

Continuum Mechanics Equations

General:

1.Kinematics – describing deformation and velocity without considering forces

2.Dynamics – equations that describe force balance, conservation of linear and angular momentum

3.Thermodynamics – relations temperature, heatflux, stress, entropy

Material-specific

4.Constitutive equations – relations describing how material properties vary as a function of T,P, stress,.... Such material properties govern dynamics (e.g., *density*), response to stress (*viscosity, elastic parameters*), heat transport (*thermal conductivity, heat capacity*)

Rheology

$$\text{deformation } (\epsilon) = \text{rheology} \cdot \text{stress } (\sigma)$$

material response to stress, depends on
material, P,T, time, deformation
history, environment (volatiles,
water)

- *elastic*
- *viscous*
- *brittle*
- *plastic*

- experiments under simple stress conditions
⇒ strain evolution under constant stress,
stress-strain rate diagrams
- thermodynamics + experimental parameters
- ab-initio calculations

Recap Fluid - Solid

- What is a solid?

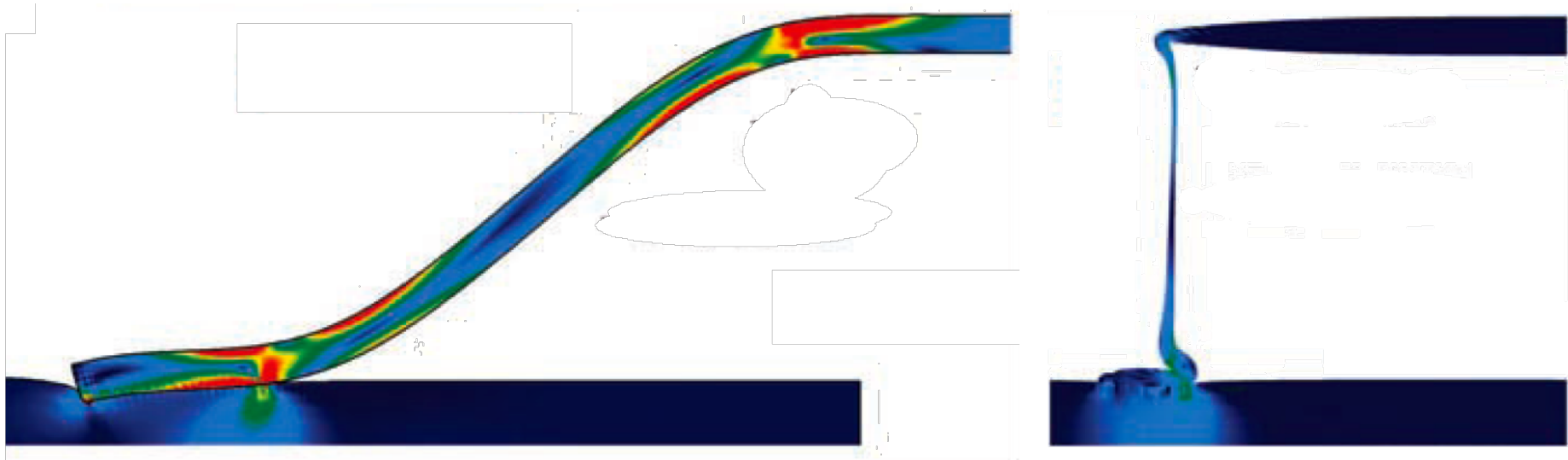
A solid acquires finite deformation under stress

stress $\sigma \sim \text{strain } \varepsilon$

- What is a fluid?

A material that flows in response to applied stress

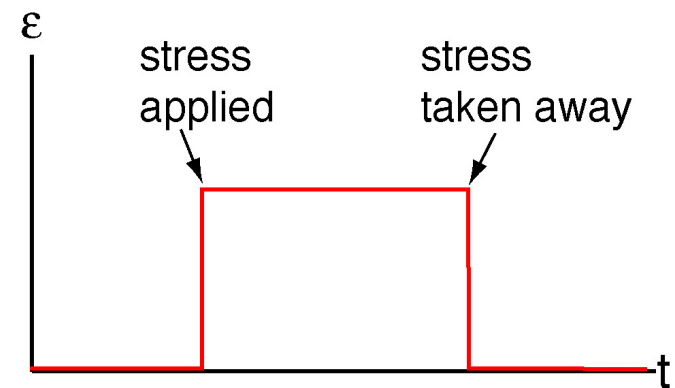
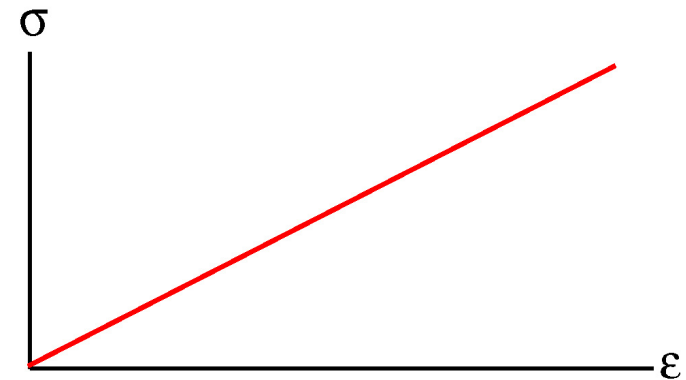
stress $\sigma \sim \text{strain rate } D\varepsilon/Dt$



Figures from Funiciello et al. (2003a)

Elasticity

- linear response to load applied
- instantaneous
- completely recoverable
- below threshold (yielding) stress
- *dominates behaviour of coldest part of tectonic plates on time scales of up to 100 m.y. -> fault loading*
- *on time scale of seismic waves the whole Earth is elastic*
- $\sigma_{ij} = C_{ijkl}\epsilon_{kl}$ - Hooke's law
 C_{ijkl} - rank 4 elasticity tensor
 3^4 elements, up to 21 independent



Elasticity tensor

C_{ijkl} $3^4=81$ elements (for $n=3$)

- symmetry of σ_{ij} and ε_{kl}
 \Rightarrow only 36 independent elements

Why 36?

Elasticity tensor

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- symmetry of σ_{ij} and ε_{kl}
 \Rightarrow only 36 independent elements

$$P = \sigma : \mathbf{D} \approx \sigma : \mathbf{D} \varepsilon / Dt = D U / Dt$$

- conservation of elastic energy $U = \sigma : \varepsilon = \mathbf{C} : \varepsilon : \varepsilon \geq 0$

$$\Rightarrow C_{ijkl} = C_{klij}$$

\Rightarrow only 21 independent elements - most general form of \mathbf{C}

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$$\left. \begin{array}{lll} C_{1111} & C_{2222} & C_{3333} \\ C_{1212} & C_{1313} & C_{2323} \end{array} \right\} \begin{array}{l} 6 \text{ symmetric} \\ [36 - 6] / 2 = 15 \end{array}$$

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- other symmetries further reduce the number of independent elements

Elasticity tensor

- for example for *isotropic* media

Only 2 independent elements (λ, μ):

$$\begin{aligned}\sigma_{ij} &= \lambda \delta_{ij} \delta_{kl} \varepsilon_{kl} + \alpha \delta_{ik} \delta_{jl} \varepsilon_{kl} + \beta \delta_{il} \delta_{jk} \varepsilon_{kl} \\ &= \lambda \delta_{ij} \varepsilon_{kk} + \alpha \varepsilon_{ij} + \beta \varepsilon_{ji} \\ &= \lambda \delta_{ij} \theta + (\alpha + \beta) \varepsilon_{ij}\end{aligned}$$

$$\Rightarrow \sigma_{ij} = \lambda \theta \delta_{ij} + 2\mu \varepsilon_{ij}$$

What is isotropic?

3 isotropic rank

4 tensors:

$$\delta_{ij} \delta_{kl}, \delta_{ik} \delta_{jl}, \delta_{il} \delta_{jk}$$

Hooke's law for isotropic material: 2 independent coefficients

Lamé constants

λ and μ : $\sigma_{ij} = \lambda \varepsilon_{kk} \delta_{ij} + 2\mu \varepsilon_{ij}$

Bulk and shear modulus

K and $\mu=G$: $\sigma_{ij} = -p\delta_{ij} + \sigma'_{ij}$

where: $-p = \frac{\sigma_{kk}}{3} = \left(\lambda + \frac{2}{3}\mu \right) \theta = K\theta$

$\sigma'_{ij} = \cancel{\lambda\theta\delta_{ij}} + 2\mu\varepsilon_{ij} + p\delta_{ij} = 2\mu\varepsilon'_{ij}$

hydrostatic

deviatoric



$-\left(\cancel{\lambda} + \frac{2}{3}\mu\right)\theta\delta_{ij}$

$2\mu \underbrace{\left(\varepsilon'_{ij} - \frac{\theta}{3} \delta_{ij} \right)}_{\varepsilon'_{ij}}$

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hydrostatic

deviatoric

Young's modulus and Poisson's ratio

\mathbf{E} and ν : $E = \sigma_{11}/\varepsilon_{11}$, $\nu = -\varepsilon_{33}/\varepsilon_{11}$ (uniaxial stress)

Determine in problem set

Wave equation

For infinitesimal deformation:

spatial coordinates \approx material coordinates

$$v_i \text{ (spatial)} \approx \partial u_i / \partial t$$

$$a_i \text{ (spatial)} \approx \partial v_i / \partial t = \partial^2 u_i / \partial t^2$$

$$\text{Equation of motion: } f_i + \partial \sigma_{ji} / \partial x_j = \rho \partial^2 u_i / \partial t^2 \quad (1)$$

$$\text{Elastic rheology: } \sigma_{ij} = \lambda \varepsilon_{kk} \delta_{ij} + 2\mu \varepsilon_{ij} \quad (2)$$

Substitute (2) in (1) if (infinitesimal) deformation is consequence of force balance

Wave equation

Equation of motion: $f_i + \partial \sigma_{ji} / \partial x_j = \rho \partial^2 u_i / \partial t^2$

Elastic rheology: $\sigma_{ij} = \lambda \varepsilon_{kk} \delta_{ij} + 2\mu \varepsilon_{ij}$

$$\begin{aligned} \partial \sigma_{ji} / \partial x_j &= \lambda \partial \varepsilon_{kk} / \partial x_i + \mu \partial (\partial u_i / \partial x_j + \partial u_j / \partial x_i) / \partial x_j \\ &= \lambda \partial (\partial u_k / \partial x_k) / \partial x_i + \mu \partial^2 u_i / \partial^2 x_j + \mu \partial (\partial u_j / \partial x_j) / \partial x_i \end{aligned}$$

$\nabla \cdot \sigma =$ **Write vector equation**

Using: $\nabla^2 \mathbf{u} = \nabla(\nabla \cdot \mathbf{u}) - \nabla \times \nabla \times \mathbf{u}$

\Rightarrow $\rho \partial^2 \mathbf{u} / \partial t^2 = \mathbf{f} + (\lambda + 2\mu) \nabla(\nabla \cdot \mathbf{u}) - \mu \nabla \times \nabla \times \mathbf{u}$

what type of deformation do the two terms represent?

Wave equation

Equation of motion: $\mathbf{f}_i + \partial \sigma_{ji} / \partial x_j = \rho \partial^2 u_i / \partial t^2$

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$$\begin{aligned} \partial \sigma_{ji} / \partial x_j &= \lambda \partial \varepsilon_{kk} / \partial x_i + \mu \partial (\partial u_i / \partial x_j + \partial u_j / \partial x_i) / \partial x_j \\ &= \lambda \partial (\partial u_k / \partial x_k) / \partial x_i + \mu \partial^2 u_i / \partial^2 x_j + \mu \partial (\partial u_j / \partial x_j) / \partial x_i \end{aligned}$$

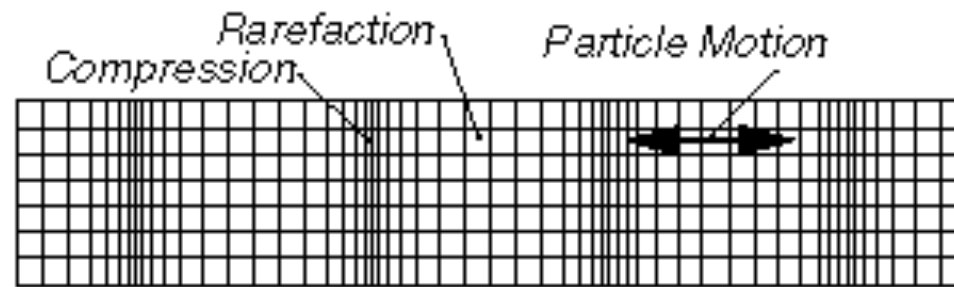
$$\nabla \cdot \boldsymbol{\sigma} = (\lambda + \mu) \nabla (\nabla \cdot \mathbf{u}) + \mu \nabla^2 \mathbf{u}$$

Using: $\nabla^2 \mathbf{u} = \nabla (\nabla \cdot \mathbf{u}) - \nabla \times \nabla \times \mathbf{u}$

$$\Rightarrow \boxed{\rho \partial^2 \mathbf{u} / \partial t^2 = \mathbf{f} + (\lambda + 2\mu) \nabla (\nabla \cdot \mathbf{u}) - \mu \nabla \times \nabla \times \mathbf{u}}$$

what type of deformation do the two terms represent?

P wave



Travel Direction →

S wave

