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# Raspberry PI 400 Install Notes

John HR Schuster

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Installation and customization of Raspberry PI 400 for development environment.

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The GitHub Repository is located at this [Link](#)

The GeekMustHave Blog Post is located at this [Link](#)

# 1. Introduction

These are notes from the start up installation and configuration of the RPI400.

## 2. Additional Software

### 2.1. Double commander

Dual pane file manager

```
sudo apt-get install doublecmd-qt
```

After this install the Double commander should be in the [Accessories](#)

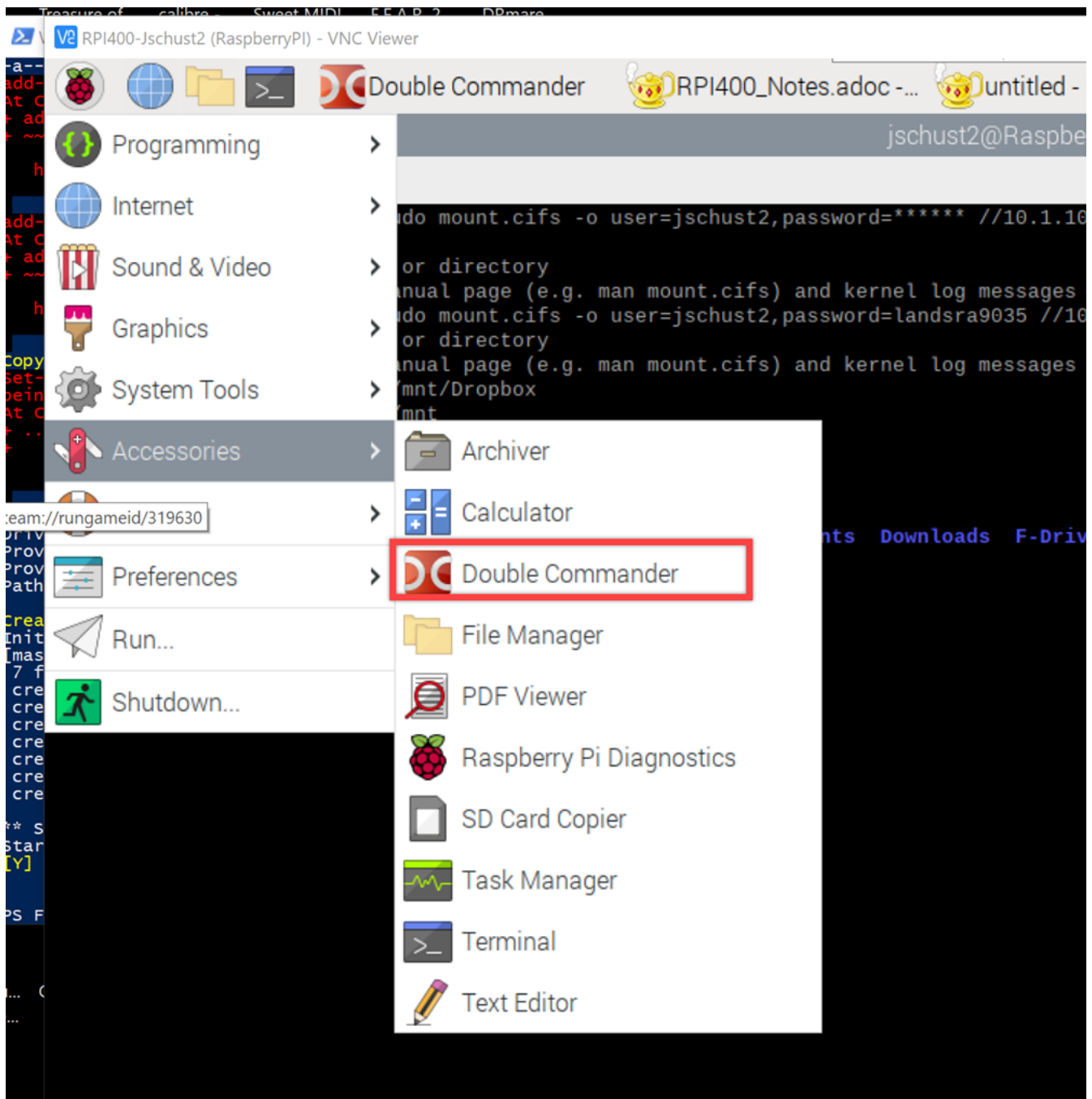


Figure 1. Double Commander

## 2.2. Visual Studio Code

IDE and editor with great extension library

Reference: <https://code.visualstudio.com/docs/setup/raspberry-pi>

```
sudo apt update
sudo apt install code
```

## 2.3. Arduino IDE

C++ IDE editor for arduino based boards

Reference: <https://www.raspberrypi-spy.co.uk/2020/12/install-arduino-ide-on-raspberry-pi/>



The install below results in the installation of Arduino IDE version 1.6. This is an extremely outdated version which makes it difficult to use or impossible to flash certain devices.

```
sudo apt install arduino
```

Download current IDE from website <https://www.arduino.cc/en/software>

Linux Arm 64 bit, as rgw RPI400 project is 64 bit based.

Copy of `arduino-1.8.19-linuxarm64.tar` is located [here](#)

Go to download and untar

```
tar -xvf arduino-1.8.19-linuxarm64.tar.xz
```

Move the folder to the `opt` directory.

```
sudo mv arduino-1.8.19 /opt
```

Run the script to install it

```
sudo /opt/arduino-1.8.19/install.sh
```

The script will add an entry to the `Programming` tab for Arduino IDE.

## 3. Chrome Extensions

### 3.1. ASCIIDoctor JS extension

This Chrome extension will allow viewing of an \*.*adoc* file directly in the browser.

Reference: <https://chrome.google.com/webstore/detail/asciidoctorjs-live-previe/iaalpfgpbocpdfblpnhhgllgdbdbchmia>

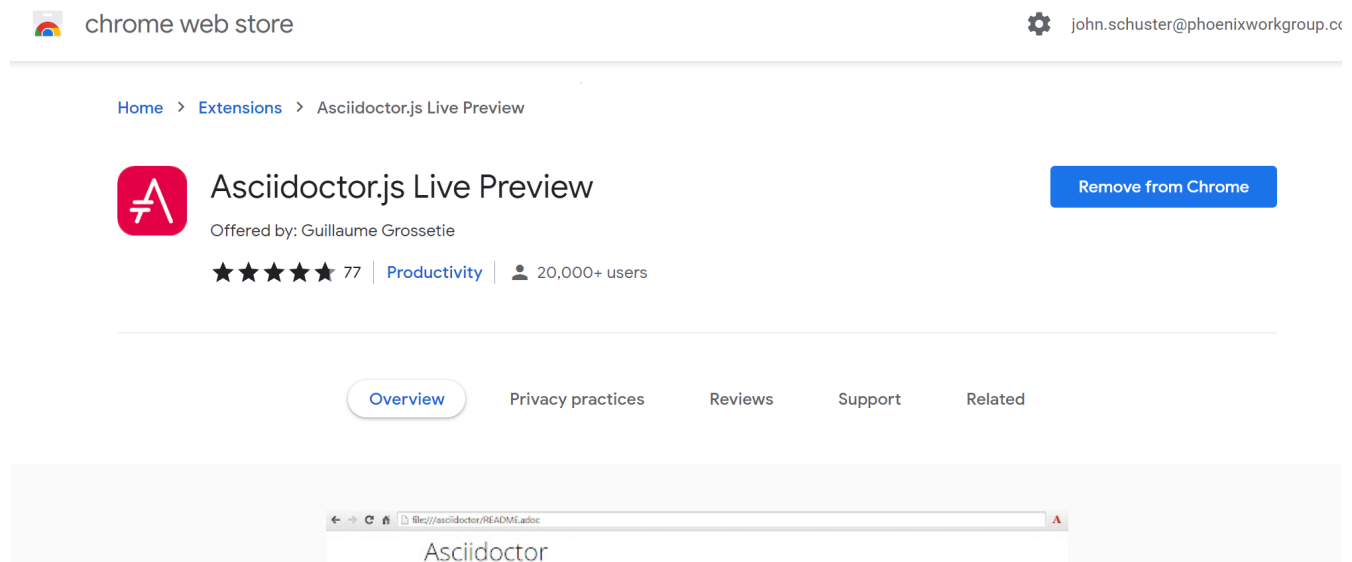


Figure 2. Chrome Store

The extension must be enabled to allow use of File URLs.

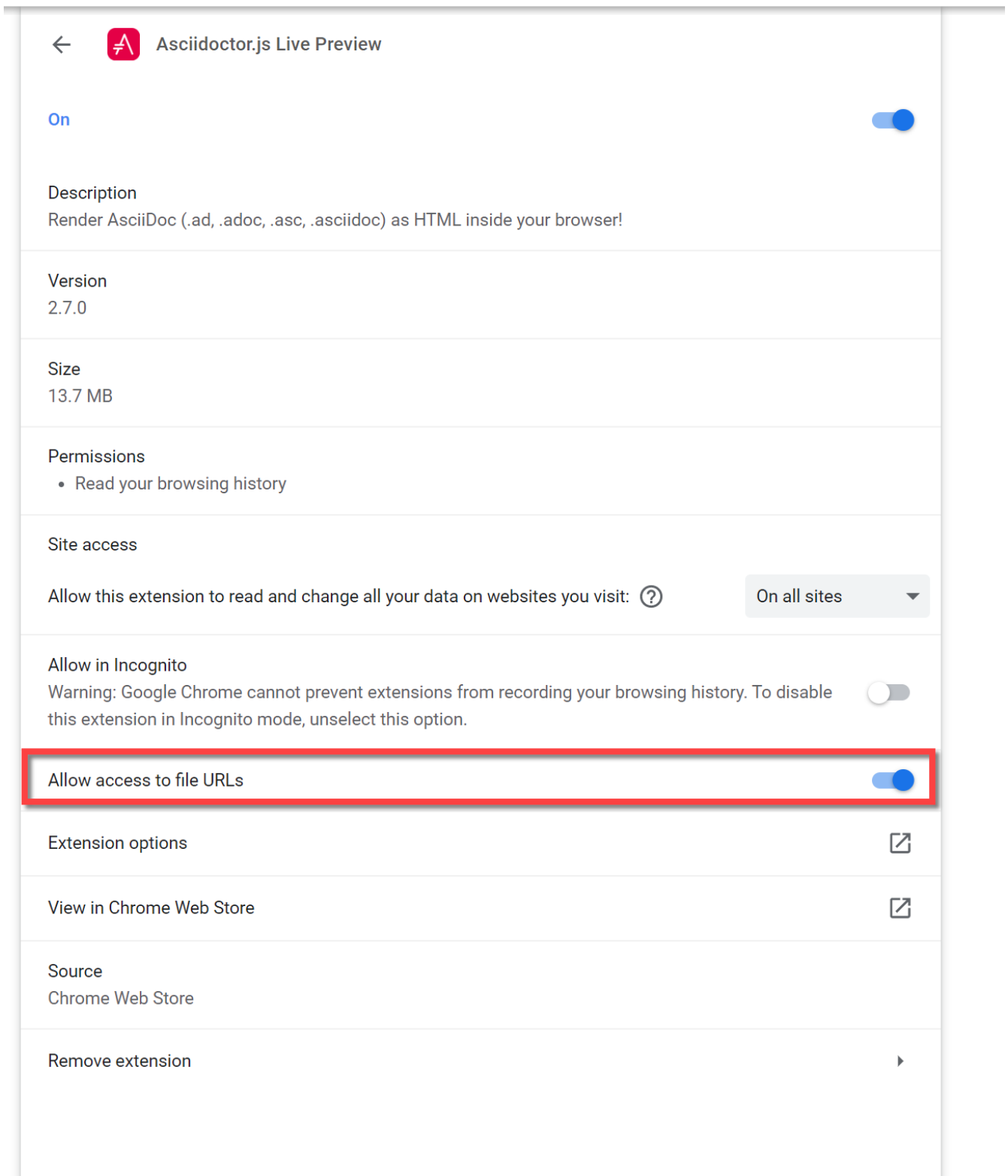


Figure 3. Extension Setting

## 4. Networking

### 4.1. VNC Server

The VNC server will allow for GUI remote access for Windows systems.

In RPI Terminal enter

```
sudo raspi-config
```

Go to Interface options, then to VNC, then enable VNC server

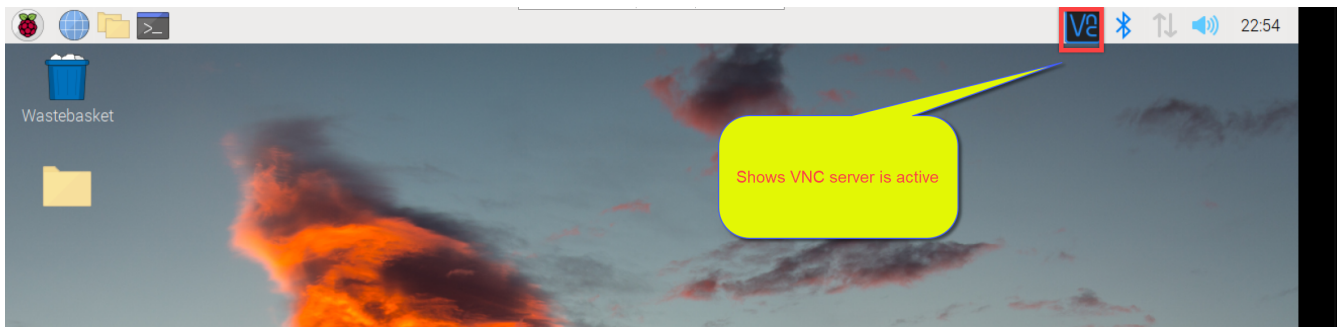


Figure 4. Verify VNC running

## 5. Windows Mount RPI400 Share

Using Windows file explorer map a drive

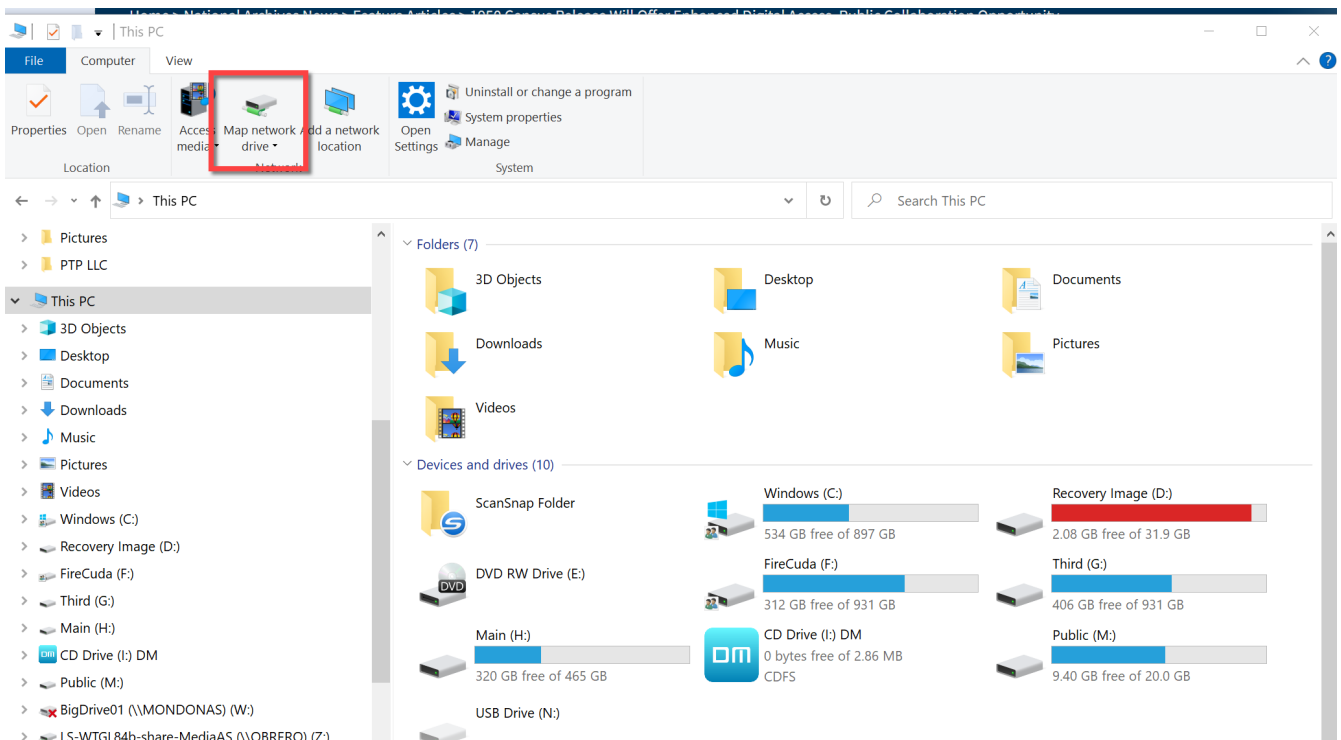


Figure 5. Map Drive

The go to the proper RPI400 share



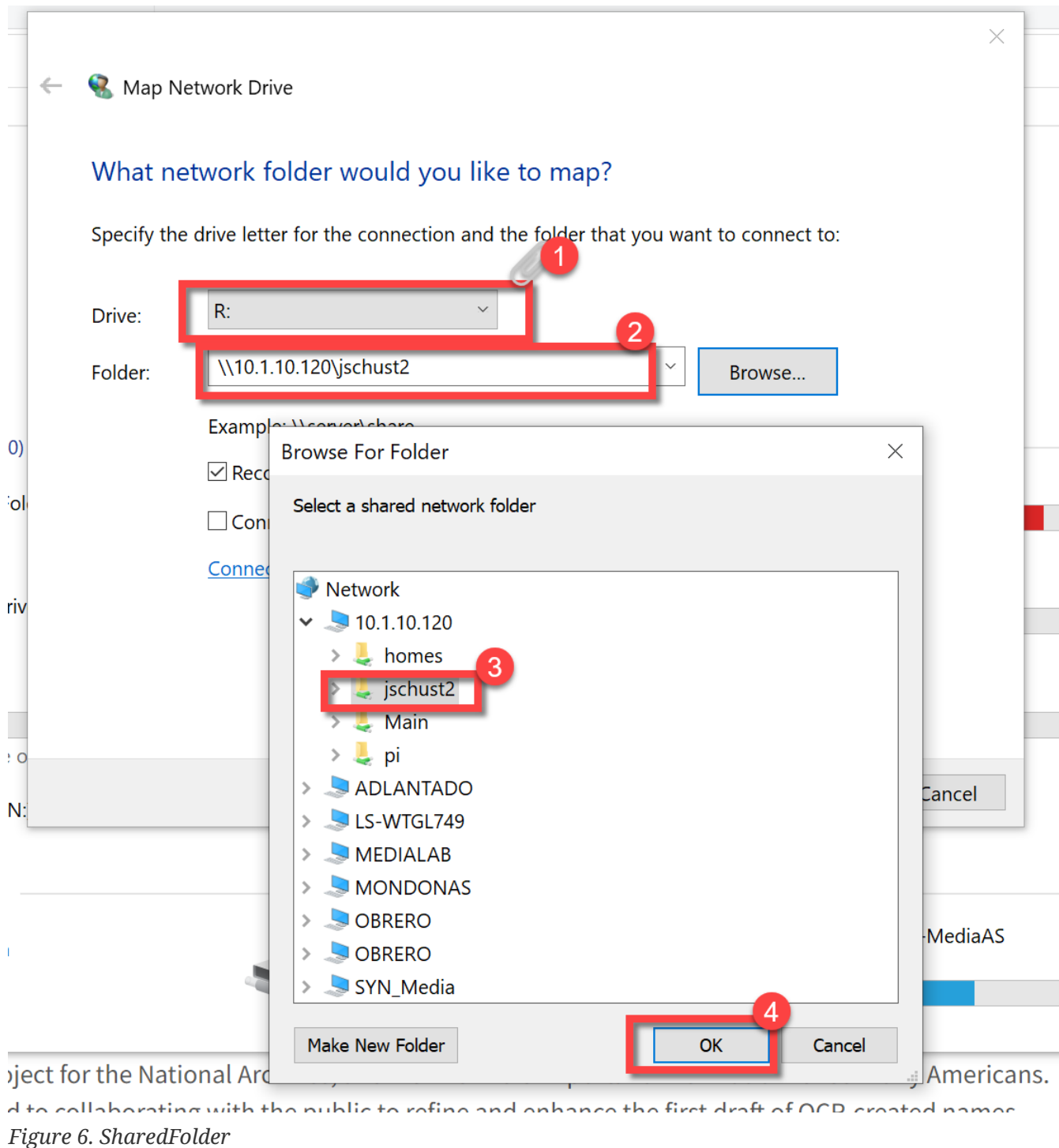


Figure 6. SharedFolder

## 5.1. Mount Windows share



The following section never worked!!!! All I ever got was

```
jschust2@RaspberryPI:~ $ sudo mount.cifs //10.1.10.22/Dropbox /home/jschust2/Dropbox/
-o user=jschust2,password=landsra9035
mount error(2): No such file or directory
Refer to the mount.cifs(8) manual page (e.g. man mount.cifs) and kernel log messages
(dmesg)
jschust2@RaspberryPI:~ $
```

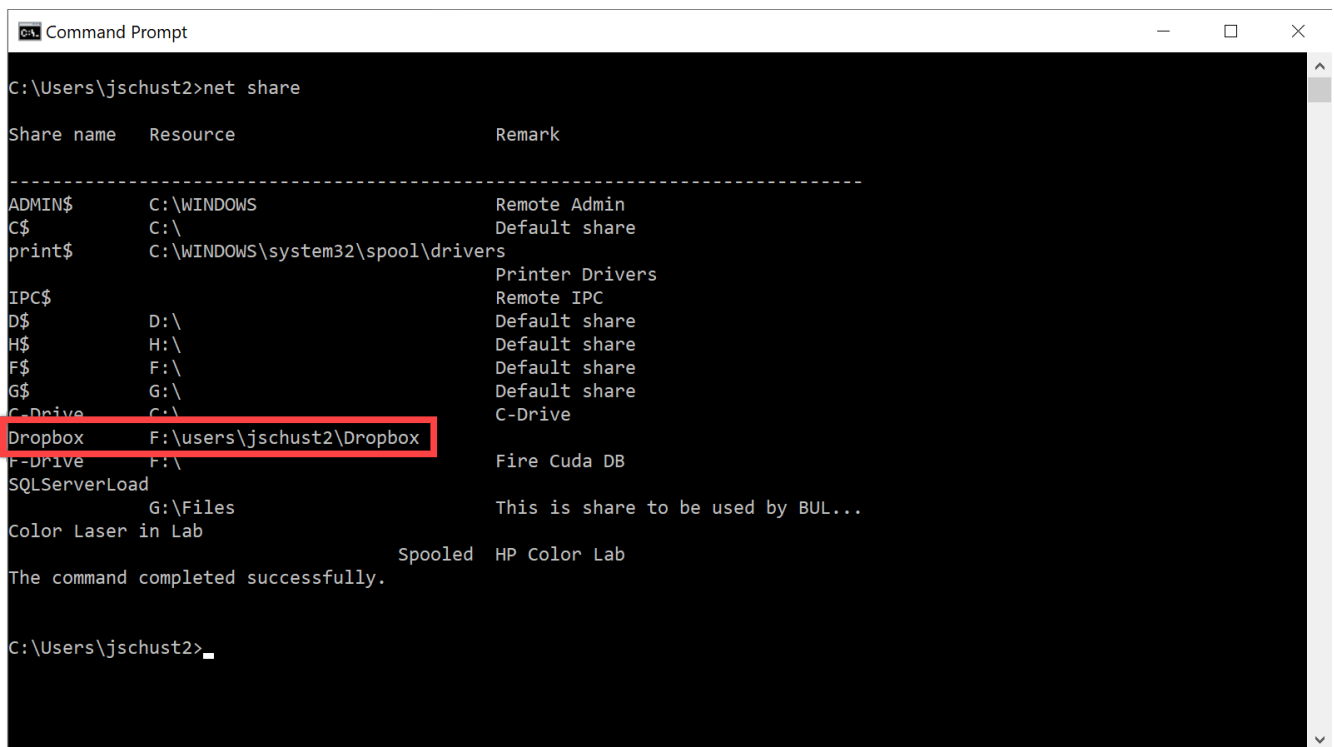
Reference: <https://www.bitpi.co/2015/02/16/accessing-a-windows-share-with-a-raspberry-pi/>

This will allow the Dropbox folder on the Windows desktop be available to the RPI400.

Verify using Windows **CMD** that Windows share is available using the following command.

```
net share
```

The share must be listed here to use in on RPI.



```
ca Command Prompt
C:\Users\jschust2>net share

Share name      Resource                                Remark
-----
ADMIN$          C:\WINDOWS                             Remote Admin
C$              C:\                                     Default share
print$          C:\WINDOWS\system32\spool\drivers       Printer Drivers
IPC$            C:\                                     Remote IPC
D$              D:\                                     Default share
H$              H:\                                     Default share
F$              F:\                                     Default share
G$              G:\                                     Default share
C-Drive         C:\                                     C-Drive
Dropbox         F:\users\jschust2\Dropbox              Fire CUDA DB
F-Drive         F:\                                     Fire CUDA DB
SQLServerLoad   G:\Files                               This is share to be used by BUL...
Color Laser in Lab Spooled HP Color Lab

The command completed successfully.

C:\Users\jschust2>
```

Figure 7. Verify Windows share

Verify the proper permissions exist

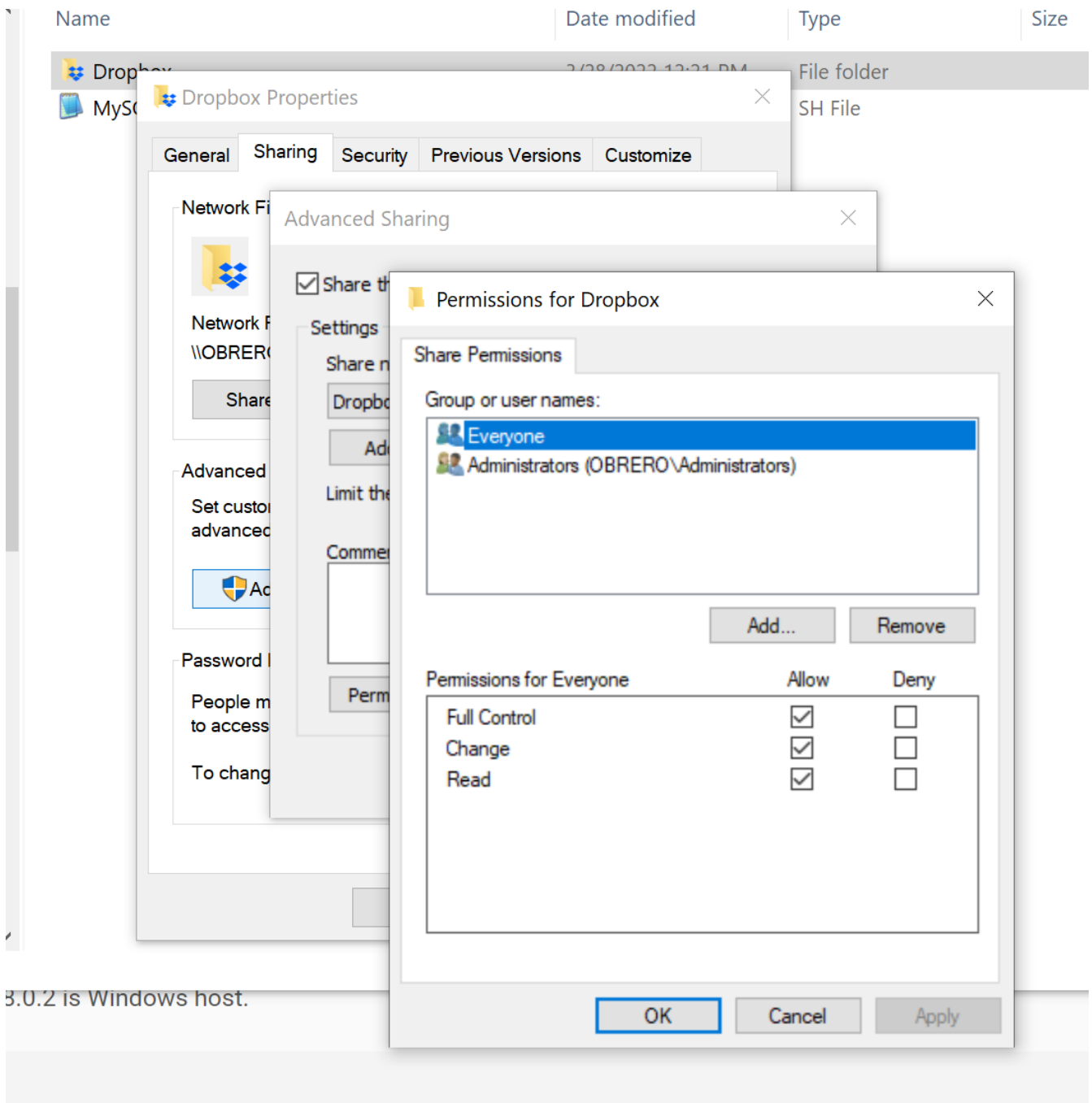


Figure 8. Dropbox folder permissions



Respect the RPI User name you logged in under. In this case the login is **jschust2** not **pi**

Using the RPI GUI Raspberry PI Configuration utility, Turn off the Auto login feature to avoid confusing **jschust2** and **pi**. There were a lot of headaches here.

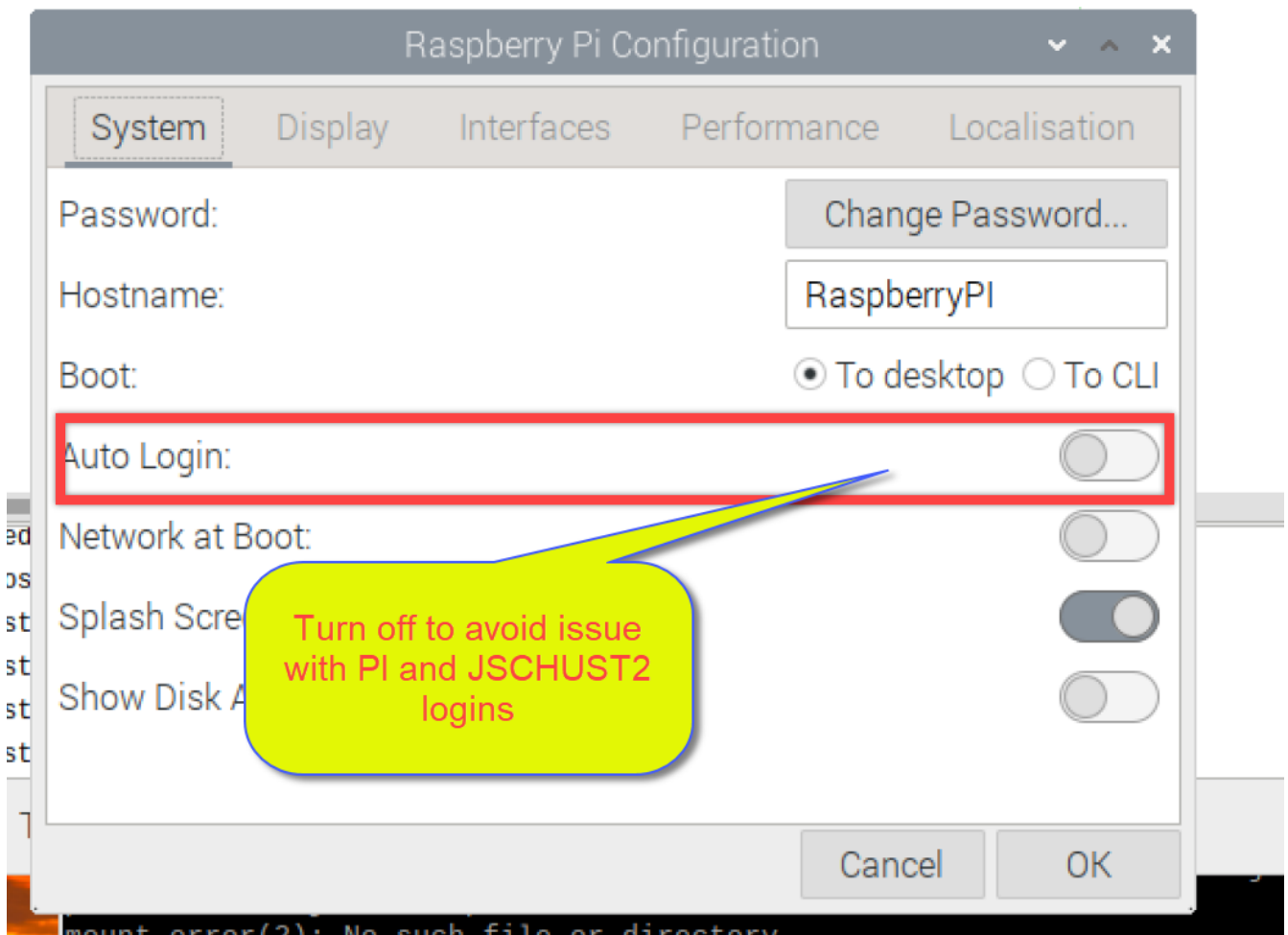


Figure 9. RPI Auto Login

Install SAMBA and Utilities for SMB support.

```
sudo apt-get install samba
```

```
sudo apt-get install samba-common-bin
```

We will need to install cifs-utils. This will help us mount SMB directories- which is what we get from Windows. We can install easily on Raspbian by running the following command:

```
sudo apt-get install cifs-utils;
```

Establish mount to a Windows share

Now we will create a mount point in the `mnt` directory:

```
mkdir /mnt/Dropbox/
```

The mount command for the Dropbox folder on the desktop the newly created folder on the RPI400.

```
sudo mount.cifs -o user=jschust2,password=***** //10.1.10.22/Dropbox /mnt/Dropbox
```



No space between user and password, all optional args are comma separated.

In order for your Raspberry Pi to mount the network shares on boot up, we need to modify the `/etc/fstab` file.

There may be entries there already. All we need to do is add the following to the end of the file:

```
//10.1.10.22/Dropbox /mnt/Dropbox cifs  
username=jschust2,password=***** ,iocharset=utf8,sec=ntlm 0 0
```

Now we can manually run the same mount process at boot up from the command line by running:

```
sudo mount -a;
```

restart the samba service so that it loads in our configuration changes.

```
sudo systemctl restart smbd
```

## 6. References

## 7. Document History

*Table 1. Document History*

Date	Version	Author	Description
04/01/2022	V2.1b	JHRS	Initial version