Implementation

(4)

```
× q5_2.m × q6_2.m × hybrid.m × bisection.m × newtons.m
     function [zero, res, niter] = bisection(f,a,b,tol,nmax)
1
2
3 -
       x = [a (a+b)/2 b]; y = f(x); niter = 0; I = (b-a)/2;
 4 -
       if(y(1)*y(3)>0)
5 -
           error('The sign of the function at the extrema must be opposite');
 6 -
       elseif y(1) == 0
7 -
           zero = a; res = 0; return
       elseif y(3) == 0
8 -
9 -
           zero = b; res = 0; return
10 -
       end
11 -
     while (I>=tol && niter < nmax)
12 -
           if sign(y(1))*sign(y(2))<0
13 -
               x(3) = x(2); x(2) = (x(1)+x(3))/2;
14 -
               y = f(x); I = (x(2)-x(1))/2;
15 -
           elseif sign(y(3))*sign(y(2))<0
16 -
                x(1) = x(2); x(2) = (x(1)+x(3))/2;
17 -
                y = f(x); I = (x(2)-x(1))/2;
18 -
               x(2) = x(find(y==0)); I = 0;
19 -
20 -
21 -
           niter = niter + 1;
22 -
       end
23
24 -
       if(niter >= nmax)
25 -
            fprintf('bisection method exited without convergence');
26 -
       end
27 -
       zero = x(2); res = f(x(2));
28
29 -
       end
                                       bisection
                                                                       Ln 1
                                                                               Col 56
```

Figure 1: Bisection Method Code

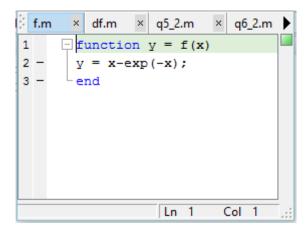


Figure 2: Equation for (4)

```
× q5_2.m × q6_2.m × hybrid.m × bisection.m × newtons.m
 df.m
      function [zero, res, niter] = newtons(f, df, x0, tol, nmax)
 1
 2 -
       niter = 0;
       x = x0 - f(x0)/df(x0);
 3 -
 4
      \Box while abs (x0-x) >= tol && niter <= nmax
 5 -
            x0 = x;
            x = x0 - f(x0)/df(x0);
 8 -
           niter = niter + 1;
 9 -
       -end
10
11 -
       if niter > nmax
12 -
            fprintf('Newtons method stopped without convergence\n');
13 -
       end
15 -
       zero = x; res = f(x);
16
17
18 -
      ∟end
                         newtons
                                                         Ln 6
                                                                 Col 12
```

Figure 3: Newton's Method Code

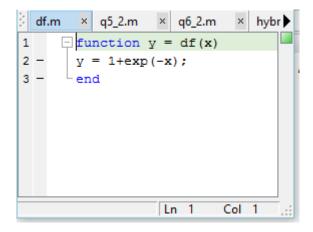


Figure 4: Derived equation for (4)

```
Command Window

>> [zero,res,niter] = bisection (@f,0,10,10^(-8),100)

zero =

0.5671

res =

-1.6221e-08

niter =

28

fr >> |
```

Figure 5: Answer for (4)(a)

(b)

Figure 6: Answer for (4)(b)

(c)

```
df.m
       × q5_2.m
                  × q6_2.m
                             × hybrid.m
                                        × bisection.m
                                                         newtons.m
1
     function [zero,res,niter] = hybrid(f,df,a,b,tol,nmax)
2 -
           [a,b,c] = bisection(f,a,b,tol,2);
           [zero,res,niter] = newtons(f, df, a, tol, nmax);
3 -
       end
5
                  hybrid
                                                   Ln 5
                                                           Col 1
```

Figure 7: Hybrid Method Code

Figure 8: Answer for (4)(c)

(d)

| Method | Bisection | Newton | Hybrid |
|------------|-----------|--------|--------|
| Number of | 20 | 5 | 1 |
| iterations | 20 | 3 | 4 |

Fastest algorithm to solve this problem is the Hybrid algorithm.

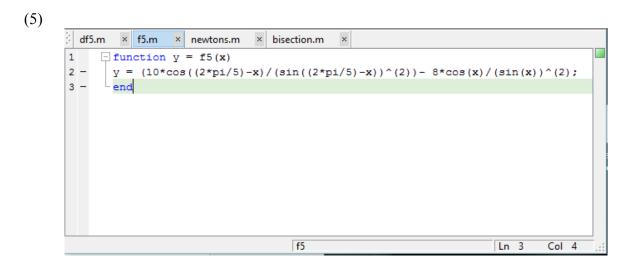


Figure 9: Equation for (5)

Figure 10: Derived equation for (5)

Figure 11:Answer for (5)

In 5th question initial point was chosen by considering the alpha's characteristics. Alpha is an acute angle. Therefore minimum value was chosen as the initial point.

(6)

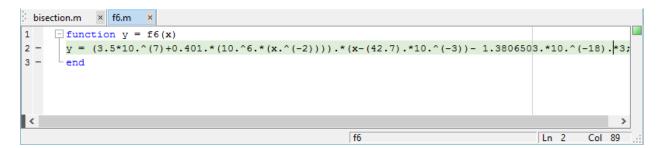


Figure 12: Equation for (6)

```
Command Window
  >> [zero, res, niter] = bisection(@f6,-100,100,10^(-12),100)
  zero =
      0.0427
  res =
    -3.1248e-04
  niter =
      46
fx >>
```

Figure 13: Answer for (6)