```
arch::ROSComponent
# rosComponentDescriptor
+ ROSComponent()
+ ~ROSComponent()
+ setUp()
+ tearDown()
+ run()
+ body()
# getRosNodeName()
   arch::target system
         ::Probe
   # handle
   + Probe()
   + ~Probe()
   + setUp()
   + tearDown()
   + body()
   + collectEvent()
   + collectStatus()
```