

# ECE4179 Final Project Brief

## Team members

Wong Zhi Wei 28326865, Ivan Chan Jing Ming 28325028, Eugene Low You Jun 28696492

## Title: Deep Reinforcement Learning for Playing Snake Game

### Background into the problem/Task you wish to explore

"The Snake" is a popular game created in 1997 being first introduced in Nokia Phones. The snake begins with a length 1 and increases its length by 1 after eating a "fruit". After that, a new randomized positioned fruit is generated on the game board. This has introduced a competitive environment between players. However, the problem lies with the limitation of the human as it requires a combination of spatial and mechanical skills.

Objectives for this project is:

- Outperform human performance/human benchmark on playing snake games.
- Developing a Deep Learning Model to effectively complete the game with the highest score.

### Brief overview of your proposed method/solution

The following model will adopt a Deep Q-Network (DQN) methodology:

The Q value is updated accordingly to the Bellman's equation, Q value is initialised with random weights. Initialize memory,  $D$  with capacity of  $N$ .

Epsilon-greedy,  $\epsilon$  initialised = 1.

For episode =  $[1, M]$ :

For  $i = [0, T]$ :

- 1) Get the current state,  $s_t$  (observation space).
- 2) With epsilon-greedy,  $\epsilon$ , select random action,  $a_t$ . Otherwise,  $a_t = \max_a Q^*(a)$ ,  $1 - \epsilon$ . So as the training goes on, the random action would minimize and relies more on its learnt network. (Exploration or Exploitation)
- 3) Execute  $a_t$  and snake will move according to the  $a_t$ . Reward,  $r_t$  is given and the new state,  $s_{t+1}$  is captured.
- 4) Stores the  $a_t, s_t, s_{t+1}$  and  $r_t$  into the memory,  $D$ . Update the stack of the last 4 frames.
- 5) Sample random minibatch of transition  $(s_{t+1}, a_t, s_t, r_t)$  from  $D$ . (Replay Memory)
- 6) Then update Q-value,  $Q_{NEW} = y_i$  according to the Bellman's equation. But if the game ended at  $s_{t+1}, y_i = r_i$ .
- 7) Back propagation:  $Loss = MSE(Q_i - y_i)$  or  $\frac{1}{N} \sum_{i=0}^{N-1} (Q_i - y_i)^2$  where  $y_i = Q_{NEW}$

As for Step 5, after storing the experiences into the memory buffer,  $D$  with enough experiences, then sample a random batch of experiences from the memory buffer [1-6].

### Initial research conducted

Initial possible algorithm patterns [7]:

- Best search distance =  $|p1-p2| + |q1-q2|$ , the distance of the snake head and fruit.
- Greedy best first search.

## **Proposed datasets/training environments**

Proposed dataset: States from each frame when running "The Snake" from Pygame modules.

Proposed training environment: "The Snake" from pygame

## **References:**

- [1] V. M. and K. K. , "Playing Atari with Deep Reinforcement Learning," *DeepMind Technologies*, pp. 1-9, 2013.
  
- [2] M. C. "towards data science," 15 November 2018. [Online]. Available: <https://towardsdatascience.com/how-to-teach-an-ai-to-play-games-deep-reinforcement-learning-28f9b920440a>. [Accessed 20 April 2021].
  
- [3] "DeepLizard," 1 December 2018. [Online]. Available: <https://deeplizard.com/learn/video/0bt0SjbS3xc>. [Accessed 25 April 2021].
  
- [4] J. T. "towardsdatascience," 16 August 2020. [Online]. Available: <https://towardsdatascience.com/deep-q-network-dqn-ii-b6bf911b6b2c>. [Accessed 25 April 2021].
  
- [5] "DeepLizard," 3 November 2018. [Online]. Available: [https://deeplizard.com/learn/video/Bcuj2fTH4\\_4](https://deeplizard.com/learn/video/Bcuj2fTH4_4). [Accessed 25 April 2021].
  
- [6] freeCodeCamp.org, "An introduction to Deep Q-Learning: let's play Doom," *freeCodeCamp.org*, Mar. 29,2018. [Online]. Available: <https://www.freecodecamp.org/news/an-introduction-to-deep-q-learning-lets-play-doom-54d02d8017d8/>. [Accessed 30 Apr 2021].
  
- [7] S. Sharma, S. Mishra, N. Deodhar, A. Katageri, and P. Sagar, "Solving The Classic Snake Game Using AI", 2019.