

Jan 9<sup>th</sup>/17

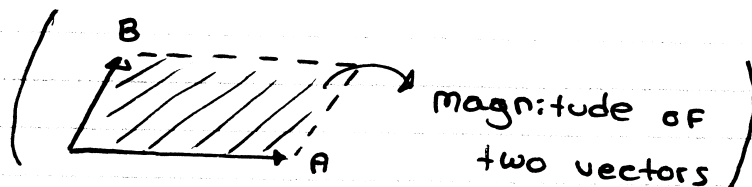
## Vectors (Review)

- 1) Given vectors  $\vec{A}$  and  $\vec{B}$ , determine graphically

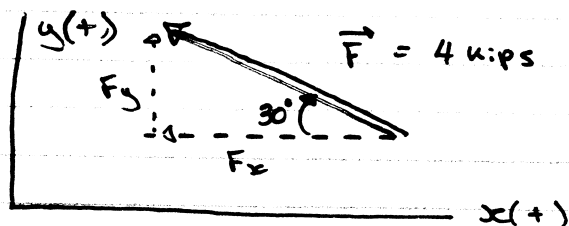
$$\vec{A} \pm \vec{B}$$

$a\vec{A}$  when  $a > 0$ ,  $a < 0$ , and  $a = 0$

- 2) Determine  $\vec{A} \times \vec{B}$



- 3) Express the following vectors in rectangular components

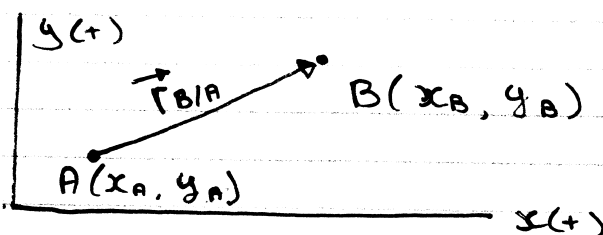


$$\vec{F} = 4 \text{ kips}$$

$$F_x = \cos(30^\circ) 4 \Rightarrow -3.464 \vec{i}$$

$$F_y = \sin(30^\circ) 4 \Rightarrow 2 \vec{j}$$

$$\vec{F} = -3.464 \vec{i} + 2 \vec{j} \text{ kips}$$



$(x_A, y_A)$  known

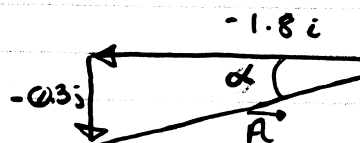
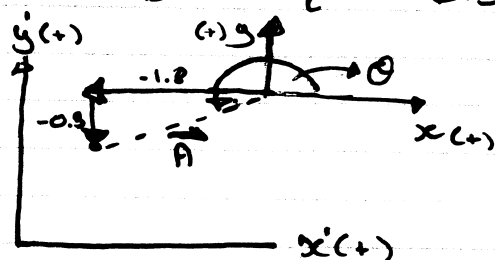
$(x_B, y_B)$

$$\vec{r}_{B/A} = (x_B - x_A) \vec{i} + (y_B - y_A) \vec{j}$$

- 4) Visualize (Draw) the following vectors, and determine the angles that the vectors make with respect to the  $x$ -axis.

$$\vec{A} = -1.8 \vec{i} - 0.3 \vec{j}$$

$$\vec{B} = -\vec{i} + 0.5 \vec{j}$$



$$\alpha = 9.5$$

$$\theta = \alpha + 180^\circ$$

$$\theta = 189.5^\circ$$

(2)

- 5) For the  $\vec{A}$  and  $\vec{B}$  vectors given in 4), evaluate  $\vec{A} \cdot \vec{B}$ , and  $\vec{A} \times \vec{B}$

$$\vec{A} \cdot \vec{B} = (-1.8 \times -1) + (-0.3 \times 0.5) \\ = 1.65$$

$$\vec{A} \times \vec{B} = \begin{vmatrix} \hat{i} & \hat{j} \\ -1.8 & -0.3 \\ -1 & 0.5 \end{vmatrix} = -1.2 \hat{k} \quad (\text{review})$$

- 6) What is the unit vector associated with  $\vec{B}$  in 4)

$$\vec{B} = -\hat{i} + 0.5\hat{j} \Rightarrow \|\vec{B}\| = 1.118 \\ \vec{u}_B = \frac{-\hat{i} + 0.5\hat{j}}{1.118}$$

$$\vec{u}_B = -0.894\hat{i} + 0.447\hat{j}$$

- 7) What are the unit vectors associated with co-ordinate axes x-y-z?

↳  $\hat{i}$ ,  $\hat{j}$ , and  $\hat{k}$

### Statics (Review)

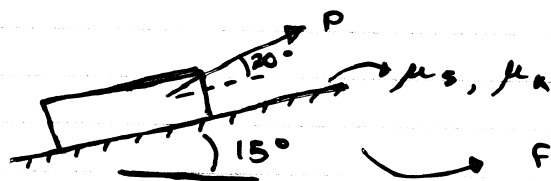
FBD: Part of Problem Solving in Ch. 12 and Ch. 16

Friction: Present in the real world

Forces in components: For ease in problem solving

Example:

The coefficients of static and kinetic friction between the 100 kg block and inclined surface are 0.3 and 0.2, respectively. If  $P = 700 \text{ N}$ , would the block be stationary, or in motion?



Finish for tutorial

## Time-differentiation and Integration

Time-differentiation means to differentiate with respect to time  $t$ .

For example,  $x = \cos t$ , then  
 $dx/dt = -\sin t$

Time differentiation involving composition of Functions, or application of chain rule.

(1) Example:  $y = x^2$ ,  $x = \cos t$ ,  $dy/dt = ?$

(2) Example:  $z = (e^{\sin t})^2$ ,  $dz/dt = ?$

(3) Example:  $z = y^2$ ,  $y = e^x$ ,  $x = x(t)$ ,  $dz/dt = ?$

### Techniques of Differentiation

Implicit differentiation in particular

Example (1) =  $y = (\cos t)^2$   
 $dy/dt = -\sin(2t)$

Example (2) =  $z = (e^{\sin t})^2$   
 $dz/dt = 2 \cos t \underbrace{e^{2\sin t}}_{(e^{\sin t})^2}$

Example (3) =  $\frac{dz}{dt} = \frac{dz}{dy} \cdot \frac{dy}{dx} \cdot \frac{dx}{dt}$   
 $= 2y \cdot e^x \cdot \frac{dx}{dt}$   
 $= 2e^{x(t)} \cdot e^{x(t)} \cdot \frac{dx}{dt}$   
 $= 2e^{2x(t)} \cdot \frac{dx}{dt}$

Jan. 11/17

Two types of integrals

{ indefinite integrals, or anti-derivatives:  $\int f(x) dx$   
 definite integrals:  $\int_a^b f(x) dx$

1) Indefinite Integrals

a) if  $F'(x) = f(x)$ , then  $\int f(x) dx = F(x) + C$   
 where  $C$  is any constant

b) indefinite integral of  $f(x)$  is a function  
 and answers the question, "what function,  
 when differentiated gives  $f(x)$ ?"

c) some basic indefinite integrals

Power Functions:  $f(x) = x^n$  ( $n \neq -1$ )

Polynomials:  $f(x) = p_0 + p_1 x + \dots + p_n x^n$

Trig Functions:  $f(x) = \sin x$ , or  $\cos x$

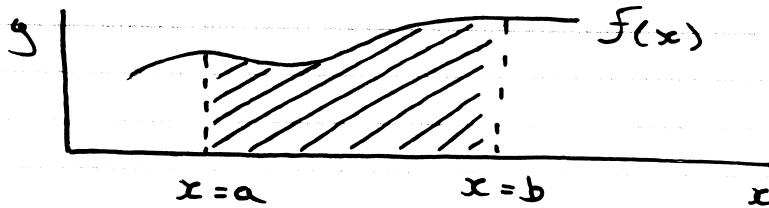
Exponential Func:  $f(x) = e^x$

and:  $\int \frac{1}{x} dx = \ln|x| + C$

remember absolute signs

2) Definite Integrals

a) definite integral  $\int_a^b f(x) dx$  is a number,  
 and represents the area under the  
 curve  $f(x)$  from  $x=a$  to  $x=b$



b) "a" and "b" are called the lower and  
 upper limit of integration, respectively.

c) By FTC,  $\int_a^b f(x) dx = F(b) - F(a)$

d) The limit a or b can be a variable; as a  
 result, definite integral gives a function.

$$\int_a^x f(x) dx = F(x) - F(a)$$

## Ch. 11 Kinematics of Particles

### Organization of Chapter 11

#### Rectilinear motion of a particle

§ 11.1 ~ § 11.3

Focus on only § 11.1, § 11.2A+B, § 11.3

#### Curvilinear motion of a particle

§ 11.4 ~ § 11.5

Rectangular components

Tangential + normal components

Radial + Transverse components

### Introduction (P. 616)

Dynamics includes two branches

#### 1. Kinematics

Study of the geometry of motion, such as displacement, velocity, acceleration in relation to time, without reference to the cause of motion.

#### 2. Kinetics

Study of the relation between forces acting on an object, the mass of the object and the motion of the object. The object can be a particle (Ch. 12) or a rigid body (Ch. 16)

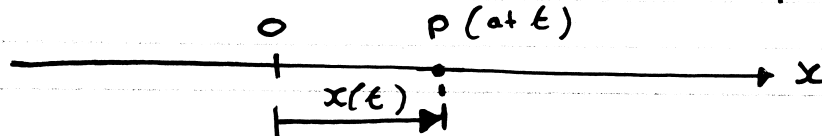
### § Ch. 11.1 Rectilinear Motion of Particles

#### 11.1A Position, Velocity, and Acceleration

##### 1. Rectilinear Motion

↳ A particle is said to be in rectilinear motion if it moves along a straight line.

##### 2. Position and Coordinate Setup



(From previous) :

$x$ -axis :

the straight line along which the particle is moving

origin  $O$  :

Fixed on the straight line

Position of particle at time  $t$   
by position coordinate  $x(t)$

For example,  $x(t) = 6t^2 - t^3$  (m)

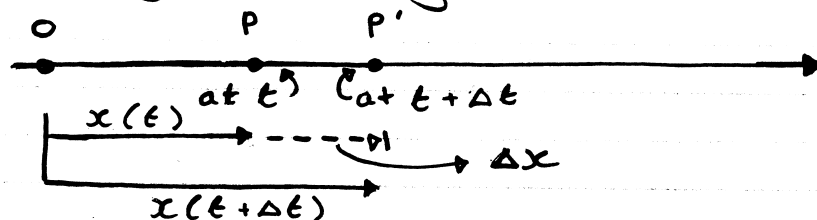
units : time  $t$ : seconds, or s

$x$ : SI: meter, or m

US customary : Foot, or ft  
inch, or in

$$x(t) = (6 \text{ m/s}^2) \cdot t^2 - (1 \text{ m/s}^3) t^3$$

### 3. Average velocity and instantaneous velocity



$$\text{Average velocity} = \frac{\Delta x}{\Delta t}$$

Instantaneous velocity (or simply velocity)

$$v = \lim_{\Delta t \rightarrow 0} \frac{\Delta x}{\Delta t} = \frac{dx}{dt}$$

1) Units : m/s  
ft/s or in/s

2)  $v > 0$  : Particle moves in positive direction  
 $< 0$  : Particle moves in negative direction

3) Speed =  $|v|$  magnitude of velocity

4) irreversible motion : one in which the velocity does not change the sign

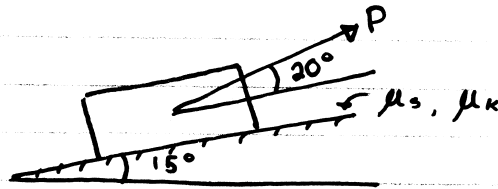
reversible motion : one in which the velocity changes sign, at least once

5) For reversible motion to occur,  $v = 0$  must be true, at least once.

JAN. 12/17

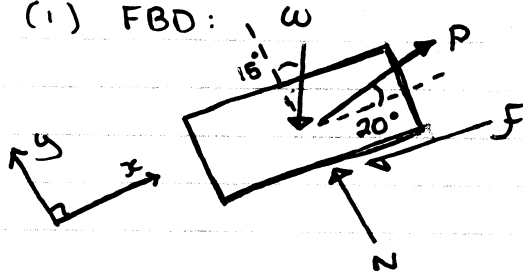
## EXAMPLE:

The coefficients of static and kinetic friction between the 100-kg block and the inclined surface are 0.3 and 0.2, respectively. If  $P = 700\text{ N}$ , would the block be stationary, or in motion?



Solution:

(1) FBD:



$$W = 100\text{ kg} \cdot 9.81\text{ m/s}^2$$

$$W = 981\text{ N}$$

(2) Assume the block is stationary:

$$P = 700\text{ N}$$

Unknowns:  $N?$ ,  $f?$ 

$$\sum F_x = 700 \cdot (\cos 20^\circ) - 981 \cdot (\sin 15^\circ) - f = 0$$

$$\therefore f = 403.88\text{ N}$$

$$\sum F_y = N - 981 \cdot (\cos 15^\circ) + 700 \cdot (\sin 20^\circ)$$

$$\therefore N = 708.16\text{ N}$$

$$f/N > 0.3$$

$\therefore$  This assumption is not true.



(3) Overcoming impending motion:

$$f = f_{\max} = 0.3 \cdot N$$

Unknown:  $P?$   $N?$

$$\text{Solving leads to: } P = 516.5 \text{ (N)}$$

$$N = 771.0 \text{ (N)}$$

$\therefore$  block is in motion

From example 3: (Previous notes)

$$\frac{dz}{dt} = 2e^{2x(t)} \frac{dx}{dt}$$

(?) - by product rule, chain rule

$$\begin{aligned} \frac{d^2z}{dt^2} &\Rightarrow 2 \left[ \frac{d}{dt} (e^{2x(t)}) \cdot \frac{dx}{dt} + e^{2x(t)} \cdot \frac{d}{dt} \left( \frac{dx}{dt} \right) \right] \\ &\Rightarrow 2 \left[ e^{2x(t)} \cdot 2 \cdot \frac{dx}{dt} \cdot \frac{dx}{dt} + e^{2x(t)} \cdot \frac{d^2x}{dt^2} \right] \\ &\Rightarrow 2e^{2x(t)} \left[ 2 \left( \frac{dx}{dt} \right)^2 + \frac{d^2x}{dt^2} \right] \end{aligned}$$

$$\text{Note: } \frac{d}{dt} (e^{2x(t)}) \rightsquigarrow e^{2x(t)} \cdot 2 \cdot \frac{dx}{dt}$$

$$\text{and: } \frac{d}{dt} \left( \frac{dx}{dt} \right) \rightsquigarrow \frac{d^2x}{dt^2}$$

$$I_1 = \int \left( x - \frac{lx}{\sqrt{l^2 + x^2}} \right) dx \quad (\text{Prob. 11.20})$$

$$I_2 = \int \left[ -\frac{32.2}{(1 + (\frac{y}{20.9 \times 10^6})^2)^2} \right] dy \quad (\text{Prob. 11.29})$$

$$I_1 = \frac{x^2}{2} - l \sqrt{l^2 + x^2} + C \quad \left[ \begin{array}{l} \text{(Note } l \text{ is treated as a constant.)} \\ \text{For } I_1: u = l^2 + x^2 \\ du = 2x dx \\ \therefore x dx = \frac{1}{2} du \end{array} \right]$$

$$I_2 = (672.98 \times 10^6) \cdot \left( \frac{1}{1 + (\frac{y}{20.9 \times 10^6})^2} \right) + C$$

$$\left[ \begin{array}{l} \text{For } I_2: u = 1 + \frac{y^2}{20.9 \times 10^6} \\ \int f(x) \cdot dy = f(x) \cdot y + C \end{array} \right]$$