Qin + W short, in + W pressure, net: 
$$n = \frac{dE_{sys}}{dt}$$
  
 $e = u + ke + Pe = u + \frac{V^2}{2} + gz$   
 $\frac{dE_{sys}}{dt} = \frac{d}{dt} \int_{cs} ep dv + \int_{cs} ep(\overline{v_i} \cdot \overline{v_i}) A$ 

Quetin + Wishart, in + wpressure, nelin = d/dt Jou epn+ Jos ep(v; r) dA

Fixed C.V.: Quet, in + Wishaft, net in = dt Jeu ep dV + Jes ( \$ +e) p( v. r) da

Quet: n + W shart, net: n = d/dt Scuepdu + Z m (P+e) - Z m (P+e)

wheat added to swork added to

System

where Q = U + Ke+Pe

where e = a + ke+pe

Quel, in + Washard, notin - ddf Sou ep du + 2 m ( + 4 + 2+92 ) - 2 m ( + 4 + 2+92 ) - 2 m ( + 4 + 2+92 )

where h = u+ Pv

= 
$$u + P/\rho$$

Steady state:

Ones,:n + Wshafi, net:n = m(hz-h, + Uz2-U,2 + g(z.-Zz)

Gnet, in + Wshart, net in = hz-h, + Uzz-U,z + g(Z, -Zz)

Le h = u+ P/P

Wshaft, net: n +  $\frac{P.}{P.}$  +  $\frac{V.^2}{2}$  + gZ. =  $\frac{P_2}{P}$  +  $\frac{Vz^2}{2}$  +  $gZ_z$  +  $(U_z - U_z - Q_{net,:n})$ 

Ideal Flow (no mech. energy 1055): Enel, in = Uz-U.

Real Flow ( w/ mech. energy 1055): Cmech, 1055 = Uz-U, - Gnes,:n

Check, in = Check, out + Check, loss

$$\frac{P_1}{P_1g} + \frac{V_1^2}{2g} + Z_1 + h_{pump,u} = \frac{P_2}{P_2g} + \frac{V_2^2}{2g} + Z_2 + h_L + h_{turb;ne,e}$$

Vinetic energy correction factor, or

Ex by replacing 
$$\frac{\sqrt{2}}{2}$$
 by  $\frac{\sqrt{2}}{2}$  by  $\frac{\sqrt{2}}{2}$   $\frac{\sqrt{2}}{2}$  +  $\frac{2$ 

## Example

Kinetic energy Correction factor using actual velocity distribution.

$$KE_{oct} = \int WeSm = \int_{A} \frac{1}{2} [UCr)^{2} ] [PUCr) dA]$$

$$= \frac{1}{2} P \int_{A} [UCr)^{2} dA$$

m=pVangA, p=const. KEang = 1 mVang = 1 DAV ang

KEary = 
$$2 \text{ m V ang} = \frac{1}{2} \text{ PHV ang}$$

$$C = \frac{\text{KEary}}{\text{KEary}} = \frac{1}{A} \left( \frac{\text{V(r)}}{\text{Vang}} \right)^{2} dA$$



Example | Pump powered by 15 kW motor, 
$$\mathcal{R}_{motor} = 90^{\circ}$$
.

 $\dot{V} = 50^{\circ} \text{ Hz}$ ,  $\dot{D}_{in} = D_{out}$ ,  $\dot{Z}_{i} = Z_{z}$ 
 $\mathcal{R}_{pump} = \frac{\dot{W}_{pump}}{\dot{W}_{pump}}$ ,  $u$ 
 $\dot{W}_{pump}$ ,  $s_{nart}$ 
 $\dot{m} = p \dot{V} = (1000 \times 0.050) = 50^{\circ} \text{ ug/s}$ 
 $\dot{w}_{u} + \dot{m} \begin{pmatrix} P'/\rho_{i} + \alpha_{i} & v_{i}z'_{2} + gZ_{i} \end{pmatrix} = \dot{m} \begin{pmatrix} Pz/\rho_{i} + \alpha_{z} & v_{i}z'_{2} + gZ_{z} \end{pmatrix}$ 
 $\dot{w}_{u} = \dot{m} \begin{pmatrix} Pz-P_{i} + \alpha_{z} & v_{i}z'_{2} - \alpha_{i} & v_{i}z'_{2} + g(Z_{z} - Z_{i}) \end{pmatrix}$ 
 $\dot{R}_{i}\dot{V}_{i} = \dot{R}_{z}\dot{V}_{z}$ 

A. = A. - V. = V.

 $\dot{W}_{u} = \dot{m} \left( \frac{\rho_{z} - \rho_{z}}{\rho_{z}} \right) = 50 \left( \frac{300 - 100}{1000} \right) = 10 \text{ kW}$ 

$$\dot{E}_{1655} = \dot{m}C\Delta T \implies \Delta T = \frac{\dot{E}_{1055}}{\dot{m}C}$$

$$\Delta T = (3.5) = 0.017 °C$$

$$(50)(4.18)$$

Example:

V = 100 m3/s , Z = 120 m , P = Pz , V = V = 0

=> hturb = Z, -h.

= 120-35 = 85m

Wturb, ideal = mighturb = pighturb = (1000)(100)(9.81)(85)

Wtorb, : Lear = 83400 KW

Wtorb, our = Ntorrgen Wtorb, ideal = (0.8)(83400) = 66.7 MW

Oct. 31/18

Example "A Fan is to be selected to cool a computer care..."

$$\dot{m}(P) + \alpha \cdot \frac{1}{2} + g^2 \cdot 1 + \dot{w}_{Fan} = \dot{m}(P)/\rho + \alpha \cdot \frac{v_a^2}{2} + g^2 \cdot 1 + \dot{E}_{WROS}^2$$
 $\dot{m} = \rho\dot{v}$ 
 $\dot{m} = \rho\dot{v}$ 
 $\dot{v} = q600/(s = q600 \text{ cm}^3/s)$ 
 $\dot{v} = q600/(s = q600 \text{ cm}^3/s)$ 
 $\dot{m} = (1.2)(q.6 \times 10^{-3}) = 0.0115 \text{ Mols}^5$ 
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For Fully developed turbulent flow  $\alpha_2 = 1.11$ 
 $\dot{m} = (1.2)(4) D^2 = \frac{rc(0.0.6)^2}{4} = 1.96 \times 10^{-3} \text{ m}^4$ 
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 $\dot{m} = (1.2)(4) D^2 = 1.96 \times 10^{-3} \text{ m}^4$ 
 $\dot{m} = (1.2)(4) D^2 = 1.96 \times$ 

Linear momentum:
$$F = ma = m \frac{dV}{dt} = \frac{d(mV)}{dt}$$

Angular momentum:

$$\vec{M} = \vec{I} \vec{\alpha} = \vec{I} \frac{d\vec{\omega}}{dt} = \frac{d(\vec{z}\vec{\omega})}{dt} = \frac{d\vec{H}}{dt}$$

about X-axis:

$$M_z = Z_x \frac{d\omega_x}{dt} = \frac{dH_x}{dt}$$

Total angular momentum of a rotating body remains constant when the net torque acting on it is zero.

Thus, anguar momentum is conserved.

Body Forces: gravity, electric, magnetic

Surface Forces: that act on the control Surface

(such as pressure and viscous forces

and reaction forces at points of contact)

General: 
$$ZF = dt \int_{CU} PV dV + \int_{CS} PV (V. p.) dA$$

The sum of

all forces acting

on CU

The time rate of

the time rate of

change of lin. mom.

of the contents of CU

by more from