```
arch::ROSComponent
 # rosComponentDescriptor
 + ROSComponent()
 + ~ROSComponent()
 + setUp()
 + tearDown()
 + run()
 + body()
 # getRosNodeName()
        DataAccess
# handle
+ DataAccess()
```

+ processTargetSystemData()
+ receivePersistMessage()

+ ~DataAccess()

+ processQuery()

+ setUp() + tearDown() + body()