```
arch::ROSComponent
# rosComponentDescriptor
+ ROSComponent()
+ ~ROSComponent()
+ setUp()
+ tearDown()
+ run()
+ body()
# getŘosNodeName()
             Δ
   arch::target_system
       ::Component
   # handle
   + Component()
   + ~Component()
   + setUp()
   + tearDown()
   + run()
   + body()
+ sendEvent()
   + sendStatus()
   + reconfigure()
   # activate()
   # deactivate()
   # sigIntHandler()
          Sensor
   # type
   # active
   # buffer_size
   # replicate_collect
   # noise_factor
   # battery
   # data
   + Sensor()
   + ~Sensor()
   + setUp()
   + tearDown()
   + run()
   + body()
+ apply_noise()
+ reconfigure()
   + injectUncertainty()
   + collect()
   + process()
   + transfer()
   # isActive()
   # turnOn()
   # turnOff()
   # recharge()
             Λ
          G3T1 2
       + G3T1
               _2()
       + ~G3T1
                  <u>2()</u>
       + setUp()
       + tearDown()
       + collect()
       + process()
       + transfer()
```