

Reinforcement

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Probability Mass Function Generator

```
In [1]: def randomizer(a, probabilities):
        import numpy as np
        cumulative=[]
        num_classes=len(a)
        i=0
        while i<num_classes:
            sum=0
            for j in range(i+1):
                sum+=probabilities[j]
            cumulative.append(sum)
            i+=1
        if cumulative[num_classes-1]>1 or cumulative[num_classes-1]<1:
            print("error")
            return -1
        cumulative.insert(0,0.)
        number=np.random.uniform(0.,1.)
        i=1
        while i<=(num_classes):
            if number>=cumulative[i-1] and number<cumulative[i]:
                return(a[i-1])
            i+=1
```

0.0.1 Markov Process

```
In [2]: def markov_process(S_vec, states, Ptr, states_req):
        import numpy as np
        import tensorflow_core as tf
        for i in range(states_req):
            print("State at Time t={}: {}".format(i,np.argmax(S_vec)))
            Q_vec=np.matmul(S_vec,Ptr)
            S_vec=tf.keras.utils.to_categorical(randomizer(states, Q_vec),len(S_vec))
```

For 3 states

```
In [3]: import numpy as np
        Ptr=np.array([
            [0.1,0.4,0.5],
            [0.3,0.2,0.5],
            [0.5,0.3,0.2]
        ])
        S_vec=np.array([1.,0.,0.])
        states=[0,1,2]
        states_req=10

        markov_process(S_vec, states, Ptr, states_req)

State at Time t=0: 0
State at Time t=1: 2
State at Time t=2: 2
State at Time t=3: 0
State at Time t=4: 1
State at Time t=5: 0
State at Time t=6: 2
State at Time t=7: 0
State at Time t=8: 2
State at Time t=9: 0
```

For 4 states

```
In [4]: import numpy as np
        Ptr=np.array([
            [0.1,0.3,0.2,0.4],
            [0.3,0.2,0.2,0.3],
            [0.2,0.3,0.2,0.3],
            [0.1,0.2,0.4,0.3]
        ])
        S_vec=np.array([1.,0.,0.,0.])
        states=[0,1,2,3]
        states_req=10

        markov_process(S_vec, states, Ptr, states_req)

State at Time t=0: 0
State at Time t=1: 3
State at Time t=2: 2
State at Time t=3: 1
State at Time t=4: 0
State at Time t=5: 1
State at Time t=6: 2
State at Time t=7: 1
```

```
State at Time t=8: 0
State at Time t=9: 3
```

0.0.2 Markov Reward Process

```
In [5]: def MRP(S_vec, reward, states, Ptr, states_req):
        import numpy as np
        import tensorflow_core as tf
        for i in range(states_req):
            print("State at Time t={}: {}".format(i,np.argmax(S_vec),reward))
            Q_vec=np.matmul(S_vec,Ptr)
            S_vec=tf.keras.utils.to_categorical(randomizer(states, Q_vec),len(S_vec))
```

For 3 states

```
In [6]: import numpy as np
        Ptr=np.array([
            [0.1,0.4,0.5],
            [0.3,0.2,0.5],
            [0.5,0.3,0.2]
        ])
        R=np.array([2,3,5])
        S_vec=np.array([1.,0.,0.])
        states=[0,1,2]
        states_req=10

        MRP(S_vec, R, states, Ptr, states_req)
```

```
State at Time t=0: 0, Reward gained= 2
State at Time t=1: 0, Reward gained= 2
State at Time t=2: 2, Reward gained= 5
State at Time t=3: 0, Reward gained= 2
State at Time t=4: 1, Reward gained= 3
State at Time t=5: 0, Reward gained= 2
State at Time t=6: 2, Reward gained= 5
State at Time t=7: 2, Reward gained= 5
State at Time t=8: 2, Reward gained= 5
State at Time t=9: 0, Reward gained= 2
```

For 4 States

```
In [7]: import numpy as np
        Ptr=np.array([
            [0.1,0.3,0.2,0.4],
            [0.3,0.2,0.2,0.3],
```

```

        [0.2,0.3,0.2,0.3],
        [0.1,0.2,0.4,0.3]
    ])
    R=np.array([2,3,5,4])
    S_vec=np.array([1.,0.,0.,0.])
    states=[0,1,2,3]
    states_req=10

    MRP(S_vec, R, states, Ptr, states_req)

State at Time t=0: 0, Reward gained= 2
State at Time t=1: 2, Reward gained= 5
State at Time t=2: 1, Reward gained= 3
State at Time t=3: 0, Reward gained= 2
State at Time t=4: 2, Reward gained= 5
State at Time t=5: 3, Reward gained= 4
State at Time t=6: 0, Reward gained= 2
State at Time t=7: 1, Reward gained= 3
State at Time t=8: 1, Reward gained= 3
State at Time t=9: 3, Reward gained= 4

```

In []: