Numerical methods for partial differential equations

Exercise 10 - 26. May 2020

Example 10.1

1. Implement the weak formulation of the Dirichlet boundary conditions on the unit square with non homogenous Dirichlet boundary conditions $u_D = y(1-y)(1-x)$ and a zero right hand side. In NGSolve use the spaces

2. Follow the same steps as in the derivation of the mixed methods for the weak formulation of the Dirichlet boundary conditions in the lecture to derive a mixed method for the Poisson problem with Robin boundary conditions

$$-\Delta u = f \quad \text{in } \Omega$$
$$u - u_D = \varepsilon \frac{\partial u}{\partial n} \quad \text{on } \partial \Omega$$

with a given ε and u_D . Implement this method with $f = 100e^{-100((x-0.5)^2+(y-0.5)^2)}$, $\varepsilon = 1$ and $u_D = 1$.

Example 10.2

We continue with the findings of the previous example. Let $\Omega_1 = (0,1) \times (0,1)$ and $\Omega_2 = (1,2) \times (0,1)$. Further let $\Gamma_{int} := \{1\} \times (0,1)$ and $\Gamma_{out} := (\partial \Omega_1 \cup \partial \Omega_2) \setminus \Gamma_{int}$. Solve the problem

$$\begin{split} -\Delta u_1 &= 10 \quad \text{in } \Omega_1 \\ -\Delta u_2 &= 0 \quad \text{in } \Omega_2 \\ u_1 &= u_2 = 0 \quad \text{on } \Gamma_{out} \\ u_1 - u_2 &= \varepsilon \frac{\partial u_1}{\partial n_1} \quad \text{on } \Gamma_{int} \\ \frac{\partial u_1}{\partial n_1} &= -\frac{\partial u_2}{\partial n_2} \quad \text{on } \Gamma_{int}, \end{split}$$

with $\varepsilon = 0.1$. We approximate both solutions in H^1 -conforming finite element spaces defined on Ω_1 and Ω_2 and use a mixed method to incorporate the boundary conditions. Use the file jump.py as starting point.

Example 10.3

Consider the instationary Navier-Stokes equations with homogeneous Dirichlet boundary conditions ($u_D = 0$ on $\partial\Omega$) and f = 0. Show that the kinematic energy

$$\frac{1}{2} \int_{\Omega} |u|^2 \, \mathrm{d}x$$

is monotone decreasing (in time). Give a physical interpretation.

Hint: Try to reformulate the convective term and use $\operatorname{div}(u) = 0$. Note that the *i*-th component of $(u \cdot \nabla)u$ is given by

$$[(u \cdot \nabla)u]_i = \sum_{i=1}^d u_i \frac{\partial u_i}{\partial x_i}.$$

Does your proof also hold for a discrete method? (How is the divergence constraint incorporated...)

Example 10.4 (Right inverse of divergence)

Let Ω be star shaped with respect to $\omega \subset \Omega$, and let $a \in \omega$. Let $p \in L_0^2(\Omega)$ and extend it trivially by zero to $L^2(\mathbb{R}^d)$. We define

$$u_a(x) := -(x-a) \int_1^\infty t^{d-1} p(a+t(x-a)) dt \quad x \neq a,$$

and $u_a(a) = 0$. Show: if $\int_{\Omega} p = 0$, then we have

$$\operatorname{div}(u_a) = p$$
 in Ω , and $u = 0$ on $\partial \Omega$.

Where do we need the assumption $\int_{\Omega} p = 0$? You can assume that p is smooth enough such that all integrals and derivations exist.

Remark: Using the above result one can then define an averaging over all star-points

$$u := \frac{1}{|\omega|} \int_{\omega} u_a \, \mathrm{d}a.$$

Then we still have $\operatorname{div}(u) = p$ and it is possible to prove that $||u||_{H^1} \leq ||p||_{L^2}$. Thus above constructions proves the continuous Stokes-LBB if Ω is star shaped.