

# Computer Communication Networks I

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## Lecture 2

### What happens when a signal is applied to the channel?

- Assume the bandwidth of the signal is  $W_s$
- Assume that the bandwidth of the channel is  $W_c$
- If the bandwidth of the signal is larger than the bandwidth of the channel (that is:  $W_s > W_c$ ) – then output signal will not contain all of the frequencies of the input signal.
- In other words, channel bandwidth determines the bandwidth of the signals that can pass through the channel.
- Suppose we increase the signaling speed -> pulses become narrower (higher signal bandwidth)
- The **bandwidth of a channel places a limit** on the rate at which we can send pulses through the channel.

### A very important result

If the channel has bandwidth of  $W$ , then the narrowest pulse that can be transmitted through the channel has duration of  $1/2W$  seconds.

Therefore, the maximum rate at which pulses can be transmitted through the channel is given by

$$r_{\max} = 2W \text{ pulses/second}$$

This rate is called the **Nyquist rate**.

The term **baud rate** is also used to denote the signaling rate in pulses/second.

### **Multilevel transmission**

- We can transmit binary information by sending a pulse with amplitude  $+A$  (denote 1) and  $-A$  (denote 0).
- We can increase the bit rate by sending more levels.
- Example:  $\{-A - A/3 + A/3 + A\}$  to denote  $\{00, 01, 10, 11\}$
- This is called **multilevel transmission**.

### **Important**

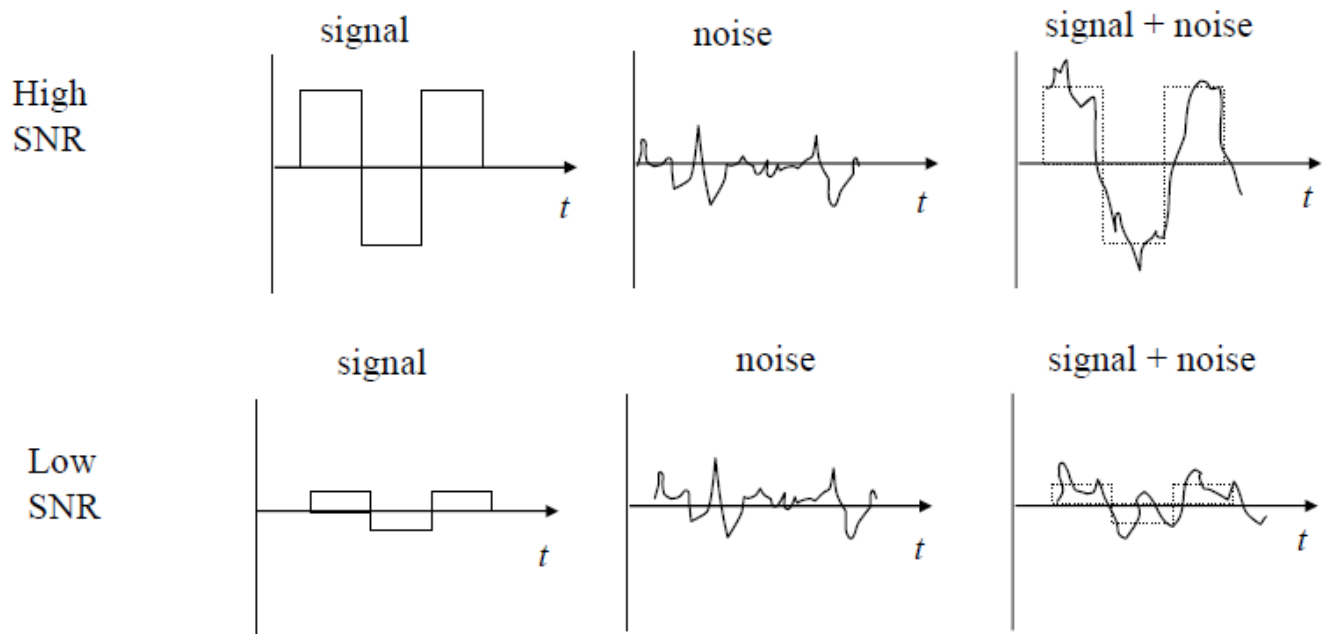
- If we use multilevel transmission with  $M=2^m$  amplitude levels, we can transmit at a bit rate of  $R=2W$  pulses/second  $\times m$  bits/pulse =  $2Wm$  bits/second.

### **Signal-to-noise ratio (SNR)**

- Noise is a major problem encountered in all communication systems.
- Noise consists of extra signals added to the transmitted signal at the input to the transmitter.
- The signal-to-noise ratio measures the relative amplitudes of the signal and the noise. It is normally stated in dB (decibels)

$$\text{SNR} = \frac{\text{Average signal power}}{\text{Average noise power}}$$

$$\text{SNR (dB)} = 10 \cdot \log_{10}(\text{SNR})$$



### Signal-to-noise ratio

### Channel Capacity

- The channel capacity of a transmission system is the **maximum rate** at which bits can be transferred **reliably**.
- Claude Shannon derived an expression for the channel capacity of an ideal low-pass channel.
- Reliable transmission of data rates above the capacity is not possible.

- The Shannon channel capacity is given by the following formula:

$$C = W \log_2 ( 1 + \text{SNR} ) \text{ bits/second}$$

### **Example**

Consider a telephone channel with  $W=3.4$  kHz and  $\text{SNR} = 40$  dB.

First convert the dB in SNR into SNR (linear)

$$\text{SNR} = 40 \text{ dB}$$

$$40 = 10 \cdot \log_{10}(\text{SNR})$$

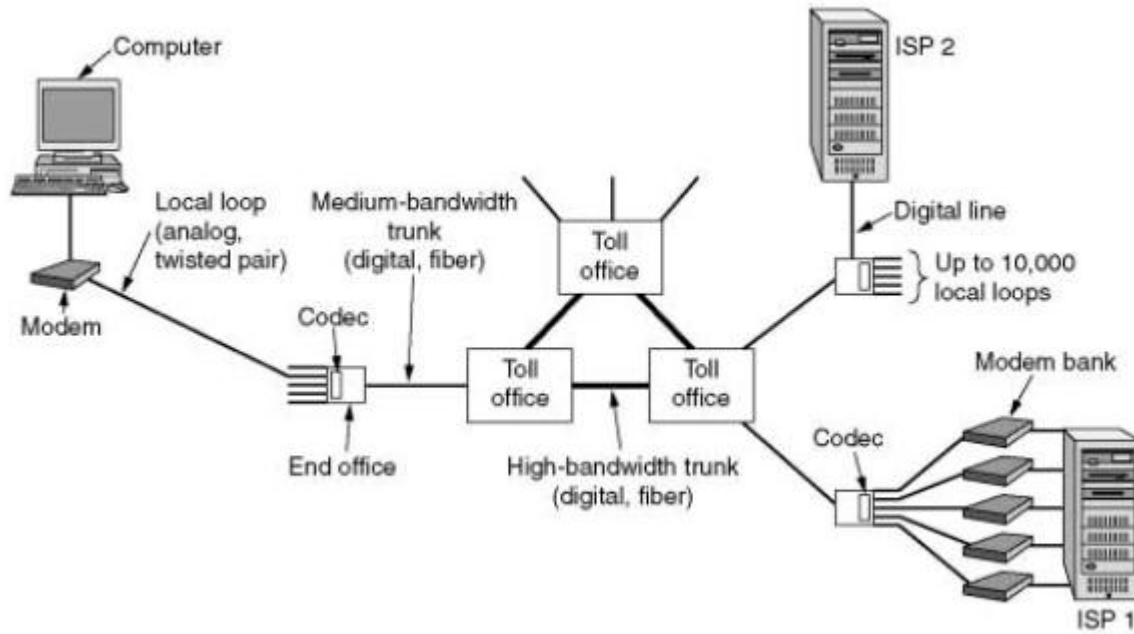
$$\text{SNR} = 10,000$$

The channel capacity is given by

$$\begin{aligned} C &= 3400 \cdot \log_2(1+10,000) \\ &= 45,200 \text{ bits/second} \end{aligned}$$

## Data encoding techniques

### Analog and Digital Transmissions



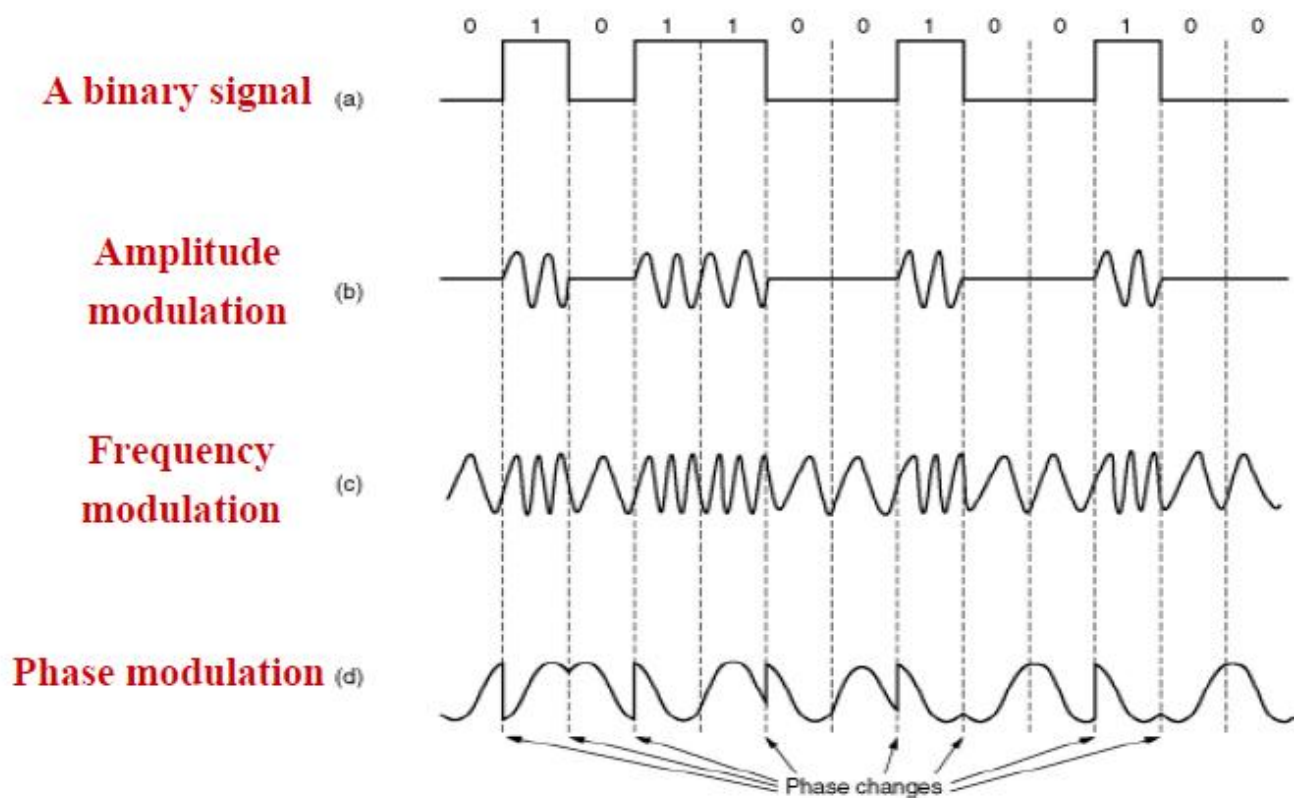
**Figure: Use of both analog and digital transmissions for a computer to computer call.**

## Data Encoding Techniques

- Digital Data, Analog Signals [**modem**]
- Digital Data, Digital Signals [**wired LAN**]
- Analog Data, Digital Signals [**codec**]

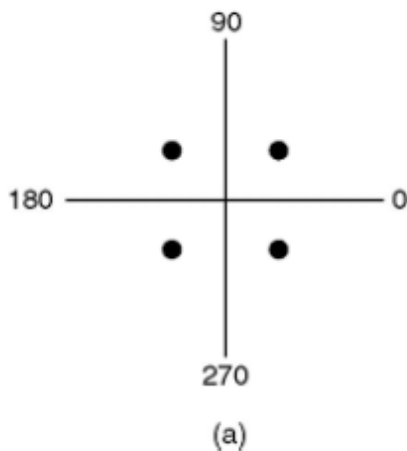
## Digital Data, Analog Signals

- Basis for analog signaling is a continuous, constant-frequency signal known as the **carrier frequency**.
- Digital data is encoded by **modulating** one of the three characteristics of the carrier:
  1. Amplitude
  2. Frequency
  3. Phase or some combination of these.

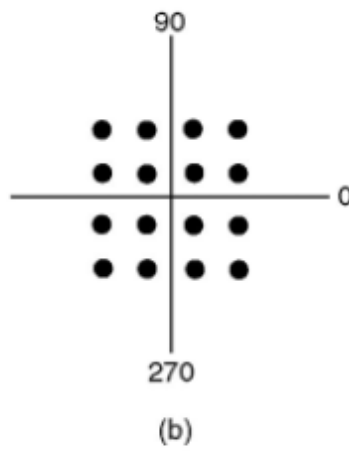


## Modems

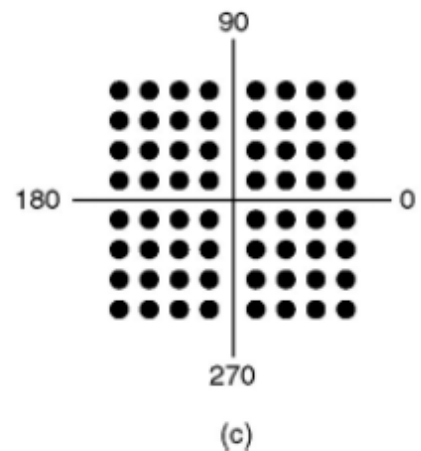
- All advanced modems use a combination of modulation techniques to transmit multiple bits per baud.
- Multiple amplitude and multiple phase shifts are combined to transmit several bits per symbol.
- QPSK (Quadrature Phase Shift Keying) uses multiple phase shifts per symbol.
- Modems actually use Quadrature Amplitude Modulation (QAM).
- These concepts are explained using constellation points where a point determines a specific amplitude and phase.



(a) QPSK.



(b) QAM-16.



(c) QAM-64.

**Figure: Constellation diagrams**

## **Digital data, Digital signals**

### **Line Coding**

- Line coding is the method used for converting a binary information sequence into a digital signal in a digital communication system.

#### **Uses of line coding**

- In systems such as wireless local area networks (WLANs) an important design consideration is the need to recover the bit **timing information**.
- Also many systems do not pass the DC (zero frequency) and low-frequency content.
- Some line coding methods have error detection capabilities.
- Some line coding methods are good against noise

### **NRZ ( Non-Return-to-Zero) Codes**

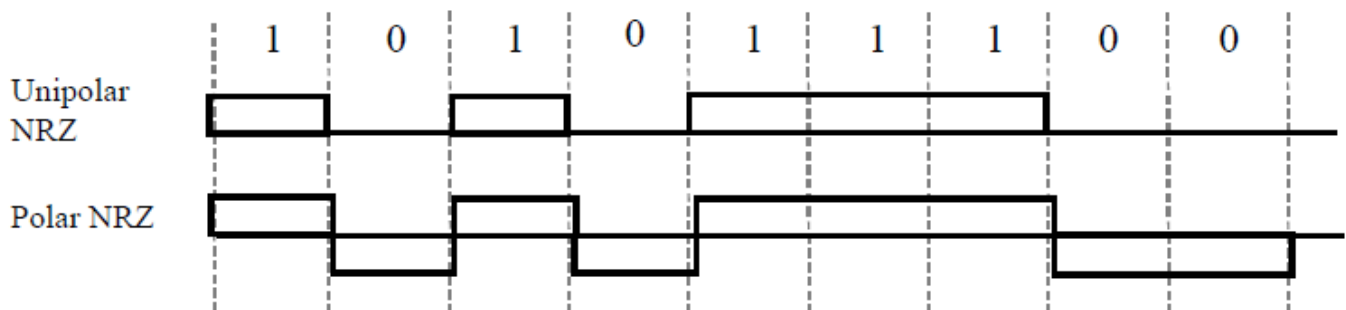
- Uses two different voltage levels (one positive and one negative) as the signal elements for the two binary digits.

### **NRZ-L ( Non-Return-to-Zero-Level)**

- The voltage is constant during the bit interval.



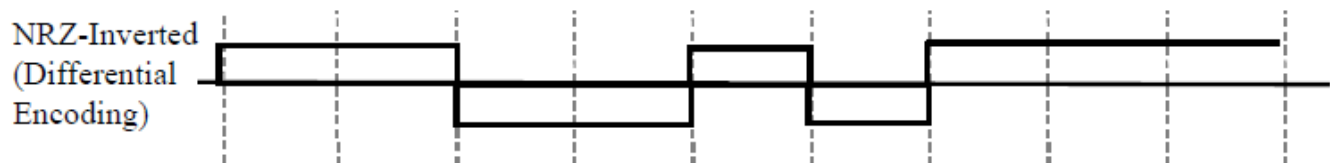
- Binary 1 is transmitted by sending a  $+A/2$  and binary 0 is transmitted by sending a  $-A/2$ .
- More efficient than NRZ code in terms of the average transmitted power.



### NRZ-I (Non-Return-to-Zero-Inverted)

- The two level NRZ-I signal has a transition at a clock boundary if the bit being transmitted is a logical 1, and does not have a transition if the bit being transmitted is a logical 0.
- NRZ-I is a **differential encoding** (i.e., the signal is decoded by comparing the polarity of adjacent signal elements.)

Example: 1 0 1 0 1 1 1 0 0



### **Bi-Polar encoding**

- Bi-Polar encoding method was developed to produce a spectrum that is more suitable to channels that do not pass low frequencies.
- In this method binary 0s are mapped into 0 voltage, and therefore makes no contribution to the digital signals.
- Consecutive ones are alternatively mapped into  $+A/2$  and  $-A/2$ .

### **Manchester encoding**

- There is **always** a mid-bit transition (which is used as a clocking mechanism)

#### Encoding Rule

- Zero (0) is represented by low-to-high
- One (1) is represented by high-to-low

### **Differential Manchester encoding**

- The clock half-period always begins with a transition from low to high or from high to low.
- The data half-period makes a transition for one value and no transition for the other value.
- One version of the code makes a transition for 0 and no transition for 1 in the data half-period;
- The other version makes a transition for 1 and no transition for 0.

Example: 1 0 1 0 1 1 1 0 0

