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1	Tips	
	1. pow 返回浮点数可能会导致误差,慎用!!! 自己写。	
	2. 样例数用 long long 可能会 TLE	
	3. 多组数据记得初始化	
	4. 小心过程量 overflow	
	5. Type convertions	
	6. 在取余的情况下,要避免减法运算的结果出现负数 (+ MOD) % MOD;	
	7. fill 注意初始范围为从 1 到 n 的情况	
	8. 提交换行	
	9. c++11: long long int abs (long long int n);	
	10. 输入读取判断其中一个为零	
	11. 搜索 flag 标记可能要加上方案数	
	12. 数据范围特别大时考虑不可能情况	
	13. SegmentTree 开大点以防 RE (1e5 -> 1 << 17) 14. 滚动数组未全部清零	
	中,从XANXX22小工即/月文	

# 2 Basic Algorithm

#### 2.1 Sort

```
1  // Bubble Sort
2  for (int i = 0; i < N; i++)
3    for (int j = 0; j < N - i - 1; j++)
4    if (A[j] > A[j + 1]) swap(A[j], A[j + 1]);
```

```
// Selection Sort
for (int i = 0; i < N; i++)
for (int j = i + 1; j < N; j++)
if (A[i] > A[j]) swap(A[i], A[j])
```

```
// Merge Sort
   void merge_sort(int A[], int l, int r) {
3
        if (l >= r) return ;
       int mid = (l + r) / 2;
4
5
       merge_sort(A, l, mid);
       merge_sort(A, mid + 1, r);
7
       int i, j, k;
       i = l; j = mid + 1; k = l;
9
       while (i <= mid && j <= r) {</pre>
10
            if (A[i] <= A[j]) B[k] = A[i++];</pre>
            else B[k] = A[j++];
11
            k++;
12
        }
13
14
        while (i <= mid) {</pre>
15
            B[k] = A[i++];
16
            k++;
17
        while (j <= r) {
19
            B[k] = A[j++];
20
            k++;
```

```
21    }
22    memcpy(A, B, r - l + 1);
23    return;
24 }
```

```
// Quick Sort
   void quicksort(int A[], int l, int r) {
       int i = l, j = r, mid = A[(r - l) / 2 + l];
4
       while (i <= j) {
5
            while (A[i] < mid) i++;</pre>
            while (A[j] > mid) j--;
6
7
            if (i <= j) {
8
                swap(A[i], A[j]);
9
                ++i; --j;
            }
10
11
       }
       if (i < r) quicksort(A, i, r);</pre>
12
13
       if (l < j) quicksort(A, l, j);
14
       return ;
15
   }
```

• Heap Sort (见堆的内容)

#### 2.2 DP

#### 2.2.1 LIS

#### 2.2.2 Knapsack Problem

• 0/1 背包

```
f[i,j] = \max(f[i-1,j], f[i-1,j-w[i]] + v[i])
```

```
for (int i = 0; i < N; ++i)
for (int j = W; j >= w[i]; --j)
f[j] = max(f[j - w[i]] + c[i], f[j]);
```

• 完全背包

$$f[i,j] = \max(f[i-1,j], f[i-1,j-w[i]] + j[i])$$

```
for (int i = 0; i < N; ++i)

for (int j = w[i]; j <= W; ++j)

f[j] = max(f[j - w[i]] + c[i], f[v]);</pre>
```

注意循环顺序的不同背后思路。

- 一个简单的优化:若两件物品 i、j 满足  $w[i] \le w[j]$  且  $c[i] \ge c[j]$ ,则讲物品 j 去掉,不用考虑。
- 转化为 01 背包问题求解:
  - 第 i 种物品转化为  $\frac{V}{v(i)}$  件费用于价值均不变的物品。
  - 第 i 种物品拆成费用为  $w[i]*2^k$ ,价值为  $c[i]*2^k$  的若干件物品其中 k 满足  $w[i]*2^k < V$
- 多重背包

$$f[i,j] = \max(f[i-1,j-w[i]*k] + v[i]*k|0 <= k <= m[i])$$

- 优化: 转化为 01 背包问题
  - 将第 i 件物品分成若干件物品,每件物品的系数分别为:  $1, 2, 4, ..., 2^{(k-1)}, n[i] 2^k$
  - \*\* 根据 w, v 范围改变 DP 对象,可以考虑针对不同价值计算最小的重量。(f[i][j],其中 i 代表价值总和)\*\*

```
for (int i = 0; i < N; ++i) {
   int num = m[i];

for (int k = 1; num > 0; k <<= 1) {
      int mul = min(k, num);

      for (int j = W; j >= w[i] * mul; --j) {
            f[j] = max(f[j - w[i] * mul] + v[i] * mul, f[j]);

      }

      num -= mul;

    }
```

10 }

• 混合三种背包

弄清楚上面三种背包后分情况就好

• 超大背包

-  $1 \le n \le 40$ ,  $1 \le w_i, v_i \le 10^{15}$ , \$ 1 < W < 10 (15)\$

```
int n;
   ll w[MAX_N], v[MAX_N], W;
3
   Pll ps[1 << (MAX_N / 2)]; // (w, v);
   void solve() {
4
5
       int n2 = n / 2;
6
        for (int i = 0; i < 1 << n2; ++i) {</pre>
7
            ll sw = 0, sv = 0;
            for (int j = 0; j < n2; ++j)
8
                 if (i >> j & 1) {
9
10
                     sw += w[j];
11
                     sv += v[j];
12
                }
            ps[i] = Pll(sw, sv);
13
14
        }
15
        sort(ps, ps + (1 << n2));
        int m = 1;
16
        for (int i = 1; i < 1 << n2; ++i)</pre>
            if (ps[m - 1].second < ps[i].second)</pre>
18
19
                ps[m++] = ps[i];
20
        ll res = 0;
21
        for (int i = 0; i < 1 << (n - n2); ++i) {</pre>
22
            ll sw = 0, sv = 0;
            for (int j = 0; j < n - n2; ++j)</pre>
23
24
                 if (i >> j & 1) {
25
                     sw += w[n2 + j];
                     sv += v[n2 + j];
26
                 }
27
28
            if (sw <= W) {
29
                ll tv = (lower_bound(ps, ps + m, make_pair(W - sw, INF)) -
                    1)->second;
30
                 res = max(res, sv + tv);
31
            }
32
        printf("%lld\n", res);
33
34 }
```

#### • 二维费用背包

$$f[i, j, k] = max(f[i-1, j, k], f[i-1, j-a[i], k-b[i]) + c[i])$$

二维费用可由最多取m件等方式隐蔽给出。

• 分组背包

$$f[k,j] = \max(f[k-1,j], f[k-1,j-w[i]] + v[i]|i \in K)$$

```
for (int k = 0; k < K; ++k)

for (j = W; j >= 0; --j)

for (int i = 0; i <= m[k]; ++i)

f[j] = max(f[j - w[i]] + v[i], f[j]);</pre>
```

显然可以对每组中物品应用完全背包中"一个简单有效的优化"

• 有依赖背包

由 NOIP2006 金明的预算方案引申, 对每个附件先做一个 01 背包, 再与组件得到一个 V-w[i]+1 个物品组。更一般问题,依赖关系由「森林」形式给出,涉及到树形 DP 以及泛化物品,这里不表。

• 背包问题方案总数

$$f[i,j] = sum(f[i-1,j], f[i-1,j-w[i]] + v[i]), f[0,0] = 0$$

更多内容详见「背包九讲」

#### 2.2.3 Maximum Subarray Sum

```
int max_subarray_sum(int A[], int n) {
   int res, cur;
   if (!A || n <= 0) return 0;
   res = cur = a[0];
   for (int i = 0; i < n; ++i) {
      if (cur < 0) cur = a[i];
      else cur += a[i];
      res = max(cur, res);
}</pre>
```

```
return res;

11 }
```

### 2.3 Set

```
1 // 子集枚举
2 int sub = sup;
3 do {
     sub = (sub - 1) \& sup;
  } while (sub != sup); // -1 & sup = sup;
6 // 势为 k 的集合枚举
7
  int comb = (1 << k) - 1;
8 while (comb < 1 << n) {</pre>
9
      int x = comb & -comb, y = comb + x;
      comb = ((comb \& ~y) / x >> 1) | y;
10
11 }
12 // 排列组合
13 do {
15 } while (next_permutation(A, A + N)); // prev_permutation
```

#### 2.4 Bit operation

```
int __builtin_ffs (unsigned int x)

//返回x的最后一位1的是从后向前第几位,比如7368 (1110011001000) 返回4。

int __builtin_clz (unsigned int x)

// 返回前导的0的个数。

int __builtin_ctz (unsigned int x)

// 返回后面的0个个数,和__builtiin_clz相对。

int __builtin_popcount (unsigned int x)

// 返回二进制表示中1的个数。

int __builtin_parity (unsigned int x)

// 返回x的奇偶校验位,也就是x的1的个数模2的结果。
```

#### 3 Data Structure

```
// Heap
   int heap[MAX_N], sz = 0;
3
   void push(int x) {
4
        int i = sz++;
5
6
       while (i > 0) {
7
            int p = (i - 1) / 2;
8
            if (heap[p] <= x) break;</pre>
9
            heap[p] = heap[i];
10
            i = p;
11
        }
12
        heap[i] = x;
13
14
   int pop() {
15
        int ret = heap[0];
16
        int x = heap[--sz];
       int i = 0;
17
       while (i * 2 + 1 < sz) {
18
            int a = i * 2 + 1, b = i * 2 + 2;
19
20
            if (b < sz && heap[b] < heap[a]) a = b;</pre>
21
            if (heap[a] >= x) break;
22
            heap[i] = heap[a];
23
            i = a;
24
        }
25
        heap[i] = x;
26
        return ret;
27 }
```

```
// Binary Search Tree
   struct node {
3
       int val;
4
       node *lch, rch;
5
   };
6
   node *insert(node *p, int x) {
7
       if (p == NULL) {
8
            node *q = new node;
            q \rightarrow val = x;
9
10
            q->lch = q->rch = NULL;
            return q;
11
12
       } else {
            if (x < p->val) p->lch = insert(p->lch, x);
13
            else p->rch = insert(p->rch, x);
14
```

```
return p;
16
       }
17
   }
18
   bool find(node *p, int x) {
       if (p == NULL) return false;
19
       else if (x == p->val) return true;
20
21
       else if (x < p->val) return find(p->lch, x);
       else return find(p->rch, x);
22
23
24
   node *remove(node *p, int x) {
25
       if (p == NULL) return NULL;
26
       else if (x < p->val) p->lch = remove(p->lch, x);
27
       else if (x > p->val) p->rch = remove(p->rch, x);
       else if (p->lch == NULL) {
28
29
           node *q = p->rch;
30
           delete p;
31
           return q;
32
       } else if (p->lch->rch == NULL) {
33
           node *q = p -  lch;
34
           q->rch = p->rch;
35
           delete p;
           return q;
       } else {
37
38
           // 把左儿子子孙中最大的节点提到需要删除的节点上
39
           node *q;
           for (q = p->lch; q->rch->rch != NULL; q = q->rch);
40
41
           node *r = q->rch;
           q->rch = r->lch;
42
           r->lch = p->lch;
43
           r->rch = p->rch;
44
45
           delete p;
46
           return r;
47
       }
48
       return p;
49 }
```

```
// Union-find Set
int par[MAX_N];
int rnk[MAX_N];

void init(int n) {
    for (int i = 0; i < n; ++i) {
        par[i] = i;
        rnk[i] = 0;
}</pre>
```

```
8 }
9
   }
10 int find(int x) {
       return par[x] == x? x : par[x] = find(par[x]);
11
12
13 bool same(int x, int y) {
14
       return find(x) == find(y);
15 }
16 void unite(int x, int y) {
17
       x = find(x);
       y = find(y);
18
19
       if (x == y) return;
20
       if (rnk[x] < rnk[y]) {
21
           par[x] = y;
22
       } else {
23
           par[y] = x;
24
           if (rnk[x] == rnk[y]) rnk[x]++;
25
       }
26 }
```

### 当然, 更快捷简单的做法, 是使用 C++ 的 container。

```
1 // Segment Tree
const int MAX_N = 1 << 17;</pre>
3 int n, dat[2 * MAX_N - 1];
   void init(int _n) {
5
       n = 1;
6
       while (n < _n) n <<= 1;</pre>
7
       for (int i = 0; i < 2 * n - 1; ++i)
8
           dat[i] = INF;
9
   }
   void update(int k, int a) {
10
11
       k += n - 1;
       dat[k] = a;
12
       while (k > 0) {
13
14
           k = (k - 1) / 2;
           dat[k] = min(dat[2 * k + 1], dat[2 * k + 2]);
16
       }
17
18 // query [a, b), index k in [l, r)
19 // query(a, b, 0, 0, n)
20 int query(int a, int b, int k, int l, int r) {
21 if (r <= a || b <= l) return INF;
```

```
if (a <= l && r <= b) return dat[k];
else {
    int v1 = query(a, b, k * 2 + 1, l, (l + r) / 2);
    int v2 = query(a, b, k * 2 + 2, (l + r) / 2, r);
    return min(v1, v2);
}
</pre>
```

```
// RMQ
   int n, dat[2 * MAX_N - 1];
   void init(int _n) {
4
       n = 1;
5
       while (n < _n) n <<= 1;</pre>
6
       for (int i = 0; i < 2 * n - 1; ++i)</pre>
            dat[i] = INF;
7
8
9
   void update(int k, int a) {
       k += n - 1;
10
       dat[k] = a;
11
12
       while (k > 0) {
            k = (k - 1) / 2;
            dat[k] = min(dat[2 * k + 1], dat[2 * k + 2]);
14
15
       }
16 }
   // query [a, b), index k in [l, r)
17
   // query(a, b, 0, 0, n)
19 int query(int a, int b, int k, int l, int r) {
       if (r <= a || b <= l) return INF;</pre>
20
       if (a <= l && r <= b) return dat[k];
21
22
       else {
            int v1 = query(a, b, k * 2 + 1, l, (l + r) / 2);
23
24
            int v2 = query(a, b, k * 2 + 2, (l + r) / 2, r);
25
            return min(v1, v2);
26
       }
27 }
```

```
//Sparse Table
const int MAX_N = 1e5 + 10;
const int MAX_K = 31 - __builtin_clz(MAX_N);
int n, ST[MAX_N][MAX_K + 1], A[MAX_N];
void build(int N) {
   for (int i = 0; i < N; ++i)
     ST[i][0] = A[i];</pre>
```

```
int k = 31 - __builtin_clz(N);
9
        for (int j = 1; j <= k; ++j)</pre>
            for (int i = 0; i <= N - (1 << j); ++i)</pre>
10
                ST[i][j] = min(ST[i][j - 1i], ST[i + (1 << (j - 1))][j - 1])
11
12
   int query(int l, int r) {
       if (l >= r) return 0;
        int ans = INF, k = 31 - __builtin_clz(r - l);
15
16
        for (int j = k; j >= 0; --j)
            if (l + (1 << j) - 1 <= r) {
17
18
                ans = min(ans, ST[l][j]);
19
                l += 1 << j;
            }
20
21
        return ans;
22
23 int RMQ(int l, int r) {
24
        if (l >= r) return 0;
25
        int k = 31 - __builtin_clz(r - l);
        return min(ST[l][k], ST[r - (1 << k)][k]);</pre>
26
27 }
```

## 4 Graph

```
struct edge {
    int from;
    int to, dis;
};

vector<edge> G[MAX_V];

vector<edge> es;

bool vis[MAX_V];

int V, E, pre[MAX_V], dist[MAX_V];

// int cost[MAX_V][MAX_V];
```

```
// Shortest Way
void floyed() {
   for (int k = 1; k <= n; ++k)
        for (int i = 1; i <= n; ++i)
        for (int j = 1; i <= n; ++j)</pre>
```

```
6
                     dis[i][j] = min(dis[i][k] + dis[k][j], dis[i][j]);
 7
   }
8
   void dijkstra(int s) {
9
        priority_queue<Pii, vector<Pii>, greater<Pii> > que;// fisrt 是最短
            距离, second 是顶点编号
        fill(dist, dist + V, INF);
10
11
        dist[s] = 0; que.push(Pii(0, s));
        while (!que.empty()) {
12
13
            Pii p = que.top(); que.pop();
14
            int v = p.second;
            if (dist[v] < p.first) continue;</pre>
15
            for (int i = 0; i < G[v].size(); i++) {</pre>
16
17
                edge e = G[v][i];
                if (dist[e.to] > dist[v] + e.dis) {
18
19
                     dist[e.to] = dist[v] + e.dis;
20
                     que.push(Pii(dist[e.to], e.to));
                }
21
22
            }
23
        }
24
   }
25
   void bellman_ford(int s) {
        fill(dist, dist + V, INF);
26
        dist[s] = 0;
27
28
        while (true) {
29
            bool update = false;
            for (int i = 0; i < E; ++i) {</pre>
30
                edge e = es[i];
31
                if (dist[e.from] != INF && dist[e.from] + e.dis < dist[e.to</pre>
32
                    ]) {
33
                     update = true;
34
                     dist[e.to] = dist[e.from] + e.dis;
                }
35
36
37
            if (!update) break;
        }
38
39
   }
   bool find_negative_loop() {
40
        memset(dist, 0, sizeof dist);
41
        for (int i = 0; i < V; ++i)</pre>
42
            for (int j = 0; j < E; ++j) {
43
44
                edge e = es[j];
45
                if (d[e.to] > d[e.from] + e.dis) {
                     d[e.to] = d[e.from] + e.dis;
46
```

```
if (i == V - 1) return true;
47
48
                }
49
            }
50
        return false;
51
   void spfa(int s) {
52
53
        queue<int> que;
54
        fill(dist, dist + V, INF);
        fill(vis, vis + V, false);
55
56
        dist[s] = 0; que.push(s); vis[s] = true;
57
        while (!que.empty()) {
58
            int v = que.front(); que.pop();
59
            vis[v] = false;
            for (int i = 0; i < G[v].size(); ++i) {</pre>
60
61
                 int u = G[v][i].to;
                 if (dist[u] > dist[v] + G[v][i].dis) {
62
                     dist[u] = dist[v] + G[v][i].dis;
63
64
                     if (!vis[u]) {
65
                         que.push(u);
                         vis[u] = true;
66
                     }
67
                }
68
            }
69
70
       }
   }
71
```

```
// Spanning Tree
   int prime() {
3
       /*
4
       fill(dist, dist + V, INF);
5
       fill(vis, vis + V, false);
6
       dist[0] = 0;
7
       int res = 0;
       while (true) {
8
9
           int v = -1;
10
            for (int u = 0; u < V; ++u) {
                if(!vis[u] \&\& (v == -1 || dist[u] < dist[v])) v = u;
11
           }
12
            if (v == -1) break;
13
           vis[v] = true;
14
15
            res += dist[v];
16
            for (int u = 0; u < V; u++)
17
                dist[u] = min(dist[u], cost[v][u]);
```

```
18
19
        //*/
20
        priority_queue<Pii, vector<Pii>, greater<Pii> > que;
21
        int res = 0;
22
        fill(dist, dist + V, INF);
23
        fill(vis, vis + V, false);
24
        dist[0] = 0;
25
        que.push(Pii(0, 0));
        while (!que.empty()) {
26
27
            Pii p = que.top(); que.pop();
28
            int v = p.second;
29
            if (vis[v] || dist[v] < p.first) continue;</pre>
            res += dist[v]; vis[v] = true;
31
            for (int i = 0; i < G[v].size(); ++i) {</pre>
                 edge e = G[v][i];
                 if (dist[e.to] > e.dis) {
34
                     dist[e.to] = e.dis;
                     que.push(Pii(dist[e.to], e.to));
36
                 }
            }
37
38
        }
39
        return res;
40
41
   bool cmp(const edge e1, const edge e2) {
42
        return e1.dis < e2.dis;</pre>
43
   }
44
   int kruskal() {
45
        sort(es.begin(), es.end(), cmp);
        init(V);
46
47
        int res = 0;
        for (int i = 0; i < E; ++i) {</pre>
48
            edge e = es[i];
49
            if (!same(e.from, e.to)) {
50
51
                 unite(e.from, e.to);
                 res += e.dis;
52
53
            }
54
        }
55
        return res;
   }
56
```

```
1 // SCC
2 int V, cmp[MAX_V];
3 vector<int> G[MAX_V], rG[MAX_V], vs;
```

```
bool used[MAX_V];
   void add_edge(int from, int to) {
7
       G[from].push_back(to); rG[to].push_back(from);
8
9
   void dfs(int v) {
10
       used[v] = true;
        for (int i = 0; i < G[v].size(); ++i)</pre>
11
            if (!used[G[v][i]]) dfs(G[v][i]);
12
13
       vs.push_back(v);
14
   }
15
   void rdfs(int v, int k) {
16
       used[v] = true;
17
        cmp[v] = k;
18
        for (int i = 0; i < rG[v].size(); ++i)</pre>
19
            if (!used[rG[v][i]]) rdfs(rG[v][i], k);
20 }
21
   int scc() {
22
       memset(used, 0, sizeof used);
23
       vs.clear();
       for (int \vee = 0; \vee < \vee; ++\vee)
24
25
            if (!used[v]) dfs(v);
       memset(used, 0, sizeof used);
26
27
       int k = 0;
28
        for (int i = vs.size() - 1; i >= 0; --i)
29
            if (!used[vs[i]]) rdfs(vs[i], k++);
30
        return k;
31 }
```

```
// Bipartite Matching
   void add_edge(int u, int v) {
3
       G[u].push_back(v); G[v].push_back(u);
4
   }
5
   bool dfs(int v) {
6
       used[v] = true;
7
       rep(i, 0, G[v].size()) {
           int u = G[v][i], w = match[u];
8
           if (w < 0 || (!used[w] && dfs(w))) {</pre>
9
10
                match[v] = u; match[u] = v;
                return true;
11
            }
12
13
       }
14
       return false;
```

```
15
   }
   int bipartite_matching() {
16
17
       int res = 0;
18
       memset(match, -1, sizeof match);
       rep (v, 0, V)
19
20
            if (match[v] < 0) {
                memset(used, false, sizeof used);
21
                if (dfs(v)) ++res;
22
23
24
       return res;
25
   }
```

```
// Network Flow
   struct edge{
3
       int to, cap, rev;
4
   };
5 vector<edge> G[MAX_V];
  int level[MAX_V], iter[MAX_V];
7
   void add_edge(int from, int to, int cap) {
8
       G[from].push_back((edge){to, cap, static_cast<int>(G[to].size())});
9
       G[to].push_back((edge){from, 0, static_cast<int>(G[from].size() - 1)
           });
10
   }
11
   // Ford-Fulkerson
   int dfs(int v, int t, int f) {
12
       if (v == t) return f;
13
14
       flag[v] = true;
15
       rep(i, 0, G[v].size()) {
           edge &e = G[v][i];
16
17
           if (!flag[e.to] && e.cap > 0) {
                int d = dfs(e.to, t, min(f, e.cap));
18
19
                if (d > 0) {
20
                    e.cap -= d;
21
                    G[e.to][e.rev].cap += d;
22
                    return d;
23
                }
            }
24
       }
25
26
       return 0;
27
28
   int max_flow(int s, int t) {
29
       int flow = 0;
30
       for(;;) {
```

```
memset(flag, false, sizeof flag);
31
32
            int f = dfs(s, t, INF);
            if (!f) return flow;
34
            flow += f;
35
        }
36
   }
37
   // Dinic
38
   void bfs(int s) {
39
        memset(level, -1, sizeof(level));
40
        queue<int> que;
        level[s] = 0; que.push(s);
41
        while (!que.empty()) {
42
43
            int v = que.front(); que.pop();
            for (int i = 0; i < G[v].size(); ++i) {</pre>
44
45
                 edge &e = G[v][i];
                 if (e.cap > 0 && level[e.to] < 0) {</pre>
46
                     level[e.to] = level[v] + 1;
47
48
                     que.push(e.to);
49
                 }
50
            }
        }
51
   }
52
53
   int dfs(int v, int t, int f) {
        if (v == t) return f;
54
        for (int &i = iter[v]; i < G[v].size(); ++i) {</pre>
56
            edge &e = G[v][i];
            if (e.cap > 0 && level[v] < level[e.to]) {</pre>
57
58
                 int d = dfs(e.to, t, min(f, e.cap));
                 if (d > 0) {
59
60
                     e.cap -= d;
61
                     G[e.to][e.rev].cap += d;
                     return d;
62
                 }
63
            }
64
        }
65
66
        return 0;
67
68
   int max_flow(int s, int t) {
69
        int flow = 0;
        for (;;) {
70
71
            bfs(s);
72
            if (level[t] < 0) return flow;</pre>
            memset(iter, 0, sizeof iter);
73
```

```
int f;
while ((f = dfs(s, t, INF)) > 0) {
    flow += f;
}

}

}
```

```
// min_cost_flow
   void add_edge(int from, int to, int cap, int cost) {
3
       G[from].push_back((edge){to, cap, cost, (int)G[to].size()});
       G[to].push_back((edge){from, 0, -cost, (int)G[from].size() - 1});
4
5
   }
6
   int min_cost_flow(int s, int t, int f) {
7
       int res = 0;
8
       fill(h, h + V, 0);
9
       while (f > 0) {
            priority_queue<Pii, vector<Pii>, greater<Pii> > que;
11
            fill(dist, dist + V, INF);
            dist[s] = 0; que.push(Pii(0, s));
12
           while (!que.empty()) {
13
14
                Pii p = que.top(); que.pop();
15
                int v = p.second;
16
                if (dist[v] < p.first) continue;</pre>
17
                rep(i, 0, G[v].size()) {
                    edge &e = G[v][i];
18
                    if (e.cap > 0 && dist[e.to] > dist[v] + e.cost + h[v] -
19
                        h[e.to]) {
20
                        dist[e.to] = dist[v] + e.cost + h[v] - h[e.to];
21
                        prevv[e.to] = v;
22
                        preve[e.to] = i;
23
                        que.push(Pii(dist[e.to], e.to));
24
                    }
                }
25
26
            }
27
            if (dist[t] == INF) return -1;
28
            rep(v, 0, V) h[v] += dist[v];
            int d = f;
29
            for (int v = t; v != s; v = prevv[v])
31
                d = min(d, G[prevv[v]][preve[v]].cap);
            f -= d;
32
            res += d * h[t];
            for (int v = t; v != s; v = prevv[v]) {
34
35
                edge &e = G[prevv[v]][preve[v]];
```

```
// stoer_wagner 全局最小割
   void search() {
3
       memset(vis, false, sizeof vis);
4
       memset(wet, 0, sizeof wet);
5
       S = T = -1;
6
       int imax, tmp;
7
       rep(i, 0, V) {
8
            imax = -INF;
9
            rep(j, 0, V)
                if (!cmb[j] && !vis[j] && wet[j] > imax) {
10
11
                    imax = wet[j];
12
                    tmp = j;
13
                }
14
            if (T == tmp) return;
            S = T; T = tmp;
15
16
            mc = imax;
17
            vis[tmp] = true;
            rep(j, 0, V)
18
                if (!cmb[j] && !vis[j])
19
20
                    wet[j] += G[tmp][j];
       }
21
22
   }
23
   int stoer_wagner() {
24
       memset(cmb, false, sizeof cmb);
25
       int ans = INF;
       rep(i, 0, V - 1) {
26
27
            search();
28
            ans = min(ans, mc);
29
            if (ans == 0) return 0;
            cmb[T] = true;
            rep(j, 0, V)
31
                if (!cmb[j]) {
32
33
                    G[S][j] += G[T][j];
                    G[j][S] += G[j][T];
34
                }
35
36
```

```
37    return ans;
38 }
```

```
// LCA--Doubling
   const int MAX_LOG_V = 32 - __builtin_clz(MAX_V);
3 vector<int> G[MAX_V];
4 int root, parent[MAX_LOG_V][MAX_V], depth[MAX_V];
   void dfs(int v, int p, int d) {
6
        parent[0][v] = p;
7
       depth[v] = d;
        for (int i = 0; i < G[v].size(); i++)</pre>
8
9
            if (G[v][i] != p) dfs(G[v][i], v, d + 1);
10
   }
   void init(int V) {
11
12
       dfs(root, -1, 0);
13
        for (int k = 0; k + 1 < MAX_LOG_V; k++)</pre>
            for (int \vee = 0; \vee < \vee; \vee ++)
14
15
                if (parent[k][v] < 0) parent[k + 1][v] = -1;</pre>
                else parent[k + 1][v] = parent[k][parent[k][v]];
16
17
   }
18
   int lca(int u, int v) {
19
       if (depth[u] > depth[v]) swap(u, v);
        for (int k = 0; k < MAX_LOG_V; k++)</pre>
20
21
            if ((depth[v] - depth[u]) >> k & 1)
22
                v = parent[k][v];
        if (u == v) return u;
23
24
        for (int k = MAX_LOG_V - 1; k >= 0; k--)
25
            if (parent[k][u] != parent[k][v])
26
                u = parent[k][u], v = parent[k][v];
27
        return parent[0][u];
28 }
29
   // LCA--RMQ
30 vector<int> G[MAX_V];
31 int root, vs[MAX_V * 2 - 1], depth[MAX_V * 2 - 1], id[MAX_V];
32 int ST[2 * MAX_V][MAX_K];
33
   void rmq_init(int* A, int N) {
        for (int i = 0; i < N; i++)</pre>
34
            ST[i][0] = i;
        int k = 31 - __builtin_clz(N);
36
        for (int j = 1; j <= k; j++)</pre>
37
            for (int i = 0; i <= N - (1 << j); ++i)</pre>
                if (A[ST[i][j - 1]] <= A[ST[i + (1 << (j - 1))][j - 1]])</pre>
39
40
                     ST[i][j] = ST[i][j - 1];
```

```
41
                else ST[i][j] = ST[i + (1 << (j - 1))][j - 1];
42
   int query(int l, int r) {
43
        if (l >= r) return -1;
44
        int k = 31 - __builtin_clz(r - l);
45
46
        return (depth[ST[l][k]] <= depth[ST[r - (1 << k)][k]]) ? ST[l][k] :</pre>
           ST[r - (1 << k)][k];
47
   }
   void dfs(int v, int p, int d, int &k) {
48
49
       id[v] = k;
       vs[k] = v;
50
51
       depth[k++] = d;
52
        for (int i = 0; i < G[v].size(); i++) {</pre>
            if (G[v][i] != p) {
53
54
                dfs(G[v][i], v, d + 1, k);
                vs[k] = v;
55
                depth[k++] = d;
56
57
            }
58
       }
59
   }
60 void init(int V) {
        int k = 0;
61
        dfs(root, -1, 0, k);
62
63
        rmq_init(depth, 2 * V - 1);
64 }
65 int lca(int u, int v) {
        return vs[query(min(id[u], id[v]), max(id[u], id[v]) + 1)];
66
   }
67
```

## **5 Computational Geometry**

```
const double EPS = 1e-8;
int sgn(double x) { return x < -EPS ? -1 : x > EPS ? 1 : 0;}
struct Point {
    double x, y;
    Point(double x = 0, double y = 0) : x(x), y(y) {}
    Point operator + (Point p) { return Point(x + p.x, y + p.y); }
    Point operator - (Point p) { return Point(x - p.x, y - p.y); }
    Point operator * (double d) { return Point(x * d, y * d); }
```

```
bool operator < (Point p) {</pre>
10
            return x != p.x? x < p.x : y < p.y;
11
       }
       double dot(Point p) { return add(x * p.x, y * p.y); }// 内积
12
       double det(Point p) { return add(x * p.y, -y * p.x);}// 外积
13
14 };
   bool on_seg(Point p1, Point p2, Point q) {
       return (p1 - q).det(p2 - q) == 0 && (p1 - q).dot(p2 - q) <= 0;
17
18 P intersection(Point p1, Point p2, Point q1, Point q2) {
       return p1 + (p2 - p1) * ((q2 - q1).det(q1 - p1) / (q2 - q1).det(p2 -
            p1));
20
   }
   // 凸包
21
22 int convex_hull(Point *ps, int n, Point *ch) {
       sort(ps, ps + n);
       int k = 0;
24
       for (int i = 0; i < n; ++i) {</pre>
           while (k > 1 \&\& (ch[k - 1] - ch[k - 2].det(ps[i] - ch[k - 1]))
               <= 0) k--;
           ch[k++] = ps[i];
27
28
29
       for (int i = n - 2, t = k; i \ge 0; --i) {
           while (k > t & (ch[k - 1] - ch[k - 2].det(ps[i] - ch[k - 1]))
               <= 0) k--;
31
           ch[k++] = ps[i];
32
33
       return k - 1;
34 }
```

Simpson 公式——二次函数近似原函数积分:

$$\int_a^b f(x)dx \approx \frac{b-a}{6} * \left(f(a) + 4f(\frac{a+b}{2}) + f(b)\right)$$

### 6 Math Problem

```
// returning count of nk in range [l, r], from Infinity
template<typename T> T mps(T l, T r, T k) {
    return ((r - (r % k + k) % k) - (l + (k - l % k) % k)) / k + 1;
```

```
4
   template<typename T> T gcd(T a, T b) {
       //return (b)? gcd(b, a % b) : a;
 7
       while (b) { T t = a % b; a = b; b = t; } return a;
8
   template<typename T> T lcm(T a, T b) {
9
10
       return a / gcd(a, b) * b;
11
   // find (x, y) s.t. a x + b y = gcd(a, b) = d
12
13
   template<typename T> T exgcd(T a, T b, T &x, T &y) {
14
       T d = a;
15
       if (b) {
16
            d = exgcd(b, a \% b, y, x);
17
            y -= a / b * x;
18
       } else {
19
            x = 1; y = 0;
20
       }
21
       return d;
22
23
   template<typename T> T modular_linear(T a, T b, T n) {
24
       T d, e, x, y;
25
       d = exgcd(a, n, x, y);
       if (b % d)
26
27
            return -1;
28
       e = x * (b / d) % n + n;
29
       return e % (n / d);
30
31
   template<typename T> T mod_mult(T a, T b, T mod) {
     T res = 0;
32
33
     while (b) {
       if (b & 1) {
34
35
            res = (res + a) \% mod;
36
            // res += a;
            // if (res >= mod) res -= mod;
       }
38
39
       a = (a + a) \% mod;
       // a <<= 1;
40
       // if (a >= mod) a -= mod;
41
       b >>= 1;
42
43
     }
44
     return res;
45 }
46 template<typename T> T mod_pow(T x, T n, T mod) {
```

```
47
       T res = 1;
48
       while (n) {
49
            if (n & 1) res = mod_mult(res, x, mod);
50
            x = mod_mult(x, x, mod);
51
            n >>= 1;
52
       }
       return res;
       // return b ? mod_pow(a * a % mod, b >> 1, mod) * (b & 1 ? a : 1) %
54
           mod : 1;
55
   template<typename T> T mod_inverse(T a, T m) {
56
57
       T x, y;
58
       exgcd(a, m, x, y);
59
       return (m + x % m) % m;
60 }
   // 线性求逆元 小心乘法溢出?
61
   void init_inverse() {
63
       inv[1] = 1;
64
       for (int i = 2; i < MAX_N; i++)</pre>
            inv[i] = (MOD - (MOD / i) * inv[MOD % i] % MOD) % MOD;
65
66 }
   //A[i] * x % M[i] = B[i];
67
   std::pair<int, int> linear_congruence(const std::vector<int> &A, const
       std::vector<int> &B, const std::vector<int> &M) {
            // wa 了把中间量开大? * 溢出
69
70
            int x = 0, m = 1;
            for(int i = 0; i < A.size(); i++) {</pre>
71
                    int a = A[i] * m, b = B[i] - A[i] * x, d = gcd(M[i], a);
72
                    if(b % d != 0) return std::make_pair(0, -1); // no
73
                        solutioin
                    int t = b / d * mod_inverse(a / d, M[i] / d) % (M[i] / d
74
                        );
75
                    x = x + m * t;
                    m *= M[i] / d;
76
77
            }
78
            while (x < m) \times += m;
79
            return std::make_pair(x % m, m);
80
   ll CRT(vector<ll> &a, vector<ll> &m) {
81
       ll M = 1LL, res = 0;
82
       for (int i = 0; i < m.size(); ++i)</pre>
83
84
            M *= m[i];
       for (int i = 0; i < m.size(); ++i) {</pre>
```

```
86
             ll Mi, Ti;
87
             Mi = M / m[i]; Ti = mod_inverse(Mi, mi);
             res = (res + a[i] * (Mi * Ti % M) % M) % M;
88
89
        return res;
91
    }
    // only for MOD < 1e6;
93 ll fact[MOD + 10];
    void init() {
94
95
        fact[0] = 1;
        for (int i = 1; i <= MOD; ++i)</pre>
97
            fact[i] = fact[i - 1] * i % MOD;
98
    int mod_fact(int n, int p, int &e) {
99
        e = 0;
        if (n == 0) return 1;
        int res = mod_fact(n / p, p, e);
103
        e += n / p;
104
        if (n / p % 2 != 0) return res * (p - fact[n % p]) % p;
        return res * fact[n % p] % p;
105
    }
106
    int mod_comb(int n, int k, int p) {
107
        if (n < 0 || k < 0 || n < k) return 0;</pre>
108
109
        if (n == 0) return 1;
110
        int e1, e2, e3;
        int a1 = mod_fact(n, p, e1), a2 = mod_fact(k, p, e2), a3 = mod_fact(
111
            n - k, p, e3);
        if (e1 > e2 + e3) return 0;
112
        return a1 * mod_inverse(a2 * a3 % p, p) % p;
113
114
115 | ll lucas(ll n, ll k, const ll &p) {
        if (n < 0 || k < 0 || n < k) return 0;</pre>
        if (n == 0) return 1;
117
        return lucas(n / p, k / p, p) * mod_comb(n % p, k % p, p) % p;
118
119 }
```

```
1 // 矩阵快速幂
2 typedef vector<int> vec;
3 typedef vector<vec> mat;
4 mat G(MAX_N);
5 mat mat_mul(mat &A, mat &B) {
    mat C(A.size(), vec(B[0].size()));
6 for (int i = 0; i < A.size(); ++i)</pre>
```

```
for (int k = 0; k < B.size(); ++k)</pre>
9
                 for (int j = 0; j < B[0].size(); ++j)</pre>
10
                     C[i][j] = (C[i][j] + A[i][k] % MOD * B[k][j] % MOD + MOD
                         ) % MOD;
11
        return C;
12
   }
13
   mat mat_pow(mat A, ll n) {
       mat B(A.size(), vec(A.size()));
14
        for (int i = 0; i < A.size(); ++i)</pre>
15
16
            B[i][i] = 1;
        while (n > 0) {
17
            if (n & 1) B = mat_mul(B, A);
18
19
            A = mat_mul(A, A);
            n >>= 1;
20
21
        }
22
        return B;
23 }
```

```
// prime number
   bool is_prime(int n) {
3
        for (int i = 2; i * i <= n; ++i)</pre>
4
            if (n % i == 0) return false;
5
        return n != 1;
   }
6
7
   vector<int> divisor(int n) {
        vector<int> res;
8
9
        for (int i = 1; i * i <= n; ++i) {
10
            if (n % i == 0) {
11
                res.push_back(i);
                if (i != n / i) res.push_back(n / i);
12
13
            }
14
        }
15
        return res;
16
17
   map<int, int> prime_factor(int n) {
18
        map<int, int> res;
19
        for (int i = 2; i * i <= n; ++i) {</pre>
            while (n % i == 0) {
20
21
                ++res[i];
22
                n /= i;
23
            }
        }
24
25
        if (n != 1) res[n] = 1;
```

```
26
        return res;
27
28 int prime[MAX_N];
29 bool isPrime[MAX_N + 1];
   int seive(int n) {
31
       int p = 0;
        fill(isPrime, isPrime + n + 1, true);
        isPrime[0] = isPrime[1] = false;
        for (int i = 2; i <= n; ++i)</pre>
34
35
            if (isPrime[i]) {
                prime[p++] = i;
36
                for (int j = 2 * i; j <= n; j += i) isPrime[j] = false;</pre>
37
38
            }
39
        return p;
40 }
   // the number of prime in [L, r)
   // 对区间 [l, r) 内的整数执行筛法, prime[i - l] = true <=> i 是素数
43 bool segPrimeSmall[MAX_L];
   bool segPrime[MAX_SQRT_R];
   void segment_sieve(ll l, ll r) {
45
        for (int i = 0; (ll)i * i < r; ++i) segPrimeSmall[i] = true;</pre>
46
        for (int i = 0; i < r - l; ++i) segPrime[i] = true;</pre>
47
        for (int i = 2; (ll)i * i < r; ++i) {</pre>
48
49
            if (segPrimeSmall[i]) {
                for (int j = 2 * i; (ll)j * j <= r; j += i) segPrimeSmall[j]</pre>
                     = false;
                for (ll j = max(2ll, (l + i - 1) / i) * i; j < r; j += i)</pre>
51
                    segPrime[j - l] = false;
52
            }
       }
53
54
   // Miller_Rabin
   bool check(ll a, ll n, ll x, ll t) {
       ll res = mod_pow(a, x, n);
57
       ll last = res;
58
59
        for (int i = 1; i <= t; ++i) {</pre>
            res = mod_mult(res, res, n);
60
            if (res == 1 && last != 1 && last != n - 1) return true;
61
            last = res;
62
63
        if (res != 1) return true;
        return false;
66 }
```

```
bool Miller_Rabin(ll n) {
68
        if (n < MAX_N) return isPrime[n]; // small number may get wrong</pre>
            answer?!
        if (n < 2) return false;</pre>
69
        if (n == 2) return true;
70
71
        if ((n & 1) == 0) return false;
72
        ll x = n - 1, t = 0;
73
        while ((x & 1) == 0) {
74
             x >>= 1;
75
            ++t;
        }
76
77
        for (int i = 0; i < S; ++i) {</pre>
            ll a = rand() % (n - 1) + 1;
78
79
             if (check(a, n, x, t))
80
                 return false;
81
        }
        return true;
82
83
    }
84
    // find factors
    vector<ll> factor;
85
86
    ll Pollard_rho(ll x, ll c) {
87
        ll i = 1, k = 2;
        ll x0 = rand() % x;
88
89
        ll y = x0;
        while (true) {
91
            ++i;
92
            x0 = (mod_mult(x0, x0, x) + c) % x;
93
            ll d;
            if (y == x0) d = 1;
94
95
             else
                 if (y > x0)
96
                     d = gcd(y - x0, x);
97
98
                 else d = gcd(x0 - y, x);
99
             if (d != 1 && d != x) return d;
            if (y == x0) return x;
             if (i == k) {
101
102
                 y = x0;
                 k += k;
            }
104
        }
105
106
   void find_factor(ll n) {
    if (n == 1) return ;
```

```
if (Miller_Rabin(n)) {
109
110
             factor.push_back(n);
111
             return ;
        }
112
        ll p = n;
113
114
        while (p >= n) p = Pollard_rho(p, rand() % (n - 1) + 1);
115
        find_factor(p);
116
        find_factor(n / p);
117
    }
```

```
#include<bits/stdc++>
   //Meisell-Lehmer
3 const int MAX_N = 5e6 + 2;
4 bool np[MAX_N];
   int prime[MAX_N], pi[MAX_N];
6
   int getprime() {
7
       int cnt = 0;
8
       np[0] = np[1] = true;
9
       pi[0] = pi[1] = 0;
       for(int i = 2; i < MAX_N; ++i) {</pre>
10
11
            if(!np[i]) prime[++cnt] = i;
12
            pi[i] = cnt;
            for(int j = 1; j <= cnt && i * prime[j] < MAX_N; ++j) {</pre>
13
                np[i * prime[j]] = true;
14
                if(i % prime[j] == 0) break;
            }
16
17
       }
18
       return cnt;
19 }
20 const int M = 7;
21 const int PM = 2 * 3 * 5 * 7 * 11 * 13 * 17;
   int phi[PM + 1][M + 1], sz[M + 1];
23
   void init() {
24
       getprime();
25
       sz[0] = 1;
26
       for(int i = 0; i <= PM; ++i) phi[i][0] = i;</pre>
       for(int i = 1; i <= M; ++i) {</pre>
27
28
            sz[i] = prime[i] * sz[i - 1];
            for(int j = 1; j <= PM; ++j) phi[j][i] = phi[j][i - 1] - phi[j /</pre>
                prime[i]][i - 1];
30
       }
31 }
32 int sqrt2(ll x) {
```

```
ll r = (ll) sqrt(x - 0.1);
33
34
       while(r * r <= x)
35
       return int(r - 1);
36
   }
   int sqrt3(ll x) {
37
38
       ll r = (ll)cbrt(x - 0.1);
39
       while(r * r * r <= x) ++r;
       return int(r - 1);
40
41
   }
   ll getphi(ll x, int s) {
42
       if(s == 0) return x;
43
       if(s <= M) return phi[x % sz[s]][s] + (x / sz[s]) * phi[sz[s]][s];</pre>
44
45
       if(x <= prime[s]*prime[s]) return pi[x] - s + 1;</pre>
       if(x <= prime[s]*prime[s] *& x < MAX_N) {</pre>
46
47
            int s2x = pi[sqrt2(x)];
            ll ans = pi[x] - (s2x + s - 2) * (s2x - s + 1) / 2;
48
            for(int i = s + 1; i <= s2x; ++i) ans += pi[x / prime[i]];</pre>
49
50
            return ans;
51
52
       return getphi(x, s - 1) - getphi(x / prime[s], s - 1);
53
   }
   ll getpi(ll x) {
54
       if(x < MAX_N)
55
                        return pi[x];
56
       ll ans = getphi(x, pi[sqrt3(x)]) + pi[sqrt3(x)] - 1;
       for(int i = pi[sqrt3(x)] + 1, ed = pi[sqrt2(x)]; i \le ed; ++i) ans
           -= getpi(x / prime[i]) - i + 1;
58
       return ans;
59
   }
   ll lehmer_pi(ll x) {
60
61
       if(x < MAX_N)
                        return pi[x];
       int a = (int)lehmer_pi(sqrt2(sqrt2(x)));
62
       int b = (int)lehmer_pi(sqrt2(x));
63
64
       int c = (int)lehmer_pi(sqrt3(x));
       ll sum = getphi(x, a) + (ll)(b + a - 2) * (b - a + 1) / 2;
65
       for (int i = a + 1; i <= b; i++) {
66
67
            ll w = x / prime[i];
68
            sum -= lehmer_pi(w);
            if (i > c) continue;
69
            ll lim = lehmer_pi(sqrt2(w));
70
            for (int j = i; j <= lim; j++) sum -= lehmer_pi(w / prime[j]) -</pre>
               (j - 1);
72
       }
73
       return sum;
```

```
74  }
75  int main() {
76    init();
77    ll n;
78    while(~scanf("%lld",&n)) {
79        printf("%lld\n",lehmer_pi(n));
80    }
81    return 0;
82  }
```

```
// 欧拉函数
   int euler_phi(int n) {
3
        int res = n;
4
        for (int i = 2; i * i <= n; ++i) {</pre>
5
            if (n % i == 0) {
6
                res = res / i * (i - 1);
                for (; n % i == 0; n /= i);
            }
8
9
10
        if (n != 1) res = res / n * (n - 1);
11
        return res;
12
   }
13
   int euler[MAX_N];
14
   void euler_phi_sieve() {
        for (int i = 0; i < MAX_N; ++i) euler[i] = i;</pre>
15
        for (int i = 2; i < MAX_N; ++i)</pre>
16
17
            if (euler[i] == i)
                 for (int j = i; j < MAX_N; j += i) euler[j] = euler[j] / i *</pre>
                     (i - 1);
19
   }
```

• Moebius 如果

$$F(n) = \sum_{d \mid n} f(d)$$

,则

$$f(n) = \sum_{d \mid n} \mu(d) F(\frac{n}{d})$$

对于  $\mu(d)$  函数,有如下性质:

$$\sum_{d\mid n}\mu(d)=\begin{cases} 1 & \text{n = 1}\\ 0 & \text{n > 1} \end{cases}$$

$$\sum_{d|n} \frac{\mu(d)}{d} = \frac{\phi(n)}{n}$$

```
int mu[MAX_N];
   void moebius() {
3
        int cnt = 0; mu[1] = 1;
        memset(vis, 0, sizeof vis);
4
        for (int i = 2; i < MAX_N; ++i) {</pre>
5
            if (!vis[i]) {
6
7
                 prime[cnt++] = i;
8
                 mu[i] = -1;
            }
9
            for (int j = 0; j < cnt && i * prime[j] < MAX_N; ++j) {</pre>
10
11
                 vis[i * prime[j]] = true;
                 if (i % prime[j])
12
13
                     mu[i * prime[j]] = -mu[i];
14
                 else
15
                     mu[i * prime[j]] = 0, break;
            }
16
       }
17
18
19
   map<int, int> moebius(int n) {
20
        map<int, int> res;
21
        vector<int> primes;
        for (int i = 2; i * i <= n; ++i) {</pre>
22
23
            if (n % i == 0) {
24
                 primes.push_back(i);
25
                 while (n % i == 0) n /= i;
            }
26
        }
27
28
        if (n != 1) primes.push_back(n);
29
        int m = primes.size();
        for (int i = 0; i < (1 << m); ++i) {</pre>
31
            int mu = 1, d = 1;
            for (int j = 0; j < m; ++j) {</pre>
32
                 if (i >> j & 1) {
34
                     mu *= -1;
35
                     d *= primes[j];
36
37
            }
38
            res[d] = mu;
39
```

```
40    return res;
41 }
```

```
// Guass_jordan
   const double eps = 1e-8;
   typedef vector<double> vec;
   typedef vector<vec> mat;
   vec gauss_joedan(const mat &A, const vec& b) {
        int n = A.size();
6
7
        mat B(n, vec(n + 1));
        for (int i = 0; i < n; ++i)</pre>
8
9
             for (int j = 0; j < n; ++j) B[i][j] = A[i][j];</pre>
10
        for (int i = 0; i < n; ++i) B[i][n] = b[i];</pre>
        for (int i = 0; i < n; ++i) {</pre>
11
            int pivot = i;
12
            for (int j = i; j < n; ++j)</pre>
13
                 if (abs(B[j][i]) > abs(B[pivot][i])) pivot = j;
14
15
            if (i != pivot) swap(B[i], B[pivot]);
            if (abs(B[i][i]) < eps) return vec();</pre>
16
            for (int j = i + 1; j <= n; ++j) B[i][j] /= B[i][i];</pre>
17
18
             for (int j = 0; j < n; ++j) if (i != j)</pre>
19
                 for (int k = i + 1; k <= n; ++k) B[j][k] -= B[j][i] * B[i][k</pre>
                     ];
20
        }
21
        vec x(n);
        for (int i = 0; i < n; ++i) x[i] = B[i][n];</pre>
22
23
        return x;
24
   }
25
   vec gauss_joedan_xor(const mat& A, const vec& b) {
26
        int n = A.size();
27
        mat B(n, vec(n + 1));
28
        for (int i = 0; i < n; ++i)</pre>
             for (int j = 0; j < n; ++j) B[i][j] = A[i][j];</pre>
29
        for (int i = 0; i < n; ++i) B[i][n] = b[i];</pre>
31
        for (int i = 0; i < n; ++i) {</pre>
            int pivot = i;
32
             for (int j = i; j < n; ++j)</pre>
34
                 if (B[j][i]) {
35
                      pivot = j;
36
                      break;
37
38
            if (pivot != i) swap(B[i], B[pivot]);
39
```

```
for (int j = 0; j < n; ++j) if (i != j && B[j][i])</pre>
40
41
                      for (int k = i + 1; k <= n; ++k) B[j][k] ^= B[i][k];</pre>
                  }
42
43
        }
        vec x(n);
44
45
        for (int i = 0; i < n; ++i) x[i] = B[i][n];</pre>
46
        return x;
47
   }
```

# 7 String

1. Hash 2. KMP 3. Extend KMP 4. trie 树 poj2001 2503 3630 1056 hdu 1075 1251 1247 1298 1671 5. Manacher 算法 6. AC 自动机 7. 后缀数组 8. 后缀树 9. 后缀自动机 10. 回文自动机

```
// 最小最大表示法:
   int getMinString(const string &s) {
3
       int len = (int)s.length();
       int i = 0, j = 1, k = 0;
4
       while(i < len && j < len && k < len) {</pre>
5
            int t = s[(i + k) % len] - s[(j + k) % len];
7
            if(t == 0) k++;
8
            else {
9
                if(t > 0) i += k + 1;//getMaxString: t < 0</pre>
                else j += k + 1;
10
                if(i == j) j++;
11
                k = 0;
12
13
            }
14
       }
15
       return min(i, j);
16
   }
```

```
// KMP
  int nxt[MAX_N];
3
  void getNext(const string &str) {
       int len = str.length();
4
5
      int j = 0, k;
       k = nxt[0] = -1;
6
7
      while (j < len) {</pre>
           if (k == -1 || str[j] == str[k])
8
9
               nxt[++j] = ++k;
```

```
else k = nxt[k];
11
        }
12
   }
13
   int kmp(const string &tar, const string &pat) {
14
        getNext(pat);
15
        int num, j, k;
        int lenT = tar.length(), lenP = pat.length();
16
17
        num = j = k = 0;
        while (j < lenT) {</pre>
18
19
            if(k == -1 || tar[j] == pat[k])
20
                 j++, k++;
21
            else k = nxt[k];
             if(k == lenP) {
22
23
                 // \text{ res} = \max(\text{res}, j - \text{lenP});
24
                 k = nxt[k];
25
                 ++num;
26
            }
27
        }
        return num;//lenP - res - 1;
28
29 }
```

```
// Suffix Array & LCP Array
2
   int n, k;
3 int lcp[MAX_N], sa[MAX_N];
4 int rnk[MAX_N], tmp[MAX_N];
   bool compare_sa(int i, int j) {
6
        if (rnk[i] != rnk[j]) return rnk[i] < rnk[j];</pre>
7
            int ri = i + k <= n? rnk[i + k] : -1;</pre>
8
9
            int rj = j + k <= n? rnk[j + k] : -1;</pre>
10
            return ri < rj;</pre>
11
       }
12
13
   void construct_sa(string S, int *sa) {
14
        n = S.length();
15
        for (int i = 0; i <= n; i++) {</pre>
            sa[i] = i;
16
            rnk[i] = i < n? S[i] : -1;
17
18
        }
19
        for (k = 1; k <= n; k *= 2) {
20
            sort(sa, sa + n + 1, compare_sa);
21
            tmp[sa[0]] = 0;
22
            for (int i = 1; i <= n; i++)</pre>
```

```
tmp[sa[i]] = tmp[sa[i - 1]] + (compare_sa(sa[i - 1], sa[i])
23
                    ? 1 : 0);
            memcpy(rnk, tmp, sizeof(int) * (n + 1));
24
25
       }
26
   void construct_lcp(string S, int *sa, int *lcp) {
27
28
       int n = S.length();
29
       for (int i = 0; i <= n; i++) rnk[sa[i]] = i;</pre>
       int h = 0;
31
       lcp[0] = 0;
       for (int i = 0; i < n; i++) {</pre>
32
33
            int j = sa[rnk[i] - 1];
34
            if (h > 0) h--;
            for (; j + h < n && i + h < n; h++)
36
                if (S[j + h] != S[i + h]) break;
37
            lcp[rnk[i] - 1] = h;
38
       }
39
   }
```

```
// AC 自动机
   int ans[MAX_N], d[MAX_N];
3
   struct Trie {
4
        int nxt[MAX_N][26], fail[MAX_N], end[MAX_N];
5
        int root, L;
        int newnode() {
6
 7
            for(int i = 0; i < 26; i++)</pre>
8
                nxt[L][i] = -1;
9
            end[L++] = 0;
10
            return L-1;
11
        }
        void init() {
12
13
            L = 0;
14
            root = newnode();
15
16
        void insert(char buf[]) {
17
            int len = strlen(buf);
            int now = root;
18
            for(int i = 0; i < len; i++) {</pre>
19
20
                if(nxt[now][buf[i]-'a'] == -1)
21
                     nxt[now][buf[i]-'a'] = newnode();
                now = nxt[now][buf[i]-'a'];
22
23
            }
24
            end[now] = 1;
```

```
25
            d[now] = len;
26
27
        void build() {
28
            queue<int> Q;
29
            fail[root] = root;
            for(int i = 0; i < 26; i++)</pre>
31
                 if(nxt[root][i] == -1)
                     nxt[root][i] = root;
32
                 else {
34
                     fail[nxt[root][i]] = root;
35
                     Q.push(nxt[root][i]);
                 }
36
            while( !Q.empty() ) {
37
                 int now = Q.front(); Q.pop();
38
39
                 for(int i = 0; i < 26; i++)
40
                     if(nxt[now][i] == -1)
                          nxt[now][i] = nxt[fail[now]][i];
41
42
                     else {
43
                          fail[nxt[now][i]] = nxt[fail[now]][i];
                          Q.push(nxt[now][i]);
44
                     }
45
46
            }
47
48
        void solve(char buf[]) {
            int cur = root;
50
            int len = strlen(buf);
51
            int index;
52
            for(int i = 0; i < len; ++i) {</pre>
                 if(buf[i] >= 'A' && buf[i] <= 'Z')</pre>
53
                     index = buf[i] - 'A';
54
                 else if(buf[i] >= 'a' && buf[i] <= 'z')</pre>
55
                     index = buf[i] - 'a';
57
                 else continue;
58
                 cur = nxt[cur][index];
                 int x = cur;
59
                 while(x != root) {
60
                     if(end[x]) {
61
                          ans[i + 1] -= 1;
62
                          ans[i - d[x] + 1] += 1;
63
64
                          break;
65
                     }
66
                     x = fail[x];
67
```

```
68 }
69 }
70 };
71 Trie ac;
```

### 8 Others

### 8.1 Divide-and-Conquer Tree

```
//uva 12161
   struct edge {
3
       int to, damage, length, next;
4 };
5 int G[MAX_N], En, N, M, T;
6 edge E[MAX_N * 2];
   void add_edge(int from, int to, int damage, int length) {
7
       edge e = {to, damage, length, G[from]};
9
       E[En] = e;
       G[from] = En++;
10
11 }
12 int ans, subtree_size[MAX_N];
13 bool flag[MAX_N];
14 int s, t;
15 Pii ds[MAX_N];
int compute_subtree_size(int v, int p) {
17
       int c = 1;
18
       for (int j = G[v]; ~j; j = E[j].next) {
           int w = E[j].to;
19
20
           if (w == p || flag[w]) continue;
21
           c += compute_subtree_size(w, v);
22
       }
23
       return subtree_size[v] = c;
24
25
   Pii search_centroid(int v, int p, int t) {
26
       Pii res = Pii(INT_MAX, -1);
27
       int s = 1, m = 0;
       for (int j = G[v]; ~j; j = E[j].next) {
28
29
           int w = E[j].to;
           if (w == p || flag[w]) continue;
```

```
31
            res = min(res, search_centroid(w, v, t));
32
            m = max(subtree_size[w], m);
            s += subtree_size[w];
34
35
        m = max(m, t - s);
        res = min(res, Pii(m, v));
37
        return res;
38
   }
39
   void enumrate_path(int v, int p, int damage, int length) {
40
        ds[t++] = Pii(damage, length);
        for (int j = G[v]; ~j; j = E[j].next) {
41
            int w = E[j].to;
42
43
            if (w == p || flag[w]) continue;
            if (damage + E[j].damage <= M) {</pre>
                enumrate_path(w, v, damage + E[j].damage, length + E[j].
                    length);
46
            }
        }
47
48
49
   void remove_useless(int s, int &t) {
        if (s == t) return;
50
51
        int tt;
        for (int i = tt = s + 1; i < t; i++) {
52
53
            if (ds[i].first == ds[tt - 1].first) continue;
            if (ds[i].second <= ds[tt - 1].second) continue;</pre>
55
            ds[tt++] = ds[i];
56
57
       t = tt;
58
59
   void solve_sub_problem(int v) {
60
        compute_subtree_size(v, -1);
        int c = search_centroid(v, -1, subtree_size[v]).second;
61
62
        flag[c] = true;
        for (int j = G[c]; ~j; j = E[j].next) {
63
64
            if (flag[E[j].to]) continue;
65
            solve_sub_problem(E[j].to);
        }
66
        s = t = 0;
67
        for (int j = G[c]; ~j; j = E[j].next) {
68
            int w = E[j].to;
69
70
            if (flag[w]) continue;
71
            if (E[j].damage <= M)</pre>
                enumrate_path(w, v, E[j].damage, E[j].length);
72
```

```
73
            if (s > 0) {
74
                sort(ds + s, ds + t);
75
                remove_useless(s, t);
                for (int l = 0, r = t - 1; l < s && r >= s; l++) {
76
                    while (r >= s && ds[l].first + ds[r].first > M) r--;
77
78
                    if (r >= s)
79
                        ans = max(ans, ds[l].second + ds[r].second);
80
                }
81
            }
82
           sort(ds, ds + t);
83
           remove_useless(0, t);
84
           s = t;
85
       flag[c] = false;
86
87 }
```