

Fourier Transforms for Circuit and LTI Systems Analysis

Scope and Background Reading

This session we will apply what we have learned about Fourier transforms to some typical circuit problems. After a short introduction, this session will be an examples class.

The material in this presentation and notes is based on Chapter 8 (Starting at Section 8.8) of Steven T. Karris. Signals and Systems: with Matlab Computation and Simulink Modelling. 5th Edition. (<http://site.ebrary.com/lib/swansea/reader.action?docID=10547416&ppg=271>) from the **Required Reading List**. I also used Chapter 5 of Benoit Boulet. Fundamentals of Signals and Systems (<http://site.ebrary.com/lib/swansea/reader.action?docID=10228195&ppg=194>) from the **Recommended Reading List**.

Agenda

- The system function
- Examples
- The system function
- Examples

The System Function

System response from system impulse response

Recall that the convolution integral of a system with impulse response $h(t)$ and input $u(t)$ is

$$h(t) * u(t) = \int_{-\infty}^{\infty} h(t - \tau)u(\tau) d\tau.$$

We let

$$g(t) = h(t) * u(t)$$

Then by the time convolution property

$$h(t) * u(t) = g(t) \Leftrightarrow G(\omega) = H(\omega). U(\omega)$$

The System Function

We call $H(\omega)$ the *system function*.

We note that the system function $H(\omega)$ and the impulse response $h(t)$ form the Fourier transform pair

$$h(t) \Leftrightarrow H(\omega)$$

Obtaining system response

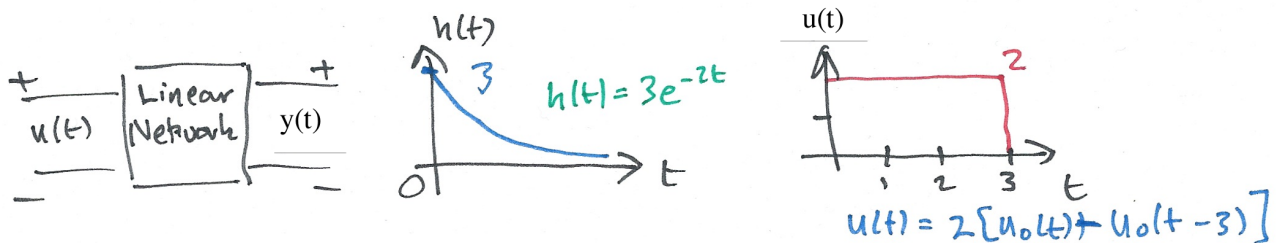
If we know the impulse response $h(t)$, we can compute the system response $g(t)$ of any input $u(t)$ by multiplying the Fourier transforms of $H(\omega)$ and $U(\omega)$ to obtain $G(\omega)$. Then we take the inverse Fourier transform of $G(\omega)$ to obtain the response $g(t)$.

1. Transform $h(t) \rightarrow H(\omega)$
2. Transform $u(t) \rightarrow U(\omega)$
3. Compute $G(\omega) = H(\omega) \cdot U(\omega)$
4. Find $\mathcal{F}^{-1} \{G(\omega)\} \rightarrow g(t)$

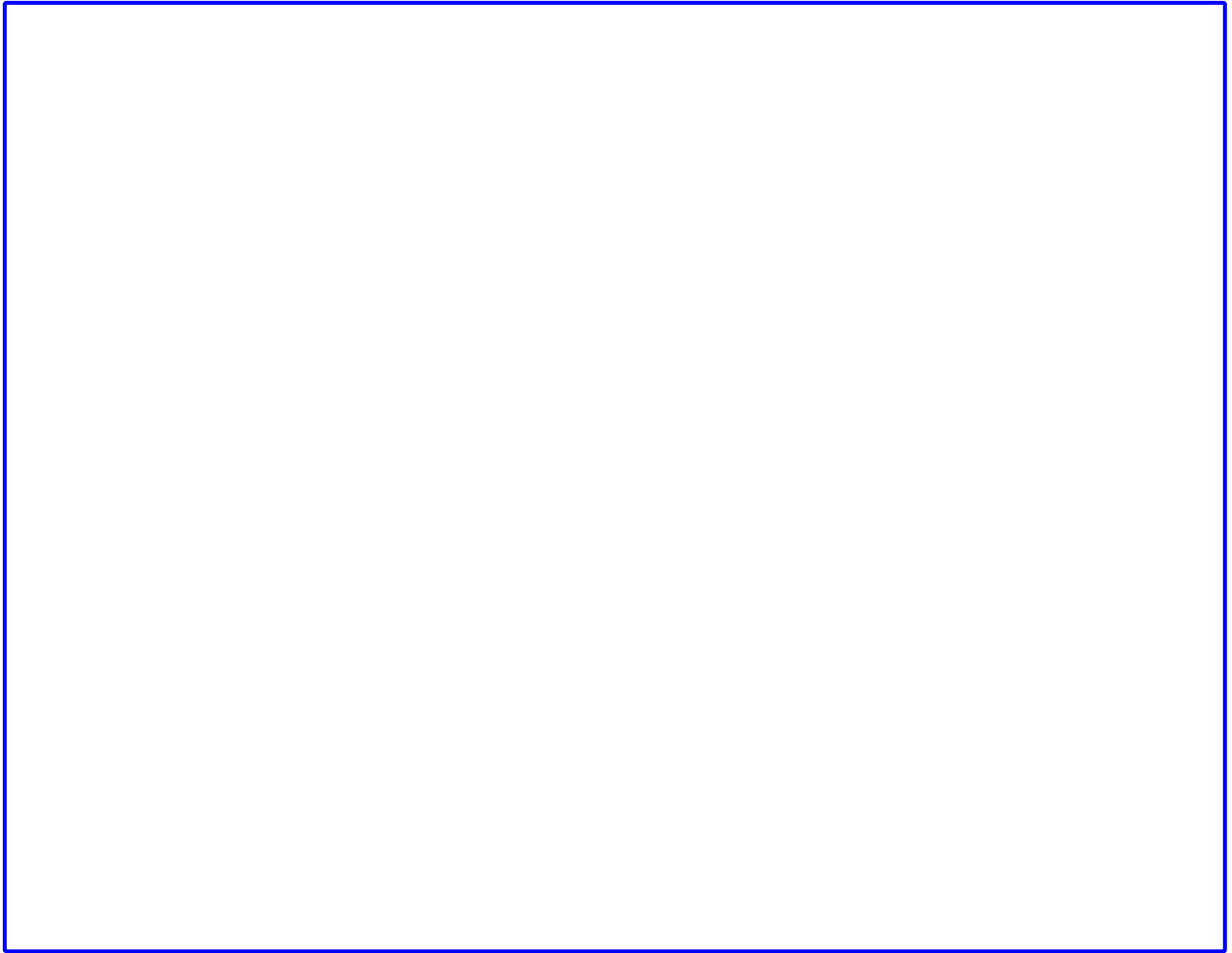
Examples

Example 1

Karris example 8.8: for the linear network shown below, the impulse response is $h(t) = 3e^{-2t}$. Use the Fourier transform to compute the response $y(t)$ when the input $u(t) = 2[u_0(t) - u_0(t - 3)]$. Verify the result with Matlab.



Solution



Matlab verification

See [ft3_ex1.m \(matlab/ft3_ex1.m\)](#)

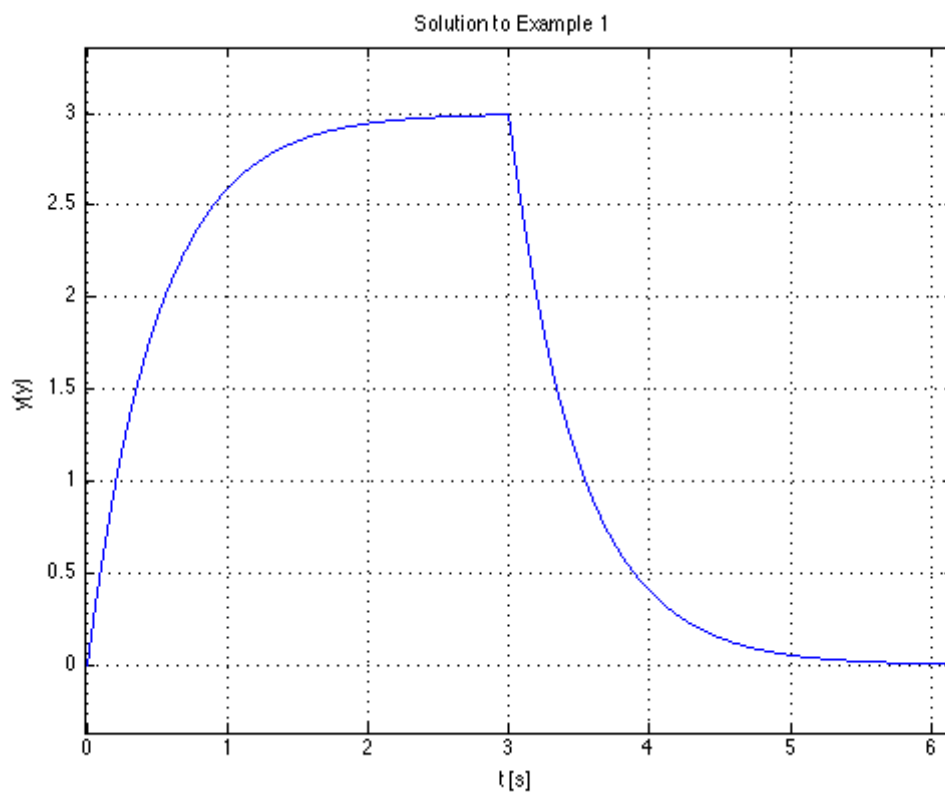
Result:

$$y = 3*\text{heaviside}(t) - 3*\text{heaviside}(t - 3) + 3*\text{heaviside}(t - 3)*\exp(6 - 2*t) - 3*\exp(-2*t)*\text{heaviside}(t)$$

Which after gathering terms gives

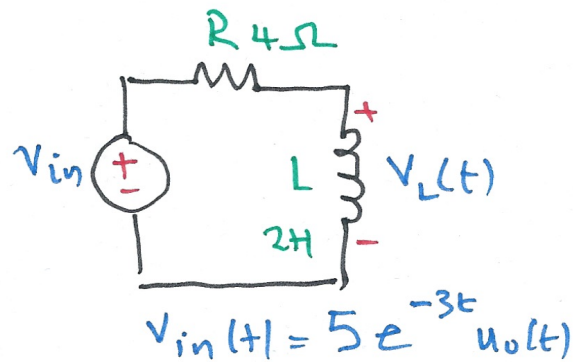
$$y(t) = 3(1 - 3e^{-2t})u_0(t) - 3(1 - 3e^{-2(t-3)})u_0(t - 3)$$

And here's a plot:



Example 2

Karris example 8.9: for the circuit shown below, use the Fourier transform method, and the system function $H(\omega)$ to compute $V_L(t)$. Assume $i_L(0^-) = 0$. Verify the result with Matlab.



Solution



Matlab verification

See [ft3_ex2.m \(matlab/ft3_ex2.m\)](#)

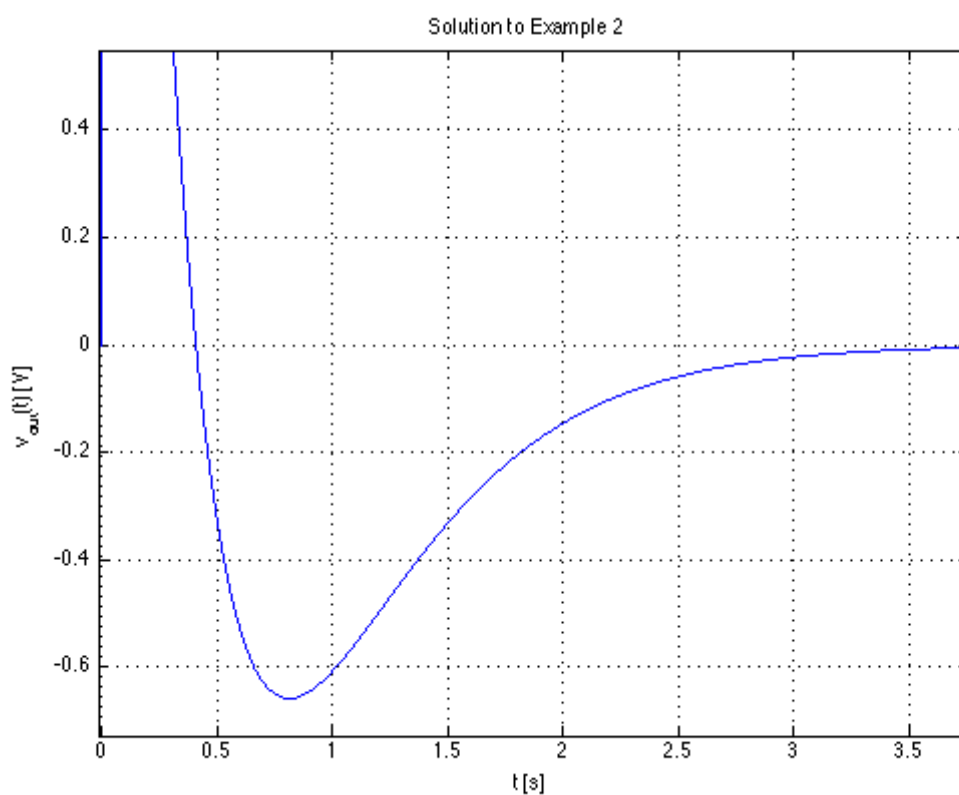
Result:

$$v_{out} = -5 \cdot \exp(-3 \cdot t) \cdot \text{heaviside}(t) \cdot (2 \cdot \exp(t) - 3)$$

Which after gathering terms gives

$$v_{out} = 5 \left(3e^{-3t} - 2e^{-2t} \right) u_0(t)$$

And here's a plot:

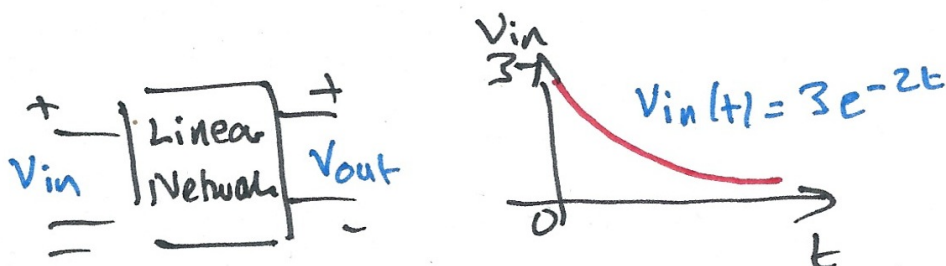


Example 3

Karris example 8.10: for the linear network shown below, the input-output relationship is:

$$\frac{d}{dt}v_{\text{out}} + 4v_{\text{out}} = 10v_{\text{in}}$$

where $v_{\text{in}} = 3e^{-2t}$. Use the Fourier transform method, and the system function $H(\omega)$ to compute the output v_{out} . Verify the result with Matlab.



Solution



Matlab verification

See [ft3_ex3.m \(matlab/ft3_ex3.m\)](#)

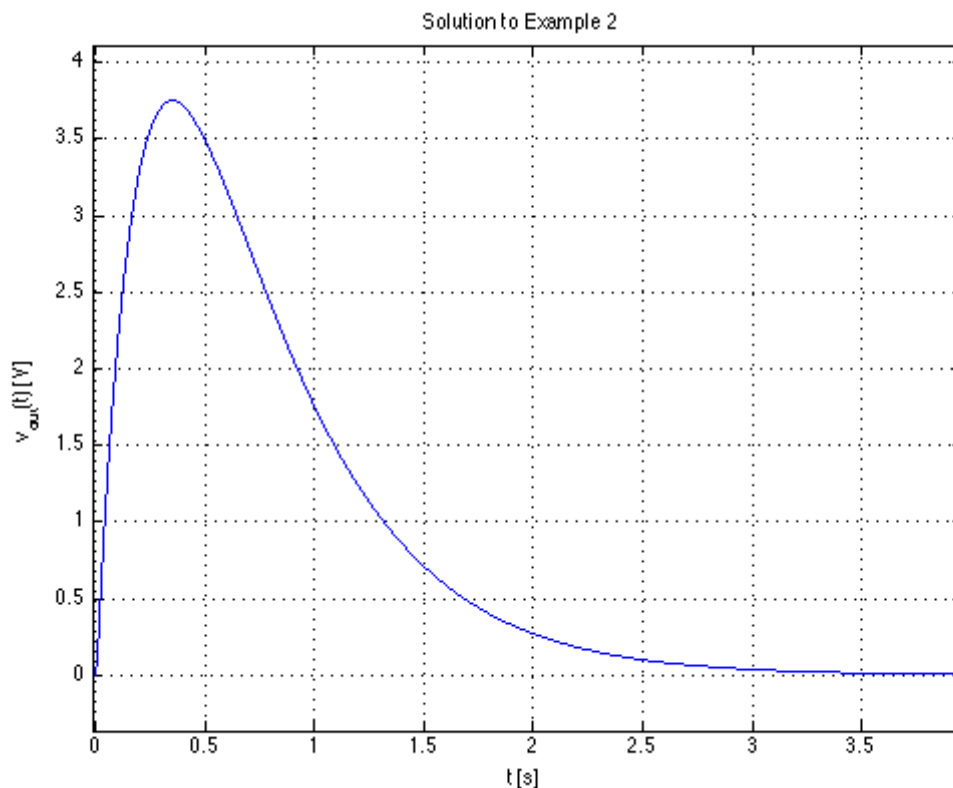
Result:

$$15 \cdot \exp(-4 \cdot t) \cdot \text{heaviside}(t) \cdot (\exp(2 \cdot t) - 1)$$

Which after gathering terms gives

$$v_{\text{out}}(t) = 15 (e^{-2t} - e^{-4t}) u_0(t)$$

And here's a plot:

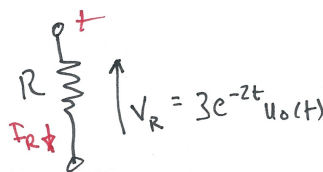


Example 4

Karris example 8.11: the voltage across a 1Ω resistor is known to be $V_R(t) = 3e^{-2t}u_0(t)$. Compute the energy dissipated in the resistor for $0 < t < \infty$, and verify the result using Parseval's theorem. Verify the result with Matlab.

Note from [tables of integrals \(http://en.wikipedia.org/wiki/Lists_of_integrals\)](http://en.wikipedia.org/wiki/Lists_of_integrals)

$$\int \frac{1}{a^2 + x^2} dx = \frac{1}{a} \arctan \frac{x}{a} + C.$$



Solution



Matlab verification

See [ft3_ex4.m \(matlab/ft3_ex4.m\)](#)

Result:

$$w_r = (51607450253003931 * \pi) / 72057594037927936 = 2.25$$

