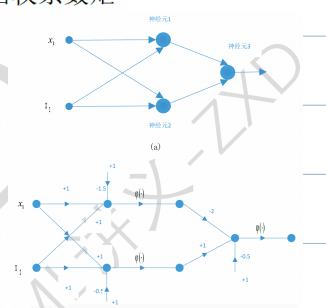


1. 在节 9.1.2 的异或神经网络中，神经网络如下图所示，对应的第一层神经网络权系数矩阵和偏置分别为

$$W^{(1)} = \begin{bmatrix} w_1 & w_2 \end{bmatrix} = \begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix}, \quad w_0 = \begin{bmatrix} 0 & -1 \end{bmatrix}^T$$

第二层的权向量和偏置为

$$w^{(2)} = \begin{bmatrix} 1 \\ -2 \end{bmatrix} \quad w_0^{(2)} = 0$$



每个神经元的激活函数是 ReLU 函数 $\varphi(a) = \max\{0, a\}$ 。通过计算验证该网络可正确计算异或输出。

$$x_1 = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

$$z_1^{(1)} = w^{(1)} x_1 + w_0 = \begin{pmatrix} 1 & 1 \end{pmatrix} \begin{pmatrix} 0 \\ 0 \end{pmatrix} + \begin{pmatrix} 0 \\ -1 \end{pmatrix} = \begin{pmatrix} 0 \\ -1 \end{pmatrix}$$

$$a_1^{(1)} = \varphi(z_1^{(1)}) = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

$$z_1^{(2)} = w^{(2)} a_1^{(1)} + w_0^{(2)} = \begin{pmatrix} 1 & -2 \end{pmatrix} \begin{pmatrix} 0 \\ 0 \end{pmatrix} + 0 = 0$$

$$o_1 = \varphi(z_1^{(2)}) = 0$$

$$x_2 = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$$

$$z_2^{(1)} = w^{(1)} x_2 + w_0 = \begin{pmatrix} 1 & 1 \end{pmatrix} \begin{pmatrix} 1 \\ 1 \end{pmatrix} + \begin{pmatrix} 0 \\ -1 \end{pmatrix} = \begin{pmatrix} 2 \\ 1 \end{pmatrix}$$

$$a_2^{(1)} = \varphi(z_2^{(1)}) = \begin{pmatrix} 2 \\ 1 \end{pmatrix}$$

$$z_2^{(2)} = w^{(2)} a_2^{(1)} + w_0^{(2)} = \begin{pmatrix} 1 & -2 \end{pmatrix} \begin{pmatrix} 2 \\ 1 \end{pmatrix} + 0 = 0$$

$$o_2 = \varphi(z_2^{(2)}) = 0$$

$$x_3 = \begin{pmatrix} 1 \\ 0 \end{pmatrix}$$

$$z_3^{(1)} = w^{(1)} x_3 + w_0 = \begin{pmatrix} 1 & 1 \end{pmatrix} \begin{pmatrix} 1 \\ 0 \end{pmatrix} + \begin{pmatrix} 0 \\ -1 \end{pmatrix} = \begin{pmatrix} 1 \\ 0 \end{pmatrix}$$

$$a_3^{(1)} = \varphi(z_3^{(1)}) = \begin{pmatrix} 1 \\ 0 \end{pmatrix}$$

$$z_3^{(2)} = w^{(2)} a_3^{(1)} + w_0^{(2)} = \begin{pmatrix} 1 & -2 \end{pmatrix} \begin{pmatrix} 1 \\ 0 \end{pmatrix} + 0 = 1$$

$$o_3 = \varphi(z_3^{(2)}) = 1$$

$$x_4 = \begin{pmatrix} 0 \\ 1 \end{pmatrix}$$

$$z_4^{(1)} = w^{(1)} x_4 + w_0 = \begin{pmatrix} 1 & 1 \end{pmatrix} \begin{pmatrix} 0 \\ 1 \end{pmatrix} + \begin{pmatrix} 0 \\ -1 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

$$a_4^{(1)} = \varphi(z_4^{(1)}) = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

$$z_4^{(2)} = w_4^{(2)} a_4^{(1)} + w_0^{(2)} = (1 \ -2) \begin{pmatrix} 1 \\ 0 \end{pmatrix} + 0 = 1$$

$$o_4 = \varphi(z_4^{(2)}) = 1$$

∴ 可以正确分类异或

3. 对于神经网络做 K 分类的输出，其样本损失函数为

$$L_n = L(\hat{y}_n, y_n) = - \sum_{k=1}^K [y_{nk} \ln \hat{y}_{nk}]$$

证明其对输出激活 $a_{nk}^{(L)}$ 的导数为

$$\frac{\partial L_n}{\partial a_{nk}^{(L)}} = \frac{\partial L(\hat{y}_n, y_n)}{\partial a_{nk}^{(L)}} = \hat{y}_{nk} - y_{nk}$$

$$L_n = L(\hat{y}_n, y_n) = - \sum_{k=1}^K (y_{nk} \ln \hat{y}_{nk})$$

$$\hat{y}_{nk} = \sigma(a_{nk}^{(L)}) = \frac{\exp(a_{nk}^{(L)})}{\sum_{j=1}^K \exp(a_{nj}^{(L)})}$$

$$\frac{\partial L_n}{\partial \hat{y}_{nk}} = \frac{\partial}{\partial \hat{y}_{nk}} - \sum_{k=1}^K (y_{nk} \ln \hat{y}_{nk}) = -y_{nk} \frac{1}{\hat{y}_{nk}} = -\frac{y_{nk}}{\hat{y}_{nk}}$$

$$\frac{\partial \hat{y}_{ni}}{\partial a_{nk}^{(L)}} = \frac{\partial}{\partial a_{nk}^{(L)}} \frac{\exp(a_{nk}^{(L)})}{\sum_{j=1}^K \exp(a_{nj}^{(L)})}$$

$i = k$ 时

$$\frac{\partial \hat{y}_{ni}}{\partial a_{nk}^{(L)}} = \frac{\exp(a_{nk}^{(L)}) \sum_{j=1}^K \exp(a_{nj}^{(L)}) - \exp(a_{nk}^{(L)}) \exp(a_{nk}^{(L)})}{(\sum_{j=1}^K \exp(a_{nj}^{(L)}))^2} = \hat{y}_{nk} (1 - \hat{y}_{nk})$$

$i \neq k$ 时

$$\frac{\partial \hat{y}_{ni}}{\partial a_{nk}^{(L)}} = \frac{-\exp(a_{ni}^{(L)}) \exp(a_{nk}^{(L)})}{(\sum_{j=1}^K \exp(a_{nj}^{(L)}))^2} = -\hat{y}_{ni} \hat{y}_{nk}$$

$$\frac{\partial L_n}{\partial a_{nk}^{(L)}} = \sum_{i=1}^K \frac{\partial L_n}{\partial \hat{y}_{ni}} \frac{\partial \hat{y}_{ni}}{\partial a_{nk}^{(L)}} = \sum_{i=1}^K -\frac{y_{ni}}{\hat{y}_{ni}} \frac{\partial \hat{y}_{ni}}{\partial a_{nk}^{(L)}} = \sum_{i \neq k} \frac{y_{ni}}{\hat{y}_{ni}} \hat{y}_{ni} \hat{y}_{nk} - \frac{y_{nk}}{\hat{y}_{nk}} \hat{y}_{nk} (1 - \hat{y}_{nk})$$

$$= \sum_{i \neq k} y_{ni} \hat{y}_{nk} + y_{nk} \hat{y}_{nk} - y_{nk}$$

$$= \hat{y}_{nk} - y_{nk}$$

1. 对于如下的二维数据和卷积核

24	76	78	45	32
44	45	89	56	30
15	32	98	98	35
17	44	110	89	40
22	54	128	98	34

1	1
-1	-1

- (1) 求有效卷积的卷积输出;
- (2) 对卷积输出通过 ReLu 激活函数后, 按照步幅 2 进行 2X2 窗口的最大池化, 写出池化输出。

$$(1) \quad \begin{matrix} 11 & 20 & -22 & -9 \\ 42 & 4 & -51 & -47 \\ -14 & -24 & -3 & 4 \\ -7 & -28 & -27 & -3 \end{matrix}$$

$$$$

$$$$

$$$$

$$(2) \quad \begin{matrix} 42 & 0 \\ 0 & 4 \end{matrix}$$

$$$$

3. 设一个简单的 RNN 网络的计算表示为

$$\mathbf{a}^{(t)} = \mathbf{b} + \mathbf{W}\mathbf{h}^{(t-1)} + \mathbf{U}\mathbf{x}^{(t)}$$

$$\mathbf{h}^{(t)} = \tanh(\mathbf{a}^{(t)})$$

$$\mathbf{o}^{(t)} = \mathbf{c} + \mathbf{V}\mathbf{h}^{(t)}$$

$$\hat{\mathbf{y}}^{(t)} = \mathbf{o}^{(t)}$$

- (1) 若 \mathbf{h} 和 \mathbf{x} 均为 2 维向量, 网络参数分别为

$$\mathbf{b} = [0.2, -0.1]^T, \quad c = 0.25, \quad \mathbf{V} = [0.5, 1]$$

$$\mathbf{W} = \begin{bmatrix} 0.8 & -0.1 \\ -0.12 & 0.8 \end{bmatrix}, \quad \mathbf{U} = \begin{bmatrix} 2 & -1 \\ 1 & 1 \end{bmatrix}$$

若输入 $\mathbf{x}^{(t)} = [\sin 0.2\pi t \quad \cos 0.5\pi t]^T$, 请借助计算机, 计算在 $1 \leq t \leq 10$ 范围内的输出 $\hat{\mathbf{y}}^{(t)}$ 序列。

- (2) 对于该网络, 若采用误差平方作为目标函数, 以 (1) 中给出的系数为初始值, 设状态初始值为 $\mathbf{h}^{(0)} = \mathbf{0}$, 若给出一个三个时刻的序列样本集:

$$\{(\mathbf{x}^{(t)}, \hat{\mathbf{y}}^{(t)})\}_{t=1}^3 = \{((1, 2)^T, -1), ((-1, 0)^T, 1), ((1, -1)^T, 2)\}$$

请利用通过时间的反向传播算法, 对网络参数进行更新。

$$(1) y^{(1)} = 1.14$$

$$y^{(2)} = 0.86$$

$$y^{(3)} = 1.42$$

$$y^{(4)} = 1.60$$

$$y^{(5)} = 1.08$$

$$y^{(6)} = -0.40$$

$$y^{(7)} = -1.12$$

$$y^{(8)} = -0.86$$

$$y^{(9)} = -1.00$$

$$y^{(10)} = -0.43$$

(2) 前向传播计算得到.

$$h^{(1)} = \begin{pmatrix} 0.197 \\ 0.994 \end{pmatrix} \quad h^{(2)} = \begin{pmatrix} -0.940 \\ -0.317 \end{pmatrix} \quad h^{(3)} = \begin{pmatrix} 0.986 \\ -0.236 \end{pmatrix}$$

$$\hat{y}^{(1)} = 1.34 \quad y^{(2)} = -0.54 \quad y^{(3)} = 0.51$$

$$\text{由 } J^{(t)} = (y^{(t)} - \hat{y}^{(t)})^2$$

$$\frac{\partial J^{(t)}}{\partial y^{(t)}} = -2(y^{(t)} - \hat{y}^{(t)}) = 2(\hat{y}^{(t)} - y^{(t)})$$

$$\frac{\partial J}{\partial o^{(t)}} = \frac{\partial J}{\partial y} \frac{\partial y}{\partial o^{(t)}} = -2(y^{(t)} - \hat{y}^{(t)}) = \{4.685, -3.075, -2.987\}$$

$$\begin{aligned} \frac{\partial J}{\partial h^{(t)}} &= \frac{\partial J}{\partial o^{(t)}} \frac{\partial o^{(t)}}{\partial h^{(t)}} + \frac{\partial J}{\partial o^{(t+1)}} \frac{\partial h^{(t+1)}}{\partial h^{(t)}} \\ &= 2V^T(y^{(t)} - \hat{y}^{(t)}) + W^T(y^{(t+1)} - \hat{y}^{(t+1)}) \text{diag}\{1 - h^{(t+1)^2}\} \\ &= \left\{ \begin{pmatrix} 2.343 \\ 4.685 \end{pmatrix}, \begin{pmatrix} -3.075 \\ 1.743 \end{pmatrix}, \begin{pmatrix} -1.497 \\ -2.990 \end{pmatrix} \right\} \end{aligned}$$

$$\therefore \frac{\partial J}{\partial c} = \sum_t \frac{\partial J}{\partial o^{(t)}} = 0.688$$

$$\frac{\partial J}{\partial b} = \sum_t \text{diag}\{1 - h^{(t)^2}\} \frac{\partial J}{\partial h^{(t)}} = \begin{pmatrix} -0.456 \\ -7.438 \end{pmatrix}$$

$$\frac{\partial J}{\partial v} = \sum_t \frac{\partial J}{\partial o^{(t)}} h^{(t)} = \begin{pmatrix} -0.436 \\ -3.169 \end{pmatrix}$$

$$\frac{\partial J}{\partial w} = \sum_t \text{diag}\{1 - h^{(t)2}\} \frac{\partial J}{\partial h^{(t)}} h^{(t-1)T} = \begin{pmatrix} 0.008 & -0.142 \\ 1.728 & -3.760 \end{pmatrix}$$

$$\frac{\partial J}{\partial u} = \sum_t \text{diag}\{1 - h^{(t)2}\} \frac{\partial J}{\partial h^{(t)}} x^{(t)T} = \begin{pmatrix} 1.374 & 2.559 \\ 1.920 & 2.935 \end{pmatrix}$$