6.035 Team **Antidaephobiax**: Optimizations Writeup

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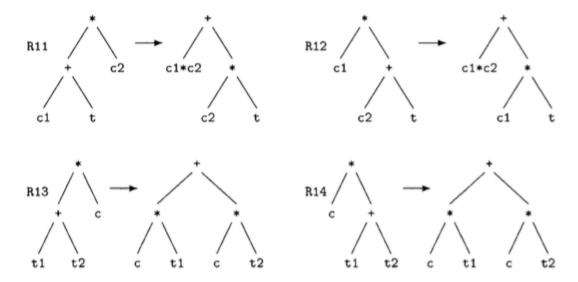
1 Overview

In this written documentation we discuss in detail, each optimization that we had considered while building our compiler and in the optimization phase of the project. We go through the rationale and decision making process for each optimization that we finally implemented. Supplemented by examples from our generated code, in the form of High Level Intermediate Representations, Low Level Intermediate Representations, and generated assembly programs, we further talk about how each optimization has helped in making our compiler more efficient, both in general, and specifically with respect to the image processing benchmarks. We also briefly discuss the correctness of each optimization, through examples and sample programs, in the process. Towards the end of this document, we discuss our full-optimizations command line option and present a detailed analysis of how and why we went our specific order of optimizations, followed by which optimizations were applied multiple times at different

2 Optimizations Implemented

We use various small Decaf programs as examples to explain the various optimizations implemented. The low level IR of such programs is represented by a mapping between a unique line label as key and the actual statement as value. Variables of the form #_tX are temporary variables generated for use in the program by the compiler.

2.1 Expression Canonicalization



Expressions in a computer program are often written so that they can be easily read and understood by a human or programmer. Examples of this may include the use of parenthetical expressions to indicate the demensions of a multi-dimensional array or multiplying a mixture of variables and constants. Moreover, these expressions can be arbitrarily complex. However, Expression Canonicalization is a technique that attempts to standardize the format of all expressions by treating expressions as tress and recursively applying algebriac properties. Expression Canonicalization often intrudes additional common subexpressions that were inacessible as well opportunities to perform compile-time computations of constants.

2.2 Parallelization

We implement an extremely restrictive version of loop parallelization for our compiler, that parallelizes very specific functions. We perform this optimization in the high level intermediate representation (IR), and the compiler detects loops that can be safely and efficiently executed in parallel and generates multithreaded code. We specifically target void return-type functions with no parameters and perfectly nested loops, and use the Analyze class of the provided library to compute their distance vectors. The following function is an example of code that can be automatically parallelized by our compiler.

```
int A[1000000];
void f() {
   int i;
   for (i = 0; i < 1000000; i += 1)
        A[i] = A[i] * 2;
}</pre>
```

2.2 Parallelization 3

Once the maximum number of threads available is set to 8, the following assembly code is a snippet of the assembly generated by our compiler for a parallelized version of the function f(). All calls to f() in the main function of the program are replaced by calls to $create_and_run_threads(f)$ from the 6035 library. Since, for the perfectly nested loops in the shown function, our distance vector is [0], we generate the following assembly code for the parallelized version of the function.

```
f_{entry}:
                 90, \%r12
        movq
                 90, \%r12
        movq
  f_FOR_COND_L4:
                 $1000000, %r13
        movq
                 1000000, %r10
        movq
                %r12, %r11
        movq
                %r10, %r11
        cmp
                 90, \%r11
        movq
9
                 $1, %r10
        movq
10
                %r10, %r11
        cmovl
11
                %r11, %r13
        movq
                %r13, %r10
        movq
                 90, \%r11
        movq
14
        cmp
                %r10, %r11
                 f_FOR_L9
        jne
16
                 f_END_FOR_L21
        jmp
  f_FOR_L9:
18
        movq
                 -48(\% \text{rbp}), \% \text{r} 10
19
        movq
                %r12, %r11
20
                %r10, %r11
        addq
21
                %r11, %r13
        movq
22
                 $2, \%r14
23
        movq
                %r13, %rax
24
        movq
                A( ,%rax , 8) , %rax
25
        movq
                %rax, -56(%rbp)
        movq
26
                 \$2, \%r 10
        movq
27
                 -56(\% \text{rbp}), \% \text{r} 11
        movq
                %r10, %r11
        imulq
                %r11, %r14
        movq
30
                %r13, %r15
        movq
                %r13, %r10
        movq
32
                %r14, %r11
        movq
33
                %r11, A(, %r10, 8)
        movq
34
                 $1, %r15
        movq
35
                 $8, %rbx
        movq
36
                 $8, %r10
        movq
                 1, \%r11
        movq
38
                %r10, %r11
        imulq
39
                %r11, %rbx
        movq
40
        movq
                %r12, %r11
41
                %rbx, %r11
        addq
42
                %r11, %r15
        movq
43
                %r15, %r12
        movq
44
                 f_FOR_COND_L4
45
        jmp
46 f_END_FOR_L21:
```

47 f_exit:

Since, we are only parallelizing the innermost loop after making sure that it is a FOR EACH type of loop, each iteration, and consequently, the computations on each thread, is independent of all the others. Given the wide prevalence of such loops in general, and in the image processing benchmark programs, implementing this optimization allowed us to leverage multithreading to gain as much as a $4\times$ speed-up for certain functions. One of the largest challenges for this design was to ensure that unsafe/non-parallelizable loops don't get parallelized, as this could lead to incorrect execution and results, or extremely slow timings, given the cost of the system calls that are made by the 6036.c library. We addressed this problem by developing an extremely restrictive criteria for functions and the loops they contain, to be parallelized. Though this caused a lot of completely parallelizable loops to get skipped over, we were able to avoid incorrect evaluations.

2.3 Common Subexpression Elimination

Here, we started by performing the available expressions data flow analysis, and determined for each point in the program the set of expressions that need not be recomputed. The following code will be our running example for common subexpression elimination, copy propagation, and dead code elimination.

```
void main ( ) {
   int a, b, c, d;
   a = get_int ( 2 );
   b = get_int ( 3 );
   c = 0;
   d = 0;
   c = ( a + b ) * ( a + b );
   d = ( a + b ) / ( a + b );
   printf ( "%d\n", c );
   printf ( "%d\n", d );
}
```

For the above mentioned program, we get the following unoptimized low level IR, and corresponding set of basic blocks for its control flow graph.

```
main : EMPTY.STATEMENT

L0 : \#_{-}t0 = 2

L1 : \#_{-}t1 = get_{-}int(\#_{-}t0,)

L2 : a = \#_{-}t1

L3 : \#_{-}t2 = 3

L4 : \#_{-}t3 = get_{-}int(\#_{-}t2,)

L5 : b = \#_{-}t3

L6 : \#_{-}t4 = 0

L7 : c = \#_{-}t4

L8 : \#_{-}t5 = 0

L9 : d = \#_{-}t5
```

```
12 L10 : \#_{-t}6 = a + b

13 L11 : \#_{-t}7 = a + b

14 L12 : \#_{-t}8 = \#_{-t}6 * \#_{-t}7

15 L13 : c = \#_{-t}8

16 L14 : \#_{-t}9 = a + b

17 L15 : \#_{-t}10 = a + b

18 L16 : \#_{-t}11 = \#_{-t}9 / \#_{-t}10

19 L17 : d = \#_{-t}11

20 L18 : \#_{-t}13 = printf(\#_{str}_{-t}12, c,)

21 L19 : \#_{-t}15 = printf(\#_{str}_{-t}14, d,)
```

After performing CSE on this algorithm, we had the following resulting low level IR. It is important to note that this has an increased size in terms of temporaries and subexpressions than the original program.

```
main : EMPTY_STATEMENT
_{2} L0 : \#_{-}t0 = 2
_3 L1 : \#_t1 = get_int(\#_t0),
4 L2 : a = \#_{-}t1
5 L3 : \#_{-}t2 = 3
_{6} L4 : \#_{t}3 = get_{int}(\#_{t}2,)
7 \text{ L5} : b = \#_{-}t3
8 L6 : \#_{-}t4 = 0
9 L7 : c = \#_{-}t4
10 L8 : \#_{-}t5 = 0
^{11} L9 : d = \#_{-}t5
12 L10 : \#_{-}t6 = a + b
13 L11 : \#_{-}t7 = \#_{-}t6
_{14} L12 : \#_{-}t8 = \#_{-}t6 * \#_{-}t7
15 \text{ L}13 : c = \#_{-}t8
16 \text{ L}14 : \#_{-}t9 = \#_{-}t6
17 L15 : \#_{t}10 = \#_{t}6
18 L16 : \#_{t}11 = \#_{t}9 / \#_{t}10
19 L17 : d = \#_{-}t11
20 L18 : \#_{t}13 = printf(\#str_{t}12, c_{t})
L19 : \#_{t}15 = printf(\#str_{t}14, d,)
```

While this process had an overall negative impact on our compiler performance against the benchmarks because of the increased size of code caused by insertion of lines with temporary variables getting allocated to available common expressions, we implemented this optimization none-the-less as it paved our way towards other optimizations, making it possible to perform copy-propagation on the program, which is discussed further in the document.

2.4 Copy Propagation

Next we perform a data flow analysis on the various variables to check for their liveness. Here, we also built Use-Definition Chains (UD Chain) for each use of each

variable. These were structured as hash tables where the symbol (or location variable) and their respective definitions were used as keys and array lists of all the corresponding uses was present as the value.

Based on the above program, we had the following result obtained from common subexpression elimination:

```
main : EMPTY_STATEMENT
_{2} L0 : \#_{-}t0 = 2
_{3} L1 : \#_{-}t1 = get_{-}int(\#_{-}t0,)
4 L2 : a = \#_{-}t1
5 L3 : \#_{-}t2 = 3
_{6} L4 : \#_{t}3 = get_{int}(\#_{t}2,)
^{7} L5 : b = \#_{-}t3
8 L6 : \#_{-}t4 = 0
9 L7 : c = \#_{-}t4
10 L8 : \#_{-}t5 = 0
11 L9 : d = \#_t 5
12 L10 : \#_t6 = a + b
13 L11 : \#_{t}7 = \#_{t}6
_{14} L12 : \#_{-}t8 = \#_{-}t6 * \#_{-}t7
15 \text{ L}13 : c = \#_{-}t8
_{16} \text{ L}_{14} : \#_{-}_{1}_{9} = \#_{-}_{1}_{6}
_{17} L15 : \#_{-}t10 = \#_{-}t6
18 L16 : \#_{t}11 = \#_{t}9 / \#_{t}10
19 L17 : d = \#_{-}t11
20 L18 : \#_{t}13 = printf(\#str_{t}12, c,)
L19 : \#_{t}15 = printf(\#str_{t}14, d,)
```

On running our copy propagation algorithm on this, we replace the occurrences of targets of direct assignments with their values. While this optimization did not directly reduce our code size, it lead to a small number of reduction in the number of the operations being performed, and acted as an enabling optimization for dead code elimination, which had very significant impact on performance of our compiler.

```
main : EMPTY_STATEMENT
_{2} L0 : \#_{-}t0 = 2
_{3} L1 : \#_{-}t1 = get_{-}int(2,)
4 L2 : a = \#_{-}t1
5 L3 : \#_{-}t2 = 3
_{6} \text{ L4} : \#_{-} \text{t3} = \text{get\_int}(3,)
7 \text{ L5} : b = \#_{-}t3
8 L6 : \#_{-}t4 = 0
^{9} L7 : c = 0
10 L8 : \#_{-}t5 = 0
11 L9 : d = 0
12 \text{ L}10 : \#_{-}t6 = \#_{-}t1 + \#_{-}t3
13 L11 : \#_{-}t7 = \#_{-}t6
14 L12 : \#_{-}t8 = \#_{-}t6 * \#_{-}t6
L13 : c = \#_{-}t8
L14 : \#_{-}t9 = \#_{-}t6
17 L15 : #_t10 = #_t6
18 L16 : \#_{t}11 = \#_{t}6 / \#_{t}6
```

```
19 L17 : d = #_t11

20 L18 : #_t13 = printf(#str_t12,#_t8,)

21 L19 : #_t15 = printf(#str_t14,#_t11,)
```

2.5 Dead Code Elimination

Next we performed dead code elimination, where we removed local variables that are assigned a value but are not read by any subsequent instruction. This optimization was a lead up from common subexpression elimination and copy propagation, and had a very significant impact on the overall performance, and led to a decrease by about 15-20% in the total execution time of the benchmark programs. In the process of translating the given program from high level to low level intermediate representation, we added multiple lines repeated lines of code. These extra lines of dead code were also cleaned up by this process - that contributed to the total perceived speedup in execution time.

From the result of the copy propagation carried out previously, we had,

```
main : EMPTY_STATEMENT
_{2} L0 : \#_{-}t0 = 2
_{3} L1 : \#_{-}t1 = get_{-}int(2,)
4 L2 : a = \#_{-}t1
5 L3 : \#_{-}t2 = 3
6 \text{ L4} : \#_{-}t3 = \text{get\_int}(3,)
          b = \#_{-}t3
7 L5:
8 L6 :
          \#_{-}t4 = 0
9 L7 :
          c = 0
10 L8 :
           \#_{-}t5 = 0
11 L9 :
           d = 0
12 \text{ L}10 : \#_{-}t6 = \#_{-}t1 + \#_{-}t3
13 L11 : \#_{t}7 = \#_{t}6
_{14} \text{ L}12 : \#_{-}t8 = \#_{-}t6 * \#_{-}t6
15 L13 :
            c = \#_{-}t8
16 \text{ L}14 : \#_{-}t9 = \#_{-}t6
_{17} \text{ L}15 : \#_{-}\text{t}10 = \#_{-}\text{t}6
18 L16 : \#_{-}t11 = \#_{-}t6 / \#_{-}t6
19 L17 : d = \#_{-}t11
20 L18 : \#_{t}13 = printf(\#str_{t}12, \#_{t}8,)
\mu_{1} L19 : \#_{t}15 = printf(\#str_{t}14, \#_{t}11, )
```

After eliminating all the dead stores, we can see that the code size, especially for this particular example from the test suite is considerably reduced, and is as follows:

```
main : EMPTY.STATEMENT

L1 : #_t1 = get_int(2,)

L4 : #_t3 = get_int(3,)

L10 : #_t6 = #_t1 + #_t3

L12 : #_t8 = #_t6 * #_t6

L16 : #_t11 = #_t6 / #_t6
```

```
7 L18 : #_t13 = printf(#str_t12,#_t8,)
8 L19 : #_t15 = printf(#str_t14,#_t11,)
```

In this particular case, we observed a reduction in the size of the generated code by approximately a factor of 14th. This further confirms the utility of this optimization and the applicability across various different programs.

2.6 Constant Folding

We perform constant folding at the low level IR stage, where we evaluate and compute constant expressions at compile time rather than computing them at runtime. This is done to avoid repeated and multiple computations, especially inside for loops, such as are in the provided benchmarks and testing suites.

For example, in the following case, constant folding saves 3 multiplication evaluations for each iteration of the loops, leading to a total reduction in about 300000 instructions getting executed. Because of the nature of programs, and presence of repeated computations in loops, this led to a very significant improvement in compiler performance.

Upon application of constant folding, followed by code generation, this program was translated to the following assembly code, where we can observe that the total number of multiplication computations relating to constants have been considerably reduced and the multiplication product for (1024*60*4), that is 245760 has been introduced in the generated code. Note that the result shown below is a small snippet of a much larger generated code for the benchmark program.

```
movq -784(%rbp), %r11

imulq %r10, %r11

movq %r11, %r10

movq %r10, -792(%rbp)

movq $245760, %r10

movq %r10, -800(%rbp)

movq $245760, %r10
```

```
-792(\% \text{rbp}), \% \text{r} 11
         movq
                  %r11, %rax
         movq
9
         cqo
         idivq
                  %r10
                   %rax, %r10
         movq
12
                  %r10, -808(%rbp)
         movq
                   -808(\% \text{rbp}), \% \text{r} 10
14
         movq
                  %r10, -176(%rbp)
         movq
                   $2193, %r10
         movq
16
                  %r10, -816(%rbp)
         movq
17
                   $2193, %r10
         movq
18
                   -16(\% \text{rbp}), \% \text{r} 11
         movq
19
                  %r10, %r11
         imulq
20
                  %r11, %r10
         movq
         movq
                  \%r10, -824(\%rbp)
                   \$3, \%r 10
         movq
                  \%r10, -832(\%rbp)
         movq
24
                   \$3, \%r 10
25
         movq
                   -40(\% \text{rbp}), \% \text{r} 11
         movq
26
                  %r10, %r11
         imulq
```

2.7 Algebraic Simplification

```
i + 0 = 0 + i = i - 0 = i
2 \cdot 0 - i = -i
3 \cdot i * 1 = 1 * i = i / 1 = i
4 \cdot i * 0 = 0 * i = 0
5 - (-i) = i
6 \cdot i + (-j) = i - j
7 \cdot b \mid | true = true \mid | b = true
8 \cdot b \mid | false = false \mid | b = b
```

Algebraic Simplification is the process by which we invoke basic algebraic identifies for to simplifying expressions or to determine whether 2 expressions are equivalent. Boolean algebraic simplifications can be particularly as they can sometimes illuminate that certain conditional branch will always evaluate to the same condition. This would enable the compiler to be able to swap out the conditional branch with an unconditional branch saving several lines of code in the process.

2.8 Unreachable Code Elimination

To minimize cache misses to whatever extent possible, we reduced the size of the code and implemented unreachable code elimination as an optimization to reduce the overall size of our code base and get rid of all the code blocks in the control flow graph (CFG) that can't ever be reached during the execution of the program, on starting

with the basic block containing the entry point for the function, and on following the directed edges from one basic block to another. This provided our compiler with a minor speedup. URE is performed at the low level IR stage via a breadth first search on the CGF, to check for connectivity.

```
f : EMPTY.STATEMENT
_{2} L0 : \#_{-}t0 = 0
_{3} L1 : i = \#_{-}t0
5 FOR_COND_L2 : EMPTY_STATEMENT
_{6} \text{ L4} : \#_{-} \text{t1} = 1000000
7 \text{ L5} : \#_{-} \text{t2} = \text{i} < \#_{-} \text{t1}
8 L6 : if #_t2 goto FOR_L3
10 L7 : goto END_FOR_L3
12 FOR_L3 : EMPTY_STATEMENT
13 L8 : \#_{-}t3 = 2
14 \text{ L9} : \#_{-}t4 = A[i]
15 L10 : A[i] = \#_t t 4
_{16} \text{ L11} : \#_{-} \text{t5} = 1
17 L12 : \#_t6 = i + \#_t5
18 L13 :
           i = \#_{-}t6
19 L14 :
           goto FOR_COND_L2
21 L15 : EMPTY_STATEMENT
22 L16 :
           EMPTY_STATEMENT
23 L17 : EMPTY_STATEMENT
           EMPTY_STATEMENT
           EMPTY_STATEMENT
  L19:
27 END_FOR_L3 : EMPTY_STATEMENT
```

In the low level IR, the set of empty (deleted/removed) statements from l15 and L1 is here the unreachable code basic block is removed, as they occur after a continue statement in the following example program and will be executed.

```
extern printf();
int A[1000000];

void f() {
   int i;
   for (i = 0; i < 1000000; i += 1) {
        A[i] = A[i] * 2;
        continue;
        printf("This code is unreachable");
   }
}</pre>
```

2.9 Register Allocation

We used a heuristic based greedy algorithm along with the use-def chains of all variable to evaluate the most used variables and locations, and allocate them to registers, thus attempting to keep the value of a variable in a register for as long as possible. Given that registers have significantly faster execution times for instructions, storing variables, large constants and values in registers also reduced the total number of reads and writes we had to make to the stack. This lead to extremely significant improvement in performance against benchmark programs and test suites, especially for programs with loops and multiple definitions and consequent uses of variables. Since we only allocated callee-saved registers for this purpose, calling conventions were not maintained and thus the optimization is extremely general and works independent of the program. For example, if we have the following unoptimized snippet of assembly code:

We significantly optimize runtime by allocating registers to each of the three variables and eliminate all accesses to the stack, as shown below:

As we realized that increasing the number of available register for allocation would have a significantly positive impact on performance, we made the %rbx register available as that wasn't being used for any other purposes.

2.10 Code Generation Optimizations

In trying to make our code run faster, we noticed that the size of the generated code, in terms of number of lines, has an impact on its performance, at least to some extent. We put in an effort to make the generated code as compact as possible. We did this by trying to take advantage of our register allocation to compress some operations that would use multiple lines had they been applied on stack locations. The following snippet of code, for example, shows how we can do a arithmetic operation in much fewer lines of code once we know what register the operands are mapped to after the register allocation.

```
# an assembly code for c = a + b,
# where c is stored in the stack location -8(\% rbp)
```

```
# a to -16(\% \text{rbp}) and b to -24(\% \text{rbp})

5 movq -24(\% \text{rbp}), \% \text{r} 10

6 movq -16(\% \text{rbp}), \% \text{r} 11

7 addq \% \text{r} 10, \% \text{r} 11

8 movq \% \text{r} 11, -8(\% \text{rbp})
```

Applying register allocation in the above code will change the code to:

```
# an assembly code for c = a + b,

# where c is mapped to the register %r12

# a to %r13 and b to %rbx

movq %rbx, %r10

movq %r13, %r11

addq %r10, %r11

movq %r11, %r12
```

Next we apply codegeneration optimization techniques to remove unnessessary lines and make the code even shorter

```
# an assembly code for c = a + b,

# where c is mapped to the register %r12

# a to %r13 and b to %rbx

movq %r13, %r11

addq %rbx, %r11

movq %r11, %r12
```

Over several thousands of lines of code, such small improvements add up to give us a much leaner code, that sometimes results in a slight improvement in performance, possibly due to better cache hit ratio.

3 Full Optimizations

On running our compiler with full optimizations enabled, we run our implemented optimizations in the following order (some optimizations are run multiple number of times as explained below):

- 1. Parallelization
- 2. Canonicalization of expressions
- 3. Algebraic Simplification
- 4. Common Subexpression Elimination
- 5. Copy Propagation

- 6. Constant Folding
- 7. Common Subexpression Elimination
- 8. Copy Propagation
- 9. Dead Code Elimination
- 10. Unreachable Code Elimination
- 11. Register Allocation

In determining the order to perform these optimizations, we first took into consideration which Intermediate Format they would need to be applied to. Both Parallelization and Canonicalization of Expressions (CE) need to be preformed on the High-Level IR because they require specific information about the program's implementation. Since much of this information would get lost after transitioning from the High-Level IR into the Lower-Level IR, we knew that Parallization and Canonicalization of Expressions be preformed first. However, the decision of determining whether Parallelization or CE should come first ultimately to a matter of convinience. That is, our implementation of parallelism was particularly sensitive the format of algebraic expressions such that we decided that it should be preformed prior to CE.

Once the High-Level optimizations were preformed, we would convert the program to a Lower-Level IR. In the Lower-Level IR, we could now preform Algebraic Simplifications, CSE, Copy Propogation, and Constant Folding. To decide on the order for these optimizations, we considered both the benefit from running the optimization itself and the how the optimization would transform the program (i.e. did the transformed program actually make more opportunities for future optimizations available). We found that while Alegbraic Simplifications did not significantly reduce the size or the runtime of the program, it did increase the number of common subexpressions throughout the program. In addition, and not as much of a surprise, we found a similar synergestic affect in running Copy Propogation after CSE and Dead Code Elimination after that.

As can be observed from the listings of our optimizations above, we found that executing CSE and CP multiple times more impactful than just running either once. This was largely due to the fact that after CSE was preformed, it could take multiple iterations of CP to propogate all variable copies that now existed throughout the program. We decide to run CSE multiple times as well since, after CP, we sometimes found that new common subexpressions were created and we wanted to optimize those as well. After running the previous optimizations multiple times, multiple superfluous variables and assignments would exist. As a result, we decided to finished off our Lower-Level IR optimizations with Dead Code Elimination and Unreachable Code Elimination.

The last optimization that we performed was Register Allocation. We necessarily had to hold off this optimization until last because it gets performed on our absolute lowest Intermediate Representation. In addition to this, we decide that it simply

did not make sense to allocate register once, perform some optimization that would further transform the program, only to have perform register allocation again.

4 Challenging Problems Faced

One of the largest challenges that we faced while attempting to leverage parallel execution for methods with loops that have iterations independent of each other, for this design, was to ensure that unsafe/non-parallelizable loops don't get parallelized, as this could lead to incorrect execution and results, or extremely slow timings, given the cost of the system calls that are made by the 6036.c library. We addressed this problem by developing an extremely restrictive criteria for functions and the loops they contain, to be parallelized. Though this caused a lot of completely parallelizable loops to get skipped over, we were able to avoid incorrect evaluations.

5 Command Line Options

5.1 Turing Optimizations On

To turn on various optimizations, the following flags may be added, in any order, to turn on their corresponding optimizations.

- --opt=cse for common subexpression elimination
- --opt=cp for copy propagation
- --opt=dce for dead code elimination
- --opt=ure for unreachable code elimination
- --opt=reg for register allocation
- --opt=parallel for loop parallelization
- --opt=as for canonicalization and algebraic simplification
- --opt=cf for constant folding

To turn on all optimizations and run them in order, as described in the section on full optimizations [3], the --opt=all flag may be used, as follows:

\$./run.sh --target=assembly --opt=all <filename> -o <outputname>

5.2 Running Generated Code

The x86-64 Assembly code generated by our compiler may be run using gcc to execute the program and get results, as follows:

- $\ gcc < filename > -o < output name > -L /< ROOT_DIRECTORY_PATH > /tests/optimizer/lib/ -16035 -lc -lpthread$
- \$./<outputname>