

Feb. 25/19

Rate of Velocity Change

$$\hat{R}_p = p e^{j\theta}$$

$$\hat{V}_p = \frac{d\hat{R}_p}{dt} = p \frac{dj\theta}{dt} e^{j\theta} = j p \omega e^{j\theta}$$

$$\omega = \frac{d\theta}{dt}$$

$$j = e^{j90^\circ}$$

$$\hat{A}_p = \frac{d\hat{V}_p}{dt} = j p \frac{d\omega}{dt} e^{j\theta} + j p \omega \frac{dj\theta}{dt} e^{j\theta} = j p \alpha e^{j\theta} - p \omega^2 e^{j\theta}$$

$$\begin{aligned} \hat{A}_p &= p \alpha e^{j(\theta + 90^\circ)} + p \omega^2 e^{j(\theta + 180^\circ)} \\ &= A_p^t + A_p^n \end{aligned}$$

→ tangential component - "t"

→ normal component - "n"

Known:

$$p = 3 \text{ in}$$

$$\theta = 4t^3 \text{ rad}$$

Find: \hat{V}_p, \hat{A}_p at $t = 1 \text{ s}$

Solution:

$$\theta = 4(1)^3 = 4 \text{ rad} \quad \text{or} \quad \frac{4}{\pi} \times (180^\circ) = 229.2^\circ = 180^\circ + 49.2^\circ$$

$$\hat{V}_p = j p \omega e^{j\theta}$$

$$\omega = (d\theta/dt) = 12t^2 = 12(1)^2 = 12 \text{ rad/s}$$

$$\hat{V}_p = 3(12) e^{j(229.2^\circ + 90^\circ)} = 36 e^{j(319.2^\circ)}$$

$$\alpha = (d\omega/dt) = 24 \text{ rad/s}^2$$

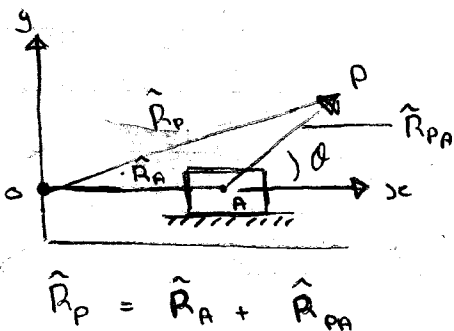
$$\begin{aligned} \hat{A}_p &= j(3)24 e^{j229.2^\circ} - (3)(12)^2 e^{j229.2^\circ} \\ &= j72 e^{j229.2^\circ} - 432 e^{j229.2^\circ} \end{aligned}$$

$$= 72(j \cos 229.2^\circ - \sin 229.2^\circ) - 432(\cos 229.2^\circ + j \sin 229.2^\circ)$$

$$= -j47.05 + 54.5 + 252.1 - j327.0$$

$$= 336.7 + j280, \quad |\hat{A}_p| = 438 \text{ m/s}^2, \quad \beta = 0.644 \text{ rad} \quad \text{or} \quad 39.17^\circ$$

$$\begin{aligned} e^{j90^\circ} &= j \sin 90^\circ = j \\ e^{j180^\circ} &= \cos 180^\circ = -1 \end{aligned}$$



$$\begin{aligned}\hat{V}_P &= \frac{d\hat{R}_P}{dt} = \frac{d\hat{R}_A}{dt} + \frac{d\hat{R}_{PA}}{dt} \\ &= \hat{V}_A + \hat{V}_{PA} = \hat{V}_A + ip\omega e^{i\theta} \\ \hat{A}_P &= \frac{d\hat{V}_A}{dt} + \frac{d\hat{V}_{PA}}{dt} = \hat{A}_A + \hat{A}_{PA}^t + \hat{A}_{PA}^n\end{aligned}$$

Example:

Known: $A_A = 10 \text{ m/s}^2$
 $\theta = 4t^2$
 $p = 0.5 \text{ m}$

Find: \hat{A}_P at $t = 1 \text{ sec}$

Solution:

$$\theta = 4(1)^2 = 4 \text{ rad or } 229.2^\circ$$

$$\omega = (d\theta/dt) = 2(4)t = 8(1) = 8 \text{ rad/s}$$

$$\alpha = (d^2\theta/dt^2) = 8 \text{ rad/s}^2$$

$$\begin{aligned}\hat{A}_{PA} &= i(0.5)(8)e^{i229.2^\circ} - 0.6(8)^2 e^{i229.2^\circ} \\ &= 4(i\cos 229.2^\circ - \sin 229.2^\circ) - 32(\cos 229.2^\circ + i\sin 229.2^\circ) \\ &= 24.02 + i21.53 \text{ m/s}^2\end{aligned}$$

$$\hat{A}_P = 10 + 24.02 + i21.53 = 34.02 + i21.53$$

$$|\hat{A}_P| = 40.26 \text{ m/s}^2, \quad \beta = 32.3^\circ$$

Graphical solution:

$$\hat{R}_B = \hat{R}_A + \hat{R}_{BA} = \hat{R}_{O_4} + \hat{R}_{BO_4}$$

$$\frac{d\hat{R}_B}{dt} = \hat{V}_A + \hat{V}_{BA} = \hat{V}_B$$

$$= iaw_2 e^{i\theta_2} + ibw_3 e^{i\theta_3} = icw_4 e^{i\theta_4}$$

$$\hat{A}_B = \hat{A}_A + \hat{A}_{BA}$$

$$\underbrace{\hat{A}_B^t}_{\omega_4} + \underbrace{\hat{A}_B^n}_{\omega_4} = \underbrace{\hat{A}_A^t}_{\alpha_2} + \underbrace{\hat{A}_A^n}_{\omega_2} + \underbrace{\hat{A}_{BA}^t}_{\omega_3} + \underbrace{\hat{A}_{BA}^n}_{\omega_3}$$

Known; $\theta_2, \theta_3, \theta_4, \omega_2, \omega_3, \omega_4$

Find; α_3, α_4

$$A_A^t = a(\alpha_z) = 10(-10) = -100 \text{ cm/s}^2$$

$$A_A^n = a\omega_z^2 = 10(-5)^2 = -250 "$$

$$A_{B0}^n = b\omega_3^2 = 6(-4.2)^2 = 105.84 "$$

$$A_B^n = c\omega_4^2 = 8(-6.6)^2 = 348.48 "$$

Scaling

$$100/50 = 2 \text{ cm}$$

$$250/50 = 5 \text{ cm}$$

$$105.84/50 = 2.1 \text{ cm}$$

$$348.48/50 = 7 \text{ cm}$$

Choose: $1 \text{ cm} = 50 \text{ cm/s}^2$

Example

(Pg. 8, Ch. 9)

Example (Chapter 7 - Page 18) in powerpoint

$$\rightarrow \overline{AB} = 2 \text{ in}$$

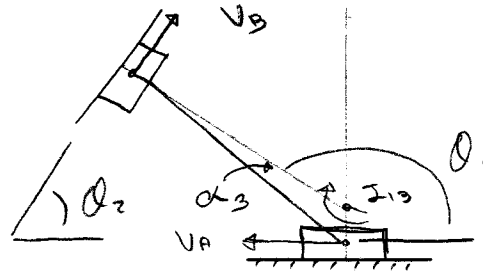
$$\hat{V}_A = -10 \text{ in/s}$$

$$A_A = -700 \text{ in/s}^2$$

$$\text{Solving, } \omega_3 = -11.55 \text{ rad/s}$$

$$V_B = 16.42 \text{ in/s}$$

$$(1) \text{ Find } \omega_3, V_B, I_{13}$$



$$(3) \hat{A}_B = \hat{A}_A + \hat{A}_{BA} \\ = \hat{A}_A + \hat{A}_{BA}^t + \hat{A}_{BA}^n$$

→ Choose a scale

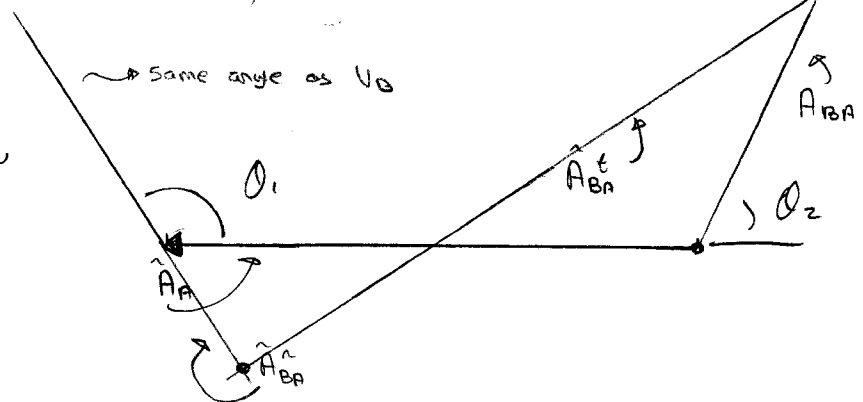
$$1 \text{ mm} = 10 \text{ in/s}^2$$

$$\hat{A}_A = 700 \text{ in/s}^2 \\ \hat{A}_{BA} = 2(-11.55)^2 = 266.8 \text{ in/s}^2 \\ (\hat{A}_{BA} = \overline{AB} \omega_3^2)$$

$$A_{BA}^t = 95 \times 10 = 950$$

$$\alpha_3 = \frac{950}{2} = 475 \frac{\text{rad}}{\text{s}^2} \text{ CW}$$

$$A_B = 45 \times 10 = 450 \text{ in/s}$$



$$(2) \hat{A}_B = \hat{A}_A + \hat{A}_{BA}^t + \hat{A}_{BA}^n$$

$$= -700 e^{j0^\circ} + j2\alpha_3 e^{j128^\circ} - 2(\omega_3)^2 e^{j128^\circ}$$

$$= -700 + j1.23\alpha_3 - 1.576\alpha_3 + 164.3 - j210.25$$

$$\hat{A}_B = |\hat{A}_B| e^{j60^\circ} = A_B \cos 60^\circ + jA_B \sin 60^\circ$$

$$A_B = |\hat{A}_B|$$

Equate real parts :

$$A_B \cos 60^\circ = -700 - 1.576\alpha_3 + 164.3 \quad (1)$$

imag parts :

$$A_B \sin 60^\circ = 1.23\alpha_3 - 210.25$$

A_B, α_3 , solve...

(2)

$$\frac{\textcircled{2}}{\textcircled{1}} \quad \frac{\sin 60^\circ}{\cos 60^\circ} = \frac{-1.23 \alpha_3 - 210.25}{-535.17 - 1.576 \alpha_3} = 1.732$$

$$\alpha_3 = -478.4 \text{ rad/s}^2$$

$$\textcircled{2} \text{ use } \textcircled{1} \quad A_B = \frac{-1.23(-478.4) - 210.25}{\sin 60^\circ} = 426.8 \text{ m/s}^2$$

→ slide 19 :

$$\hat{V}_B = \hat{V}_A + \hat{V}_{BP}$$

Differentiate :

$$\hat{A}_B = \hat{A}_A + \hat{A}_{BP}$$

$$\hat{A}_B^t + \hat{A}_B^r = \hat{A}_A^t + \hat{A}_A^r + \hat{A}_{BP}^t + \hat{A}_{BP}^r$$

$$j c \alpha_4 e^{j\theta_4} - c \omega_4^2 e^{j\theta_4} = j a \alpha_2 e^{j\theta_2} - a \omega_2^2 e^{j\theta_2} + j b \alpha_3 e^{j\theta_3} - b \omega_3^2 e^{j\theta_3}$$

$$e^{j\theta} = \cos \theta + j \sin \theta$$

Equate real parts :

$$c \sin \theta_4 \alpha_4 - b \sin \theta_3 \alpha_3 = a \alpha_2 \sin \theta_2 + a \omega_2^2 \cos \theta_2 + b \omega_3^2 \cos \theta_3 - c \omega_4^2 \cos \theta_4$$

Equate imag parts :

$$c \cos \theta_4 \alpha_4 - b \cos \theta_3 \alpha_3 = a \alpha_2 \cos \theta_2 - a \omega_2^2 \sin \theta_2 - b \omega_3^2 \sin \theta_3 + c \omega_4^2 \sin \theta_4$$

$$\begin{bmatrix} A & -B \\ D & -E \end{bmatrix} \begin{bmatrix} \alpha_4 \\ \alpha_3 \end{bmatrix} = \begin{bmatrix} C \\ F \end{bmatrix} \quad \Leftrightarrow \quad \begin{bmatrix} \alpha_4 \\ \alpha_3 \end{bmatrix} = \begin{bmatrix} A & -B \\ D & -E \end{bmatrix}^{-1} \begin{bmatrix} C \\ F \end{bmatrix}$$

$$\text{Remember: } \begin{bmatrix} a & b \\ c & d \end{bmatrix}^{-1} = \frac{\begin{bmatrix} d & -b \\ -c & a \end{bmatrix}}{(ad - cb)}$$