MARCH 29/18 MACHINE DESIGN.

Example 4: A ball bearing is to operate on the following work cycle

Radial load of 1400 lb at 200 rpm For 25% of the time "2000 lb at 500 rpm for 20%" "

800 lb at 400 rpm For 55%" "

The inner ring rotates; loads are steady. Find the Minimum value of the basic rating load C, For a Suitable bearing for this application if the required life in 7 years at 4 his per day.

Solution:

On the basis of a work cycle of 1 min, we have:

Load Assumed rpm In assumed

1b. interval 1 min interval, rev.

	, 550,	, (, , , , , , , , , , , , , , , , , ,	
16.	interval Imin	_	interval, rev.
P. = 1400	0.25	200	50
Pz = 2000	0.20	500	100
P3 = 800	0.55	400	220
TOTAL :	1		370

Then
$$\alpha_1 = \frac{50}{370}$$
; $\alpha_2 = \frac{100}{370}$; $\alpha_3 = \frac{220}{370}$

Assuming 250 working days in a year

$$\frac{10^{6}C^{3}}{Nc} = \frac{50}{370} \times 1400^{3} + \frac{100}{370} \times 2000^{3} + \frac{220}{370} \times 800^{3}$$

= 2,837,400,000

$$C^3 = 2,837.40c = 440,930,000,000$$
 $C = 7,610 \text{ lb}$

TABLE 9.1:

.. bearing No. 308 Should be satisfactory with 90% prob. of Surviving 7 years.

5-Design For Different Confidence Levels
When a degree of reliability greater than 90%
is required, the expected life will be reduced as
follows: [Ln = a, Lio]
Where a, is Found from Table 9-4 (spotts)

- see Assignment 10

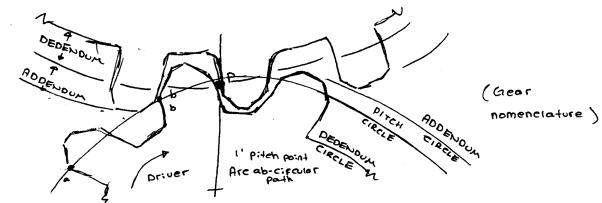
Spur Gears

1 - Characteristics:

- the drive is positive, and with circular gears, the angular velocity ratio is constant
- the center distances may be relatively short, thus making a compact drive
- Provision may be made for shifting gears, and in some cases for interchanging them to change the speed of the driven members
- the efficiency is high, since the loss of Power may be I percent or less of the Power transmitted
- the maintenance of the drive is inexpensive and the life is long.

2 - spur gear term: norogy

- Pitch surfaces: The pitch surface is the surface of the rolling cylinder that the gear may be considered to replace



Pitch circle: the pitch circle is a right section of the pitch surface

Addendum circle: the addendum circle is the circle bounding the ends

of the track

Dedendum circle: the dedendum circle is the circle bounding the bottom

OF the spaces between the teeth

Addendum: the addendum is the radial distance between the addendum circle and the Pitch circle.

Dedendum: the dedendum is the radial distance between the pitch circle and the dedendum circle

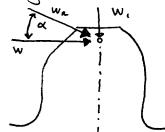
Clearance: the difference between the dedendum of one gear and the addendum of the mating gear

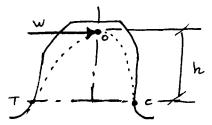
Bocklash: the difference between the tooth space of one gear and the tooth thickness of the mating gear measured on the pitch circle

Circular pitch: Circular pitch is the distance From a point on one tooth to the corresponding point on the adjacent tooth measured on the pitch eirere. Its symbol, p; the units are inches.

Diametral Pitch: diametral pitch is the number of teeth on a gear per inch of its pitch diameter. it's symbol is P.

3 - Strength of Gear Teeth (Lewis Equation)





(Forces on Gear Teeth)

Lewis assumed the tooth to be a cantilever beam of Parabolic profile, and therefore, it has uniform strength at all cross-sections. Since the tooth is stronger than the assumed beam except at TC, this is considered the critical section where he found:

 $Wh = \frac{SFt^2}{6} \qquad \text{or} \quad W = \frac{SFt^2}{6h}$

Introducing the circular pitch P

$$W = \frac{SFt^2}{6h} \times \frac{P}{P} = SFPY$$

where $y = \frac{L^2}{6hP}$ = Form Factor (Table 18-1, H.O.)

To approximate the effect of dynamic loading the allowable stress is given by:

5 all = 5 . Cv

Where, S_{all} = allowable stress, ps: S_{o} = basic stress, ps: (From table 18-2, H.O.) C_{v} = 600 (600+v) = velocity factor (table 18-4) V_{o} = table 18-4 (table 18-4) variable 18-4 (table 18-4)

(for an values in (8-)

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The induced stress is:

W = SFPy

or Sind = W

FPy

Let T = \text{transmitted torque} | b.in

D = \text{pitch diameter}, in

\Lambda = \text{number of teeth}

P = \text{diametral pitch} = \Lambda/D

K = F/P = 3 \text{ to } H \text{ (normal service)}

Then; Sind = W = WP^2 = WP^2 = VP^2P^2D

FPy P = P^2P^2y = VP^2P^2D

but W = 2T/D = 2TP/\Lambda

and Sind = \frac{2TP^2}{K\pi^2\pi y}

Based on experience it is found that For good proportions the following relation must hold:

(a must hold; 3P = F = HP

or broadly; 3P = F = HP
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Example 1 -> It is required to determine the proportions of a spur-gear drive to transmit 10 hp from a shaft rotating at 1170 rpm to a low-speed shaft with a speed reduction of 3:1. Assume that the teeth are a 200° Full-depth system, with 24 teeth on the pinion. The pinion is to be SAE-1045 and the gear SAE-1030 steel. Assume that the torque at Starting is 1300% of torque at rating.