

Ex 5.3

We know from 5.2:

$$F_2(\hat{x}, \hat{y}) = \begin{pmatrix} 1 - \frac{\hat{y}}{2} \\ \frac{1}{2} + \frac{\hat{x}}{2} \end{pmatrix} = \begin{pmatrix} x \\ y \end{pmatrix}$$

$$F_2: \hat{T} \rightarrow T_2$$

$$\Rightarrow \begin{cases} y = \frac{1}{2} + \frac{\hat{x}}{2} \Rightarrow \hat{x} = 2y - 1 \end{cases}$$

$$\Rightarrow \begin{cases} x = 1 - \frac{\hat{y}}{2} \Rightarrow \hat{y} = 2(1 - x) \end{cases}$$

Now we calculate the $\varphi_m = \hat{\varphi}_m \circ F_2^{-1}$ (and $\nabla \varphi_m$)

$$\begin{aligned} \varphi_2^T &= \hat{\varphi}_1 \circ F_2^{-1} = \varphi_1(\hat{x}) \cdot \varphi_0(\hat{y}) = \varphi_1(2y-1) \cdot \varphi_0(2(1-x)) = \\ &= \underbrace{(2y-1)}_{1-2+2x=2x-1} \underbrace{(1-2(1-x))}_{(2y-1)(2x-1)} = \cancel{2y-1} \cancel{(1-2(1-x))} = \cancel{2y-1} \cancel{(1-x)} \end{aligned}$$

$$\begin{aligned} \varphi_6^T &= \hat{\varphi}_2 \circ F_2^{-1} = \varphi_1(\hat{x}) \varphi_1(\hat{y}) = \varphi_1(2y-1) \varphi_1(2(1-x)) = \\ &= \cancel{(1-2y+1)} \cancel{(2(1-x))} = \cancel{4(1-y)} \cancel{(1-x)} = 2(2y-1)(1-x) \end{aligned}$$

$$\begin{aligned} \varphi_8^T &= \hat{\varphi}_3 \circ F_2^{-1} = \varphi_0(\hat{x}) \varphi_1(\hat{y}) = \varphi_0(2y-1) \varphi_1(2(1-x)) = \\ &= \underbrace{(1-2y+1)}_{2-2y} (2(1-x)) = 4(1-y)(1-x) \end{aligned}$$

$$\begin{aligned} \varphi_5^T &= \hat{\varphi}_0 \circ F_2^{-1} = \varphi_0(2y-1) \varphi_0(2(1-x)) = (1-2y+1)(1-2+2x) = \\ &= 2(1-y)(2x-1) \end{aligned}$$

$$\nabla \varphi_2^T = \begin{pmatrix} 2(2y-1) \\ 2(2x-1) \end{pmatrix}, \quad \nabla \varphi_6^T = \begin{pmatrix} -2(2y-1) \\ 4(1-x) \end{pmatrix},$$

$$\nabla \varphi_8^T = \begin{pmatrix} -4(1-y) \\ -4(1-x) \end{pmatrix}, \quad \nabla \varphi_5^T = \begin{pmatrix} 4(1-y) \\ -2(2x-1) \end{pmatrix}$$

~~Next~~ Next we calculate $(A_T)_{mn} = \int_{T_2} 6 \nabla \psi_m \nabla \psi_n$

→ Identify local ψ_i with the global ψ_j^T from before

$$\psi_0 = \psi_5^T, \quad \psi_1 = \psi_2^T, \quad \psi_2 = \psi_6^T, \quad \psi_3 = \psi_8^T$$

$$(A_T)_{00} = 6 \int_{T_2} \nabla \psi_0 \nabla \psi_0 = 6 \int_{[0.5, 1]^2} \left(\begin{pmatrix} 4(1-y) \\ -2(2x-1) \end{pmatrix} \right)^2 = 6 \int_{[0.5, 1]} [16(1-y)^2 + 4(2x-1)^2] dx dy =$$

$$= 6 \cdot 4 \cdot \frac{1}{2} \cdot \int_{s=0.5}^1 \underbrace{44 \cdot (1 - 2s + s^2)}_{4 - 8s + 4s^2} + 4s^2 - 4s + 1 ds =$$

$$= 12 \int_{0.5}^1 5 - 12s + 8s^2 ds = 12 \left[5s - 6s^2 + \frac{8s^3}{3} \right]_{0.5}^1 =$$

$$= 12 \left[\underbrace{5 - 6}_{-1} + \frac{8}{3} - \underbrace{\left(\frac{5}{2} - \frac{6}{4} + \frac{1}{3} \right)}_{=-\frac{10}{4} + \frac{6}{4} = -\frac{4}{4} = -1} \right] = 12[-2 + \frac{7}{3}] = 12 \cdot \frac{7-6}{3} = \underline{\underline{4}}$$

→ Jupyter with sympy

d) T_2 :

$$\begin{pmatrix} \psi_0 \\ \psi_1 \\ \psi_2 \\ \psi_3 \end{pmatrix}^{T_2} = \begin{pmatrix} \psi_5^T \\ \psi_2^T \\ \psi_6^T \\ \psi_8^T \end{pmatrix} = C_{T_2}^t \begin{pmatrix} \psi_0^T \\ \psi_1^T \\ \vdots \\ \psi_8^T \end{pmatrix}$$

$$C_{T_2}^t = \begin{pmatrix} \psi_0^T & \psi_1^T & \psi_2^T & \psi_3^T & \psi_4^T & \psi_5^T & \psi_6^T & \psi_7^T & \psi_8^T \\ 0 & 0 & 0 & 0 & 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 \end{pmatrix} \begin{matrix} \rightarrow \psi_0 \\ \rightarrow \psi_1 \\ \rightarrow \psi_2 \\ \rightarrow \psi_3 \end{matrix}$$