

# Introduction to Filters

## Scope and Background Reading

This session is Based on the section **Filtering** from Chapter 5 of f Benoit Boulet, Fundamentals of Signals and Systems (<http://site.ebrary.com/lib/swansea/docDetail.action?docID=10228195>) from the **Recommended Reading List**.

This material is an introduction to analogue filters. You will find much more in-depth coverage on Pages 11-1 — 1-48 of Karris.

## Agenda

- Frequency Selective Filters
- Ideal low-pass filter
- Butterworth low-pass filter
- High-pass filter
- Bandpass filter

## Introduction

- Filter design is an important application of the Fourier transform
- Filtering is a rich topic often taught in graduate courses so we give only an introduction.
- Our introduction *will* illustrate the usefulness of the frequency domain viewpoint.
- We will explore how filters can shape the spectrum of a signal.

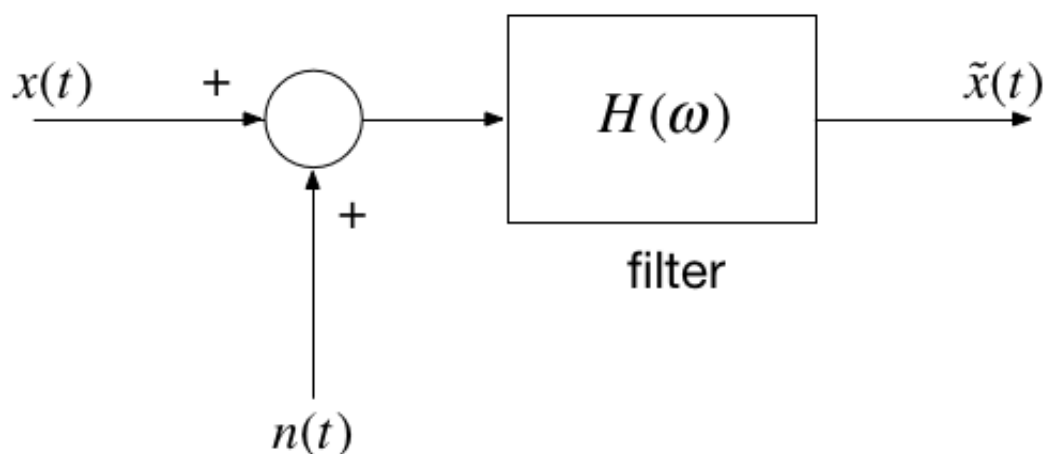
Other applications of the Fourier transform are sampling theory (introduced next week) and modulation.

## Frequency Selective Filters

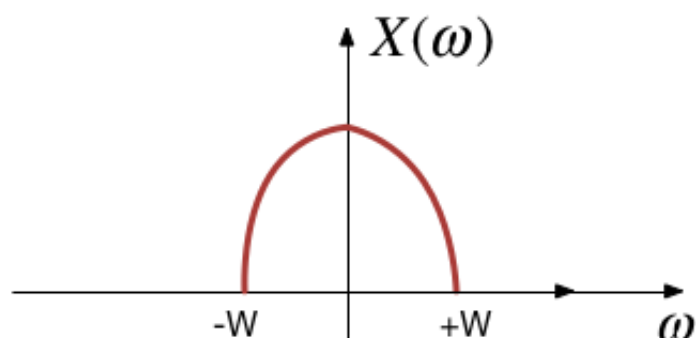
An ideal frequency-selective filter is a system that let's the frequency components of a signal through undistorted while components at other components are completely cut off.

- The range of frequencies which are let through belong to the **pass Band**
- The range of frequencies which are cut-off by the filter are called the **stopband**
- A typical scenario where filtering is needed is when noise  $n(t)$  is added to a signal  $x(t)$  but that signal has most of its energy outside the bandwidth of a signal.

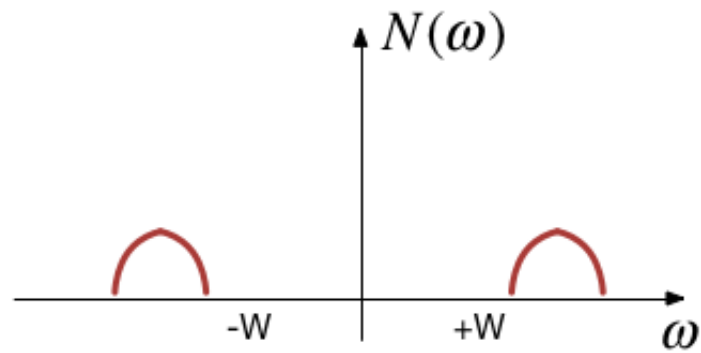
### Typical filtering problem



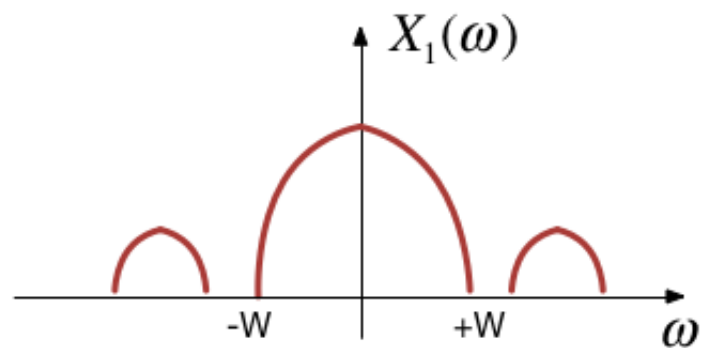
### Signal



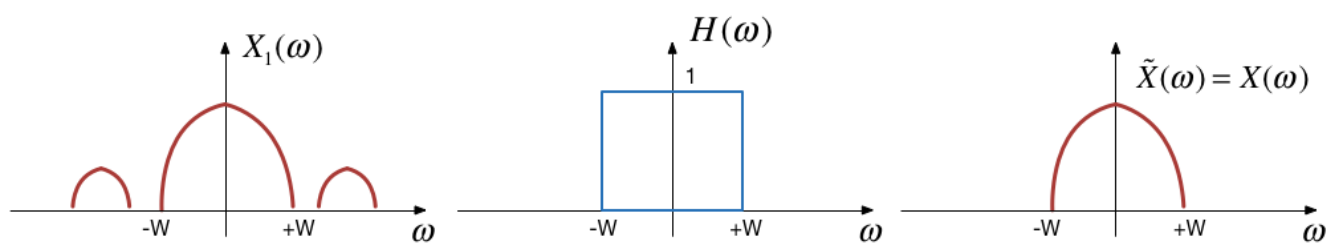
## Out-of Bandwidth Noise



## Signal plus Noise



## Filtering



## Motivating example

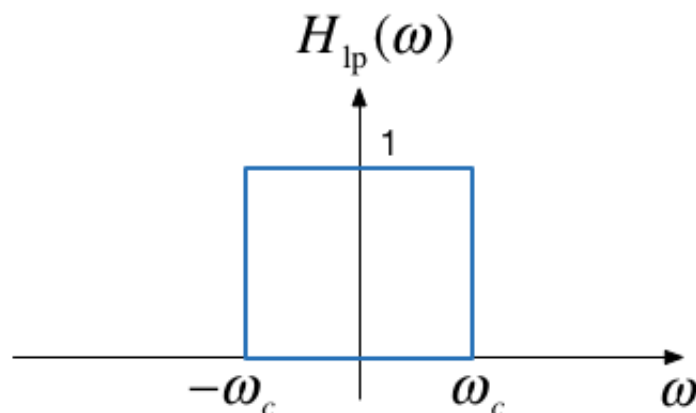
See the notes in the [OneNote Class Room notebook](https://swanseauniversity-my.sharepoint.com/personal/c_p_jobling_swansea_ac_uk/_layouts/15/WopiFrame.aspx?sourcedoc={26f94375-62db-439d-bbcb-5fe8cf2fa0fb}&action=edit&wd=target%28Content%20Library%2FLessons%2FLesson%2016%2Eor0238-6A44-8FDF-0184D3855DB0%2FBefore%20Class%7CE5AD343A-E348-0141-8096-60E0CA201E57%2F%29onenote%3Ahttps%3A%2F%2Fswanseauniversity-my%2Esharepoint%2Ecom%2Fpersonal%2Fc_p_jobling_swansea_ac_uk%2FDocuments%2FClass%247%20Signals%20and%20Systems%20%282015-2016%29or+on+Blackboard) ([https://swanseauniversity-my.sharepoint.com/personal/c\\_p\\_jobling\\_swansea\\_ac\\_uk/\\_layouts/15/WopiFrame.aspx?sourcedoc={26f94375-62db-439d-bbcb-5fe8cf2fa0fb}&action=edit&wd=target%28Content%20Library%2FLessons%2FLesson%2016%2Eor0238-6A44-8FDF-0184D3855DB0%2FBefore%20Class%7CE5AD343A-E348-0141-8096-60E0CA201E57%2F%29onenote%3Ahttps%3A%2F%2Fswanseauniversity-my%2Esharepoint%2Ecom%2Fpersonal%2Fc\\_p\\_jobling\\_swansea\\_ac\\_uk%2FDocuments%2FClass%247%20Signals%20and%20Systems%20%282015-2016%29or+on+Blackboard](https://swanseauniversity-my.sharepoint.com/personal/c_p_jobling_swansea_ac_uk/_layouts/15/WopiFrame.aspx?sourcedoc={26f94375-62db-439d-bbcb-5fe8cf2fa0fb}&action=edit&wd=target%28Content%20Library%2FLessons%2FLesson%2016%2Eor0238-6A44-8FDF-0184D3855DB0%2FBefore%20Class%7CE5AD343A-E348-0141-8096-60E0CA201E57%2F%29onenote%3Ahttps%3A%2F%2Fswanseauniversity-my%2Esharepoint%2Ecom%2Fpersonal%2Fc_p_jobling_swansea_ac_uk%2FDocuments%2FClass%247%20Signals%20and%20Systems%20%282015-2016%29or+on+Blackboard)) or on Blackboard.

## Ideal Low-Pass Filter

An ideal low pass filter cuts-off frequencies higher than its *cutoff frequency*,  $\omega_c$ .

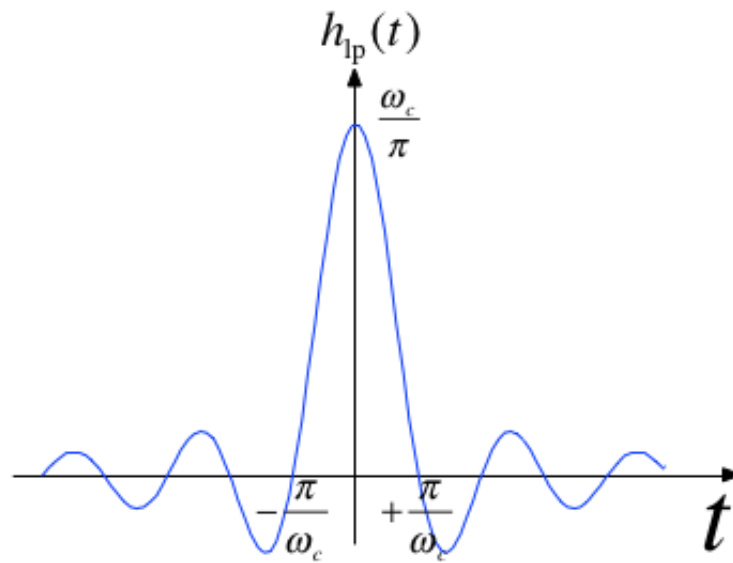
$$H_{\text{lp}}(\omega) = \begin{cases} 1, & |\omega| < \omega_c \\ 0, & |\omega| \geq \omega_c \end{cases}$$

## Frequency response



## Impulse response

$$h_{lp}(t) = \frac{\omega_c}{\pi} \text{sinc}\left(\frac{\omega_c}{\pi} t\right)$$



## Filtering is Convolution

The output of an LTI system with impulse response

$$h(t) \Leftrightarrow H(\omega)$$

subject to an input signal

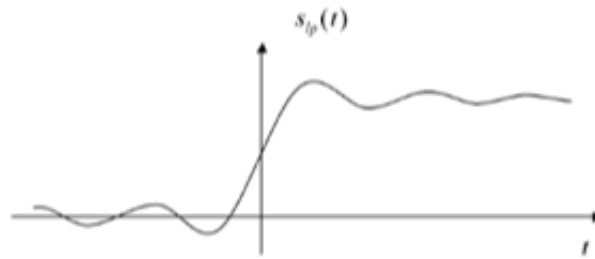
$$x(t) \Leftrightarrow X(\omega)$$

is given by

$$y(t) = h(t) * x(t) \Leftrightarrow Y(\omega) = H(\omega)X(\omega)$$

## Issues with the "ideal" filter

This is the step response:



(reproduced from Boulet Fig. 5.23 p. 205)

Ripples in the impulse response would be undesirable, and because the impulse response is non-causal it cannot actually be implemented.

## Butterworth low-pass filter

N-th Order Butterworth Filter

$$|H_B(\omega)| = \frac{1}{\left(1 + \left(\frac{\omega}{\omega_c}\right)^{2N}\right)^{\frac{1}{2}}}$$

### Remarks

- DC gain is  $|H_B(j0)| = 1$
- Attenuation at the cut-off frequency is  $|H_B(j\omega_c)| = 1/\sqrt{2}$  for any  $N$

More about the Butterworth filter: [Wikipedia Article \(http://en.wikipedia.org/wiki/Butterworth\\_filter\)](http://en.wikipedia.org/wiki/Butterworth_filter)

### Example 1: Second-order BW Filter

The second-order butterworth Filter is defined by its Characteristic Equation (CE):

$$p(s) = s^2 + \omega_c\sqrt{2}s + \omega_c^2 = 0^*$$

Calculate the roots of  $p(s)$  (the poles of the filter transfer function) in both Cartesian and polar form.

**Note:** This has the same characteristic as a control system with damping ratio  $\zeta = 1/\sqrt{2}$  and  $\omega_n = \omega_c$ !

## Solution



## Example 2

Derive the differential equation relating the input  $x(t)$  to output  $y(t)$  of the 2nd-Order Butterworth Low-Pass Filter with cutoff frequency  $\omega_c$ .

## Solution

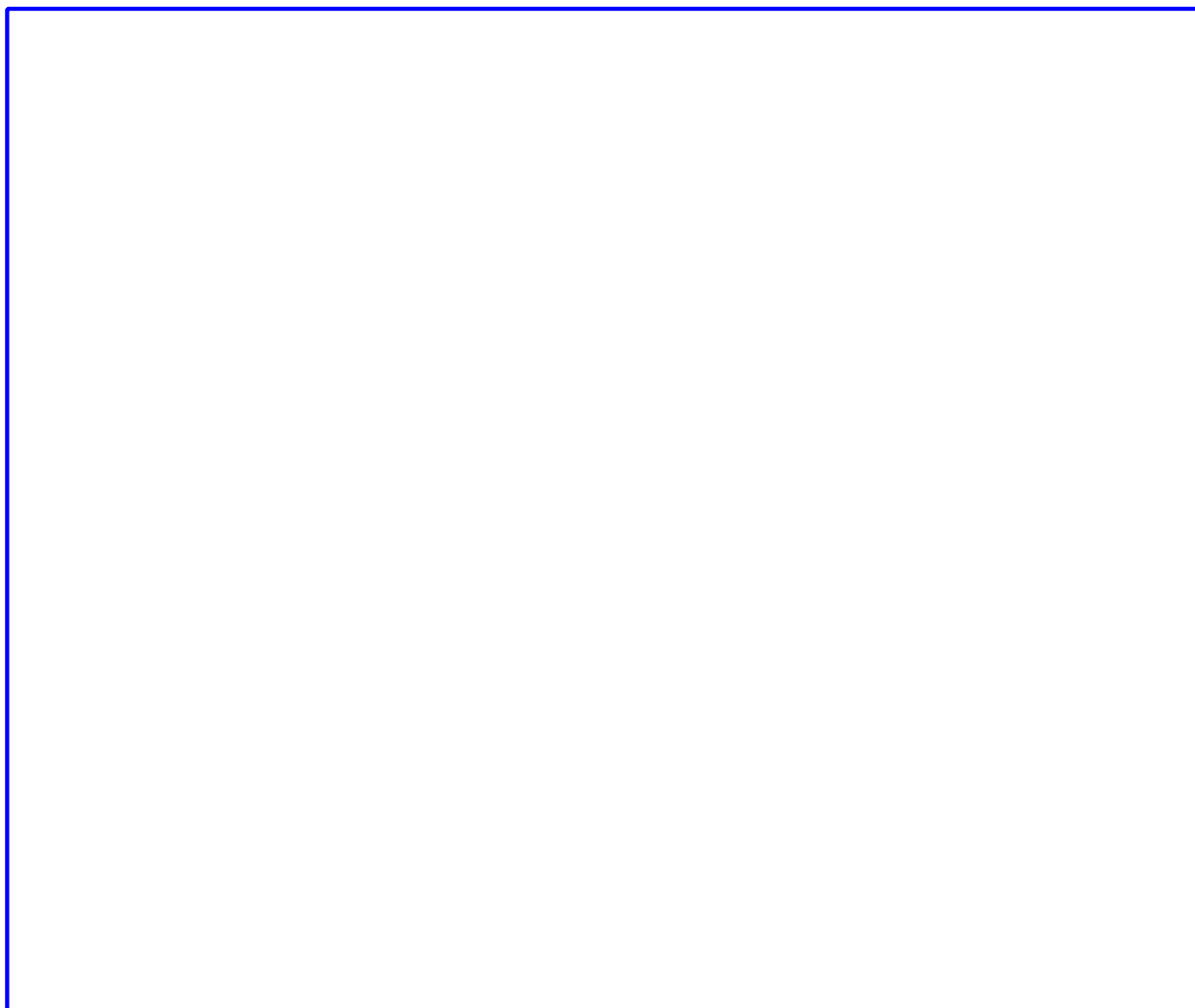


## Example 3

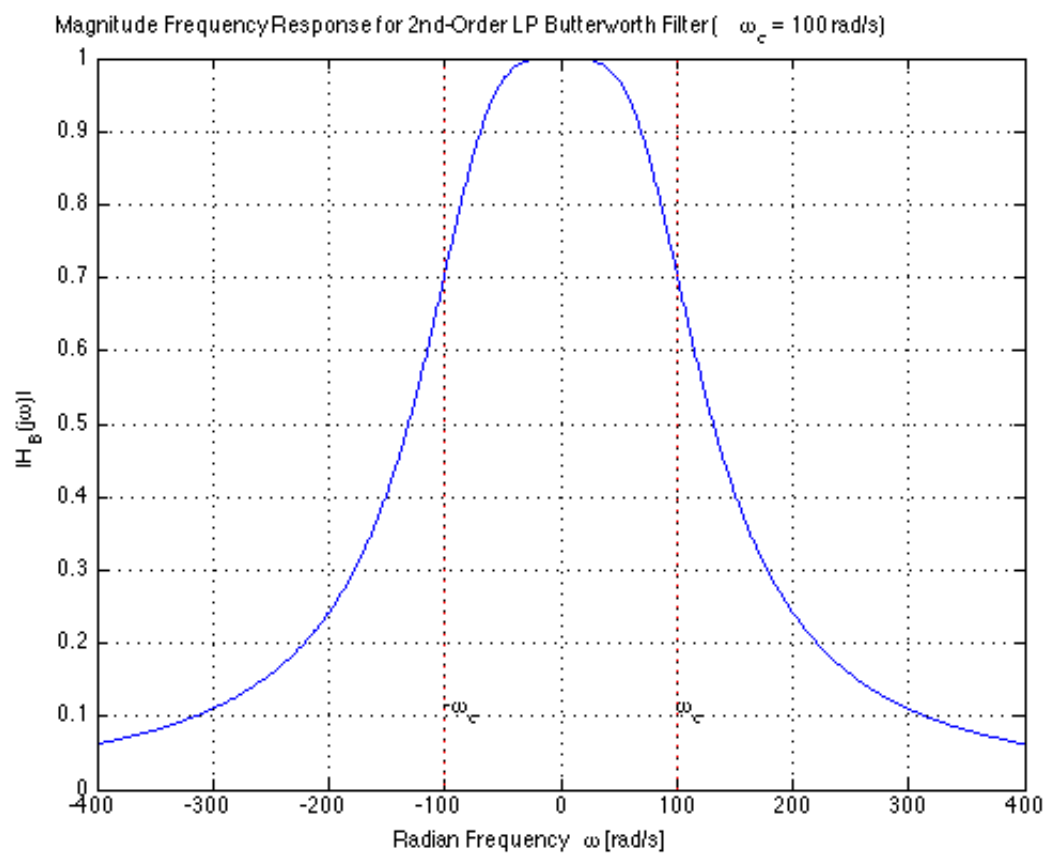
Determine the frequency response  $H_B(\omega) = Y(\omega)/X(\omega)$



## Solution

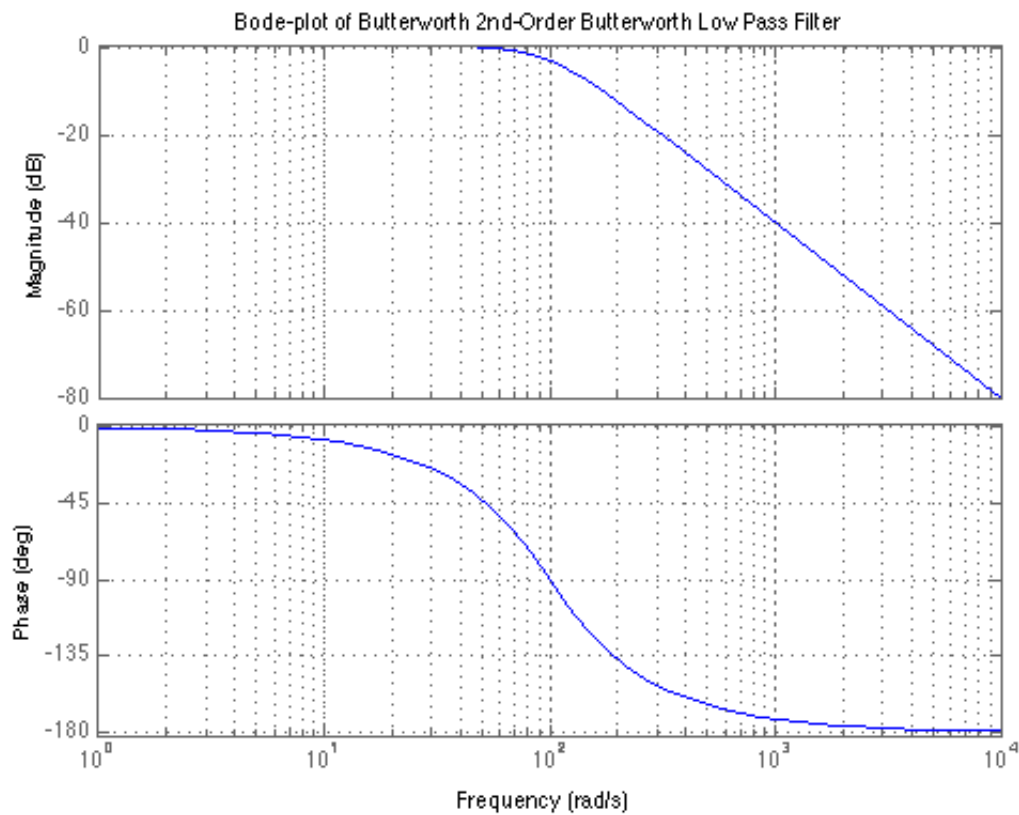


## Magnitude of frequency response of a 2nd-order Butterworth Filter



Generated with [butter2\\_ex.m \(matlab/butter2\\_ex.m\)](#)

## Bode-plot of a 2nd-order Butterworth Filter



Matlab:

```

wc = 100;
H = tf(wc^2,[1, wc*sqrt(2), wc^2])
bode(H)

```

Generated with [butter2\\_ex.m \(matlab/butter2\\_ex.m\)](#)

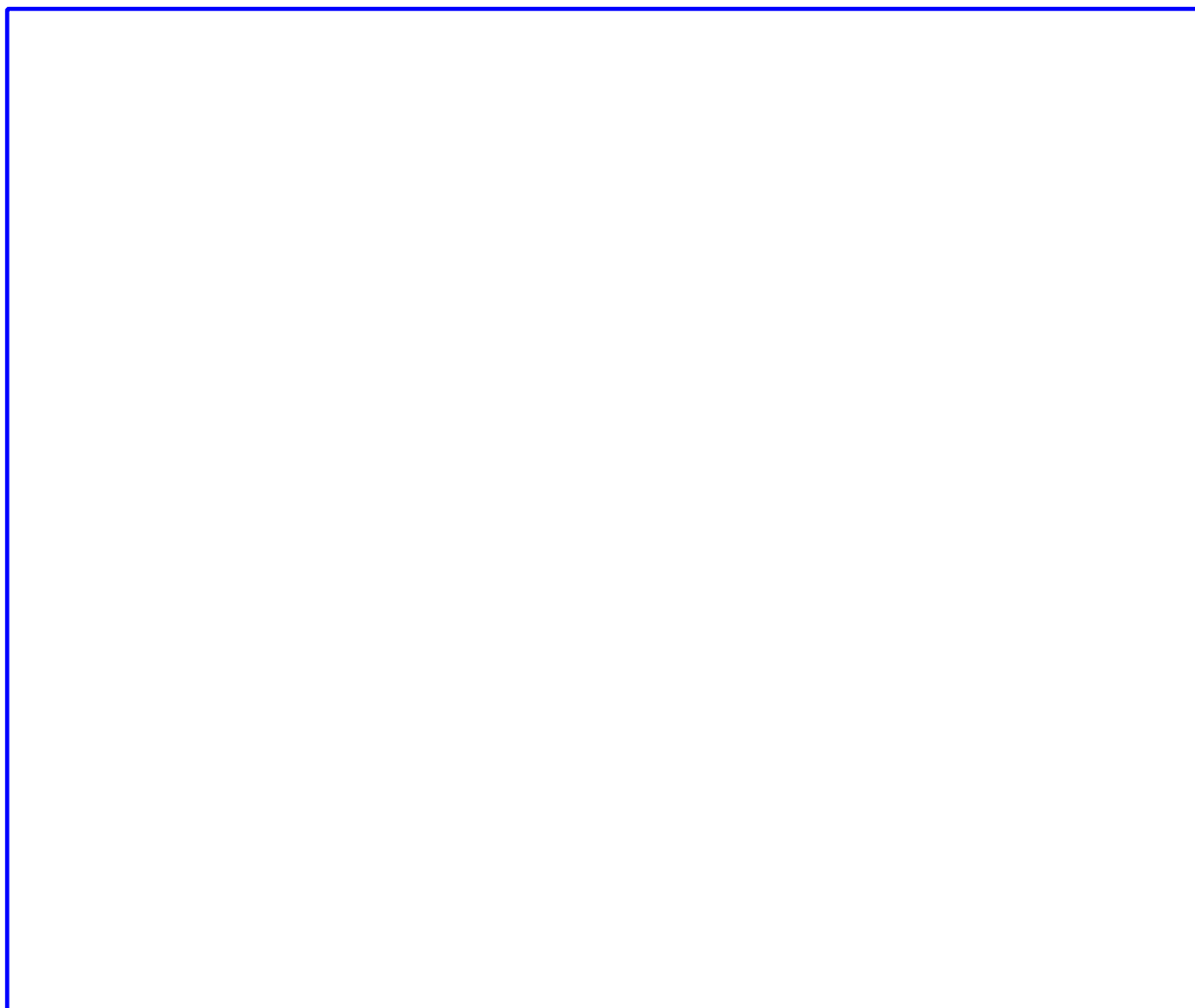
## Example 4

Determine the impulse response of the butterworth filter.

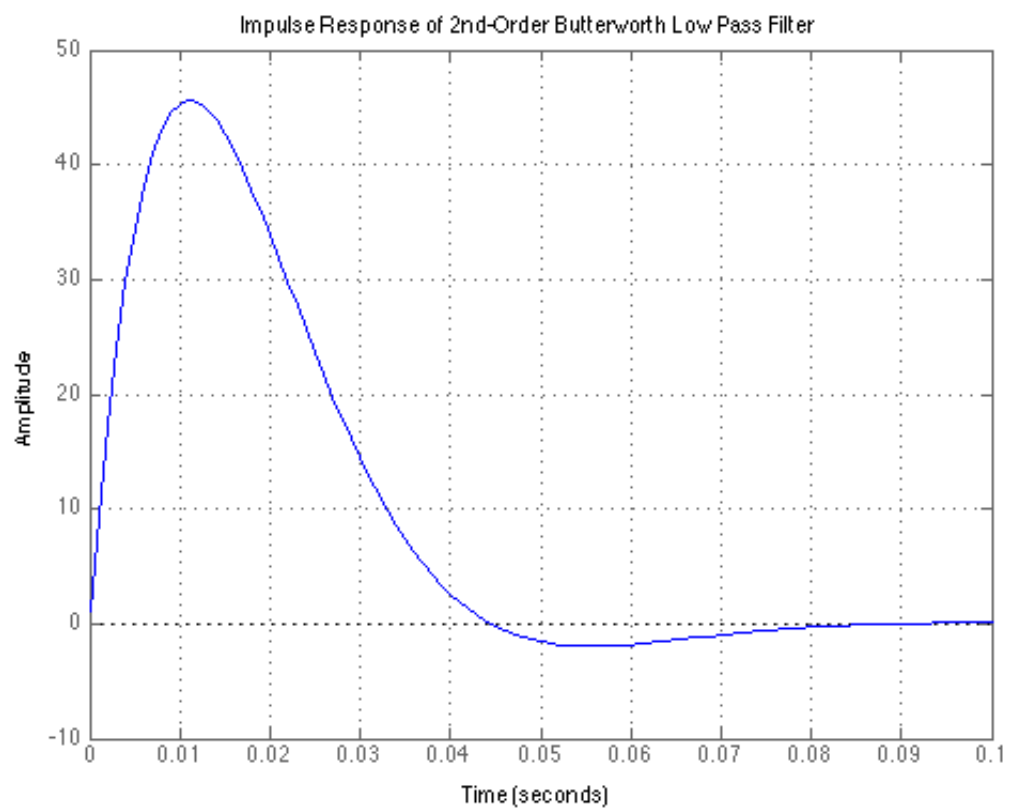
You will find this Fourier transform pair useful:

$$e^{-at} \sin \omega_0 t u_0(t) \Leftrightarrow \frac{\omega_0}{(j\omega + a)^2 + \omega_0^2}$$

## Solution



## Impulse response

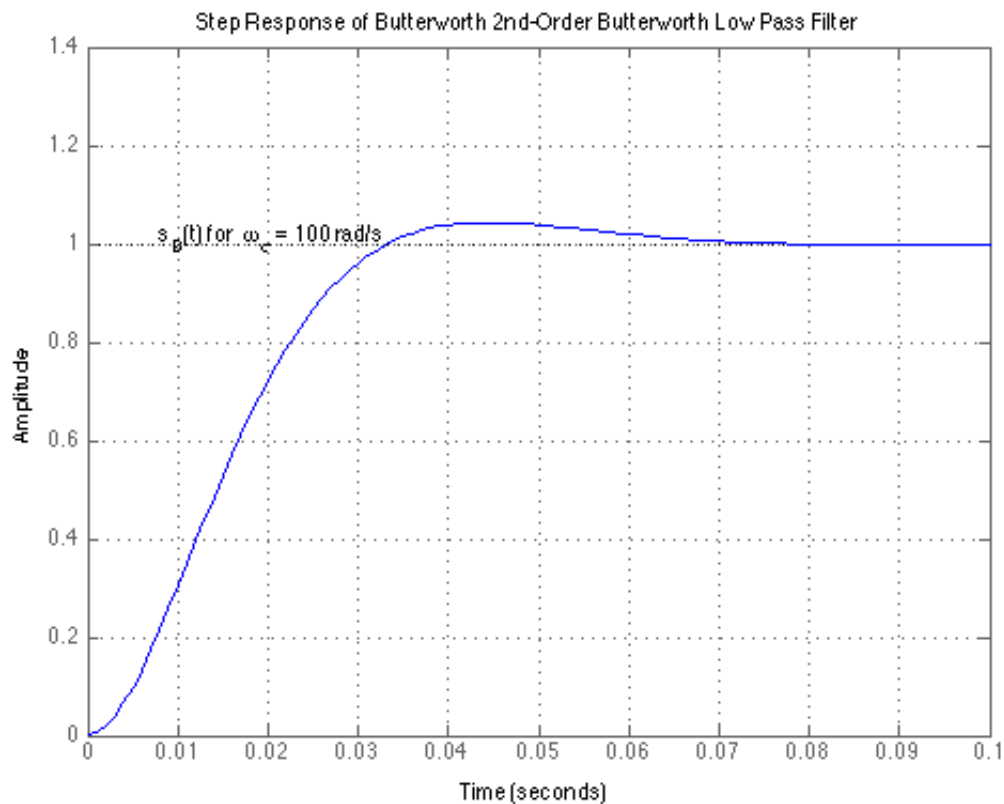


Matlab:

```
impulse(H)
```

Generated with [butter2\\_ex.m \(matlab/butter2\\_ex.m\)](#)

## Step response of of a 2nd-order Butterworth Filter



Matlab:

```
step(H)
```

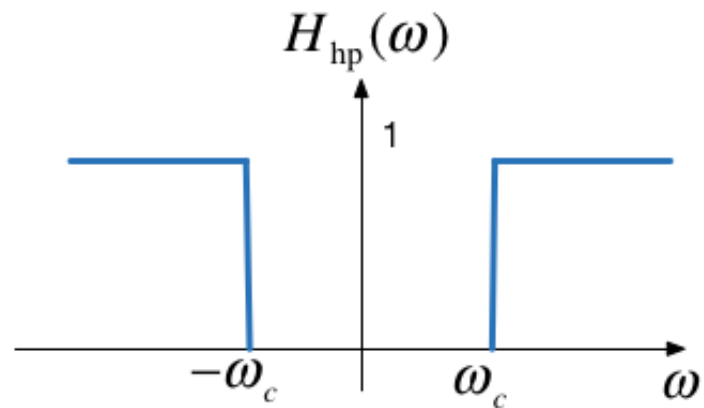
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## High-pass filter

An ideal highpass filter cuts-off frequencies lower than its *cutoff frequency*,  $\omega_c$ .

$$H_{\text{hp}}(\omega) = \begin{cases} 0, & |\omega| \leq \omega_c \\ 1, & |\omega| > \omega_c \end{cases}$$

## Frequency response



## Responses

### Frequency response

$$H_{hp}(\omega) = 1 - H_{lp}(\omega)$$

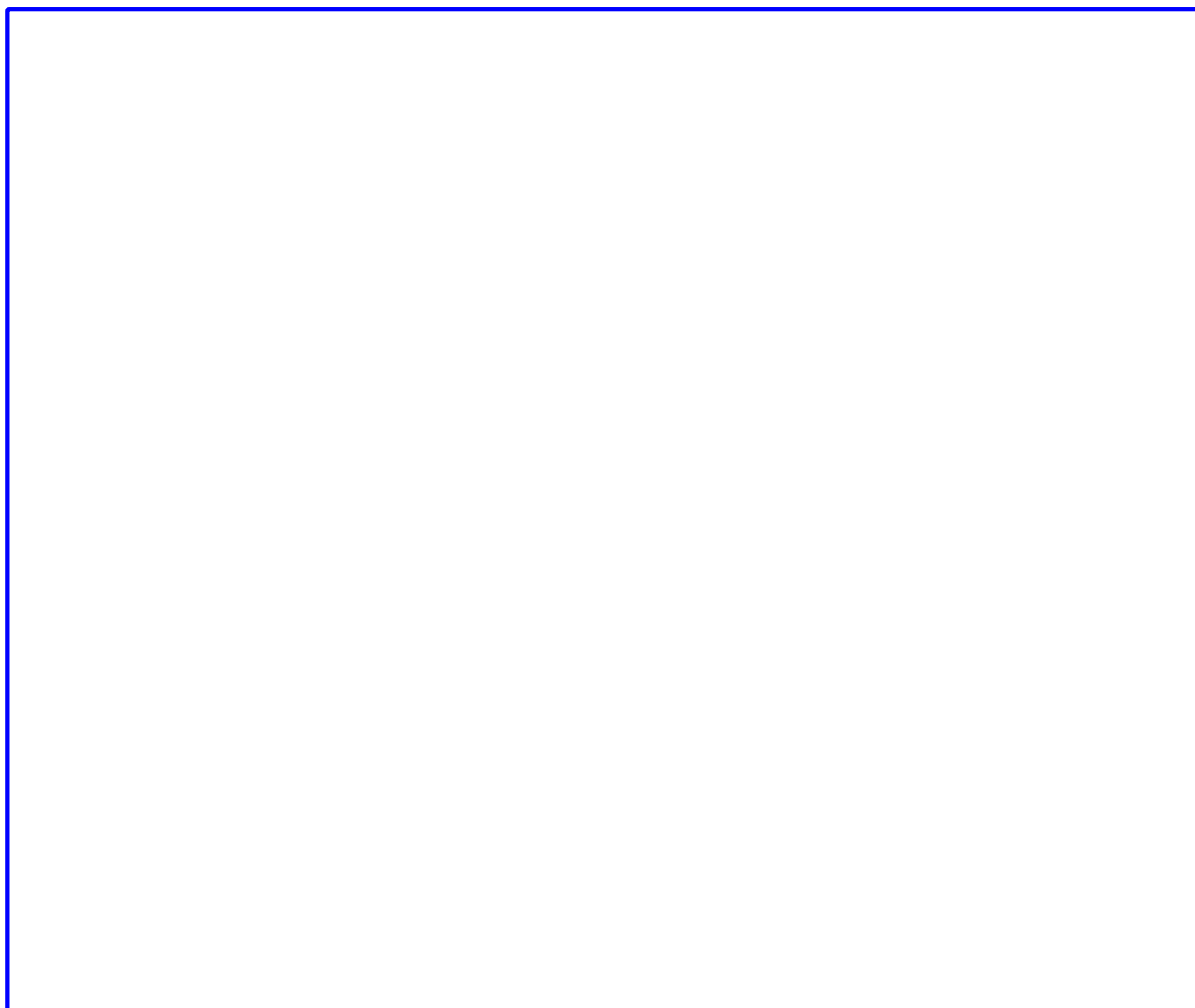
### Impulse response

$$h_{hp}(t) = \delta(t) - h_{lp}(t)$$

## Example 5

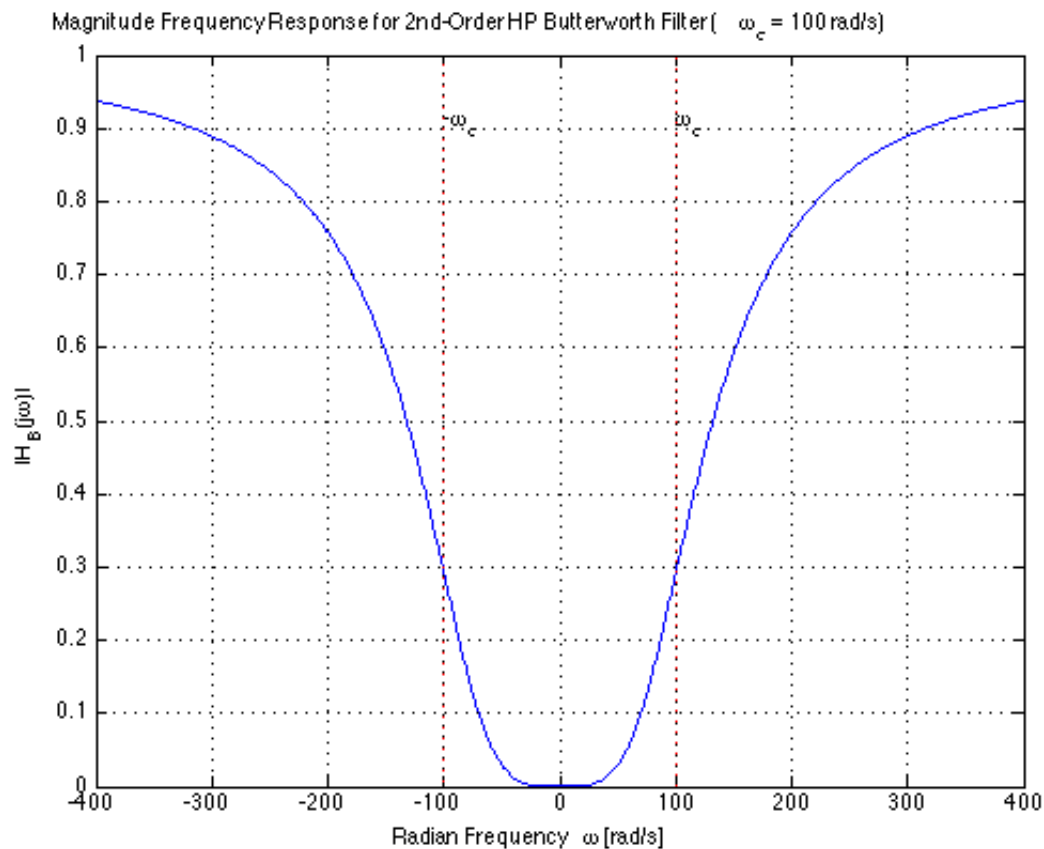
Determine the frequency response and impulse response of a 2nd-order butterworth highpass filter

## Solution





## Magnitude of frequency response of a 2nd-order Butterworth High-Pass Filter

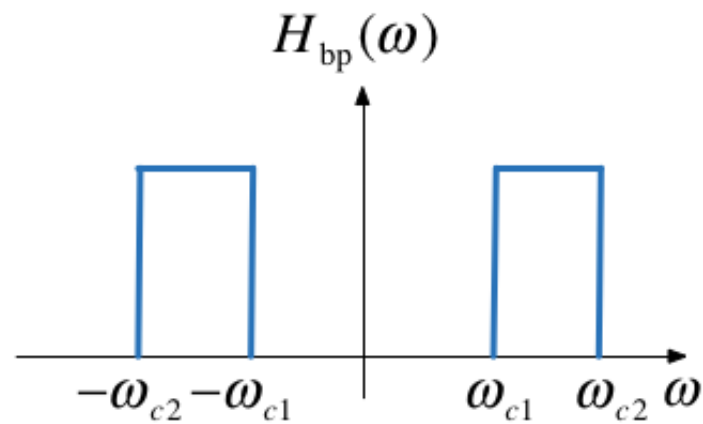


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## Band-pass filter

An ideal bandpass filter cuts-off frequencies lower than its first *cutoff frequency*  $\omega_{c1}$ , and higher than its second *cutoff frequency*  $\omega_{c2}$ .

$$H_{bp}(\omega) = \begin{cases} 1, & \omega_{c1} < |\omega| < \omega_{c2} \\ 0, & \text{otherwise} \end{cases}$$



## Bandpass filter design

A bandpass filter can be obtained by multiplying the frequency responses of a lowpass filter by a highpass filter.

$$H_{bp}(\omega) = H_{hp}(\omega)H_{lp}(\omega)$$

- The highpass filter should have cut-off frequency of  $\omega_{c1}$
- The lowpass filter should have cut-off frequency of  $\omega_{c2}$

## Summary

- Frequency Selective Filters
- Ideal low-pass filter
- Butterworth low-pass filter
- High-pass filter
- Bandpass filter

*Next Lesson* – sampling theory