```
arch::ROSComponent

# rosComponentDescriptor

+ ROSComponent()
+ ~ROSComponent()
+ setUp()
+ tearDown()
+ run()
+ body()
# getRosNodeName()
```

```
Logger

# handle

+ Logger()
+ ~Logger()
+ setUp()
+ tearDown()
+ body()
+ receiveAdaptationCommand()
+ receiveStatus()
+ receiveEvent()
+ receiveUncertainty()
```