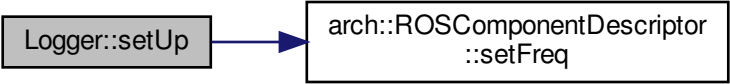


Logger::setUp



```
graph LR; A[Logger::setUp] --> B[arch::ROSCComponentDescriptor::setFreq]
```

The diagram consists of two rectangular boxes connected by a horizontal arrow. The left box is shaded gray and contains the text 'Logger::setUp'. A blue arrow points from the right side of this box to the left side of the right box. The right box is white with a black border and contains the text 'arch::ROSCComponentDescriptor::setFreq' on two lines.

arch::ROSCComponentDescriptor
::setFreq