

Lecture 10 – Model Assessment and Selection

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Bias, Variance, and Model Complexity

- ▶ Target variable Y , inputs X , $\hat{f}(X)$ prediction model estimated from training set \mathcal{T}
- ▶ Typical choices of loss functions: $L(Y, \hat{f}(X)) = (Y - \hat{f}(X))^2$ (squared error) or $L(Y, \hat{f}(X)) = |Y - \hat{f}(X)|$ (absolute error)
- ▶ The test error / generalization error, is the prediction error over an independent test sample

$$Err_{\mathcal{T}} = E[L(Y, \hat{f}(X)) | \mathcal{T}]$$

where both X and Y are drawn randomly from their joint distribution (population).

Bias, Variance, and Model Complexity

- ▶ Expected prediction error (or expected test error)

$$Err = E[L(Y, \hat{f}(X))] = E[Err_{\mathcal{T}}]$$

Bias, Variance, and Model Complexity

- ▶ Goal: estimation of $Err_{\mathcal{T}}$
- ▶ Training error is the average loss over the training sample:

$$\bar{err} = 1/n \sum_{i=1}^n L(y_i, \hat{f}(x_i)).$$

- ▶ Similar for categorical variables (but different loss function).

Bias, Variance, and Model Complexity

- ▶ Usually model depends on a tuning parameter α : $\hat{f}_\alpha(x)$
- ▶ Two different goals:
 - ▶ Model selection: estimating the performance of different models in order to choose the best one.
 - ▶ Model assessment: having chosen a final model, estimating its prediction error (generalization error) on new data.

The Bias-Variance Decomposition

- ▶ $Y = f(X) + \varepsilon$ with $E[\varepsilon] = 0$ and $Var(\varepsilon) = \sigma_\varepsilon^2$
- ▶ The expected prediction error of a regression fit $\hat{f}(X)$ at a point $X = x_0$ under squared-error loss is given by

$$Err(x) = \sigma_\varepsilon^2 + Bias^2(\hat{f}(x_0)) + Var(\hat{f}(x_0))$$

- ▶ This can be interpreted as “Irreducible Error + Bias² + Variance”.

The Bias-Variance Decomposition | Example OLS

- For linear model fit $\hat{f}_p(x) = x^T \hat{\beta}$ with p components by ols we have

$$E(x_0) = E[(Y - \hat{f}_p(x))^2 | X = x_0] = \sigma_\varepsilon^2 + [f(x_0) - E\hat{f}_p(x_0)]^2 + \|h(x_0)\|^2 \sigma_\varepsilon^2$$

$$h(x_0) = X(X^T X)^{-1} x_0$$

The Bias-Variance Decomposition | Example OLS

- Average over all sample values x_i gives:

$$1/n \sum_{i=1}^n \text{Err}(x_i) = \sigma_{\varepsilon}^2 + 1/n \sum_{i=1}^n [f(x_i) - E\hat{f}(x_i)]^2 + \frac{p}{n} \sigma_{\varepsilon}^2,$$

the in-sample error.

Optimism of the Training Error Rate

- ▶ With $\mathcal{T} = \{(x_1, y_1), \dots, (x_n, y_n)\}$ given, the generalization error of a model \hat{f} is

$$Err_{\mathcal{T}} = E_{X^0, Y^0}[L(Y^0, \hat{f}(X^0)) | \mathcal{T}]$$

(fixed training set \mathcal{T} , new observation /data point (X^0, Y^0) drawn from F , the distribution of the data)

- ▶ Averaging over training sets yields the expected error:

$$Err = E_{\mathcal{T}} E_{X^0, Y^0}[L(Y^0, \hat{f}(X^0)) | \mathcal{T}]$$

(easier to analyze)

- ▶ In general: $\bar{err} = 1/n \sum_{i=1}^n L(y_i, \hat{f}(x_i)) \leq Err_{\mathcal{T}}$

Optimism of the Training Error Rate

- ▶ Part of the discrepancy come from the location where the evaluation points occur. $Err_{\mathcal{T}}$ as extra-sample error.
- ▶ In-sample error (for analysis of \bar{err})

$$Err_{in} = 1/n \sum_{i=1}^n E_{Y^0}[L(Y_i^0, \hat{f}(x_i)) | \mathcal{T}]$$

(observation of n new response values at each of the training points x_i)

- ▶ Optimism: difference between Err_{in} and training error \bar{err} :

$$op \equiv Err_{in} - \bar{err}.$$

- ▶ Average optimism is the expectation of the optimism over training sets:

$$\omega \equiv E_y(op).$$

Optimism of the Training Error Rate

- ▶ Usually only ω and not op can be estimated (analogous to Err and $Err_{\mathcal{T}}$)
- ▶ It can be shown: $\omega = 2/n \sum_{i=1}^n Cov(\hat{y}_i, y_i)$.
- ▶ Interpretation
- ▶ In sum: $E_y(Err_{in}) = E_y(e\bar{r}r) + 2/n \sum_{i=1}^n Cov(\hat{y}_i, y_i)$
- ▶ Example: linear fit with p variables for model $Y = f(X) + \varepsilon$:
 $\sum_{i=1}^n Cov(\hat{y}_i, y_i) = p\sigma_{\varepsilon}^2$

Estimates of In-Sample Prediction Error

- ▶ General form of the in-sample estimates: $\hat{Err}_{in} = \bar{err} + \hat{\omega}$.
- ▶ C_p statistic: $C_p = \bar{err} + 2\frac{d}{n}\hat{\sigma}_\varepsilon^2$
- ▶ Akaike Information Criterion: $AIC = -\frac{2}{n}\loglik + 2\frac{d}{n}$
- ▶ Bayesian Information Criterion: $BIC = -2\loglik + (\log n)d$

Cross-Validation

- ▶ Estimation of the prediction error directly.
- ▶ CV estimates the expected extra-sample error
$$Err = E[L(Y, \hat{f}(X))]$$
- ▶ Formal description:
 - ▶ Denote κ a partitioning function: $\kappa : \{1, \dots, n\} \rightarrow \{1, \dots, K\}$
 - ▶ Denote by $\hat{f}^{-k}(x)$ the fitted function, computed with the k th part of the data removed.

Cross-Validation

- ▶ The cross-validated estimator of the prediction error is

$$CV(\hat{f}) = 1/n \sum_{i=1}^n L(y_i, \hat{f}^{-k}(x_i)).$$

- ▶ Typical choices : $K = 5, 10$, $K = n$ is called *leave-one-out* cross-validation

Cross-Validation | Tuning Parameter

Given a set of models $f(x, \alpha)$ indexed by a tuning parameter α , denote by $\hat{f}^{-k}(x, \alpha)$ the model fit with the k th part of the data removed and tuning parameter α . Then for this set of model we define

$$CV(\hat{f}, \alpha) = 1/n \sum_{i=1}^n L(y_i, \hat{f}^{-k}(x_i, \alpha)).$$

The function $CV(\hat{f}, \alpha)$ provides an estimate of the test error curve, and we find the tuning parameter $\hat{\alpha}$ that minimizes it. Our final is $\hat{f}(x, \hat{\alpha})$, which we then fit to all the data.