

This document provided by



Geek Must Have

<https://GeekMustHave.com>

Web

<https://YouTube.com/c/GeekMustHave>

YouTube

<https://GitHub.com/GeekMustHave>

GitHub

Raspberry PI 400 Install Notes

John HR Schuster

Version 2.1b, 04/01/2022: Notes

Table of Contents

1. Introduction	1
2. Additional Software	1
2.1. Double commander	1
2.2. Visual Studio Code	2
2.3. Arduino IDE	2
3. Chrome Extensions	4
3.1. ASCIIDoctor JS extension	4
4. Networking	4
5. VNC Server	4
5.1. Mount Windows share	4
6. References	5
7. Document History	6

Installation and customization of Raspberry PI 400 for development environment.

To view a PDF version of this document click this [Link](#)

The GitHub Repository is located at this [Link](#)

The GeekMustHave Blog Post is located at this [Link](#)

1. Introduction

These are notes from the start up installation and configuration of the RPI400.

2. Additional Software

2.1. Double commander

Dual pane file manager

```
sudo apt-get install doublecmd-qt
```

After this install the Double commander should be in the [Accessories](#)

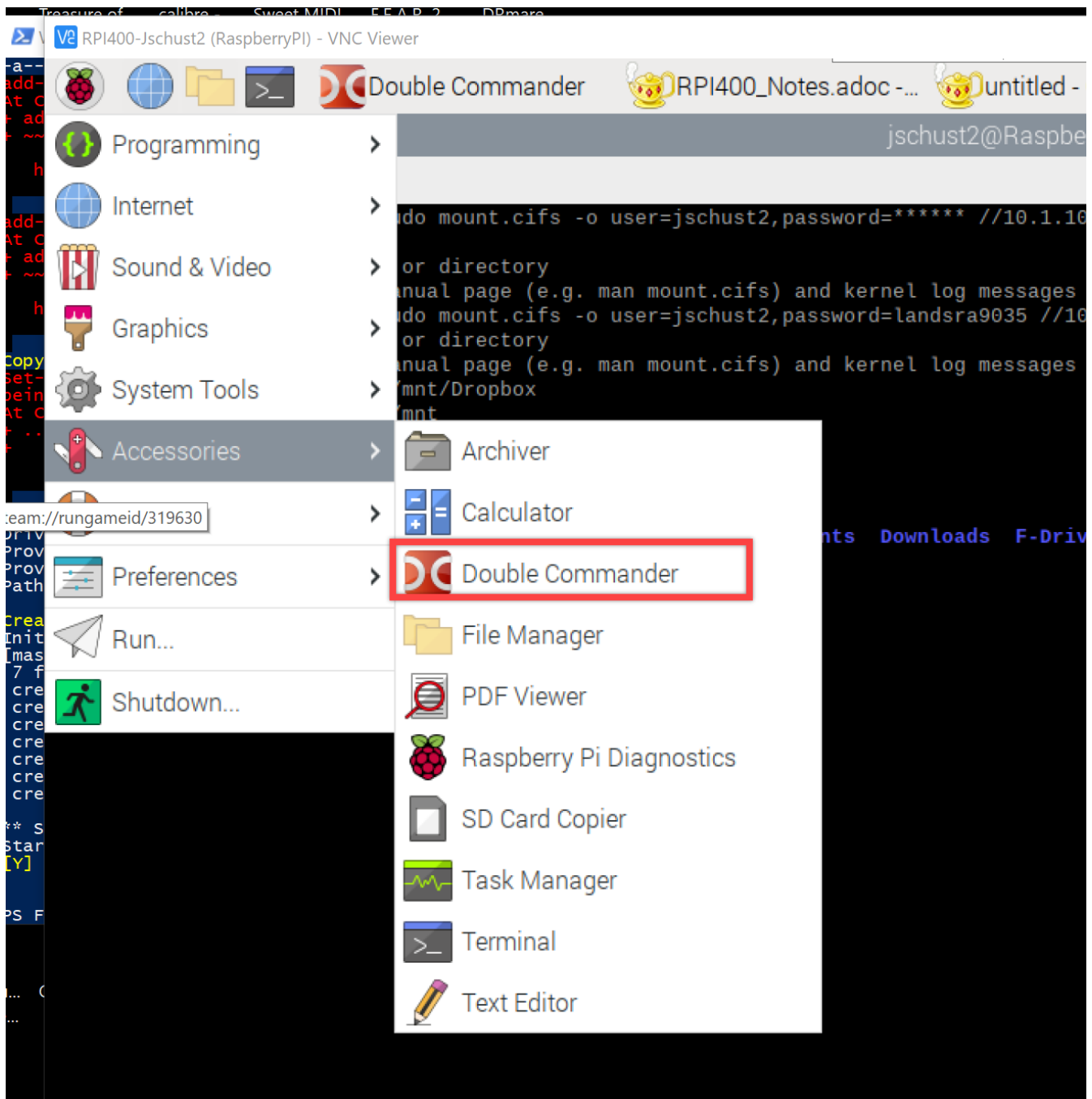


Figure 1. Double Commander

2.2. Visual Studio Code

IDE and editor with great extension library

Reference: <https://code.visualstudio.com/docs/setup/raspberry-pi>

```
sudo apt update
sudo apt install code
```

2.3. Arduino IDE

C++ IDE editor for arduino based boards

Reference: <https://www.raspberrypi-spy.co.uk/2020/12/install-arduino-ide-on-raspberry-pi/>



The install below results in the installation of Arduino IDE version 1.6. This is an extremely outdated version which makes it difficult to use or impossible to flash certain devices.

```
sudo apt install arduino
```

Download current IDE from website <https://www.arduino.cc/en/software>

Linux Arm 64 bit, as rgw RPI400 project is 64 bit based.

Copy of `arduino-1.8.19-linuxarm64.tar` is located [here](#)

Go to download and untar

```
tar -xvf arduino-1.8.19-linuxarm64.tar.xz
```

Move the folder to the `opt` directory.

```
sudo mv arduino-1.8.19 /opt
```

Run the script to install it

```
sudo /opt/arduino-1.8.19/install.sh
```

The script will add an entry to the `Programming` tab for Arduino IDE.

3. Chrome Extensions

3.1. ASCIIDoctor JS extension

This Chrome extension will allow viewing of an *.*adoc* file directly in the browser.

Reference: <https://chrome.google.com/webstore/detail/asciidoctorjs-live-previe/iaalpfgpbocpdfblpnhhgllgdbdbchmia>

The extension must be enabled to allow use of File URLs.

4. Networking

5. VNC Server

The VNC server will allow for GUI remote access for Windows systems.

In RPI Terminal enter

```
sudo raspi-config
```

Go to Interface options, then to VNC, then enable VNC server

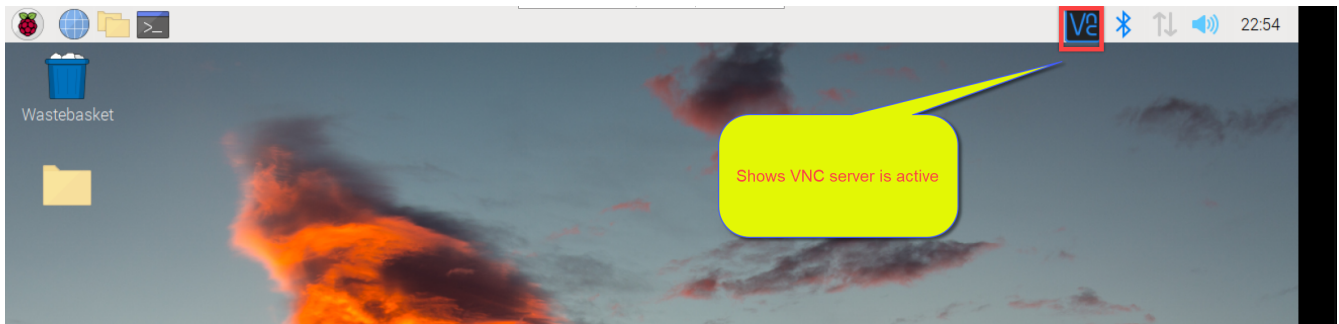


Figure 2. Verify VNC running

5.1. Mount Windows share

Reference: <https://www.bitpi.co/2015/02/16/accessing-a-windows-share-with-a-raspberry-pi/>

This will allow the Dropbox folder on the Windows desktop be available to the RPI400.

We will need to install cifs-utils. This will help us mount SMB directories- which is what we get from Windows. We can install easily on Raspbian by running the following command:

```
sudo apt-get install cifs-utils;
```

Establish mount to a Windows share

Now we will create a mount point in the `mnt` directory:

```
mkdir /mnt/Dropbox/
```

The mount command for the Dropbox folder on the desktop the newly created folder on the RPI400.

```
sudo mount.cifs -o user=jschust2,password=***** //10.1.10.22/Dropbox /mnt/Dropbox
```



No space between user and password, all optional args are comma separated.

In order for your Raspberry Pi to mount the network shares on boot up, we need to modify the `/etc/fstab` file.

```
sudo nano /etc/fstab
```

There may be entries there already. All we need to do is add the following to the end of the file:

```
//10.1.10.22/Dropbox /mnt/Dropbox cifs  
username=jschust2,password=***** ,iocharset=utf8,sec=ntlm 0 0
```

Now we can manually run the same mount process at boot up from the command line by running:

```
sudo mount -a;
```

6. References

7. Document History

Table 1. Document History

Date	Version	Author	Description
04/01/2022	V2.1b	JHRS	Initial version