

2021. 10. 19 Discrete-time models

$$N(t+1) = F(N(t))$$

↑  
mapping  
RECURSIVE equations

exponential model
logistic growth model
stability analysis

① Exponential model (geometric growth)

$$N(t+1) = R \cdot N(t)$$

Assumptions

- 1. closed population
- 2. identical individuals, no internal structure
- 3. no density dependence
- 4. time independent parameters

5. Discrete events & population census  $\Rightarrow$  specify order of events (synchronized)

fraction of ind. that give births

$$N'(t) = N(t) + \beta N(t) = (1 + \beta) N(t)$$

↑

Deaths      N      Births

$$N''(t) = N'(t) - \delta N'(t) = (1 - \delta) N'(t)$$

↑ fraction of ind. that die

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    graph TD
      N[N] -- "Births" --> N_prime[N']
      N_prime -- "Deaths" --> N_double_prime[N"]
      N -- "Census" --> N
  
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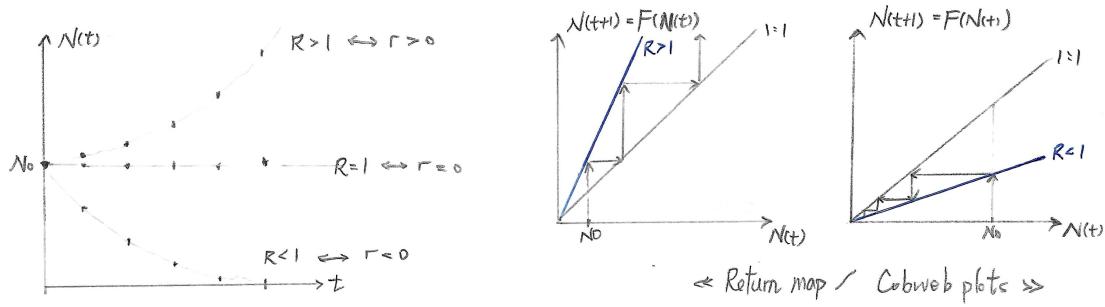
$$\Rightarrow N''(t) = N(t+1) = (1 - \delta)(1 + \beta) N(t)$$

$$\Rightarrow N(t+1) = R N(t) \quad \dots \textcircled{1}$$

Reproductive factor, constant independent to density;  $R = \frac{N(t+1)}{N(t)}$   
finite rate of increase (per unit time)

$$\Rightarrow N(t) = R^t N_0 \quad \dots \textcircled{2}$$

- Dynamics resemble that of continuous model



- Connections w/ continuous model

1. Instead of  $t \sim t+1$ , think of small  $\Delta t$  and let  $\Delta t \rightarrow 0$

In small  $\Delta t$ , we'd expect the per capita number of birth/death to be proportionately smaller (i.e.,  $\delta \Delta t$  &  $\beta \Delta t$ ), therefore from  $t \sim t+\Delta t$

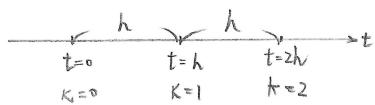
$$N(t+\Delta t) = (1 - \delta \Delta t)(1 + \beta \Delta t)N(t)$$

$$\frac{dN}{dt} = \lim_{\Delta t \rightarrow 0} \frac{N(t+\Delta t) - N(t)}{\Delta t}$$

$$= \lim_{\Delta t \rightarrow 0} \left[ \frac{N(t) + \beta \Delta t N(t) - \delta \Delta t N(t) - \delta \beta \Delta t^2 N(t) - N(t)}{\Delta t} \right]$$

$$= \lim_{\Delta t \rightarrow 0} \left[ (\beta - \delta - \underbrace{\beta \delta \Delta t}_{0}) N(t) \right] = (\beta - \delta) N$$

2. Compare with  $\frac{dN}{dt} = rN$  at specific time points  $t = hk$



↓ time interval between iteration  
usually  $h=1$ , but here more general

$$N(t) = N_0 e^{rt} \Rightarrow \text{at } t = hk, N(t) = N(hk) = N_0 e^{r(hk)}$$

↓ compare

$$N_0 \cdot R^k$$

$$\Rightarrow R = e^{rh} \Rightarrow r = \frac{\ln R}{h} \quad \text{②}$$

3. Compound interest  $\Rightarrow R = (1 + R_0) = (1 + \frac{R_0}{h})^h$ , with  $h \rightarrow 0, R_0 \rightarrow r, (1 + \frac{R_0}{h})^h \rightarrow e^r$

$$(1 + x)^{\frac{R_0}{h}}$$

## ② Discrete Logistic growth

Can derive by discretizing the continuous model

$$\frac{dN}{dt} = r_0 N \left(1 - \frac{N}{K}\right)$$

$$\Rightarrow \frac{\Delta N}{\Delta t} = r_0 N \left(1 - \frac{N}{K}\right)$$

set  $\Delta t = 1$  for discrete, non-overlapping generations

$$\Rightarrow \Delta N = N(t+1) - N(t) = r_0 N(t) \left(1 - \frac{N(t)}{K}\right) \Delta t$$

$$\Rightarrow N(t+1) = N(t) + r_0 N(t) \left(1 - \frac{N(t)}{K}\right) \stackrel{(4)}{=} N(t) \left[1 + r_0 \left(1 - \frac{N(t)}{K}\right)\right] \equiv F(N(t)) \quad (5)$$

## ③ Equilibrium for Discrete models $N(t+1) = F(N(t))$

For continuous models, zero growth  $\Rightarrow \frac{dN}{dt} = 0 = f(N^*)$

For discrete models, zero growth  $\Rightarrow N_{t+1} = N_t = N^* \quad (6)$

For Logistic growth:  $N^* = N^* \left[1 + r_0 \left(1 - \frac{N^*}{K}\right)\right] \Rightarrow N^* = D \quad \begin{matrix} \downarrow & \text{equilibrium} \\ \downarrow N^* & \\ 1 = 1 + r_0 \left(1 - \frac{N^*}{K}\right) & \uparrow \text{trivial equilibrium} \end{matrix}$

## ④ Stability analysis for discrete models $N(t+1) = F(N(t))$

Again, think about displacement and its dynamics near the equilibrium

$$\varepsilon(t) = N(t) - N^*$$

(at next time step)

Recall: Taylor expansion

$$f(a+\Delta x) = f(a) + \Delta x f'(a) + \frac{\Delta x^2}{2!} f''(a) + \dots$$

$$\varepsilon(t+1) = N(t+1) - N^* = F(N(t)) - N^* = F(N^* + \varepsilon(t)) - N^*$$

$$\approx \underbrace{F(N^*)}_{N^*} + \varepsilon(t) \cdot \frac{dF}{dN} \Big|_{N=N^*} - N^*$$

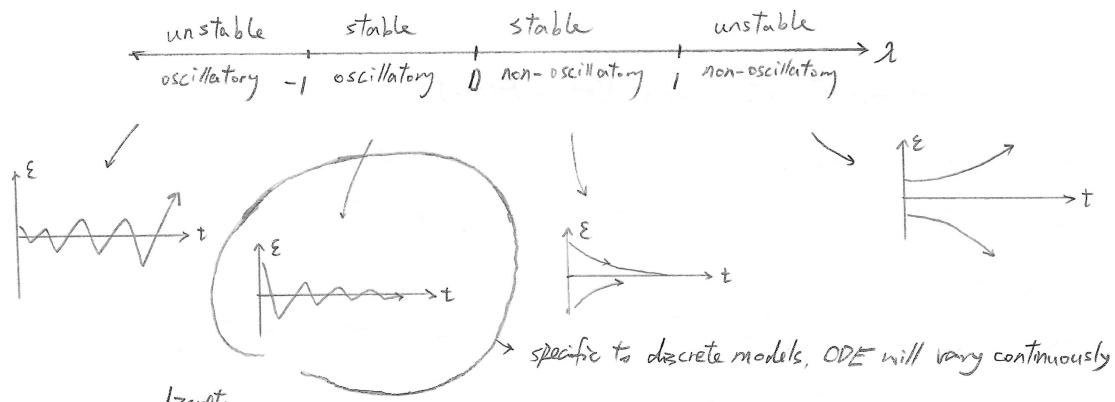
$\downarrow$  ignore higher order terms  $O(\varepsilon^2)$

$$\Rightarrow \underline{\underline{\Sigma(t+1) = \left[ \frac{dF}{dN} \Big|_{N=N^*} \right] \Sigma(t)}} \dots \textcircled{D}$$

define  $\lambda = F'(N^*)$

$$\Rightarrow \underline{\underline{\Sigma(t) = \lambda^t \Sigma(0), \text{ with } \lambda = \frac{dF}{dN} \Big|_{N=N^*} \dots \textcircled{D}}}$$

1. if  $|\lambda| < 1$ , displacements shrink,  $N^*$  is stable
2. if  $|\lambda| > 1$ , displacements amplify,  $N^*$  is unstable
- (3. if  $\lambda = 0$ , non-hyperbolic equilibrium, local stability analysis gives no answer)



For logistic model:  $N(t+1) = F(t) = N(t) \left[ 1 + r_0 \left( 1 - \frac{N(t)}{K} \right) \right]$

$$\Rightarrow \underline{\underline{\frac{dF}{dN} = \left[ 1 + r_0 \left( 1 - \frac{N(t)}{K} \right) \right] + N(t) \left( -\frac{r_0}{K} \right) = F'(N) \dots \textcircled{D}}}$$

① for  $N^* = 0$ ,  $\frac{dF}{dN} \Big|_{N=0} = 1 + r_0 \Rightarrow$  stable if  $|1 + r_0| < 1$

$\Rightarrow$  stable if  $-2 < r_0 < 0$ , not possible, 0 is unstable

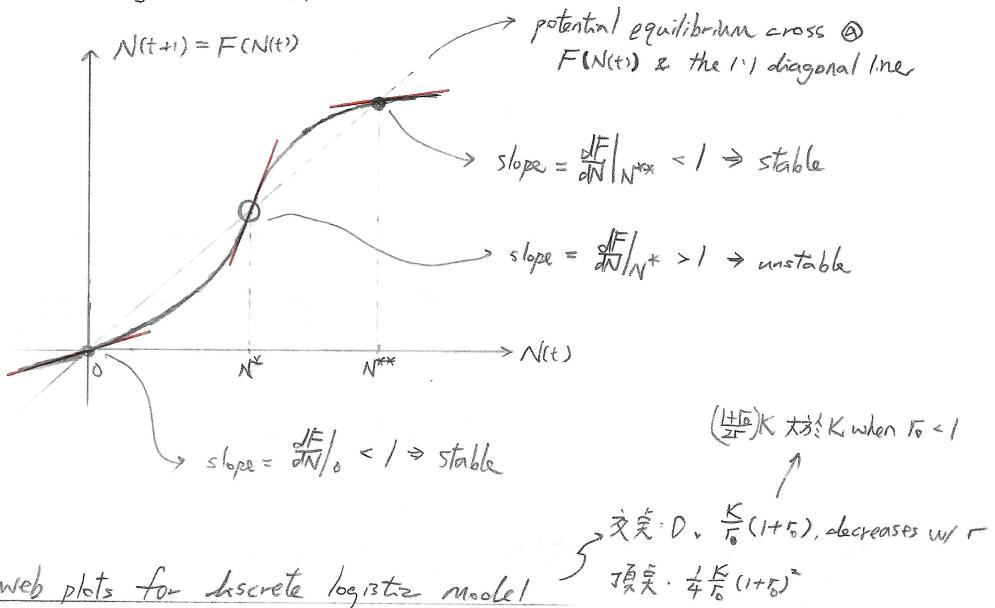
② for  $N^* = K$ ,  $\frac{dF}{dN} \Big|_{N=K} = 1 - r_0 \Rightarrow$  stable if  $|1 - r_0| < 1$

$\Rightarrow$  stable if  $0 < r_0 < 2$

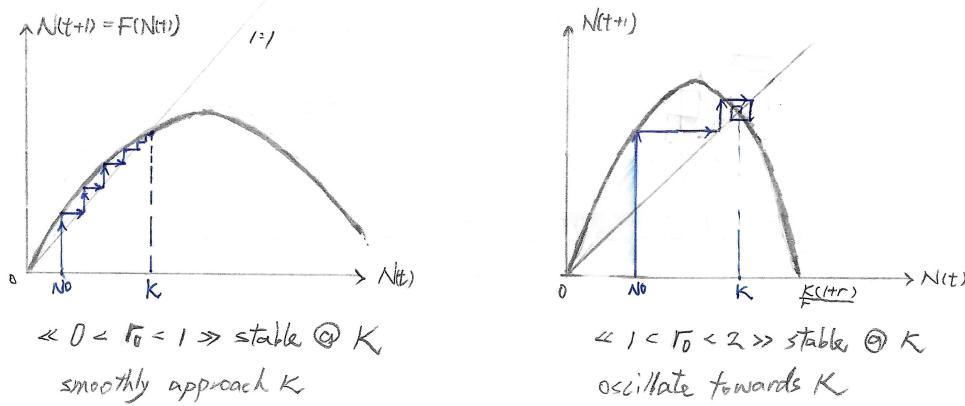
unstable if  $r_0 \geq 2$  ...  $\textcircled{D}$

$\nwarrow K$  is not always stable

## ② Links w/ graphical approach



## ③ Cobweb plots for discrete logistic model



What happens when  $R > 2$ ,  $K$  becomes unstable, BUT HOW? Simulate!

2-iteration  $F^{(2)}(N(t)) = F(F(N(t)))$  has root:  $0 \vee K \vee \frac{N_1^* + N_2^*}{2}$  equilibrium of  $F^{(2)}(N(t))$

$$N_t \left[ 1 + r_0 \left( 1 - \frac{N_t}{K} \right) \right] \left\{ 1 + r_0 \left[ 1 - \frac{1}{K} \times N_t \left[ 1 + r_0 \left( 1 - \frac{N_t}{K} \right) \right] \right] \right\} = N_{t+2}$$

$$\Rightarrow N^*(N^*-K) \left\{ r_0^3 N^{*2} + (-2r_0^2 K - r_0^3 K) N^* + (2r_0 K^2 + r_0^2 K^2) \right\} = 0$$

$$\Rightarrow N_1^* \& N_2^* = \frac{(r_0+2)K \pm K \sqrt{(r_0+2)(r_0-2)}}{2r_0} \quad \dots \textcircled{D}$$

only exist when  $r_0 > 2$

from  $p=1$  to  $p=2$  is at  $r_0 = 2$

At bifurcation boundary from  $p=2$  to  $p=4$  ( $p=2$  becomes unstable)

$$\left. \frac{dF^{(2)}}{dN} \right|_{N_1^*, N_2^*} = \left. \frac{dF}{dN} \right|_{N_1^*} \times \left. \frac{dF}{dN} \right|_{N_2^*} = -1 \quad \text{becomes unstable}$$

$$\begin{aligned} \left. \frac{dF^{(2)}}{dN} \right|_{N_1^*, N_2^*} &= \left. \frac{dF}{dN} \right|_{N_1^*} = \left. \frac{dF(y)}{dN} \right|_{N_1^*} = \left. \frac{dF}{dN} \right|_{F(N)} \times \left. \frac{dF}{dN} \right|_N \\ &= \left. \frac{dF}{dN} \right|_{F(N_1^*)} \times \left. \frac{dF}{dN} \right|_{N_1^*} = \left. \frac{dF}{dN} \right|_{N_1^*} \times \left. \frac{dF}{dN} \right|_{N_1^*} \end{aligned}$$

$$\Rightarrow \left( 1 + r_0 - \frac{2r_0}{K} N_1^* \right) \left( 1 + r_0 - \frac{2r_0}{K} N_2^* \right) = -1$$

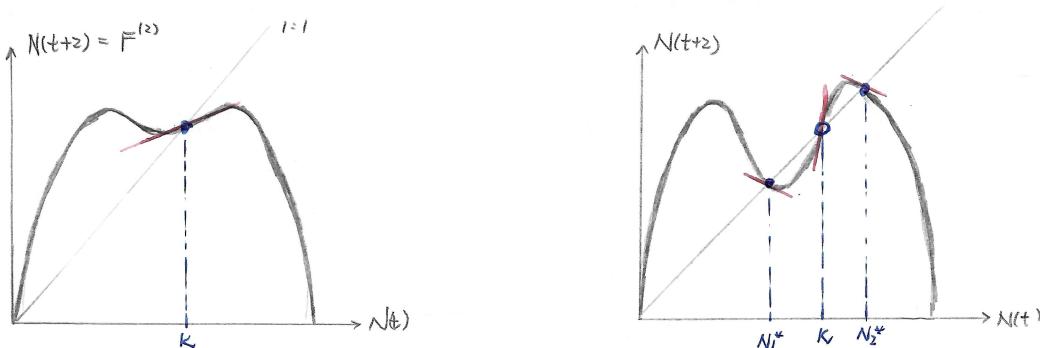
$$\Rightarrow \frac{4r_0^2}{K^2} N_1^* N_2^* - \left( \frac{2r_0}{K} + \frac{2r_0^2}{K^2} \right) (N_1^* + N_2^*) + (2r_0 + r_0^2 + 1) + 1 = 0 \quad \dots \textcircled{2}$$

$$\begin{aligned} \text{from } \textcircled{1} \quad N_1^* N_2^* &= \frac{1}{r_0^2} [2r_0 K^2 + r_0^2 K^2] = K^2 \left( \frac{2}{r_0^2} + 1 \right) \\ N_1^* + N_2^* &= \frac{1}{r_0^3} [2r_0^2 K + r_0^3 K] = K \left( \frac{2}{r_0} + 1 \right) \end{aligned}$$

$$\Rightarrow 4r_0^2 \left[ \frac{2}{r_0^2} + 1 \right] - \left[ 2r_0 + 2r_0^2 \right] \left[ \frac{2}{r_0} + 1 \right] + 2r_0 + r_0^2 + 2 = 0$$

$$\Rightarrow r_0^2 - 6 = 0 \quad (\text{負不}) \quad \dots \textcircled{2}$$

$\Rightarrow$   $p=2$  becomes unstable and give rise to  $p=4$  at  $r_0 = \sqrt{6} \approx 2.44949$ .



$\ll 1 < r_0 < 2 \gg K$  is stable on  $F^{(2)}$

$p=1$  orbit

$\gg 2 < r_0 < \sqrt{6} \gg K$  becomes unstable

newly generated  $N_1^*, N_2^*$  is stable

$p=2$  orbit