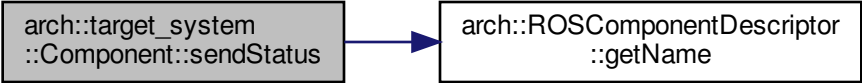


arch::target_system
::Component::sendStatus



```
graph LR; A["arch::target_system  
::Component::sendStatus"] --> B["arch::ROSComponentDescriptor  
::getName"]
```

The diagram consists of two rectangular boxes connected by a horizontal arrow. The left box is shaded gray and contains the text 'arch::target_system' followed by '::Component::sendStatus' on a new line. The right box is white with a black border and contains the text 'arch::ROSComponentDescriptor' followed by '::getName' on a new line. A dark blue arrow points from the right side of the left box to the left side of the right box.

arch::ROSComponentDescriptor
::getName