

# Recap Fluid - Solid

- What is a solid?

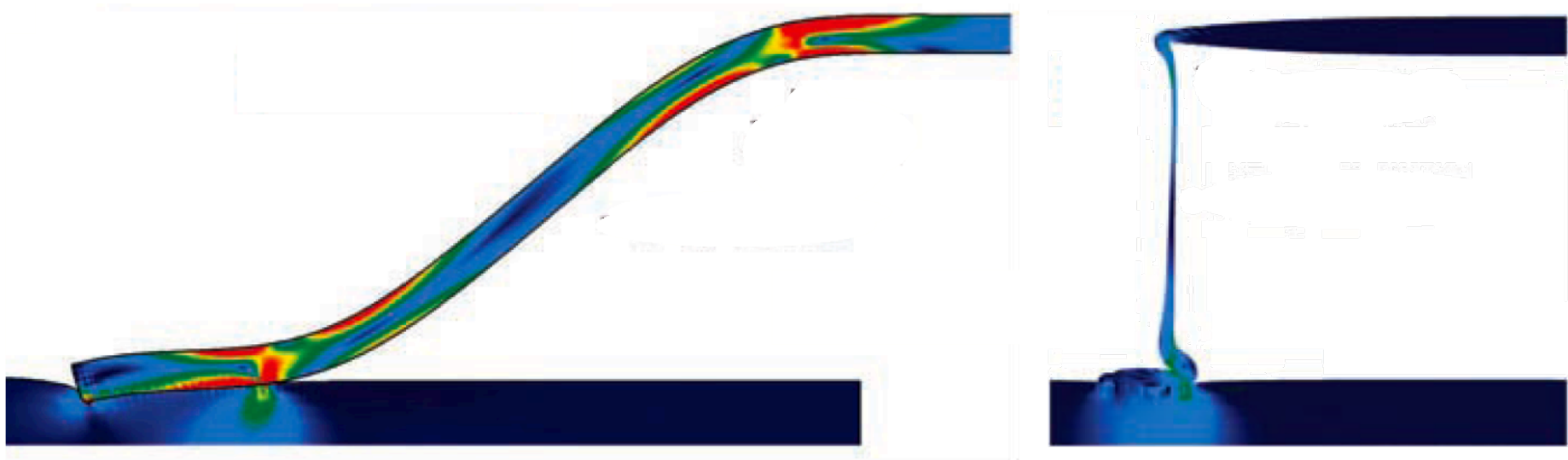
A solid acquires finite deformation under stress

*stress  $\sigma \sim \text{strain } \varepsilon$*

- What is a fluid?

A material that flows in response to applied stress *stress*

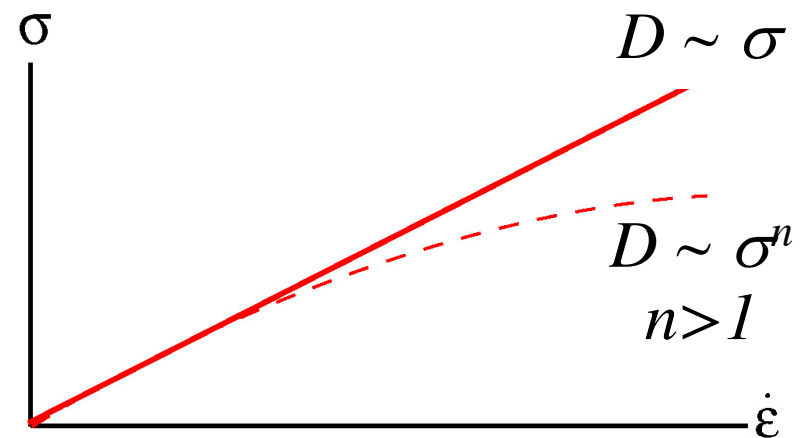
*$\sigma \sim \text{strain rate } D\varepsilon/Dt$*



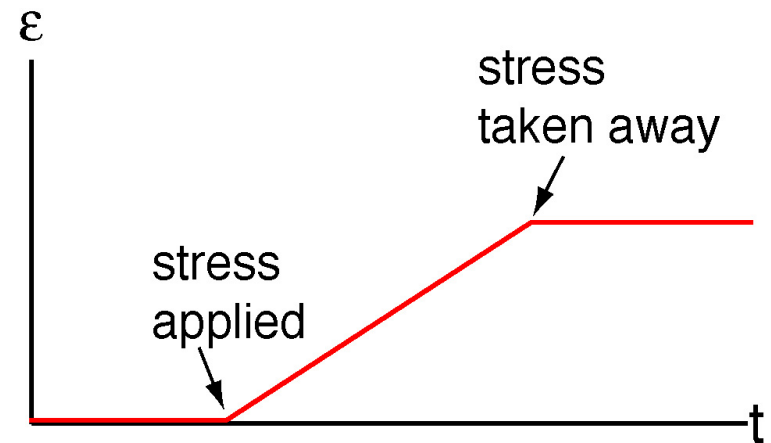
*Figures from Funiciello et al. (2003a)*

# Viscous Flow

- steady state flow at constant stress
- permanent deformation
- linear (Newtonian) or non-linear (e.g., Powerlaw) relation between strain rate and stress
- isotropic stress does not cause flow
- *on timescales > years base tectonic plates and mantle deform predominantly viscously -> plate motions, postseismic deformation, but also glaciers, magmas*



$$\dot{\epsilon} = \frac{\partial \epsilon}{\partial t}$$



# Hydrostatics

Fluids can not support shear stresses

i.e. if in rest/rigid body motion:  $\boldsymbol{\sigma} \cdot \hat{\mathbf{n}} = \lambda \hat{\mathbf{n}}$   
and this normal stress is the same on any plane:  $\boldsymbol{\sigma} = -p\mathbf{I}$

$p$  is *hydrostatic pressure*

In force balance:  $\nabla \cdot \boldsymbol{\sigma} + \mathbf{f} = 0$   
 $-\nabla p = -\mathbf{f}$

In gravity field  $\frac{\partial p}{\partial z} = \rho g \quad \Rightarrow \quad p_2 - p_1 = \rho g h$

# Newtonian Fluids

In general motion:  $\boldsymbol{\sigma} = -p\mathbf{I} + \boldsymbol{\sigma}'$

In Newtonian fluids,  
deviatoric stress varies *linearly* with *strain rate*,  $\mathbf{D}$

$$D_{ij} = (\partial v_i / \partial x_j + \partial v_j / \partial x_i) / 2$$

For *isotropic*, Newtonian fluids, 2 *material parameters*:

$$\text{Viscous stress tensor } \sigma'_{ij} = -\zeta D_{kk} \delta_{ij} + 2\eta D_{ij}$$

where  $\zeta$  is *bulk viscosity* and  $\eta$  (*shear*) *viscosity*,  $\Delta = D_{kk} = \nabla \cdot \mathbf{v}$

$$\boldsymbol{\sigma} = (-p + \zeta \Delta) \mathbf{I} + 2\eta \mathbf{D}$$

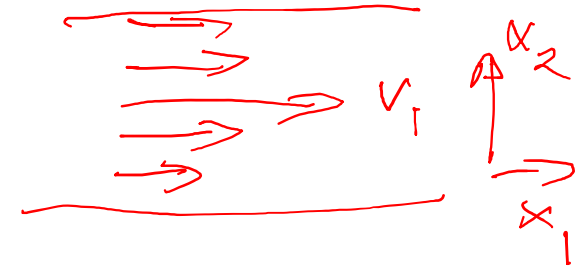
$p$  not always mean normal stress:  $\sigma_{kk} = -3p + (3\zeta + 2\eta) D_{kk}$

Consider a Newtonian shear flow with  
velocity field  $v_1(x_2)$ ,  $v_2=v_3=0$

What is  $\mathbf{D}$ ? What is  $\boldsymbol{\sigma}$ ?

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velocity field  $v_1(x_2)$ ,  $v_2=v_3=0$

What is  $\mathbf{D}$ ? What is  $\boldsymbol{\sigma}$ ?



$$D_{11}=D_{22}=D_{33}=0$$

$$\sigma_{11}=\sigma_{22}=\sigma_{33}=-p$$

$$D_{12}=D_{21}= \frac{1}{2} \frac{\partial v_1}{\partial x_2}$$

$$\sigma_{12}=\sigma_{21}= \eta \frac{\partial v_1}{\partial x_2}$$

$$D_{13}=D_{31}=D_{23}=D_{32}=0$$

$$\sigma_{13}=\sigma_{31}=\sigma_{23}=\sigma_{32}=0$$

Illustrates that  $\eta$  represents resistance to shearing

# Navier-Stokes for incompressible Newtonian Flow

For incompressible fluids  $\Delta=0$ , so that:  $\boldsymbol{\sigma} = -p\mathbf{I} + 2\eta\mathbf{D}$

Force balance:  $\nabla \cdot \underline{\underline{\boldsymbol{\sigma}}} + \mathbf{f} = \rho \frac{D\mathbf{v}}{Dt}$   $\nabla \cdot \vec{v} = 0$

Show that:  $\frac{\partial \sigma_{ij}}{\partial x_j} = -\frac{\partial p}{\partial x_i} + \eta \frac{\partial^2 v_i}{\partial x_j \partial x_j}$  Assuming  
constant  $\eta$

$$\nabla \cdot \underline{\underline{\boldsymbol{\sigma}}} = -\nabla p + \eta \nabla^2 \mathbf{v}$$

# Navier-Stokes for incompressible Newtonian Flow

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Force balance:  $\nabla \cdot \underline{\underline{\boldsymbol{\sigma}}} + \mathbf{f} = \rho \frac{D\mathbf{v}}{Dt}$

Show that:  $\frac{\partial \sigma_{ij}}{\partial x_j} = -\frac{\partial p}{\partial x_i} + \eta \frac{\partial^2 v_i}{\partial x_j \partial x_j}$  Assuming constant  $\eta$

$$\sigma_{ij} = -p\delta_{ij} + \eta \left( \frac{\partial v_i}{\partial x_j} + \frac{\partial v_j}{\partial x_i} \right)$$

$$\frac{\partial \sigma_{ij}}{\partial x_j} = -\frac{\partial p}{\partial x_i} + \eta \left( \frac{\partial^2 v_i}{\partial x_j \partial x_j} + \cancel{\frac{\partial^2 v_j}{\partial x_i \partial x_j}} \right)$$

Because  $\frac{\partial v_j}{\partial x_j} = \Delta = 0$

$$\nabla \cdot \underline{\underline{\boldsymbol{\sigma}}} = -\nabla p + \eta \nabla^2 \mathbf{v}$$



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Force balance:  $\nabla \cdot \underline{\underline{\boldsymbol{\sigma}}} + \mathbf{f} = \rho \frac{D\mathbf{v}}{Dt}$

Navier Stokes equation of motion:

$$-\nabla p + \eta \nabla^2 \mathbf{v} + \mathbf{f} = \rho \left[ \frac{\partial \mathbf{v}}{\partial t} + \mathbf{v} \cdot \nabla \mathbf{v} \right] \quad \text{Assuming constant } \eta$$

Together with continuity, 4 equations, 4 unknowns ( $p, v_x, v_y, v_z$ )

$$\nabla \cdot \mathbf{v} = 0$$

# Navier-Stokes for compressible Newtonian Flow

$$\boldsymbol{\sigma} = (-p + \varsigma \Delta) \mathbf{I} + 2\eta \mathbf{D} \qquad \nabla \cdot \underline{\underline{\boldsymbol{\sigma}}} + \mathbf{f} = \rho \frac{D\mathbf{v}}{Dt}$$

Navier Stokes equation of motion:

$$-\nabla p + (\zeta + \eta) \nabla \Delta + \eta \nabla^2 \mathbf{v} + \mathbf{f} = \rho \left[ \frac{\partial \mathbf{v}}{\partial t} + \mathbf{v} \cdot \nabla \mathbf{v} \right] \quad \begin{array}{l} \text{Assuming} \\ \text{constant} \\ \zeta, \eta \end{array}$$

+ Conservation of mass:

$$\frac{D\rho}{Dt} + \rho \nabla \cdot \mathbf{v} = 0$$

6 equations

6 unknowns

$$(p, v_x, v_y, v_z, \rho, T)$$

+ Energy equation

+ Equation of state for  $\rho(T, p)$

# Continuum Mechanics Equations

## General:

1. Kinematics – describing deformation and velocity without considering forces

2. Dynamics – equations that describe force balance, conservation of linear and angular momentum

3. Thermodynamics – relations temperature, heatflux, stress, entropy

## Material-specific

4. Constitutive equations – relations describing how material properties vary as a function of T,P, stress,.... Such material properties govern dynamics (e.g., *density*), response to stress (*viscosity, elastic parameters*), heat transport (*thermal conductivity, heat capacity*)

# Learning Objectives

- Learn main conservation equations used in continuum mechanics modelling and understand what different terms in these equations represent
- Be able to solve conservation equations for basic analytical solutions given boundary/initial conditions.
- Understand basic properties of elastic and viscous rheology and understand how the choice of rheology leads to different forms of the momentum conservation equation
- Using tensor analysis to obtain relations between the main isotropic elastic parameters

# Outline

- Conservation equations
- Energy equation
- Rheology
- Elasticity and Wave Equation
- Newtonian Viscosity and Navier Stokes

*More reading on the topics covered in this lecture can be found in, for example: Lai et al. Ch 4.14-4-16, 6.18, Ch 5.1-5.6, Ch 6.1-6.7; Reddy parts of Ch 5 & Ch 6*

# Friday Coursework

- Released at 9:00, due at 11:00 with 30 minutes to upload (until 11:30)
  - Similar style to the class exercises from lectures 5 through 8
  - Understand material covered in lectures and slides, practise class exercises (with answers), plus old exam questions (no answers released)
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- Good luck!

# Outline of course

- 1. Mathematical essentials – *Matthew Piggott*
- 2. Linear Algebra I – *Matthew Piggott*
- 3. Linear Algebra II, ODEs– *Matthew Piggott*
- 4. Verifying models– *Matthew Piggott*
- 5. Vector and Tensor Calculus - *Saskia Goes*
- 6. Stress principles - *Saskia Goes*
- 7. Kinematics and strain - *Saskia Goes*
- 8. Rheology and conservation equations - *Saskia Goes*
- 9. Dimensional analysis - *Stephen Neethling*
- 10. Potential flow - *Stephen Neethling*
- 11. Fluid flow I - *Stephen Neethling*
- 12. Fluid flow & turbulence – *Stephen Neethling*