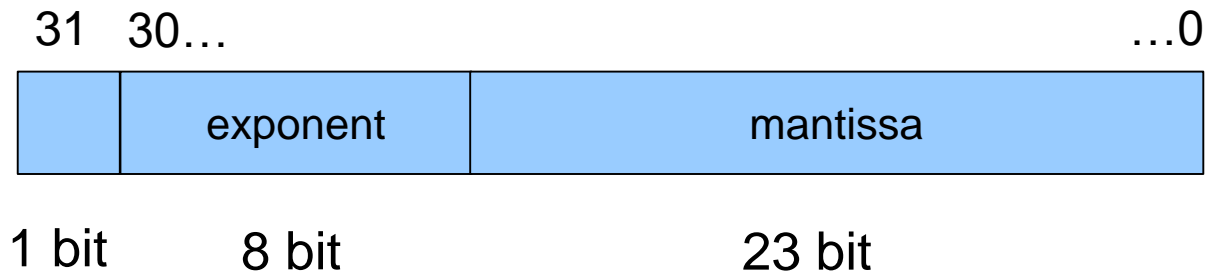
1. Convert to Binary (=1010.011)

2. Move the floating point in front of the first 1, ie.

1.010011e+3

# Memory Allocation of float

## IEEE-754 floating-point standard



Suppose we have to store 10.375

1. Convert to Binary (=1010.011)

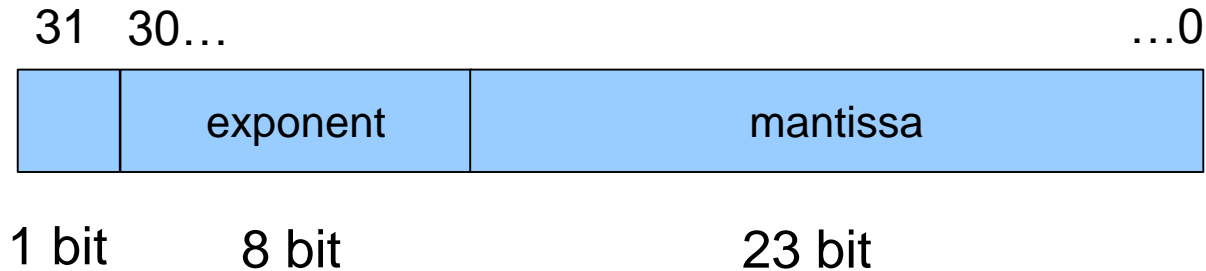
2. Move the floating point in front of the first 1, ie.

1.010011e+3

[we had written e+3 because we have moved the point 3 times on the right]

# Memory Allocation of float

## IEEE-754 floating-point standard

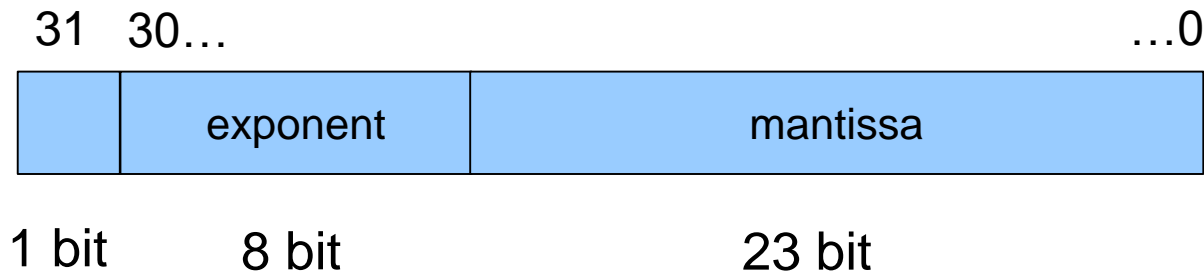


Suppose we have to store 10.375

1. Convert to Binary (=1010.011)
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1.010011e+3
3. Now the value after the floating point is the mantissa (010011)

# Memory Allocation of float

## IEEE-754 floating-point standard

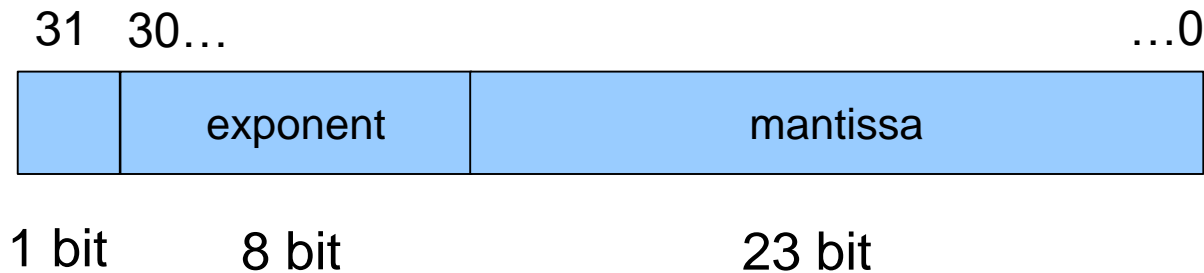


Suppose we have to store 10.375

1. Convert to Binary (=1010.011)
2. Move the floating point in front of the first 1, ie.  
1.010011e+3
3. Now the value after the floating point is the mantissa (010011)
4. To find the exponent, add 127 with 3 (=130) and convert it to binary (=10000010)

# Memory Allocation of float

## IEEE-754 floating-point standard

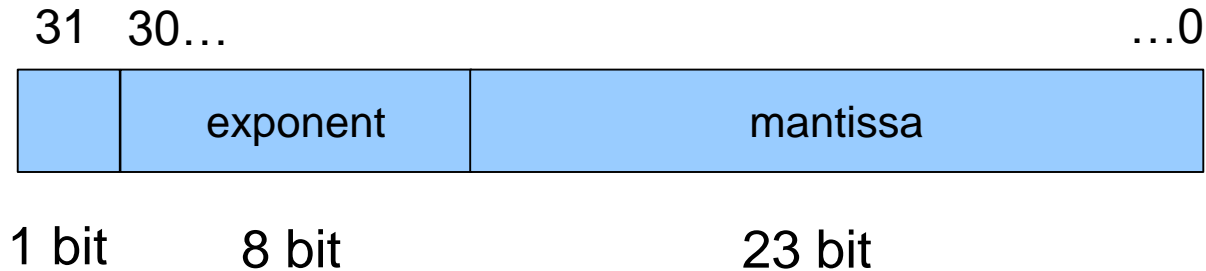


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5. The sign bit is 0 for +

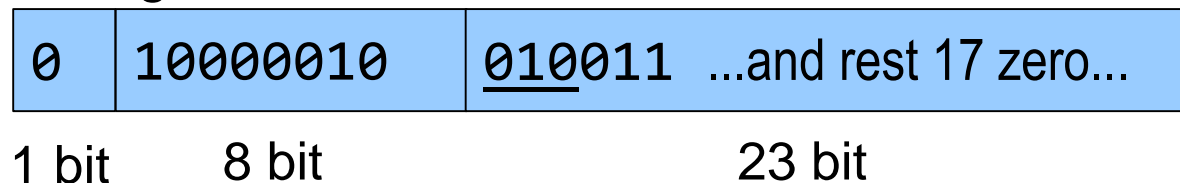
# Memory Allocation of float

## IEEE-754 floating-point standard



Suppose we have to store 10.375

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4. To find the exponent, add 127 with 3 (=130) and convert it to binary (=10000010)
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# Exercise

Convert 15.875 into IEEE-754 floating-point standard



# Special Float Values



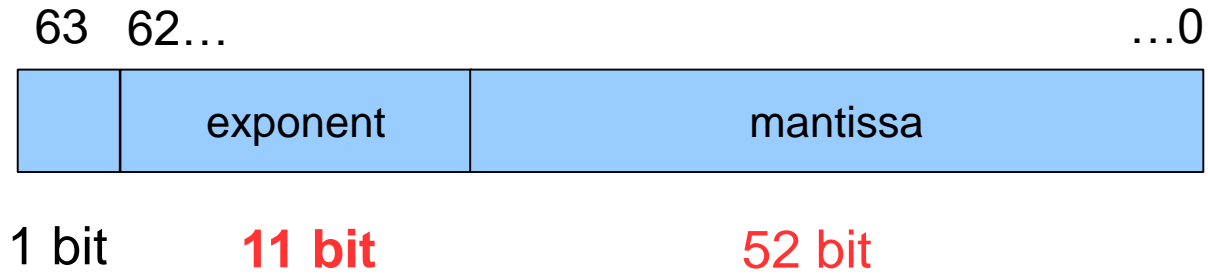
Real Number and NaN Encodings For 32-Bit Floating-Point Format

S	E	F			S	E	F
1	0	0	-0		0	0	0
1	0	0.XXX <sup>2</sup>	-Denormalized Finite	+Denormalized Finite	0	0	0.XXX <sup>2</sup>
1	1...254	Any Value	-Normalized Finite	+Normalized Finite	0	1...254	Any Value
1	255	0	-∞	+∞	0	255	0
X <sup>1</sup>	255	1.0XX <sup>2</sup>	-SNaN	+SNaN	X <sup>1</sup>	255	1.0XX <sup>2</sup>
X <sup>1</sup>	255	1.1XX	-QNaN	+QNaN	X <sup>1</sup>	255	1.1XX

- NOTES:**
1. Sign bit ignored.
  2. Fractions must be non-zero.

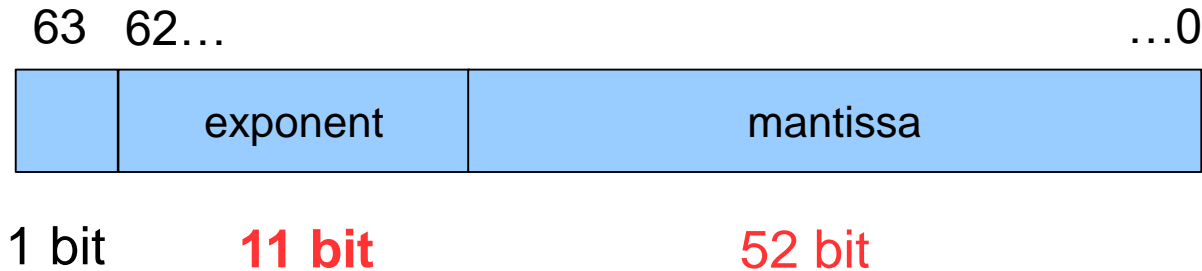
# Memory Allocation of double

64 bit memory



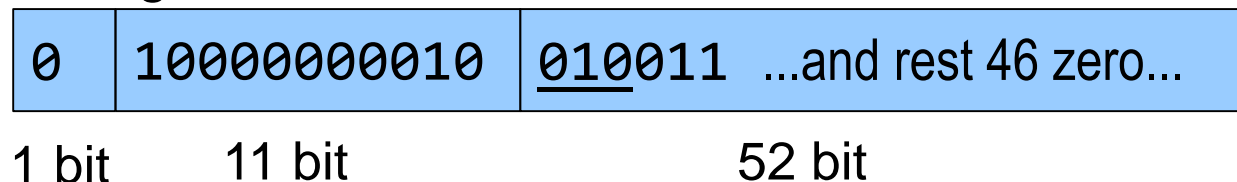
# Memory Allocation of double

64 bit memory



Suppose we have to store 10.375

1. Convert to Binary (=1010.011)
2. Move the floating point after the first 1, ie.  
1.010011e+3
3. Now the value after the floating point is the mantissa (010011)
4. To find the exponent, **add 1023** with 3 (=1026) and convert it to binary (=10000000010)
5. The sign bit is 0 for +



# Modifier

Four modifiers.

1. signed
2. unsigned
3. long
4. short

# Modifier

For char

# Modifier

For char

1. signed char (7 bit)
2. unsigned char (8 bit)

See Chapter 4.1 of Teach Yourself C, 3<sup>rd</sup> edition by Herb Schildt for size and range

# Modifier

For int

1. signed int
2. unsigned int
3. short int
4. long int
  
5. unsigned short int
6. unsigned long int

See Chapter 4.1 of Teach Yourself C, 3<sup>rd</sup> edition by Herb Schildt for size and range

# Modifier

For float

No modifier

(Previously, long float was considered double. But it is obsolete in ANSI C)

See Chapter 4.1 of Teach Yourself C, 3<sup>rd</sup> edition by Herb Schildt for size and range



# Modifier

For double

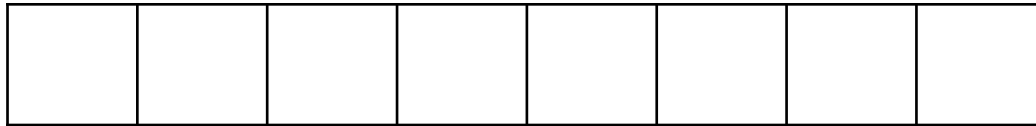
long double (10 byte: 1\_sign+15\_exp+64\_man)\*

short double (Same as double)

\*In this case, exponent bias is 16383

# Array

Contagious memory location

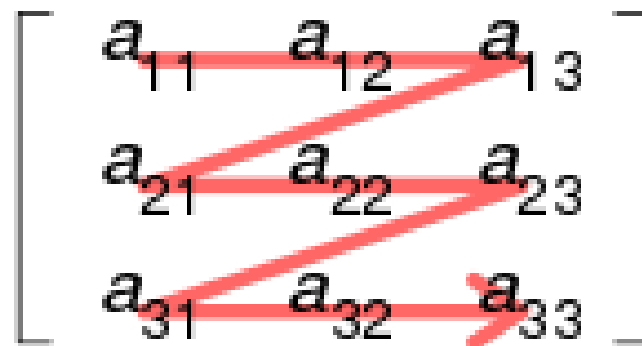


Base Address

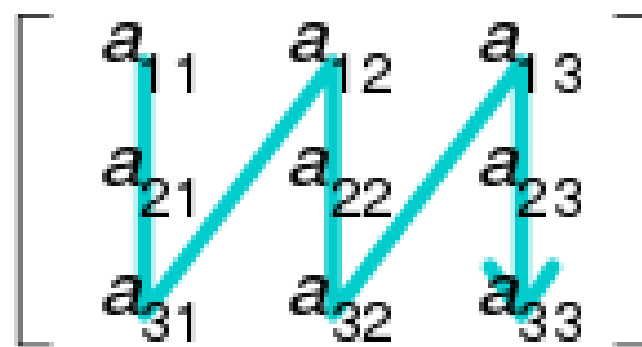


# 2D Array

Row-major order



Column-major order



# 2D Array

1. A 2D array is stored in the computer's memory one row following another.
2. The address of the first byte of memory is considered as the memory location of the entire 2D array.
3. Knowing the address of the first byte of memory, the compiler can easily compute to find the memory location of any other elements in the 2D array provided the number of columns in the array is known.

If each data value of the array requires  $B$  bytes of memory, and if the array has  $C$  columns, then the memory location of an element such as `score[m][n]` is  $(m \cdot c + n) \cdot B$  from the address of the first byte.

# 2D Array

4. Note that to find the memory location of any element, there is no need to know the total number of rows in the array, i.e. the size of the first dimension. Of course the size of the first dimension is needed to prevent reading or storing data that is out of bounds.
5. Again one should not think of a 2D array as just an array with two indexes. You should think of it as an array of arrays.
6. Higher dimensional arrays should be similarly interpreted. For example a 3D array should be thought of as an array of arrays of arrays. To find the memory location of any element in the array relative to the address of the first byte, the sizes of all dimensions other than the first must be known.

# 2D Array

```
int array1[3][2] = {{0, 1}, {2, 3}, {4, 5}};
```

In memory looks like this:

0 1 2 3 4 5

exactly the same as:

```
int array2[6] = { 0, 1, 2, 3, 4, 5 };
```

0	1
2	3
4	5

# 3D Array

array1[0][][ ] : {{0, 1}, {2, 3}, {4, 5}};

array1[1][][ ] : {{6, 7}, {8, 9}, {10, 11}};

0	1
2	3
4	5

6	7
8	9
10	11