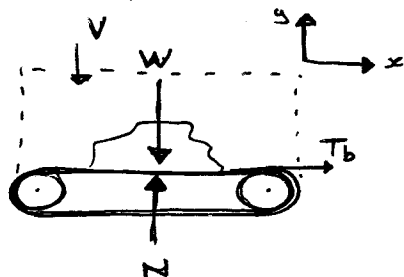


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Example (horizontal conveyor...)



$$\sum \vec{F} = \frac{\partial}{\partial t} \int_{cv} \rho \vec{V} dV + \int_{cs} \rho \vec{V} (\vec{V} \cdot \vec{n}) dA$$

$$x: \sum F_x = \frac{\partial}{\partial t} \int_{cv} \rho V_x dV + \int_{cs} \rho V_x (\vec{V} \cdot \vec{n}) dA$$

$$T_b = \frac{\partial}{\partial t} \int_{cv} \rho V_x dV + \dot{m} V_{x_2} - \dot{m} V_{x_1} \quad \text{--- (I)}$$

$$T_b = \frac{\partial}{\partial t} \int_{cv} \rho V_x dV - \frac{\partial}{\partial t} \int_{cv} \rho V_{belt} dV = V_{belt} \frac{\partial}{\partial t} \int_{cv} \rho dV$$

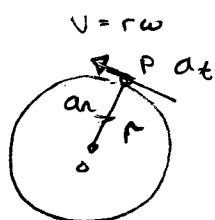
$$\frac{\partial}{\partial t} \int_{cv} \rho dV + \int_{cs} \rho \vec{V} (\vec{V} \cdot \vec{n}) dA = 0 \quad \text{--- (II)}$$

$$\frac{\partial}{\partial t} \int_{cv} \rho dV = - \int_{cs} \rho \vec{V} (\vec{V} \cdot \vec{n}) dA = -(-\dot{m}_{sand}) = \dot{m}_{sand}$$

From (I) and (II) $\Rightarrow T_b = V_{belt} \dot{m}_{sand}$

$$T_b = 3 \text{ ft/s} \times 600 \text{ lbm/s} \times 1 \text{ slug} / 32.2 \text{ lbm} \dots$$

$$\dots \frac{1 \text{ lbf} \cdot \text{s}^2}{\text{slug} \cdot \text{ft}} = \boxed{46.6 \text{ lbf}}$$



$$V = r\omega$$

$$a_n = r\omega^2$$

$$a_t = r\alpha$$

$$M_o = r F_t = r m a_t = m r^2 \alpha$$

Magnitude of Torque: $M = \int_{mass} r^2 \alpha \delta m = \left[\int_{mass} r^2 \delta m \right] \alpha$

$$\hookrightarrow (M) \quad M = I \alpha$$

Magnitude of Angular Momentum (H)

$$H = \int_{mass} r^2 \omega \delta m = \left[\int_{mass} r^2 \delta m \right] \omega = I \omega$$

$$H = I \omega$$

Angular momentum equation:

$$\vec{M} = I \vec{\alpha} = I \frac{d\vec{\omega}}{dt} = \frac{d(I\vec{\omega})}{dt} = \frac{d\vec{H}}{dt}$$

$$\dot{W}_{shaft} = FV = Fr\omega = M\omega \quad (\omega = 2\pi n)$$

$$\text{Shaft power} = \dot{W}_{shaft} = \omega M = 2\pi n M$$

$$\text{Rotational kinetic energy} \quad KE_r = \frac{1}{2} I \omega^2$$

$$a_r = \frac{v^2}{r} = r\omega^2$$

$$F_r = mV^2/r$$

$$\vec{a} = \vec{a}_t + \vec{a}_r$$

Moment of a Force : $\vec{M} = \vec{r} \times \vec{F}$

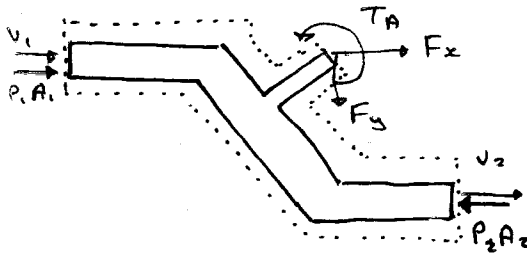
Moment of Momentum : $\vec{H} = \vec{r} \times m\vec{U}$

$$\sum \vec{M} = d\vec{H}_{sys}/dt \quad \sum \vec{M} = \sum (\vec{r} \times \vec{F})$$

$$\frac{d\vec{H}_{sys}}{dt} = \frac{d}{dt} \int_{cv} (\vec{r} \times \vec{U}) \rho dV + \int_{cs} (\vec{r} \times \vec{U}) \rho (\vec{U} \cdot \vec{n}) dA$$

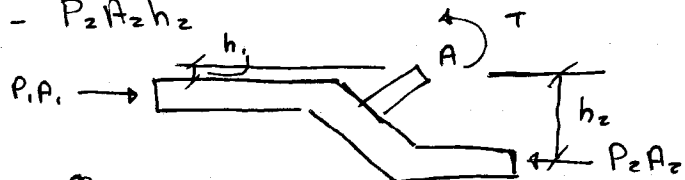
Steady flow $\sum \vec{M} = \sum_{out} (\vec{r} \times \dot{m}\vec{U}) - \sum_{in} (\vec{r} \times \dot{m}\vec{U})$

Example



$$\begin{aligned} \sum M &= T_A + \vec{r}_1 \times (-P_1 A_1) \vec{n}_1 + \vec{r}_2 \times (-P_2 A_2) \vec{n}_2 \\ &= T_A + P_1 A_1 h_1 - P_2 A_2 h_2 \end{aligned}$$

Because:



$$\sum M = \frac{d}{dt} \int_{cv} \rho (\vec{r} \times \vec{U}) dV + \int_{cs} \rho (\vec{r} \times \vec{U}) (\vec{U} \cdot \vec{n}) dA$$

$$\sum M_z = \dot{m} h_2 U_2 = \dot{m} h_1 U_1$$

$$T_A + P_1 A_1 h_1 - P_2 A_2 h_2 = \dot{m} (h_2 U_2 - h_1 U_1)$$

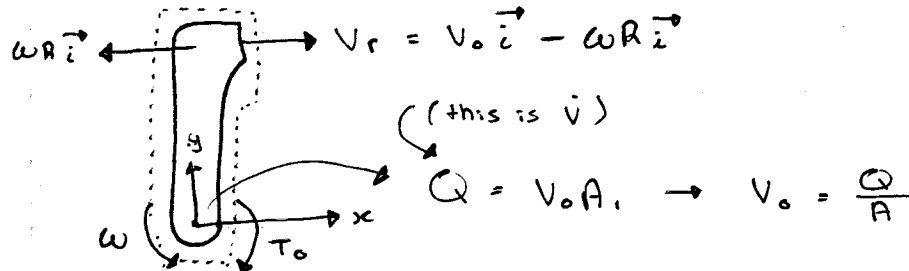
$$T_A = h_2 (P_2 A_2 + \dot{m} U_2) - h_1 (P_1 A_1 + \dot{m} U_1)$$

→ similar to Assignment 3, Q7

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Example

Lawn Sprinkler arm from above:



$$\sum \vec{M}_0 = \frac{\partial}{\partial t} \int_{cv} \rho (\vec{r} \times \vec{r}) dV + \int_{cs} \rho (\vec{r} \times \vec{v}) (\vec{v} \cdot \vec{n}) dA$$

$$\sum \vec{M}_0 = -T_0 \vec{k} = (\vec{r}_2 \times \vec{v}_2) \dot{m}_{out} - (\vec{r}_1 \times \vec{v}_1) \dot{m}_{in}$$

$$\dot{m}_{in} = \dot{m}_{out} = \dot{m} = \rho Q$$

$$-T_0 \vec{k} = (\vec{R} \times (V_0 - \omega R) \vec{i}) \dot{m} = -R(V_0 - \omega R) \dot{m} \vec{k}$$

$$T_0 = R(V_0 - \omega R) \rho Q$$

$$\omega = \frac{V_0}{R} - \frac{T_0}{\rho Q R^2}$$

Flow with no external moments

$$0 = \frac{dH_{cv}}{dt} + \sum_{out} (\vec{r} \times \dot{m} \vec{v}) - \sum_{in} (\vec{r} \times \dot{m} \vec{v})$$

$$\vec{M}_{body} = I_{body} \vec{\alpha} = \sum_{in} (\vec{r} \times \dot{m} \vec{v}) - \sum_{out} (\vec{r} \times \dot{m} \vec{v})$$

Radial-Flow Devices: pumps, turbines, etc.

involve flow in the radial direction, normal to axis of rotation.

Axial-Flow device: linear momentum equation

Radial-Flow device: angular momentum equation

The conservation of mass eq'n for steady, incompressible flow.

$$\begin{aligned} \dot{V}_1 = \dot{V}_2 = \dot{V} &\rightarrow (2\pi r_1 b_1) V_{1,n} = (2\pi r_2 b_2) V_{2,n} \quad \left. \vphantom{\dot{V}_1 = \dot{V}_2 = \dot{V}} \right\} \sum \dot{M} = \sum_{out} \dot{m} \vec{r} \times \vec{v} - \sum_{in} \dot{m} \vec{r} \times \vec{v} \\ V_{1,n} &= (\dot{V}) / (2\pi r_1 b_1) \quad V_{2,n} = (\dot{V}) / (2\pi r_2 b_2) \end{aligned}$$

Euler's turbine equation: $T_{\text{shaft}} = \dot{m}(r_2 V_{2,t} - r_1 V_{1,t})$

$$T_{\text{shaft}} = \dot{m}(r_2 V_2 \sin \alpha_2 - r_1 V_1 \sin \alpha_1)$$

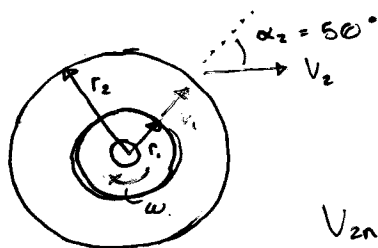
When $V_{1,t} = \omega r_1$ and $V_{2,t} = \omega r_2$

$$T_{\text{shaft, ideal}} = \dot{m} \omega (r_2^2 - r_1^2)$$

$$\dot{W}_{\text{shaft}} = \omega T_{\text{shaft}} = 2\pi \dot{n} T_{\text{shaft}}$$

→ 6.58

Example



$$V_{1t} = \frac{Q}{2\pi r_1 b_1} = \frac{0.7}{2\pi(0.2)(0.082)}$$

$$V_{1t} = 6.793 \text{ m/s}$$

$$V_{2t} = \frac{Q}{2\pi r_2 b_2} = \frac{0.7}{2\pi(0.45)(0.056)} = 4.421 \text{ m/s}$$

$$V_{1t} = V_{1t} \sin \alpha_1 = V_{1t} (0) = 0$$

$$V_{2t} = V_{2t} \sin \alpha_2 = 4.421 (\sin 50^\circ) = 5.269 \text{ m/s}$$

$$\dot{n} = 700 \text{ rpm} \Rightarrow \omega = 2\pi \dot{n} = 2\pi \left(\frac{700}{60}\right) = 73.3 \text{ rad/s}$$

$$\dot{m} = \rho Q = (1.25)(0.7) = 0.875 \text{ kg/s}$$

$$T_{\text{shaft}} = \dot{m}(r_2 V_{2,t} - r_1 V_{1,t})$$

$$T_{\text{shaft}} = (0.875)(0.45(5.269)) = 2.075 \text{ N}\cdot\text{m}$$

$$\dot{W} = \omega T_{\text{shaft}} = (73.3)(2.075) = \boxed{152 \text{ W}}$$

→ Example 6.8

Example