

MASTER CSA : Introduction to Embedded systems

"an overall of what is deep learning"

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What is it?

Deep-learning is a branch of Machine-learning which is a type of Artificial intelligence.

Machine-learning

Construct algorithm that can performed a task without explicitly programming it to do so.

Learning a **task** to a machine.

Deep-learning

Aim at doing the same... but in a more **deeper** way!

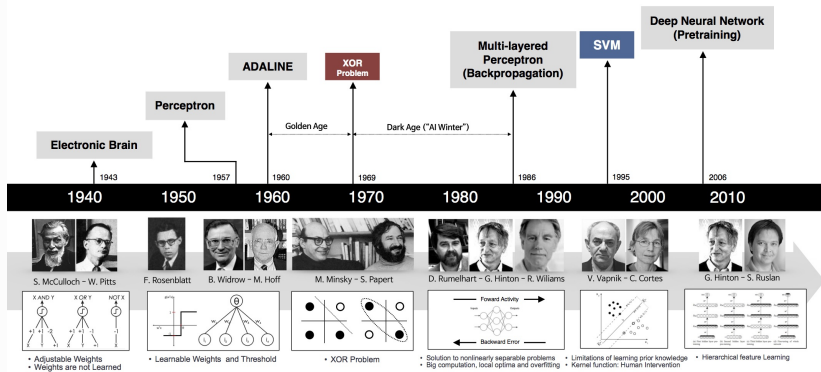
Deep-learning is based on the learning data representation **task**.

What is it?

A task in data science :

- ▶ Data Classification
- ▶ Data Clustering
- ▶ Data Modeling (Regression)
- ▶ Data Representation (encoding, compressing, visualization)

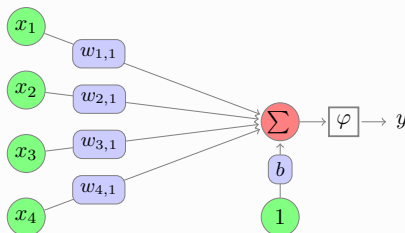
A brief history



- ▶ 1943 : Mc Culloch and Pitts → 1st generation Perceptron
- ▶ 1963 : Hebb's rule → cells that fire together, wire together
- ▶ 1986 : Multi-layered Perceptron Artificial Neuron
- ▶ ~~August 4, 1997 : Skynet's activation (Judgment's Day)~~
- ▶ 2006 : Deep neural Network
- ▶ 2012 :
- ▶ 2018 : Master CSA

Artificial Neural Network

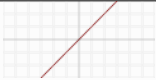
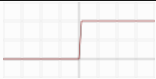
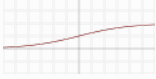


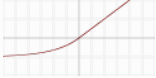
Artificial Neural (AN):



$$y = \mathcal{N}(\mathbf{x}, \mathbf{w}, b) = \varphi\left(\sum_i x_i \cdot w_i + b\right) = \varphi\left(\begin{bmatrix} w_1 & \dots & w_n \end{bmatrix} \cdot \begin{bmatrix} x_1 \\ \vdots \\ x_n \end{bmatrix} + b\right)$$

with φ an activation function (e.g. *tanh*, *relu*)

Activation function φ

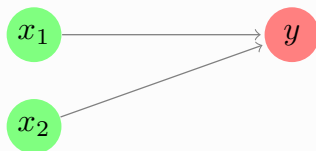
Linear		$\varphi(x)=x$
Heaviside (Perceptron)		$\varphi(x)=\begin{cases} 0, & \text{if } x < 0. \\ 1, & \text{if } x \geq 0. \end{cases}$
Sigmoid		$\varphi(x)=\frac{1}{1+e^{-x}}$
Tangent Hyperbolic		$\varphi(x)=\tanh(x)=\frac{(e^x-e^{-x})}{(e^x+e^{-x})}$
REctify Linear Unit (ReLU)		$\varphi(x)=\max(0,x)$
Exponential Linear Unit (ELU)		$\varphi(x)=\begin{cases} \alpha(e^x-1), & \text{if } x < 0. \\ x, & \text{if } x \geq 0. \end{cases}$

Perceptron

Perceptron : an artificial neuron with binary output

Each output -> linear classifier

Input layer Output layer



$$y = \varphi \left(\begin{bmatrix} w_1 & w_2 \end{bmatrix} \cdot \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} + b \right)$$

Note

Unlike all layers in a Neural Network, the output layer neurons most commonly do not have an activation function (or you can think of them as having a linear identity activation function).

Perceptron

What Perceptron can do : linear separation

Input
layer

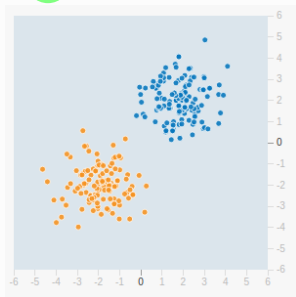
Output
layer

x_1

x_2

y

$$y = \varphi \left(\begin{bmatrix} w_1 & w_2 \end{bmatrix} \cdot \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} + b \right)$$



Perceptron

What Perceptron can do : linear separation

Input
layer

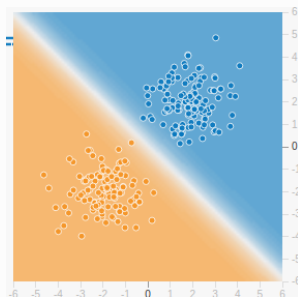
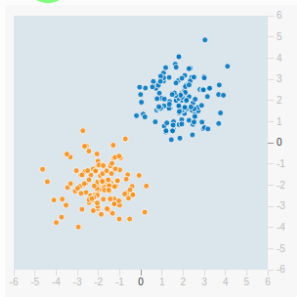
Output
layer

x_1

x_2

y

$$y = \varphi \left(\begin{bmatrix} w_1 & w_2 \end{bmatrix} \cdot \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} + b \right)$$

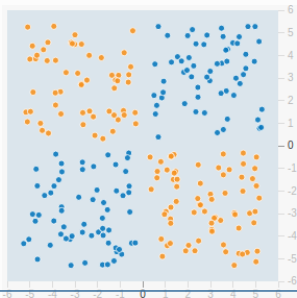
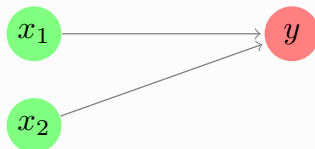


Perceptron

What Perceptron **can't** do : non-linear separation

Input
layer

Output
layer

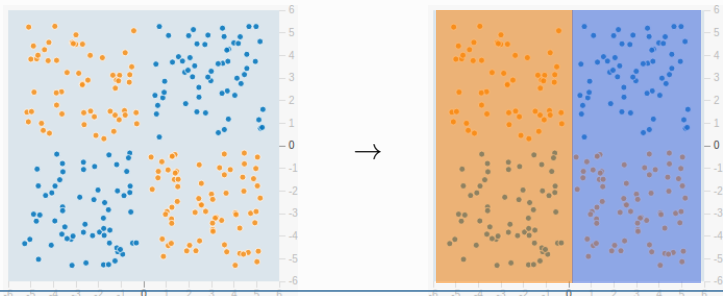
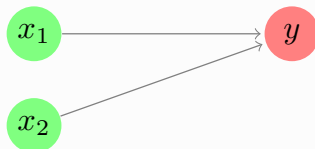


Perceptron

What Perceptron **can't** do : non-linear separation

Input
layer

Output
layer

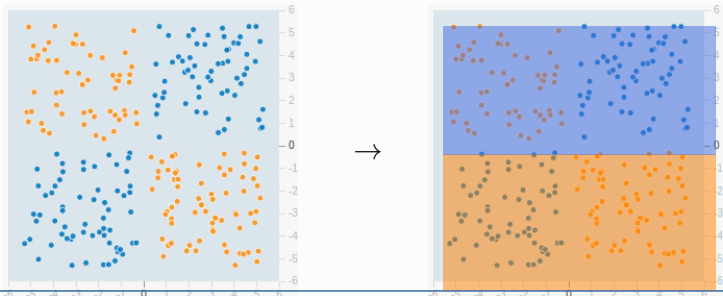
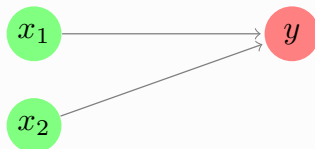


Perceptron

What Perceptron **can't** do : non-linear separation

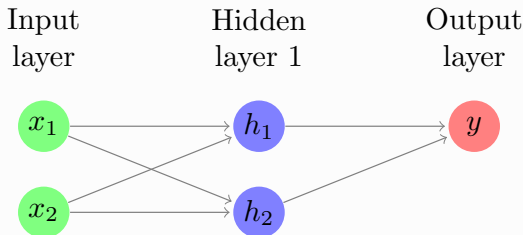
Input
layer

Output
layer



Neural network

Shallow Neural Network (SNN) : a network with one hidden layer



$$y = \varphi \left(\begin{bmatrix} w_{out1} & w_{out2} & w_{out3} \end{bmatrix} \cdot \varphi \left(\begin{bmatrix} w_{in(1,1)} & w_{in(1,2)} \\ w_{in(2,1)} & w_{in(2,2)} \\ w_{in(3,1)} & w_{in(3,2)} \end{bmatrix} \cdot \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} + \begin{bmatrix} b_1 \\ b_2 \\ b_3 \end{bmatrix} \right) + b \right)$$

$$\mathbf{y} = \varphi(\mathbf{W}_{out} \cdot \varphi(\mathbf{W}_{in} \cdot \mathbf{x} + \mathbf{b}_{in}) + \mathbf{b}_{out})$$

Deep Learning

How to learn the weight? -> Backpropagation Algorithm
(Supervised learning)

Requirements

- ▶ The inputs \mathbf{x} and their corresponding targets \mathbf{t}
- ▶ loss function : error measure \mathcal{E} (e.g. Squared Error :
 $\mathcal{E} = \sum_i (y_i - t_i)^2$)
- ▶ Random initialization of the weights \mathcal{W} and \mathbf{B}

Backpropagation Algorithm

Repeat until convergence (e.g. $\mathcal{E} < \delta$)

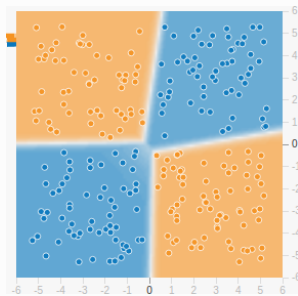
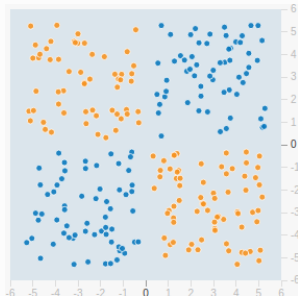
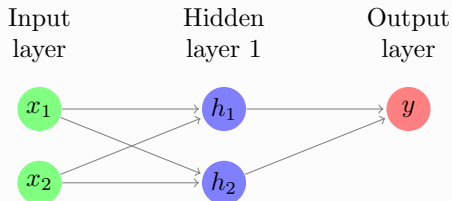
1. Compute the output of the network \mathbf{y} w.r.t \mathcal{W}
2. Compute the error \mathcal{E} w.r.t \mathbf{y} and \mathbf{t}
3. Update the weights \mathcal{W} and \mathbf{B}

Neural network

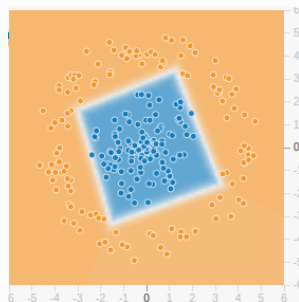
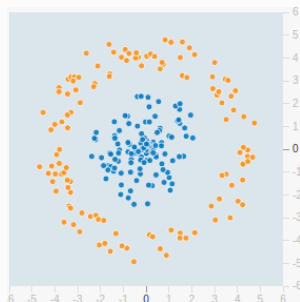
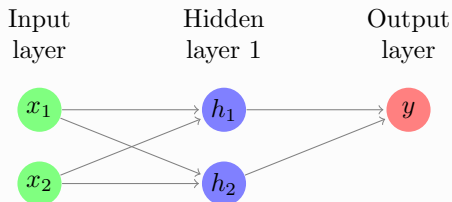
Let's try

<http://playground.tensorflow.org>

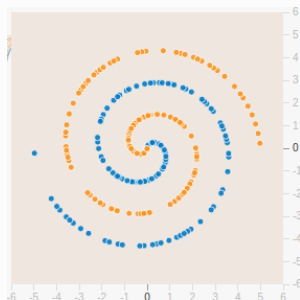
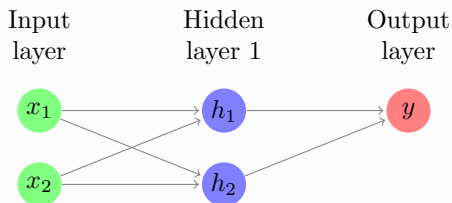
Shallow Neural network



Shallow Neural network



Shallow Neural network

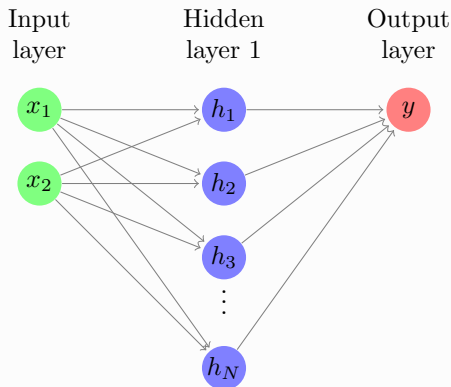


→ ?

Shallow Neural network

Cybenko 1989: Universal approximation theorem

A feed-forward network with a single hidden layer (Shallow Neural network or SNN) containing a finite number of neurons N , can approximate any continuous functions on compact subsets of \mathbb{R}^n



Neural network

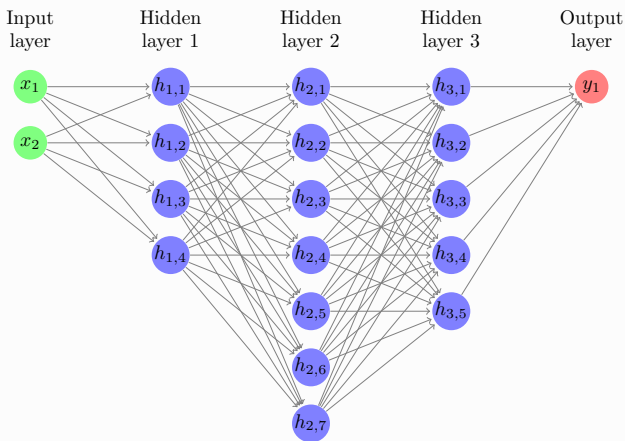
- ▶ Historically : Perceptron (binary output unit)
- ▶ Network without hidden unit are very limited in the input-output mappings they can perform
- ▶ Shallow neural network can approximate any continuous mapping

limits

- ▶ We can perform any mapping with SNN...
 - ▶ BUT how many AN are needed in the hidden layer ?
 - ▶ BUT hard to learn large SNN

Deep Neural network

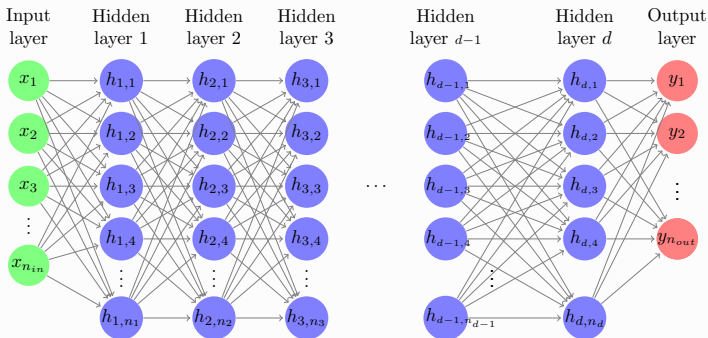
Deep neural network : more than One hidden layer Can help to solve hard problem by performing deeper mix of information



$$y(\mathbf{x}, \mathcal{W}, \mathbf{B}) = \varphi \left(\mathbf{W}_4 \cdot \varphi \left(\mathbf{W}_3 \cdot \varphi \left(\mathbf{W}_2 \cdot \varphi (\mathbf{W}_1 \cdot \mathbf{x} + \mathbf{b}_1) + \mathbf{b}_2 \right) + \mathbf{b}_3 \right) + \mathbf{b}_4 \right)$$

Deep Neural network

in a more general way ...



$$\mathbf{y}(\mathbf{x}, \mathcal{W}, \mathbf{B}) = \varphi \left(\mathbf{W}_d \cdot \varphi \left(\mathbf{W}_{d-1} \dots \varphi \left(\mathbf{W}_2 \cdot \varphi (\mathbf{W}_1 \cdot \mathbf{x} + \mathbf{b}_1) + \mathbf{b}_2 \right) \dots + \mathbf{b}_{d-1} \right) + \mathbf{b}_d \varphi \right)$$

Deep Neural Network

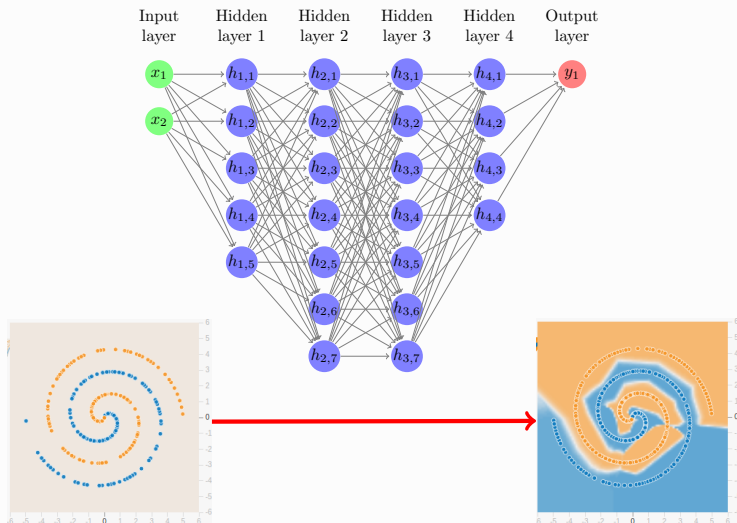
$$\mathbf{y}(\mathbf{x}, \mathcal{W}, \mathbf{B}) = \varphi \left(\mathbf{W}_d \cdot \varphi \left(\mathbf{W}_{d-1} \dots \varphi \left(\mathbf{W}_2 \cdot \varphi (\mathbf{W}_1 \cdot \mathbf{x} + \mathbf{b}_1) + \mathbf{b}_2 \right) \dots + \mathbf{b}_{d-1} \right) + \mathbf{b}_d \varphi \right)$$

with

$$\mathbf{x} = \begin{pmatrix} x_1 \\ x_2 \\ \dots \\ x_{n_{in}} \end{pmatrix} \quad \mathbf{y} = \begin{pmatrix} y_1 \\ y_2 \\ \dots \\ y_{n_{out}} \end{pmatrix} \quad \mathcal{W} = \{\mathbf{W}_1, \mathbf{W}_2, \dots, \mathbf{W}_{d-1}, \mathbf{W}_d\} \quad \mathbf{B} = \{\mathbf{b}_1, \mathbf{b}_2, \dots, \mathbf{b}_{d-1}, \mathbf{b}_d\}$$

$$\mathbf{W}_k = \begin{pmatrix} w_{k(1,1)} & w_{k(1,2)} & \dots & w_{k(1,n_k-1)} \\ w_{k(2,1)} & w_{k(2,2)} & \dots & w_{k(2,n_k-1)} \\ \vdots & \vdots & \vdots & \vdots \\ w_{k(n_k,1)} & w_{k(n_k,2)} & \dots & w_{k(n_k,n_k-1)} \end{pmatrix} \quad \mathbf{b}_k = \begin{pmatrix} b_1 \\ b_2 \\ \vdots \\ b_{k(n_k-1)} \\ b_{k(n_k)} \end{pmatrix}$$

Deep Neural Network



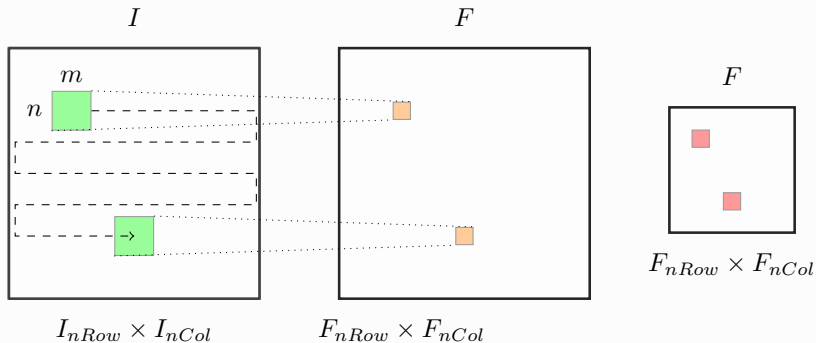
Deep Learning

Convolutional neural network

Deep Learning

Convolutional Neural Network

- ▶ Mainly performed on images (I)
- ▶ Main idea : convolution of the input by a filter W
- ▶ The result is a features map F

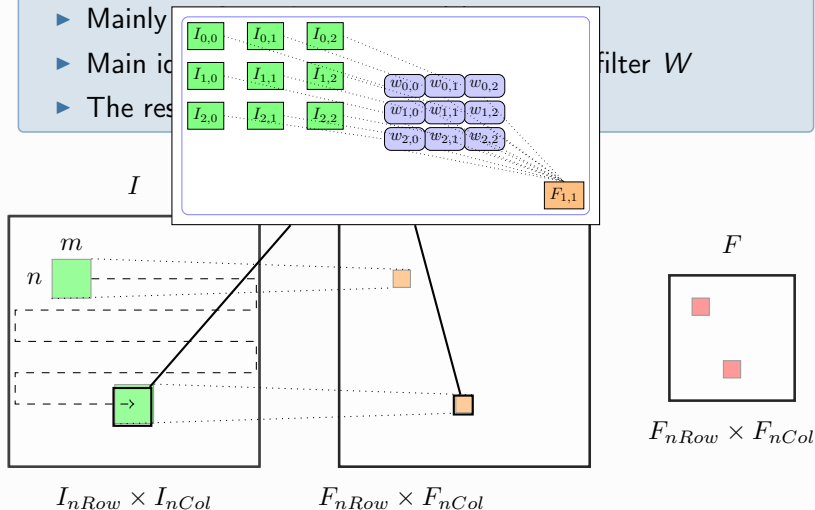


Deep Learning

Convolutional Neural Network

- ▶ Mainly
- ▶ Main id
- ▶ The res

filter W

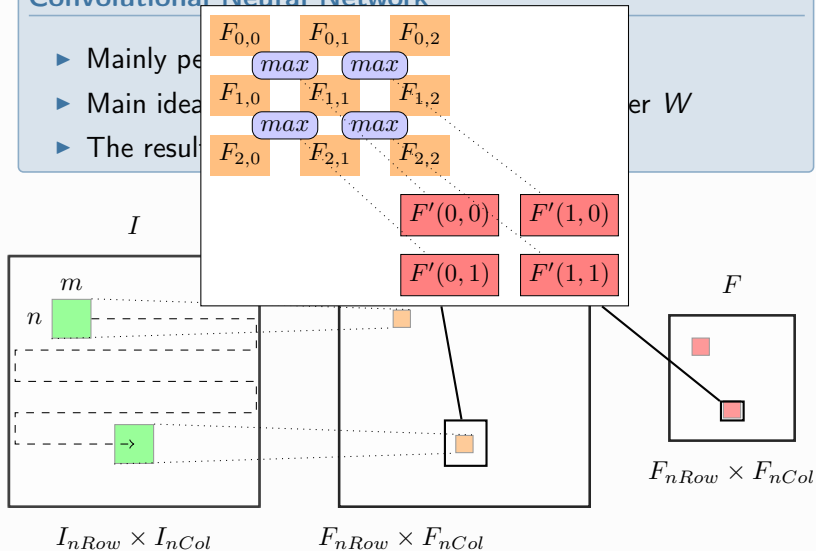


Deep Learning

Convolutional Neural Network

- ▶ Mainly pe
- ▶ Main idea
- ▶ The result

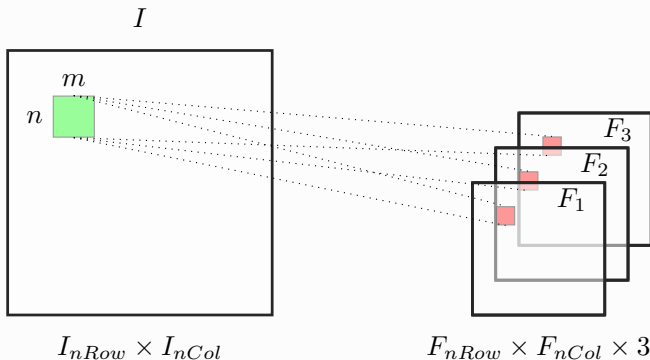
er W



Deep Learning

Convolutional Neural Network

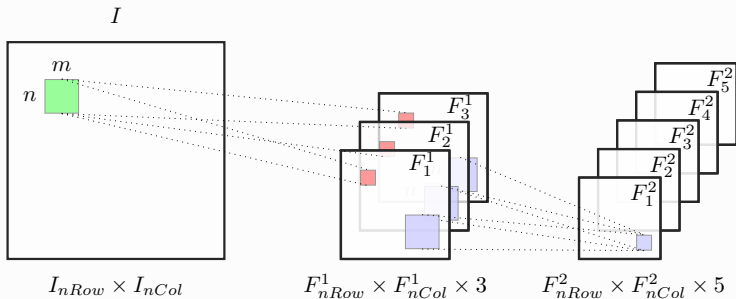
- ▶ Several convolution of the input by several filter $\{W_1, W_2, W_3\}$
- ▶ The result is **several** features map $\{F_1, F_2, F_3\}$



Deep Learning

Convolutional Neural Network

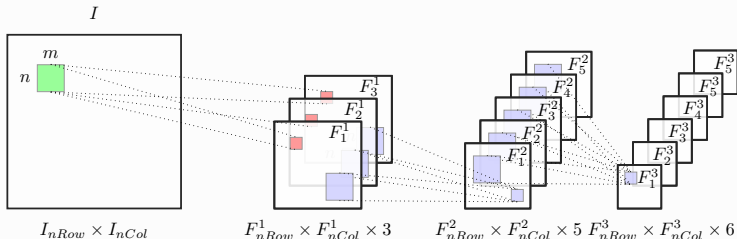
- ▶ Deep CNN : Extract features maps on features map
- ▶ The result is **several** features map $\{F_1^2, F_2^2, F_3^2, F_4^2, \dots\}$



Deep Learning

Convolutional Neural Network

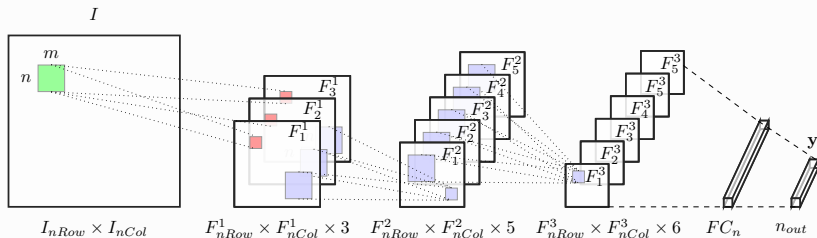
- ▶ Deep CNN : Extract features from features maps from features map ...
- ▶ The result is **several** features map $\{F_1^3, F_2^3, F_3^3, F_4^3, \dots\}$



Deep Learning

Convolutional Neural Network

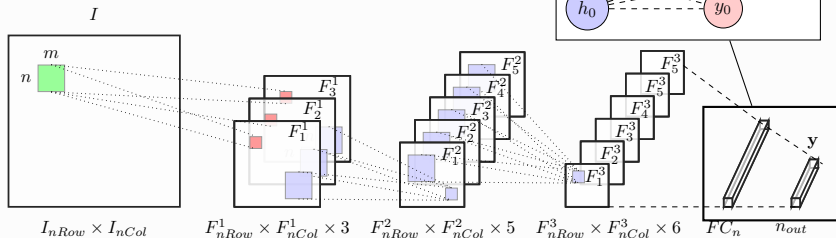
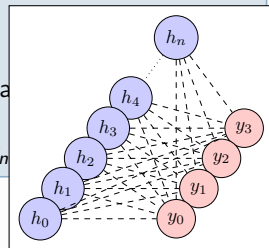
- ▶ Deep CNN : connect all of these features to a flatten fully connected layer of neurons
- ▶ The result is
 - ▶ a vector of neurons $\{h_1, h_2, \dots, h_n\}$ (a mix of the features $\{F_1^3, F_2^3, F_3^3, F_4^3, \dots\}$)
 - ▶ a vector of outputs $\mathbf{y} = \{y_1, y_2, \dots, y_n\}$



Deep Learning

Convolutional Neural Network

- ▶ Deep CNN : connect all of these features to a flatten fully connected layer of neurons
- ▶ The result is
 - ▶ a vector of neurons $\{h_1, h_2, \dots, h_n\}$ (a
 - $\{F_1^3, F_2^3, F_3^3, F_4^3, \dots\}$)
 - ▶ a vector of outputs $\mathbf{y} = \{y_1, y_2, \dots, y_n\}$



Deep Learning

example of CNN for digit recognition

<http://scs.ryerson.ca/~aharley/vis/conv/flat.html>

Convolutional Neural Network

CNN is very useful to go deeper in the learning of latent space
-> better classification performance

1. Extract features
2. Mix features
3. Output classification, Regression, etc.

Deep Neural Network

To resume

Artificial Neuron (AN)

- ▶ Formula : $y = \varphi\left(\sum_i x_i \cdot w_i + b\right)$
- ▶ Several type of unit : Linear Unit, Perceptron (binary), Sigmoid Unit, Tangent Hyperbolic unit, Rectified Linear Unit

Artificial Neural Network (ANN)

- ▶ Shallow Neural Network (SNN)
- ▶ Deep neural network (DNN)
 - ▶ Convolutional Neural Network (CNN)
 - ▶ Recurrent neural network (RNN)