

Seminarul 10

Forme polinomice. Forme economice

Spații vectoriale cu produs

scalar. Procedură Gram-Schmidt

$$\cdot f: \mathbb{R}^3 \rightarrow \mathbb{R}$$

$$Q(x) = 2x_1^2 + 5x_2^2 + 2x_3^2 - 4x_1x_2 - 2x_1x_3 + 4x_2x_3$$

$$a) G = ?$$

$$G = \begin{pmatrix} 2 & -2 & -1 \\ -2 & 5 & 2 \\ -1 & 2 & 2 \end{pmatrix}$$

$$b) g: \mathbb{R}^3 \times \mathbb{R}^3 \rightarrow \mathbb{R}$$

formă polarizată asociată

$$g(x, y) = \frac{1}{2} [Q(x+y) - Q(x) - Q(y)]$$

$$\sum_{i,j=1}^3 g_{ij} x_i y_j = 2x_1y_1 - 2x_1y_2 - x_1y_3 - 2x_3y_1 + 5x_2y_2 + 2x_2y_3 - x_3y_1 + 2x_3y_2 + 2x_3y_3$$

$$Q(x) = \sum_{i=1}^3 g_{ii} x_i^2 + \textcircled{2} \sum_{i < j} g_{ij} x_i x_j$$

Ker

c) Este  $g$  nedegenerată?

$$g \in L^1(\mathbb{R}^3, \mathbb{R}^3; \mathbb{R})$$

$$\text{ker } g = \{x \in \mathbb{R}^3 \mid g(x, y) = 0, \forall y \in \mathbb{R}^3\}$$

$$g \text{ nedegenerată} \Leftrightarrow \text{ker } g = \{0\}$$

$$\left| \begin{array}{ccc|cc} 2 & -2 & -1 & C_1 + 2C_3 \\ -2 & 5 & 2 & C_2 - 2C_3 \\ -1 & 2 & 2 & \end{array} \right| \xrightarrow{\begin{array}{l} \\ \\ \end{array}} \left| \begin{array}{ccc|cc} 0 & 0 & -1 \\ 2 & 1 & 2 \\ 3 & -2 & 2 \end{array} \right| =$$

$$= \left| \begin{array}{cc} 2 & 1 \\ 3 & -2 \end{array} \right| \neq 0 \Rightarrow \text{G nondegenerate}$$

$\rightarrow$  g nondegenerate

d) Q formó canonico

Jacobi

$$\Delta_1 = 2 \neq 0$$

$$\Delta_2 = \left| \begin{array}{cc} 2 & -2 \\ -2 & 5 \end{array} \right| = 10 - 4 = 6 \neq 0$$

$$\Delta_3 = \left| \begin{array}{ccc} 2 & -2 & -1 \\ -2 & 5 & 2 \\ -1 & 2 & 2 \end{array} \right| = 7 \neq 0$$

$$(f) W reprez \mathbb{C}\mathbb{P}^3 a.i. Q(x) = \frac{1}{\Delta_1} x_1^2 + \frac{\Delta_1}{\Delta_2} x_2^2 + \frac{\Delta_2}{\Delta_3} x_3^2$$

$$Q(x) = \frac{1}{2} x_1^2 + \frac{1}{3} x_2^2 + \frac{6}{7} x_3^2$$

(g) o) signatura

Q poz. definito

Met II Gauss

$$\begin{aligned} Q(x) &= 2(x_1^2 - 2x_1x_2 - x_1x_3) + 5x_2^2 + 2x_3^2 + 4x_2x_3 = \\ &= 2(x_1 - x_2 - \frac{1}{2}x_3)^2 + \frac{1}{2}x_2^2 + 2x_2x_3 + 5x_2^2 + 2x_3^2 + 4x_2x_3 \end{aligned}$$

$$3x_2^2 + \frac{3}{2}x_3^2 + x_2x_3$$

$$3(x_2^2 + \frac{2}{3}x_2x_3 + \frac{x_3^2}{3}) - \frac{x_3^2}{3} + \frac{3}{2}x_3^2$$

$$Q(x) = 2(x_1 - x_2 - \frac{1}{2}x_3)^2 + 3(x_2 + \frac{1}{3}x_3)^2 + \frac{7}{3}x_3^2$$

$$x_1' = x_1 - x_2 - \frac{1}{2}x_3$$

$$x_2' = x_2 + \frac{1}{3}x_3$$

$$x_3' = x_3$$

$$Q(x) = 2x_1'^2 + 3x_2'^2 + \frac{7}{3}x_3'^2$$

(3,0) signature

②

$$Q: \mathbb{P}^3 \rightarrow \mathbb{R}, Q(x) = 2x_1x_2 - 6x_1x_3 - 6x_2x_3$$

forma canonica

$$G = \begin{pmatrix} 0 & 1 & -3 \\ 1 & 0 & -3 \\ -3 & -3 & 0 \end{pmatrix}$$

$$\text{Gauss} \quad \begin{cases} x_1' = x_1 + x_2 \\ x_2' = x_1 - x_2 \\ x_3' = x_3 \end{cases} \quad \Rightarrow \begin{cases} x_1 = \frac{1}{2}(x_1' + x_2') \\ x_2 = \frac{1}{2}(x_1' - x_2') \\ x_3 = x_3' \end{cases}$$

$$\begin{aligned} Q(x) &= 2(x_1'^2 - x_2'^2) - 6x_1'x_3' \\ &= \frac{1}{2}((x_1')^2 - 12x_1'x_3' + 36(x_3')^2) - \frac{36}{2}x_3'^2 - \frac{1}{2}x_2'^2 \end{aligned}$$

$$Q(x) = \frac{1}{2}(x_1' - 6x_3')^2 - \frac{1}{2}x_2'^2 - 18x_3'^2$$

$$x_1'' = x_1' - 6x_3'$$

$$x_2'' = x_2'$$

$$x_3'' = x_3'$$

$$Q(x) = \frac{1}{2} x_1^2 - \frac{1}{2} x_2^2 - 18x_3^2$$

$S(1,2) \rightarrow Q$  nre pos def

②  ~~$Q: \mathbb{R}^3 \rightarrow \mathbb{R}$~~

$g: \mathbb{R}^3 \times \mathbb{R}^3 \rightarrow \mathbb{R}$  f bilineare

$$B = \begin{pmatrix} 3 & 2 & 0 \\ 2 & 2 & 2 \\ 0 & 2 & 1 \end{pmatrix} \text{ matrices associat.}$$

este parámetro  $(\mathbb{R}^3, g)$  sp. resp. euclidian real?

(esta  $g$  prod. scalar)

$$G = G^t \rightarrow g \text{ simétrico} \quad \left| \begin{array}{l} \rightarrow g \in L^{\Delta}(\mathbb{R}^3, \mathbb{R}^3, \mathbb{R}) \\ g \text{ bilinearia} \end{array} \right. \quad \begin{array}{l} \text{f bil sim.} \end{array}$$

$$Q(x) = 3x_1^2 + 2x_2^2 + x_3^2 + 4x_1x_2$$

$$\Delta_1 = 3$$

$$\Delta_2 = \begin{vmatrix} 3 & 2 \\ 2 & 2 \end{vmatrix} = 2 > 0$$

$$\Delta_3 = \begin{vmatrix} 3 & 2 & 0 \\ 2 & -2 & 2 \\ 0 & 0 & 1 \end{vmatrix} = -10 < 0$$

sign  $(2,1) \rightarrow$  nro este pos def

③  $(\mathbb{R}^3, g_0)$  s.v.e.R

$g_0$  - produsul scalar canonice

$$g_0: \mathbb{R}^3 \times \mathbb{R}^3 \rightarrow \mathbb{R} \quad g_0(x, y) = \sum_{i=1}^3 x_i y_i$$

$$U = \{x \in \mathbb{R}^3 \mid x_1 + x_2 - x_3 = 0\}$$

a)  $U^\perp = ?$

b) Rotationsmat =  $R_1 \cup R_2$  în  $\mathbb{R}^3$

unde  $R_1$  rep ortogonalitate în  $U$

$R_2$  rep ortogonalitate în  $U^\perp$

$$\mathbb{R}^3 = U \oplus U^\perp$$

a)  $U^\perp = \{x \in \mathbb{R}^3 \mid g_0(x, y) = 0 \quad \forall y \in U\}$

$$U = \{(1, 1, -1)\}$$

b)  $U = \{(x_1, x_2, x_1 + x_2) \mid x_1, x_2 \in \mathbb{R}\} \Rightarrow$

$$\Rightarrow U = \{(1, 0, 1), (0, 1, 1)\} \quad \begin{matrix} f_1 \\ f_2 \end{matrix}$$

APLICĂM PROCEDУЛ DE ORTOGONALIZARE GRAD-SCHMIDT

$$e_1 = f_1 = (1, 0, 1) \quad \cancel{f_1 \cdot 0 + 0 \cdot 1 + 1 \cdot 1}$$

$$e_2 = \frac{f_2 - \langle f_2, e_1 \rangle}{\|e_1\|} e_1 = (0, 1, 1) - \frac{1}{\sqrt{2}} (1, 0, 1) =$$

produs scalar  $= \left( -\frac{1}{2}, \frac{1}{2}, \frac{1}{2} \right) = \frac{1}{2} (-1, 1, 1)$

$$e_1' = \frac{e_1}{\|e_1\|} = \frac{1}{\sqrt{2}} (1, 0, 1) \quad \textcircled{1}$$

Def:  $\|x\| = \sqrt{g_0(x, x)} = \sqrt{x_1^2 + x_2^2 + x_3^2}$

$$e_2' = \frac{e_2}{\|e_2\|} = \frac{1}{\sqrt{6}} (-1, 2, 1) \quad \textcircled{2}$$

Ges.:  $V = 2V'$ , also

$$\frac{V}{\|V\|} = \frac{V'}{\|V'\|}$$

Aus  $\textcircled{1}, \textcircled{2} \Rightarrow R_1 = \{e_1, e_2'\}$  representation ein  $U$

$R_2 = \left\{ \frac{1}{\sqrt{3}} (1, 1, -1) \right\}$  representation ein  $U^{\perp}$

$R = R_1 \cup R_2$  representation  $\mathbb{R}^3$

$$R = \{e_1, e_2', \frac{1}{\sqrt{3}} (1, 1, -1)\}$$

$$\text{Ges.: } U = \left\{ x \in \mathbb{R}^3 \mid \begin{array}{l} g_0(x, f_1) = 0 \\ g_0(x, f_2) = 0 \end{array} \right\} =$$

$$= \left\{ x \in \mathbb{R}^3 \mid \begin{array}{l} x_1 + x_3 = 0 \\ x_2 + x_3 = 0 \end{array} \right\} =$$

$$= \left\{ (-x_2, -x_3, x_3) \mid x_3 \in \mathbb{R} \right\} = \langle \{(-1, -1, 1)\} \rangle$$

Ges.:  $\mathbb{R}^3 \xrightarrow{A} \mathbb{R}$

$$d(A) > 0$$

$$A = \begin{pmatrix} \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{6}} & \frac{1}{\sqrt{3}} \\ 0 & \frac{1}{\sqrt{6}} & \frac{1}{\sqrt{3}} \\ \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{6}} & -\frac{1}{\sqrt{3}} \end{pmatrix}$$

$$\det A = \frac{1}{6} \begin{vmatrix} 1 & -1 & 1 \\ 0 & 2 & 1 \\ 1 & 1 & -1 \end{vmatrix} \xrightarrow{L_3-L_1} \frac{1}{6} \begin{vmatrix} 1 & -1 & 1 \\ 0 & 2 & 1 \\ 0 & 2 & -2 \end{vmatrix}$$

$$\Rightarrow \frac{1}{6} (-4 - 2) = -1$$

$$R_0 \xrightarrow{A} R$$

$R$  nu este poz. orientat de  $R_0$  ( $\det A < 0$ )

⑤  $(\mathbb{R}^3, g_0)$ ,  $A \in \mathbb{R}$

$$R = \{ \vec{f}_1 = (1, 2, 3), \vec{f}_2 = (0, 1, 1), \vec{f}_3 = (1, 2, 5) \}$$

a)  $R$  reper din  $\mathbb{R}^3$

Să se determine

$$\text{i)} \vec{f}_1 \times \vec{f}_2, \vec{f}_1 \wedge \vec{f}_2 \wedge \vec{f}_3$$

$$\begin{vmatrix} 1 & 0 & 1 \\ 2 & 1 & 2 \\ 3 & 1 & 5 \end{vmatrix} \xrightarrow{C_3-C_1} \begin{vmatrix} 1 & 0 & 0 \\ 2 & 1 & 0 \\ 3 & 1 & 2 \end{vmatrix} = \begin{vmatrix} 1 & 0 \\ 1 & 2 \end{vmatrix} = 2 \neq 0$$

Cazuri:  $R_0 \xrightarrow{A} R$

•  $\det A > 0 \rightarrow R_0, R$  lez fel orientate

$$e_1 = \vec{f}_1 \wedge e_1' = \frac{1}{\sqrt{14}} (1, 2, 3)$$

$$e_2 = \vec{f}_2 \rightarrow e_2' = \vec{f}_2 - \frac{\langle \vec{f}_2, e_1 \rangle}{\langle e_1, e_1 \rangle} e_1$$

$$e_2 = (0, 1, 1) - \frac{5}{14} (1, 2, 3) =$$

$$= \left( -\frac{5}{14}, \frac{2}{7}, 1 - \frac{15}{14} \right) = \frac{1}{14} (-5, 4, -1)$$

$$e_2' = \frac{e_2}{\|e_2\|} = \frac{1}{\sqrt{42}} (-5, 4, -1)$$

$$e_2 = f_3 - \frac{\langle f_3, e_1 \rangle}{\langle e_1, e_1 \rangle} e_1 - \frac{\langle f_3, e_2 \rangle}{\langle e_2, e_2 \rangle} e_2$$

$$e_3' = \frac{e_3}{\|e_3\|}$$

$$f_1 \times f_2 = \begin{vmatrix} i & j & k \\ 1 & 2 & 3 \\ 0 & 1 & 1 \end{vmatrix} = \begin{cases} i = (1, 0, 0) \\ j = (0, 1, 0) \\ k = (0, 0, 1) \end{cases}$$

$$= \left( \begin{vmatrix} 2 & 3 \\ 1 & 1 \end{vmatrix}, - \begin{vmatrix} 1 & 3 \\ 0 & 1 \end{vmatrix}, \begin{vmatrix} 1 & 2 \\ 0 & 1 \end{vmatrix} \right) =$$

$$= (-1, -1, 1)$$

$$e_3' = \frac{1}{\sqrt{3}} (-1, -1, 1)$$

$$f_1 \wedge f_2 \wedge f_3 = \underbrace{\begin{vmatrix} 1 & 2 & 5 \\ 1 & 2 & 3 \\ 0 & 1 & 1 \end{vmatrix}}_{\text{coord line } f_3} =$$

(say)

$$\Rightarrow g_0(f_3, f_1 \times f_2) = -1 - 2 + 5 = 2.$$