

Optimization of Reverse Osmosis Performance

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Abstract

A condensed description of my work.

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Permeate
Reject
RO
Flux
Pressure
Osmosis
Reverse Osmosis
Semi-permeable membrane
Conductivity
more

1

Introduction

1.1 Background

The Water Technologies department at Baxter develops water systems for use in mixing fluid for dialysis treatments. The water quality is important in order to not harm to the patients when using the final product. The water systems used for water purification are using the reverse osmosis (RO) method as the finest level of filtration. It remove impurities, as salt and inorganic molecules from the water[Company, 2018].

In a RO-system the feed water is pressurized by a pump and forced through the RO-membrane to overcome the osmotic pressure. The RO-membrane is a semi-permeable membrane and let water passes freely true the membrane creating a purified product stream.

The pump in the current system has two purposes, creating a pressure to overcome the osmotic pressure and creating a flow on the reject side of the RO-membrane to prevent aggregation of impurities on the membrane surface.

1.2 Motivation

By using two pumps instead of one in the RO-system it will be possible to control the pressure on the module and the flow on the reject side independently and thus get better possibility to optimize the performance of the RO-system, focusing on reducing impurities and water consumption.

As the current model does not take temperature dependencies in concern, the model will be redesigned in order to handle temperature dependencies.

1.3 Goal

The purpose of this masters thesis is to evaluate the feasibility of replacing the main RO-pump with two pumps, one for controlling the flow through the membrane and one for controlling the pressure.

To achieve good performance it will be necessary to design a realistic model of the system, once the model has been designed and tested a control algorithm is to be developed. This algorithm, should be able to control the flow and pressure over the RO-membrane to maximize the efficiency of the filter while minimizing the amount of waste water that is produced.

The temperature dependencies will be taken in concern in the new model.

Framing of questions

- Is it possible to upgrade the RO-membrane model to include temperature dependencies?
- Is it possible to control the system with two pumps instead of one, which is used today?
- Is it possible to control the two pumps in order to gain better efficiency in reducing water waste, noise or performance? (In comparison with the current system).

1.4 Method

In order to investigate the performance of the current system and to compare it with the new model following steps will be evaluated:

- Research on the RO-membrane that is implemented in the system
- Research on previous work on the field
- Modelling of the system to identify suitable component properties and design of the flow path
- Design of control algorithms
- Control simulations
- Implementation in a test rig to verify the performance of the system
- Run tests to determine the performance
- Improve if possible

2

Theory

2.1 Semi-permeable membrane

A membrane is defined as a barrier between two homogeneous phases. The process is a continuous steady-state operation consisting three streams: feed, permeate and reject. Main concern in the process boundary is the semipermeable barrier that selectively allows the passage of some components but not others. [R, 2015]

2.2 Osmosis

The osmosis process occurs when two solutions of different chemical concentration are separated by a semi-permeable membrane. The two different solutions will try to reach equilibrium. The solution with less concentration will have a natural tendency to migrate through the membrane over to the side with higher concentration. Osmosis is a naturally occurring phenomenon and one of the most important processes in nature. The pressure that occurs is called the osmotic pressure. The phenomenon can be seen in Figure 2.1

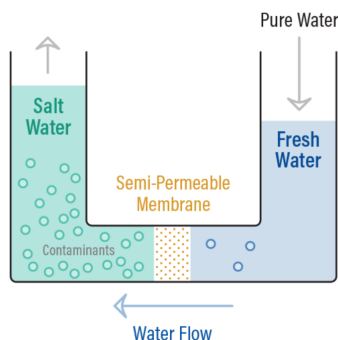


Figure 2.1 Osmosis

2.3 Reverse osmosis

The reverse osmosis(RO) process is the reverse process of the osmosis. When pressure is applied to a semipermeable membrane, the water molecules are forced through the semipermeable membrane and the contaminants are not allowed true. The amount of pressure required depends on the salt concentration of the water. In order to gain reverse osmosis the pressure applied must be greater than the osmosis pressure. The membrane employs cross filtration rather than standard filtration. With cross filtration, the solution passes through the filter with two outlets. One solution passes true the membrane and is called permeate and is the filtered solution.

The other solution can be drained or be fed back into the filtering system. The contaminants build up at the surface area and it is of great importance to try to sweep them away and hold the surface clean. If the contaminants build up the performance of the membrane will decrease, and cleaning with chemicals or heat water might be necessary[*What is reverse osmosis*]. The phenomenon of reverse osmosis can be seen in 2.2. In order to obtain good performance over the RO membrane there

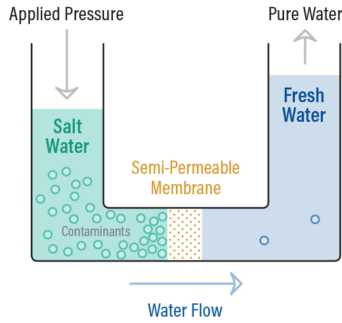


Figure 2.2 Reverse Osmosis

are some parameters that should be taken in consideration when designing a RO system. These are:

Pressure: feed (P_f), permeate (P_p), reject, (P_r)

Conductivity: feed, C_f , permeate (C_p), reject (C_r)

Flow: feed (Q_f), permeate (Q_p), reject(Q_r)

Temperature: feed (T_f), permeate (T_p), reject (T_r)

Fouling

Fouling occurs when contaminants accumulate on the surface of the membrane. The fouling contributes to a pressure drop that will decrease the performance of the membrane and cause less permeate flow. Fouling will happen eventually to some extent given the fine pore size of the membrane. A high reject flow and proper pretreatment will extend the operational time between cleaning procedures of the membrane[*What is reverse osmosis*].

2.4 Mathematical modeling of reverse osmosis

There are different models to describe the flow of solutes and solvents in the reverse osmosis process. The mass balance equations are central in modeling the process.

Figure 2.2 shows the main process.

A hydraulic pressure is applied to the feed stream of concentration, C_f and results in a flow rate Q_f . Some of the solvent, pure water, passes through the RO-membrane characterized by solvent permeability, solute permeability and surface area. The product water (purified water), is called permeate and has the concentration C_p and flow Q_p . The concentration, called reject has the concentration C_r with flow Q_r . The study objective of this basic RO-modeling is to calculate output concentrations and flow rates in terms of input and operation conditions. Parameters used to evaluate the performance of the RO-membrane is rejection ratio:

$$R = 1 - \frac{C_p}{C_f} \quad (2.1)$$

and recovery ratio:

$$Y = \frac{Q_p}{Q_f} \quad (2.2)$$

which express the quality and quantity of the solvent product respectively. Mass balance in the system gives:

$$Q_f = Q_p + Q_r \quad (2.3)$$

and:

$$C_f Q_f = C_p Q_p + C_r Q_r \quad (2.4)$$

Solvent flux per unit time per unit membrane surface area is described by:

$$J_w = \frac{Q_p}{A_m} = A(\Delta P - \Delta \pi) \quad (2.5)$$

where $\Delta \pi = \pi_f - \pi_p$ is the osmotic pressure difference between feed and permeate side and A_m is membrane surface area. Solute flux is given by:

$$J_s = B(C_f - C_p) \quad (2.6)$$

where B is the solute permeability.

The permeate concentration can be described by:

$$C_p = \frac{C_f}{1 + \frac{A}{B}(\Delta P - \Delta \pi)} \quad (2.7)$$

where A is solvent permeability. Permeate flow is described by:

$$Q_p = Q_f Y \quad (2.8)$$

The four mass balance equations (2.3 - 2.6) make the RO process mathematically solvable.

In order to model the osmotic pressure the van't Hoff principle can be used. It gives the osmotic pressure:

$$\Delta\pi = b(C_f - C_p) \quad (2.9)$$

where b is a proportionality. In van't Hoff's equation $b=RT$, where R is the gas constant and T is the absolute temperature on the membrane system.

2.5 Control theory

The system is considered a slow system

3

Equipment

3.1 Reverse Osmosis Membrane

The membrane used is a reverse osmosis membrane manufactured by the DOW chemicals company. It is a custom made membrane for Baxter AB.

3.2 Pumps

The pumps used in the system are magnet drive rotary vane pump TSSS401 from Fluid-o-Tech. They are designed to deliver a smooth flow reliably and optimized to reduce noise and power consumption. They are made for a maximum static pressure of 20 bar and has a speed limit of 1725 rpm. The nominal flow rate is 400 l/h.

3.3 Simscape/Simulink

Simscape is a graphical programming tool within the Matlab simulink environment designed to model and simulate physical systems. A model of the RO-membrane and the flow path is designed using simscape and the simulated system could then be controlled using a control algorithm running in Simulink, a Matlab software too. The RO-membrane model incorporate separate mathematical models of the most important system dependencies, such as temperature , flow, pressure and conductivity.

The system control is implemented in Simulink.

3.4 Speedgoat Real-Time Target Machine

Speedgoat is a realtime target machine used for development. It is an FPGA I/O module with Simulink driver blocks. It is capable of simultaneous sampling and is used to drive the system rig. It contains an Intel 2.0 GHz quad core CPU. More technical information can be seen in Appendix

3.5 Measurement instruments

Different instruments used to measure pressure, flow, temperature and conductivity in the physical rig.

Conductivity sensor block

A conductivity sensor block built by Gambro Lundia AB, called C3 is used to measure the water conductivity. In order to measure the required range two of the blocks where adjusted and calibrated. Two of the blocks, implemented in feed and recirculation path measures in range 0-3000 μS . The sensors cell implemented on permeate side measures up to 1500 μS .

Temperature sensor

The C3 cell described in section 3.5 contains sensors for temperature measurements and are used for the temperature measurements in the system.

Pressure sensor

Pressure sensors were implemented in the C3 block, described in section 3.5, and calibrated in order to achieve the pressure at feed, recirculation and permeate side of the membrane. The pressure sensors range is between 0-20 bar.

Flow sensor

A flow sensor from Bronkhorst High-Tech B.V is used to measure the flow on permeate side. The flowmeter works in 4-1500 ml/min range and 0-100 bar with water as liquid flowing through. It has an accuracy of ± 1 ml/min.

4

Method/Implementation

4.1 Flowchart investigation

To obtain a system to run tests on some different flowchart are considered. The current pump will be replaced by two pumps. Following requirements will be desirable when obtaining a updated model of the flowchart:

Pressure drop over the membrane is high

Flow through membrane is high

The model shall contribute with the following:

Permeate conductivity (minimized)

Fouling on the membrane (minimized)

Temperature dependencies

Waste water going through drain (minimized)

Mainly two different systems containing two pumps were considered.

System 1

The first system with one with pump on feed side and one pump on permeate side, as seen in Figure ???. Benefits with this setup is

System 2

The second system considered with one pump on feed side and one pump on reject-side, in recirculation path, seen in Figure ??.

4.2 Tests on current system

In order to compare results of the current system, furthermore called "System 1" and the updated system, "System 2", some test will be done on the current setup. Reasonable values for the test cases were set and can be seen in Table 4.1:

4.3 Modeling

Simscape software tool described in section 3.3 is used to do a physical modeling in order to achieve the characteristics of the membrane. Mathematical equations from the manufacturer of the membrane and physics of the solution-diffusion model described in section 2.4 were used and implemented.

Case	Temperature °C	Feed Conductivity (μS)
1	20 °C	500 μS
2	20 °C	1000 μS
3	20 °C	2000 μS
4	20 °C	3000 μS
5	30 °C	500 μS
6	30 °C	1000 μS
7	30 °C	2000 μS
8	30 °C	3000 μS
9	40 °C	500 μS
10	40 °C	1000 μS
11	40 °C	2000 μS
12	40 °C	3000 μS

Table 4.1 Testcases for System 1 and 2

4.4 Implementation Test Rig

In order to run all tests a physical rig was built. A first version to meet the specifications of the system used in the current water device were built according to Figure ?? and tests were executed. A new, second, system were built, according to Figure ?? in order to do the tests for the modified system including two pumps. In order to log all signals and to run the system the Real-Time Target Machine described in section 3.4 were connected with all significant signals. Different interfaces, as i^2c , XXXXX were used to implement the communication between the Real-Time Target Machine and measurement instruments. Circuits were built to transform voltage supply to required level for each component.

FIGURES

4.5 Design of control algorithms

Control algoritms were developed in Matlab Simulink for the updated system.

4.6 Control simulations

4.7 Improvements

5

Results

5.1 Test on current system

5.2 Flowchart investigation

Figures

5.3 Modeling

5.4 Design of control algorithms

5.5 Control simulations

5.6 Implementation test rig

5.7 Improvements

6

Discussion

discuss

7

Conclusion

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A

Appendix A