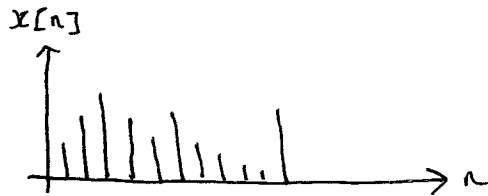


$$x[n], n = 0, 1, 2, \dots, (N-1)$$

N

- infinitely long \rightarrow leakage
- rectangular window



$$x'[n] = x[n] \cdot w[n]$$

$$x'[n] \neq x[n]$$

on the amplitude spectrum, leakage \downarrow

$$\rightarrow x(t) = \cos(40\pi t)$$

$$\omega = 40\pi \text{ rad/s}$$

$$f = \omega / 2\pi = 20 \text{ Hz}$$

- $f_s = 100 \text{ Hz}$;
- $T = 1/f_s$; (sec) - used for demonstration
- $t = 0 : T : 1$;
- $x = x'$;
- $X_r = \text{abs}(\text{fft}(x))$;
- $w = \text{hanning}(\text{length}(x))$;
- $xw = x \cdot w$;
- $X_{amp} = \text{abs}(\text{fft}(xw))$;
- $L_2 = \text{fix}(\text{length}(X_r)/2)$; (look @ half the signal)
- $\text{freq} = (0 : (L_2 - 1) / L_2 * (f_s/2))$

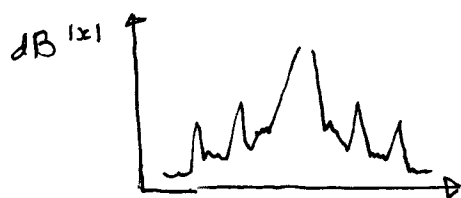
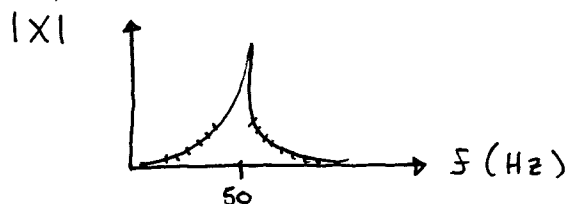
MATLAB code

\rightarrow will send code

$$X[K] = \sum_n x[n] e^{-j2\pi kn/N}$$

$$X(\omega) = \text{DTFT}$$

$$\text{dB} // 1 \text{ dB} = 20 \log_{10} |A/B|$$

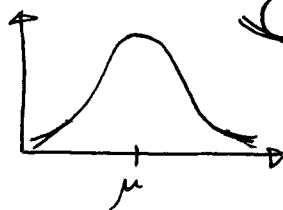


Kurtosis,



random

pdf



$$KU = \mu_4 / \sigma^4$$

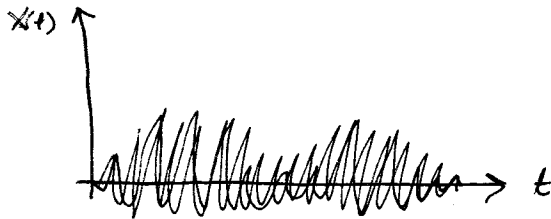
Crest Factor, $CF = X_{\text{max}} / \sigma$

For a healthy system, signal \rightarrow gaussian pdf

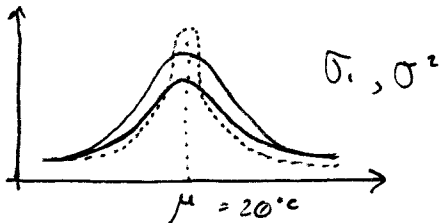
$$KU = 3$$

Gaussian Signal

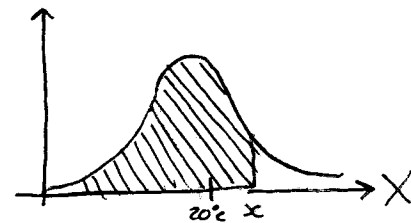
Peak amplitude probability (%)	CF	KU
4.6	2	3
0.1	3.3	3
0.01	3.9	3



Gaussian p.d.f.



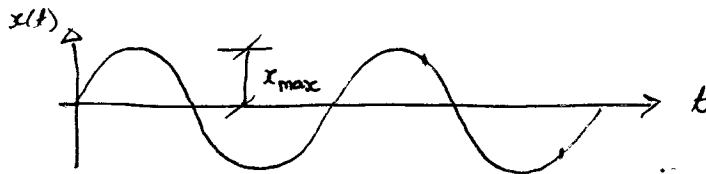
Z-table



$$P(x) \quad \text{CF} = I_{\max} / \sigma$$

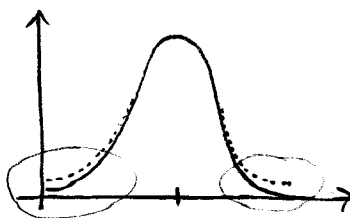
Table 5.2 : The CF and KU for various Functions

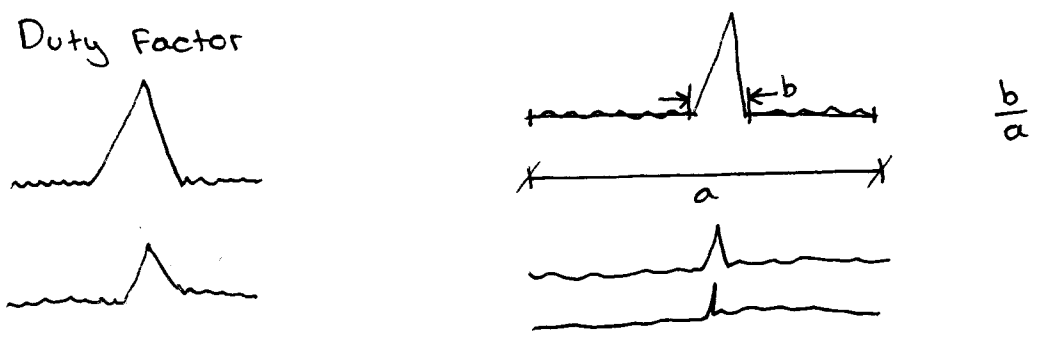
Signal details	CF	KU
Sine wave pulse train	2	1.5



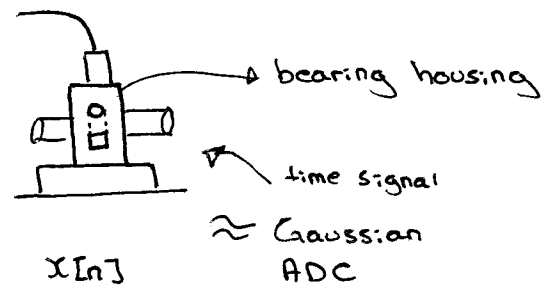
$$CF = I_{\max} / \sigma$$

$$KU = \mu^4 / \sigma^4 \sim \text{p.d.f. tail properties}$$





→ can do Q1-4 on A3.



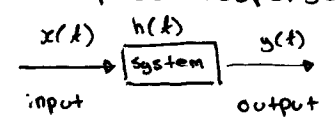
→ Anti-aliasing Filtering First
 → ADC second

→ need to read material for bearing fault detection (Ch.12?)

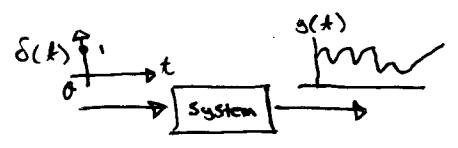
Chapter 4 : Design of Digital Filters

4.1 Analysis of Ideal Filter

1) Impulse response



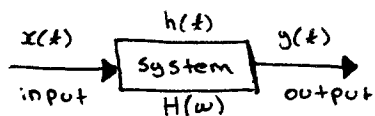
$h(t)$ = impulse (unit pulse) response fn



$$y(t) = h(t) \otimes x(t)$$

$$y[n] = h[n] \otimes x[n], \quad n = 0, 1, 2, \dots, N-1$$

2) Filters and Filtering



Input: $x(t) = A \cos(\omega_0 t)$

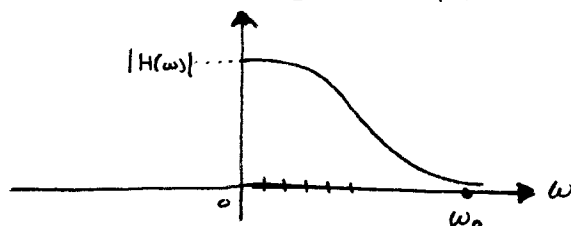
$$x(t) \leftrightarrow X(\omega)$$

$$Y(\omega) = X(\omega) * H(\omega)$$

$$Y(\omega) \leftrightarrow y(t)$$

$$y(t) = A |H(\omega_0)| \cos(\omega_0 t + \phi_H)$$

$$\phi_H = \text{phase delay} : \phi_H = \arctan \frac{\text{Im}(H(\omega_0))}{\text{Re}(H(\omega_0))}$$



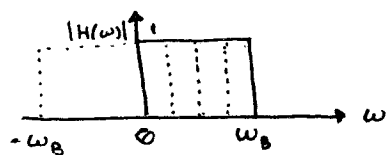
$$|H(\omega_0)| = 0$$

$$y(t) = 0$$

Filter, Filtering

3) Ideal Filters

① Ideal low pass Filter



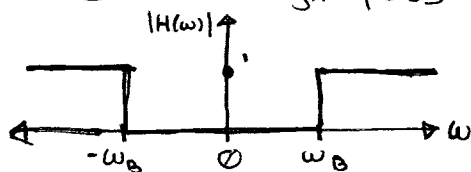
$$|H(\omega)| = \begin{cases} 1, & -\omega_B < \omega < \omega_B \\ 0, & \omega > \omega_B, \omega < -\omega_B \end{cases}$$

$-\omega_B \sim \omega_B$ = pass band

$\omega_B \sim +\infty, -\infty \sim -\omega_B$ = stop band

band width $\sim \omega_B$

② Ideal high pass Filter



$$|H(\omega)| = \begin{cases} 1, & \omega \geq \omega_B, \omega \leq -\omega_B \\ 0, & \text{otherwise} \end{cases}$$

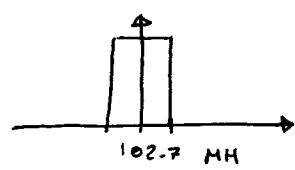
pass bands = $-\infty \sim -\omega_B$

" " = $\omega_B \sim \infty$

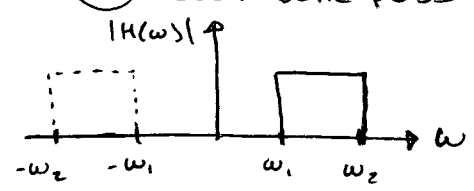
stop band = $-\omega_B \sim \omega_B$

LU Radio Station

102.7 MHz

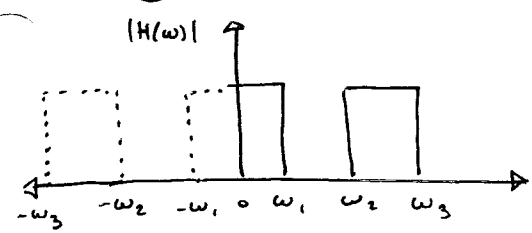


3 Ideal band pass Filter

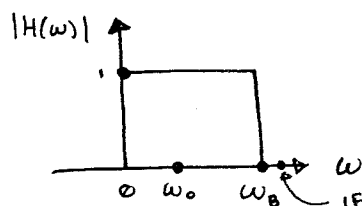


$$|H(\omega)| = \begin{cases} 1 & \omega_1 \leq \omega \leq \omega_2, \quad -\omega_2 \leq -\omega \leq -\omega_1 \\ 0 & \omega < -\omega_2, \quad \omega > \omega_2 \\ & -\omega_1 \leq \omega \leq \omega_1 \end{cases}$$

4 Ideal band stop Filters

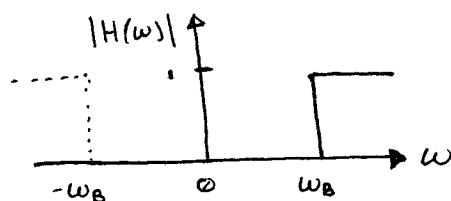


$$|H(\omega)| = \begin{cases} 1 & -\omega_1 \leq \omega \leq \omega_1, \quad \omega_2 \leq \omega < +\infty \\ 0 & -\omega_2 \leq -\omega \leq -\omega_1, \quad \omega_1 \leq \omega \leq \omega_2 \end{cases}$$

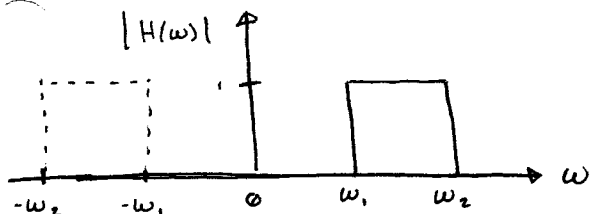
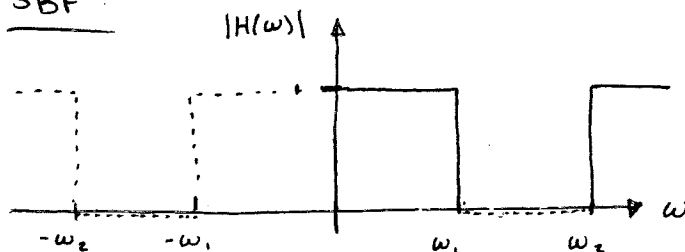
LPF : $\omega_B = \text{cutoff freq.}$ low pass Filter

$$x(t) = A \cos(\omega_0 t)$$

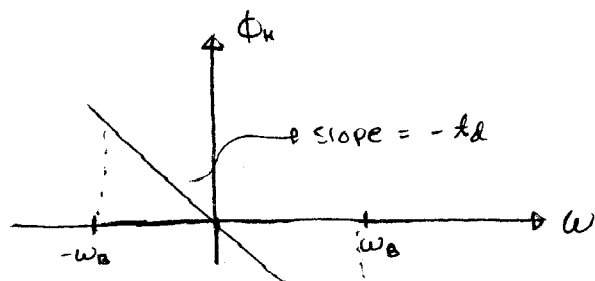
$$y(t) = A |H(\omega_0)| \cos(\omega_0 t + \phi_n)$$

IF this was ω_0 this amplitude becomes zero.HPL :high pass Filter

BPF

band pass FilterSBFStop-band Filter4.2 Phase Function of Ideal Filters

A linear phase over the passband



$$\phi_H = -\omega t_d$$

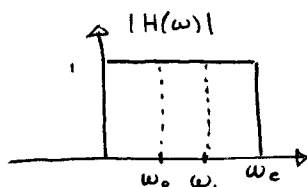
$$x(t) = A \cos(\omega_0 t)$$

Output :

$$\begin{aligned} y(t) &= A |H(\omega_0)| \cos(\omega_0 t - \omega_0 t_d) \\ &= A \times 1 \times \cos(\omega_0(t - t_d)) \end{aligned}$$

delay

$$x = A_0 \cos(\omega_0 t) + A_1 \cos(\omega_1 t)$$

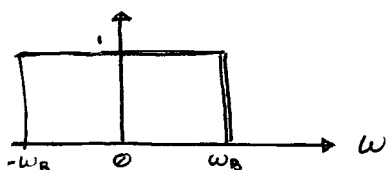


$$y(t) = A_0 |H(\omega)| \cos(\omega_0 t - \omega_0 t_d) + A_1 |H(\omega)| \cos(\omega_1 t - \omega_1 t_d)$$

delay

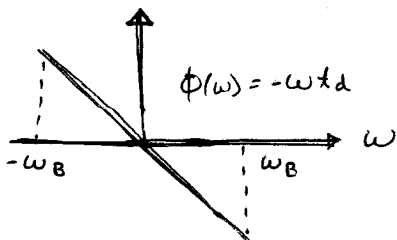
If ϕ_H is not a linear function of ω over the PB

$$\phi_H = C$$



CFT

$h(t)$



$$H(\omega) = \begin{cases} 1 & ; -\omega_B \leq \omega \leq \omega_B \\ 0 & ; \text{otherwise} \end{cases}$$

$$\phi_H = \begin{cases} -\omega t_d & ; -\omega_B \leq \omega \leq \omega_B \\ 0 & \end{cases}$$

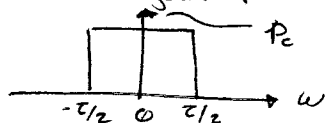
Polar ex.

$$H(\omega) = 1 \times e^{-j\omega t_d} = \cos(-\omega t_d) + j \sin(-\omega t_d) \quad \text{⚡} \quad |e^{j\theta}| = \cos\theta + j \sin\theta$$

$$H(\omega) = P_{20} e^{-i\omega t_d}$$

P_{20} = rectangular function $-\omega_B \sim \omega_B$

P_z = rectangular pulse with τ



$$\tau \operatorname{sinc}\left(\frac{\tau t}{2\pi}\right) \longleftrightarrow 2\pi P_z$$

$$\frac{\tau}{2\pi} \operatorname{sinc}\left(\frac{\tau t}{2\pi}\right) \longleftrightarrow P_z$$

$$\tau = 2\omega_B$$

$$\frac{2\omega_B}{2\pi} \operatorname{sinc}\left(\frac{2\omega_B t}{2\pi}\right) \longleftrightarrow P_{20}$$

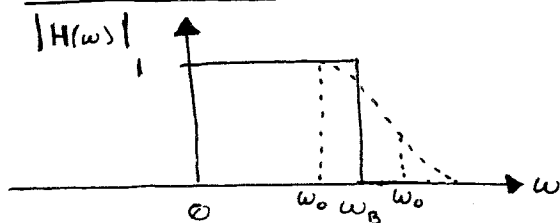
$$\delta(t-c) \longleftrightarrow e^{-i\omega c}$$

$$c = t_d$$

$$\left(\frac{\omega_B}{\pi}\right) \operatorname{sinc}\left(\frac{\omega_B(t-t_d)}{\pi}\right) \longleftrightarrow P_{20} e^{-i\omega t_d}$$

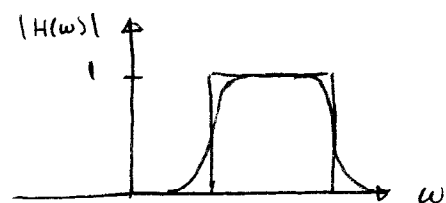
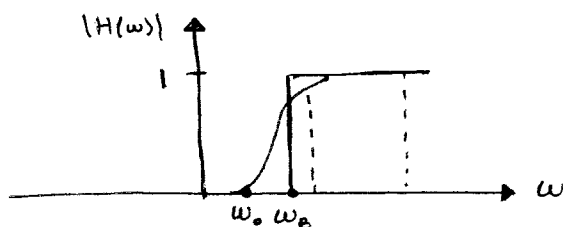
$h(t) \rightarrow$ non-causal

4.2 Causal Filters

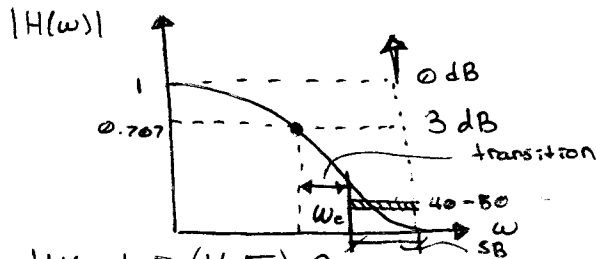


Input: $x(t) = A \cos(\omega_0 t)$

Output: $y(t) = A \underbrace{|H(\omega)|}_{\text{e.g.}} \cos(\omega_0 t + \phi_H)$

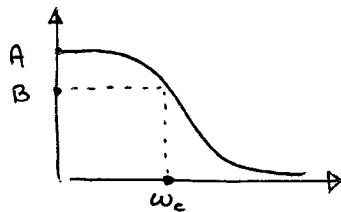


Passband of LPF



$$|H(\omega)| \geq (1/\sqrt{2}) \approx 0.707 \sim 3\text{dB (magic number)}$$

$$\text{dB} = 20 \log_{10} |H(\omega)|$$



$$3\text{dB} = 20 \log_{10} (A/B) = 20 \log_{10} A/A/\sqrt{2}$$

$$B = A/\sqrt{2}$$

ω_c = cut-off freq. of the LPF

Pass-band : $0 \sim \omega_c$

- Stop band : drop $40 \sim 50$ dB
- transition region should be as narrow as possible
- Butterworth Filters

$$H(s) = \frac{\omega_n^2}{s^2 + 2\zeta\omega_n s + \omega_n^2}$$

$\zeta > 0$ damping ratio

$$s = j\omega$$

$$H(\omega) = \frac{\omega_n^2}{-\omega^2 + j2\zeta\omega_n\omega + \omega_n^2}$$