

2017 IEEE International Conference on Unmanned Systems (IEEE ICUS 2017)

国际咨询/指导变负会			
Hao Dai,	中国	Quanmin Zhu,	英国
王飞跃,	中国	Didier Theilliol,	法国
陈阳泉,	美国	Aarne Halme,	芬兰
Frank L. Lewis,	美国	Lihua Xie,	新加坡
Chai Wah Wu,	美国	Ben M.Chen,	新加坡
Yang Shi,	加拿大	余星火,	澳大利亚
Youmin 7hang.	加拿大	吕全唐,	中国

加拿大

Erwin Prassler, Maciej Ogorzalek, 大会主席

中国工程院院士, 北京理工大学,

大会副主席

Simon X. Yang,

秦继荣,中国指挥与控制学会,陈鹏万,北京理工大学, 北京理工大学, 中国

程序委员会主席 李东光, 北京理工大学, 中国

程序委员会副主席

泉, 中国 欣, 中国 丁文锐, 中国 杜志江, 陈哨东, 何玉庆, 中国 敏,

全体会议和半全体会议主席 王亚斌,中国

刘建华, 中国

宣传/区域主席

Lihua Xie,新加坡 张定国, 中国 张定国,钱志辉, Yantao Shen, 英英英英英 Shijun Guo, Roland Hin Kwan Wong, 胡天江, 中国 Walter Sweeting, Dhammika Widanalage, 英国 加拿大 Walter Sweeting, 吴文健, 中国 胡劲文, Youmin Zhang, 陈 曦, 中 李道春, 中 冯 星, 中 季海波, 中国 星,卫, 中国中国 中国中国

李文彬, 苏 波,

行业/展览主席

中航工业 613 所, 北京宇达科技有限公司, 北京海鹰科技情报研究所, 北方无人机研发中心, 付俊辉, 陈少春, 苏 波, 中国 孙柏原, AUVSC,

出版主席

国防科技大学,

注册主席

中国

腾, 中国 IEEE International Conference on Unmanned Systems in 2017 (IEEE ICUS 2017) will be held from October 27th to 29th in Beijing, China. The conference offers a unique and interesting platform for scientists, engineers and practitioners throughout the world to present and share their most recent research and innovative ideas in the areas of unmanned systems, robotics, automation, and intelligent systems. The aim of the IEEE ICUS2017 is to stimulate among researchers active in the areas pertinent to intelligent unmanned systems.

The topics of interests include, but are not limited to:

1. Unmanned Aerial Vehicles

2. Unmanned Ground Vehicles

3. Unmanned Underwater Vehicles

4. Unmanned System Command and Control

5. Sensing, Navigation and Control

6. Cooperative Control of Unmanned Systems

7. Unmanned System Dynamics

8. Unmanned System Modeling and Simulation

9. Artificial Intelligence and Intelligent Systems

10. Robotic Systems

11. Bionic Technology

12. New Concept Unmanned Systems

13. Other Related Technologies for Unmanned Systems

Invited Sessions:

The conference will feature invited sessions on new topics and innovative applications. These sessions will consist of 8-10 articles and undergo a regular review process. Prospective organizers should include a brief statement of purpose for the session as well as the abstracts of the papers.

Submissions & Publication:

Please prepare your paper using the IEEE Template. LaTeX style, Microsoft Word style.

Please submit the first draft of your paper in PDF format through the website. A maximum of 6 pages per first draft are permitted. Detailed instructions for paper submission are available on the website.

Papers should describe original and unpublished work on the above or the related topics. All manuscripts will be reviewed by three members of the international program committee.

Instructions for preparation and electronic submission will be available shortly on the website.

Contact Address:

IEEE ICUS 2017 Conference Secretariat Beijing Institute of Technology, China Tel: +8610-6891-2761 (Prof. Hongbin Deng)

E-mail: denghongbin@bit.edu.cn

Website: http://www.c2.org.cn or http://www.icus.org.cn

Important Dates:

Deadline for manuscript paper submission: July 1, 2017 **Notification of acceptance:** Aug. 15, 2017 Submission of camera-ready: Aug. 30, 2017 Deadline for early bird registration: Sep. 15, 2017 Conference: Oct. 27-29, 2017

http://www.icus.org.cn

Accepted high-quality papers will be recommended to be considered as special issue papers in International Journal of Robotics and Automation (SCI-indexed), International Journal of Modeling Identification and Control (El-indexed) and



















