

1) $(\mathbb{R}^3, (\mathbb{R}^3, g_0), \Psi)$

$$g_0: \mathbb{R}^3 \times \mathbb{R}^3 \rightarrow \mathbb{R}, g_0(x, y) = x_1y_1 + x_2y_2 + x_3y_3$$

$$\Psi: \mathbb{R}^3 \times \mathbb{R}^3 \rightarrow \mathbb{R}^3, \Psi(u, v) = v - u$$

$$A(3, -1, 3), B(5, 1, -1), u = (-3, 5, -6)$$

a) ecuația dreptei \mathcal{D} a.i. $A \in \mathcal{D}, \Psi_{\mathcal{D}} = \{u\}$ b) ecuația dreptei AB c) puncte de intersecție ale dreptei \mathcal{D} cu planele de coordonate

$$a) \frac{x_1 - 3}{-3} = \frac{x_2 + 1}{5} = \frac{x_3 - 3}{-6} = t \Leftrightarrow \begin{cases} x_1 = -3t + 3 \\ x_2 = 5t - 1, t \in \mathbb{R} \\ x_3 = -6t + 3 \end{cases}$$

$$b) \vec{AB} = \Psi(A, B) = (5 - 3, 1 + 1, -1 - 3) = (2, 2, -4) = 2(1, 1, -2)$$

$$AB: \frac{x_1 - 3}{1} = \frac{x_2 + 1}{1} = \frac{x_3 - 3}{2} = t \Leftrightarrow \begin{cases} x_1 = t + 3 \\ x_2 = t - 1 \\ x_3 = 2t + 3 \end{cases}$$

$$c) O \times x_2 \cdot x_3 = 0$$

$$\mathcal{D} \cap O_{x_1 x_2} \Rightarrow x_3 = 0 \Rightarrow -6t + 3 = 0 \Rightarrow t = \frac{-3}{-6} = \frac{1}{2}$$

$$M\left(-3 \cdot \frac{1}{2} + 3, 5 \cdot \frac{1}{2} - 1, 0\right) \Rightarrow M\left(\frac{3}{2}, \frac{3}{2}, 0\right)$$

$$\mathcal{D} \cap O_{x_1 x_3} \Rightarrow x_2 = 0 \Rightarrow 5t - 1 = 0 \Rightarrow t = \frac{1}{5}$$

$$N\left(-3 \cdot \frac{1}{5} + 3, 0, -6 \cdot \frac{1}{5} + 3\right) \Rightarrow N\left(\frac{12}{5}, 0, \frac{9}{5}\right)$$

$$\mathcal{D} \cap O_{x_2 x_3} \Rightarrow x_1 = 0 \Rightarrow -3t + 3 = 0 \Rightarrow t = 1$$

$$Q(0, 4, -3)$$

2. $\mathcal{D} = ?$ a.i. $A(2, -5, 3) \in \mathcal{D}$, $\mathcal{D} \parallel \mathcal{D}'$

$$\mathcal{D}' \left\{ \begin{array}{l} 2x_1 - x_2 + 3x_3 + 1 = 0 \\ 5x_1 + 4x_2 - x_3 + 1 = 0 \end{array} \right. \quad (*)$$

Metoda 1:

$$N_1 = (2, -1, 3) \quad N_2 = (5, 4, -1)$$

$$u_{\mathcal{D}'} = N_1 \times N_2 = \begin{vmatrix} e_1 & e_2 & e_3 \\ 2 & -1 & 3 \\ 5 & 4 & -1 \end{vmatrix} = e_1 \begin{vmatrix} -1 & 3 \\ 4 & -1 \end{vmatrix} - e_2 \begin{vmatrix} 2 & 3 \\ 5 & -1 \end{vmatrix} + e_3 \begin{vmatrix} 2 & -1 \\ 5 & 4 \end{vmatrix}$$

$$= e_1 (1 - 12) - e_2 (-2 - 15) + e_3 (8 + 5) = (-11, 17, 13)$$

$$\mathcal{D} \parallel \mathcal{D}' \Leftrightarrow \mathcal{V}_{\mathcal{D}} = \mathcal{V}_{\mathcal{D}'} = \{u_{\mathcal{D}'}\}$$

$$\mathcal{D}: \frac{x_1 - 2}{-11} = \frac{x_2 + 5}{17} = \frac{x_3 - 3}{13} = t \quad \left\{ \begin{array}{l} x_1 = -11t + 2 \\ x_2 = 17t + 5 \\ x_3 = 13t + 3 \end{array} \right.$$

Metoda 2:

(*) sistem compatibil simplu nehomogen

$$x_3 = t$$

$$\left\{ \begin{array}{l} 2x_1 - x_2 = -1 - 3t \mid \cdot 4 \\ 5x_1 + 4x_2 = t - 1 \\ 8x_1 - 4x_2 = -4 - 12t \end{array} \right| \Rightarrow 13x_1 = -11t - 5$$

$$x_1 = \frac{-11t - 5}{13}$$

$$x_2 = \frac{2(-11t - 5) + 13 + 33t}{13} = \frac{17t + 30}{13}$$

$$\mathcal{D}' \therefore \left\{ \begin{array}{l} x_1 = \frac{-11}{13}t - \frac{5}{13} \\ x_2 = \frac{17}{13}t + \frac{30}{13} \\ x_3 = t \end{array} \right. \quad w = \left(\frac{-11}{13}, \frac{17}{13}, 1 \right) = \frac{1}{13}(-11, 17, 13)$$

$$\mathcal{D}_1: \begin{cases} x_1 + x_3 = 0 \\ x_2 - x_3 - 1 = 0 \end{cases}, \quad \mathcal{D}_2: \begin{cases} x_2 = 0 \\ x_3 = 0 \end{cases}$$

- a) $\mathcal{D}_1, \mathcal{D}_2$ - necoplanare
 b) ilustra perpendicularelor comune a dreptelor $\mathcal{D}_1, \mathcal{D}_2$
 c) dist ($\mathcal{D}_1, \mathcal{D}_2$)

a) $\mathcal{D}_1: \begin{cases} x_1 = -t \\ x_2 = t+1 \\ x_3 = t \end{cases} \Rightarrow \frac{x_1}{-1} = \frac{x_2-1}{1} = \frac{x_3}{1} = t$

$$u_1 = (-1, 1, 1)$$

$$A(0, 1, 0) \in \mathcal{D}_1$$

$$\mathcal{D}_2: \begin{cases} x_1 = s \\ x_2 = 0 \\ x_3 = 0 \end{cases}$$

$$u_2 = (1, 0, 0)$$

$$B(0, 0, 0) \in \mathcal{D}_2$$

$$\vec{AB} = (0, -1, 0)$$

$$\Delta = \begin{vmatrix} -1 & 1 & 0 \\ 1 & 0 & -1 \\ 1 & 0 & 0 \end{vmatrix} = \begin{vmatrix} 1 & 0 \\ 0 & -1 \end{vmatrix} = -1 \neq 0 \Rightarrow \mathcal{D}_1, \mathcal{D}_2 \text{ necoplanare}$$

$$\text{fie } P_1(-t, t+1, t) \in \mathcal{D}_1, P_2(1, 0, 0) \in \mathcal{D}_2$$

$$\vec{P_1 P_2} = (1+t, -t-1, -t) \quad \left\{ \begin{array}{l} g_0(\vec{P_1 P_2}, u_1) = 0 \\ g_0(\vec{P_1 P_2}, u_2) = 0 \end{array} \right.$$

$$\Leftrightarrow \begin{cases} -\lambda - x - x - 1 - x = 0 \\ \lambda + x = 0 \end{cases} \Leftrightarrow \begin{cases} -\lambda - 3x - 1 = 0 \\ \underline{\lambda + x = 0} \\ -2x = 1 \end{cases}$$

$$x = -\frac{1}{2}$$

$$\lambda = \frac{1}{2}$$

$$P_1 \left(\frac{1}{2}, \frac{1}{2}, -\frac{1}{2} \right) \quad P_2 \left(\frac{1}{2}, 0, 0 \right)$$

$$\overrightarrow{P_1 P_2} = \left(0, -\frac{1}{2}, \frac{1}{2} \right)$$

Q

$$P_1 P_2 \therefore \frac{x_1 - \frac{1}{2}}{0} = \frac{x_2}{-\frac{1}{2}} = \frac{x_3}{1} = t \Leftrightarrow \begin{cases} x_1 = \frac{1}{2} \\ x_2 = -t \\ x_3 = t \end{cases}$$

$$\text{dist } (\mathcal{D}_1, \mathcal{D}_2) - \text{dist } (P_1, P_2) =$$

$$\|\overrightarrow{P_1 P_2}\| = \sqrt{0 + \frac{1}{4} + \frac{1}{4}} = \frac{\sqrt{2}}{2}$$

Q h. $\mathcal{D}_1: \frac{x_1 - 1}{1} = \frac{x_2 - \frac{1}{2}}{-\frac{1}{2}} = \frac{x_3 + 2}{2}$

$$\mathcal{D}_2: \begin{cases} 2x_1 - x_3 - 1 = 0 \\ 2x_2 + x_3 + 3 = 0 \end{cases}$$

- a) $\mathcal{D}_1, \mathcal{D}_2$ coplanare
- b) ecuatie planului determinat de $\mathcal{D}_1, \mathcal{D}_2$
- c) $\text{dist } (\mathcal{D}_1, \mathcal{D}_2)$

Q

$$N_1 = (2, 0, -1)$$

$$N_2 = (0, 2, 1)$$

$$n_2 = N_1 \times N_2 = \begin{vmatrix} x_1 & x_2 & x_3 \\ 2 & 0 & -1 \\ 0 & 2 & 1 \end{vmatrix} = x_1 \begin{vmatrix} 0 & -1 \\ 2 & 1 \end{vmatrix} - x_2 \begin{vmatrix} 2 & -1 \\ 0 & 1 \end{vmatrix} + x_3 \begin{vmatrix} 2 & 0 \\ 0 & 1 \end{vmatrix} =$$

$$-2e_1 - 2e_2 + 4e_3 = (2, -4, 4) = 2(1, -1, 2) = 2\mathbf{v}_1 \parallel \mathbf{v}_2$$

$$\mathbf{v}_1(1, 2, -2)$$

$$\mathbf{v}_2\left(\frac{1}{2}, -\frac{3}{2}, 0\right)$$

$$\overrightarrow{\mathbf{v}_1 \mathbf{v}_2} = \left(\frac{1}{2} - 1, -\frac{3}{2} - 2, 0 + 2\right) = \left(-\frac{1}{2}, -\frac{7}{2}, 2\right) = \frac{1}{2} \underbrace{(-1, -7, 4)}_{w}$$

$$\mathbf{u}_1 = (1, -1, 2) \quad \Pi = \pi(\mathbf{v}_1, \mathbf{u}_1, w)$$

$$\forall \mathbf{v} \in \Pi$$

$$(x_1 - 1, x_2 - 2, x_3 + 2) = \pm(1, -1, 2) + \gamma(-1, 7, 4)$$

$$\mathbf{v} = x\mathbf{v}_1 + \gamma\mathbf{u}_1$$

$$\begin{cases} x_1 - 1 = -t - \gamma \\ x_2 - 2 = -t + 7\gamma, \quad t, \gamma \in \mathbb{R} \\ -x_3 + 2 = 2t + 4\gamma \end{cases}$$

$$\Pi: \begin{vmatrix} x_1 - 1 & 1 & -1 \\ x_2 - 2 & -1 & -2 \\ x_3 + 2 & 2 & 4 \end{vmatrix} = 0$$

$$(x_1 - 1) \begin{vmatrix} -1 & -2 \\ 2 & 4 \end{vmatrix} - (x_2 - 2) \begin{vmatrix} 1 & -1 \\ 2 & 4 \end{vmatrix} + (x_3 + 2) \begin{vmatrix} 1 & -1 \\ -1 & -2 \end{vmatrix} = 0$$

$$10(x_1 - 1) - 6(x_2 - 2) - 6(x_3 + 2) = 0$$

$$\text{II: } 5x_1 - 3x_2 - 3x_3 - 7 = 0$$

Methode 2:

$$\Pi: \begin{vmatrix} x_1 & x_2 & x_3 & 1 \\ x_1 + x_2 + x_3 & 1 & 1 & 1 \\ x_1 B & x_2 B & x_3 B & 1 \\ x_1 C & x_2 C & x_3 C & 1 \end{vmatrix} = 0$$

- $A(1, 3, 0), B(3, -2, 1) \in (\alpha, 1, -3), D(7, -2, 3)$
- $\alpha = ?$ a.s. A, B, C, D se plănuiește

$$\begin{vmatrix} 1 & 3 & 0 & 1 \\ 3 & -2 & 1 & 1 \\ \alpha & 1 & -3 & 1 \\ 7 & -2 & 3 & 1 \end{vmatrix} = 0 \quad \Rightarrow \quad \begin{vmatrix} 2 & -5 & 1 & 0 \\ \alpha-1 & -2 & -3 & 0 \\ 6 & -5 & 3 & 0 \end{vmatrix} = 0$$

$$\Rightarrow \begin{vmatrix} 2 & -5 & 1 \\ \alpha-1 & -2 & -3 \\ 6 & -5 & 3 \end{vmatrix} = 0 \quad \Rightarrow \quad \begin{vmatrix} 2 & -5 & 1 \\ \alpha+5 & -17 & 0 \\ 0 & 10 & 0 \end{vmatrix} = 0 \Rightarrow$$

$$\rightarrow 10(\alpha+5) = 0 \Rightarrow \alpha = -5$$

- $M(1, 1, 1), \Pi: x_1 + 2x_2 + 3x_3 - 1 = 0 \quad \text{d: } \begin{cases} x_1 - x_2 + x_3 + 1 = 0 \\ x_1 - 2x_3 - 1 = 0 \end{cases}$
- a) $\Pi_1 = ?$ a.s. $M \in \Pi_1, M \perp \Pi_1 \parallel \Pi$

$$\Pi_1 \parallel \Pi \rightarrow N_1 = N = (1, 2, 3)$$

$$\Pi_1: x_1 + 2x_2 + 3x_3 + d = 0, M \in \Pi_1, M(1, 1, 1) \rightarrow 1+2+3+d=0 \rightarrow d=-6$$

Studiind poziția relativă a lui d față de Π

$$\begin{cases} x_1 = 2t+1 \\ x_2 = 3t+2 \\ x_3 = t \end{cases} \Rightarrow \text{d} \cap \Pi \rightarrow 2t+1 + 6t + 4t + 3t - 1 = 0 \quad \text{d} \parallel \Pi \Rightarrow t = -\frac{4}{11}$$

$$d \ni M \quad M_{\Pi_1} = N = (1, 2, 3) \Rightarrow \text{d} \ni \frac{x_1-1}{1} = \frac{x_2-1}{2} = \frac{x_3-1}{3} = t \Rightarrow$$

$$d \perp \Pi$$

$$\Rightarrow \begin{cases} x_1 = t+1 \\ x_2 = 2t+1 \\ x_3 = 3t+1 \end{cases}$$

$$\text{dist}(P, \Pi) = \text{dist}(P, Q) = \| \vec{PQ} \|$$