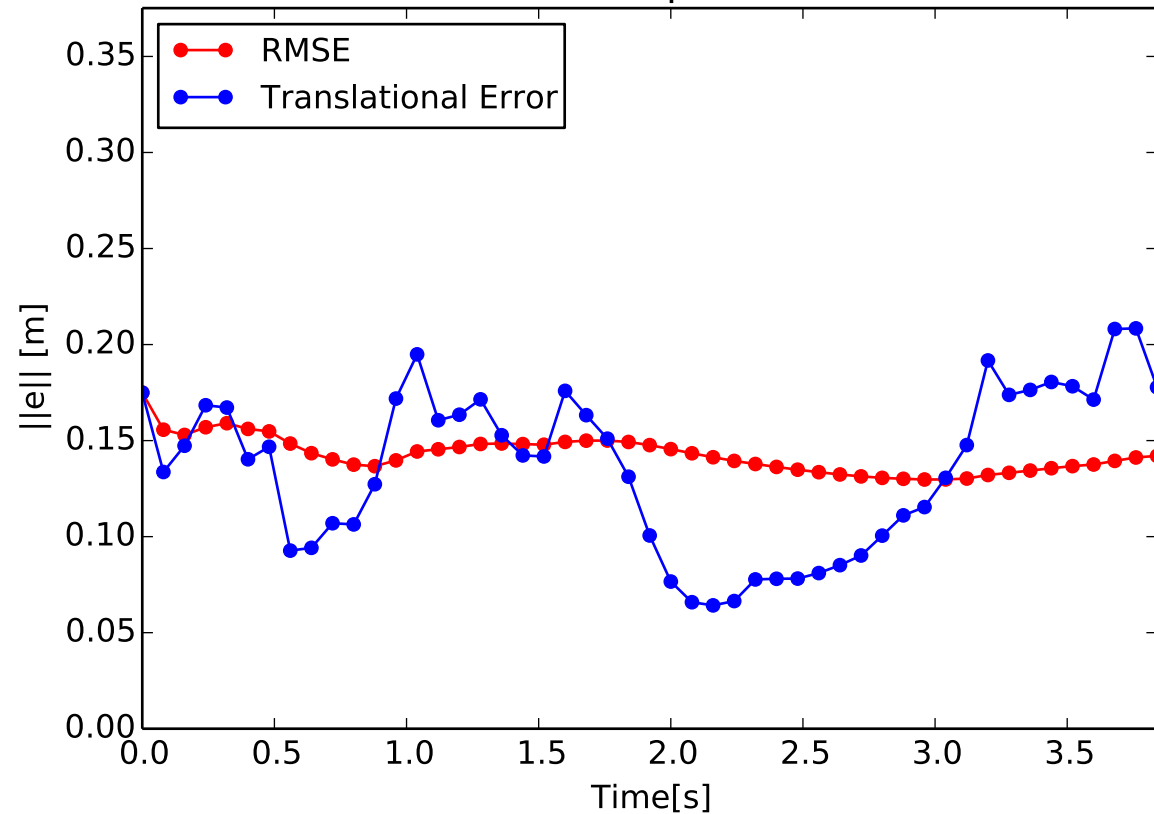


# precision\_tests\_walk\_moving\_bot04.bag

## Root mean squared error



## Error distribution

