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FLOW123D - draft, scheme of new inputs

version 1.7.0

Documentation of file formats and brief user manual.

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Chapter 1

Overview

Flow123D is a software for simulation of water flow and reactionary solute transport in a heterogeneous porous and fractured medium. In particular it is suited for simulation of underground processes in a granite rock massive. The program is able to describe explicitly processes in 3D medium, 2D fractures, and 1D chanels and exchange between domains of different dimension. The computational mesh is therefore collection of 3D tetrahedrons, 2D triangles and 1D line segments.

The water flow model assumes a saturated medium described by Darcy law. For discretization, we use lumped mixed-hybrid finite element method. We support both steady and unsteady water flow.

The solute transport model can deal with several dissolved substances. It contains non-equilibrium dual porosity model, i.e. exchange between mobile and immobile pores. There is also model for several types of adsorption in both the mobile and immobile zone. The implemented adsorption models are linear adsorption, Freundlich isotherm and Langmuir isotherm. The solute transport model uses finite volume discretization with up-winding in space and explicit Euler discretization in time. The dual porosity and the adsorption are introduced into transport by operator splitting. The dual porosity model use analytic solution and the non-linear adsorption is solved numerically by the Newton method.

Reaction between transported substances can be modeled either by a SEMCHEM module, which is slow, but can describe all sorts of reactions. On the other hand, for reactions of the first order, i.e. linear reactions or decays, we provide our own solver which is much faster. Reactions are coupled with transport by the operator splitting method,

The program provides output of the pressure, the velocity and the concentration fields in two file formats. You can use file format of GMSH mesh generator and post-processor or you can use output into widely supported VTK format. In particular we recommend Paraview software for visualization and post-processing of VTK data.

The program is implemented in C/C++ using essentially PETSC library for linear algebra. The water flow as well as the transport simulation and reactions can be computed in parallel using MPI environment.

The program is distributed under GNU GPL v. 3 license and is available on the project web page: http://dev.nti.tul.cz/trac/flow123d

1.1 Basic usage

1.1.1 How to run the simulation.

On the Linux system the program can be started either directly or through a script flow123d.sh. When started directly, e.g. by the command

> flow123d -s example.ini

the program requires one argument after switch -s which is the name of the principal input file. Full list of possible command line arguments is as follows.

-s file

Set principal INI input file. All relative paths in the INI file are relative against current directory.

-S file

Set principal INI input file. All relative paths in the INI file are relative against directory of the INI file. This is equivalent to change directory to the directory of the INI file at the start of the program.

-i path

When there is string \${INPUT} in the any path in the INI file, it will be replaced by given path.

-o *path*

Every relative path for any output file will be relative to this path.

All other parameters will be passed to the PETSC library. An advanced user can influence lot of parameters of linear solver. In order to get list of supported options use parameter -help.

Alternatively, you can use script flow123d.sh to start parallel jobs or limit resources used by the program. This script accepts the same parameters as the program itself and further following additional parameters:

-h

Usage overview.

-t timeout

Upper estimate for real running time of the calculation. Kill calculation after *timeout* seconds. Can also be used by PBS to choose appropriate job queue.

-np number of processes

Specify number of parallel processes for calculation.

-m memory limit

Limits total available memory to memory limit bytes.

-n priority

Change (lower) priority for the calculation. See nice command.

-r out file

Stdout and stderr will be redirected to out file.

On the Windows system we use Cygwin libraries in other to emulate Linux API. Therefore you have to keep the Cygwin libraries within the same directry as the program executable. The Windows package that can be downloaded from project web page contains both the Cygwin libraries and the mpiexec command for starting parallel jobs on the Windows workstations.

Then you can start the sequential run by the command:

```
> flow123d.exe -s example.ini
```

or the parallel run by the command:

```
> mpiexec.exe -np 2 flow123d.exe -s example.ini
```

The program accepts the same parameters as the Linux version, but there is no script similar to flow123d.sh for the Windows system.

1.1.2 Structure of input

The principal input file of the program is an INI file which contains names of other necessary input files. Those are the file with calculation mesh (*.msh), the file with specification of adjacency between dimensions (*.ngh), the file with material description (*.mtr) and the file with boundary conditions for the water flow problem (*.bcd). For unsteady water flow you have to specify file with initial condition for the pressure (key Input/Initial) and optionally one can introduce file with water sources (key Input/Sources).

In the case of transport simulation one have to specify also the file with transport boundary conditions (*.tbc) and the file with transport initial condition for individual substances (*.tic).

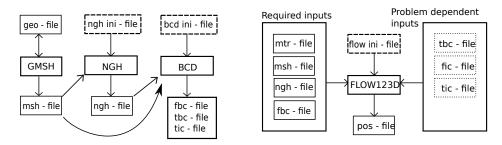


Figure 1.1: Preparation of input files.

For the preparation of input files we use several utilities (see Figure 1.1). We usually begin with a *.geo file as a description of the domain geometry. This come as an input for the GMSH mesh generator, which produce the mesh file. Then we run program ngh to produce adjacency file. Finally we can use program bcd for the preparation of files with boundary and initial conditions. The file with material properties has to be created

manually, preferably by modifying some of the example problems. The programs ngh and bcd are distributed together with flow123d with their own limited documentation.

The output files can be either *.msh files accepted by the GMSH or one can use VTK format that can be post-processed by Paraview.

In the following chapter, we briefly describe structure of individual input files in particular the main INI file. In the last chapter, we describe mathematical models and numerical methods used in the Flow123d.

Chapter 2

New input files

The input consists of the root input file given as the parameter on the command line and possibly several other files with large input data. In this section we shall describe format of the input files. At first, we specify syntax of an extension to the JSON file format. Then we set rules for input of more specific data constructs. We continue by description of general scheme for input of boundary conditions and material time-space variable data. And finally, we describe setting of particular equations and their solvers.

The aim of this draft is twofold. First, we want to outline the way how to translate current input file format (in version 1.6.5) into the new one without extending the existing functionality. Second, we want to propose a new way how to input general boundary and material data. Desired features are:

- input simple data in simple way
- possibility to express very complex input data
- possibility to generate data automatically, and input very large input sets
- input interface that provides uniform access to the data in program independent of the input format

[... something else?]

As this is a draft version there are lot of remarks, suggestions and questions in square brackets. Some keys are marked OBSOLETE, which means that we want to replace them by something else.

2.1 Root file format

The root input file is in the Humanized JSON file format. That is the JSON file format with few syntax extensions and several semantic rules particular to Flow123d. The syntax extensions are

- 1. You can use one line comments using hash #.
- 2. The quoting of the keys is optional if they do not contain spaces (holds for all Flow keys).

- 3. You can use equality sign = instead of colon : for separation of keys and values in JSON objects.
- 4. You can use any whitespace to separate tokens in JSON object or JSON array.

The aim of these extensions is to simplify writing input files manually. However these extensions can be easily filtered out and converted to the generic JSON format. (This way it can be also implemented in Flow123d.)

For those who are not familiar with the JSON file format, we give the brief description right here. The full description can be found at http://www.json.org/. However, we use term record in the place of the JSON object in order to distinguish JSON object, which is merely a data structure written in the text, and the C++ object, i.e. instance of some class.

2.1.1 Humanized JSON

The JSON format consists of four kind of basic entities: null token, true and false tokens, number, string. Number is either integer or float point number possibly in the exponential form and string is any sequence of characters quoted in "" (backslash \ is used as escape character and Unicode is supported, see full specification for details).

In the following, we mean by white space characters: space, tab, and new line. In particular the newline character (outside of comment or quoting) is just the white space character without any special meaning.

The basic entities can be combined in composed entities, in a *record* or in an *array*. The *record* is set of assignments enclosed in the curly brackets

```
#basic syntax
"some_number":124,
"some_string":"Hallo",
"some_subrecord":{},
"some_array":[],

#extended syntax
non_quoted_key_extension=123,
separation_by_whitespace="a" sbw_1="b"
sbw_2="c"
}
```

One assignment is a pair of the *key* and the *value*. *Key* is *string* or token matching regexp

[a-zA-Z_] [a-zA-Z_0-9]*. Value is basic or composed entity. The key and the value are separated by the colon (generic syntax) or equality sign (extended syntax). Pairs are separated by a comma (generic syntax) or sequence of white space characters (extended syntax). The values stored in the record are accessed through the keys like in an associative array. Records are usually used for initialization of corresponding classes.

The second composed entity is the *array* which is sequence of (basic or composed) entities separated by comma (generic syntax) or whitespace sequence (extended syntax)

and enclosed in the square brackets. The values stored in the array are accessed through the order. The Flow reader offers either initialization of a container from JSON array or a sequential access. The latter one is the only possible access for the included arrays, which we discuss later.

On any place out of the quoted string you can use hash mark # to start a one line comment. Everything up to the new line will be ignored and replaced by single white space.

[What about multiple line strings? (Should be allowed)]

2.1.2 Special keys

Apart from small extensions of JSON syntax, we impose further general rules on the interpretation of the input files by Flow123d reader. First, the capital only keywords have a special meaning for Flow JSON reader. On the other hand, we use only small caps for keys interpreted through the reader. The special keywords are:

TYPE:

```
TYPE= <enum>
```

The **<enum>** is particular semantic construct described later on. When appears in the record, it specifies which particular class to instantiate. This only has meaning if the record initializes an abstract class. In consistency with the source code, we shall call such records *polymorphic*.

In fact we consider that every record is of some *type* at least implicitly. The *type* of the record is specification of the keys that are interpreted by the program Flow123d. At some places the program assumes a record of specific *type* so you need not to specify TYPE key in those records.

INCLUDE_RECORD:

This is a simple inclusion of another file as a content of a record:

```
{
    INCLUDE_RECORD = "<file name>"
}
```

$INCLUDE_ARRAY:$

```
array=
{
          INCLUDE_ARRAY = "<file name>"
          FORMAT = "<format string>"
}
```

The reader will substitute the include record by a sequentially accessible array. The file has fixed number of space separated data fields on every line. Every line becomes one element in the array of type record. Every line forms a record with key names given by the <format string> and corresponding data taken form the line.

The key difference compared to regular JSON arrays is that included arrays can be accessed only sequentially within the program and thus we minimize reader memory overhead for large input data. The idea is to translate raw data into structured format and use uniform access to the data.

Basic syntax for format string could be an array of strings — formats of individual columns. Every format string is an address of key that is given the column. Onother possibility is to give an arbitrary JSON file, where all values are numbers of columns where to take the value.

```
[... better specify format string]
```

[Possible extensions: - have sections in the file for setting time dependent data - have number of lines at the beginning - have variable format - allow vectors in the 'line records']

REFERENCE:

```
time_governor={
   REF=<address>
}
```

This will set key time_governor to the same value as the entity specified by the address. The address is an array of strings for keys and integers for indices. The address can be absolute or relative identification of an entity. The relative address is relative to the entity in which the reference record is contained. One can use string ".." to move to parent entity and string "//" to move to the root record of current file. Indices in address starts from 0.

For example assume the file

```
mesh={
          file_name="xyz"
}
array=[
          {x=1, y=0}
          {x=2, y=0}
          {x=3, y=0}
]
outer_record={
          output_file="x_out"
          inner_record={
               output_file={REF=["..","output_file"]} # value "x_out"
        }
        x={REF="/array/2/x"} # value "3"
```

Concept of addres should be better explained and used consistently in reader interface.

2.1.3 Semantic rules

Implicit creation of composed entities

Consider that there is a *type* of record in which all keys have default values (possibly except one). Then the specification of the record *type* can contain a *default key*. Then user can use the value of the *default key* instead of the whole record. All other keys apart from the *default key* will be initialized by default values. This allows to express simple tasks by simple inputs but still make complex inputs possible. In order to make this working, developers should provide default values everywhere it is possible.

Similar functionality holds for arrays. If the user sets a non-array value where an array is expected the reader provides an array with a unique element holding the given value. See examples in the next section for application of these two rules.

Enum construct

Enum values can be integers or strings from particular set. Strings should be preferred for manual creating of input files, while the integer constants are suitable for automatic data preparation.

The input reader provides a way how to define names of members of an enum class and then initialize this enum class from input file. [Need better description]

String types

For purpose of this documentation we distinguish several string types with particular purpose and treatment. Those are:

input filename This has to be valid absolute or relative path to an existing file. The string can contain variable \${INPUT} which will be replaced by path given at command line through parameter -i.

[In order to allow input of time dependent data in individual files, we should have also variable \${TIME_LEVEL} From user point of view this is not property of general input filename string, however in implementation this should be done in the same way as \${INPUT}.]

[? Shall we allow both Windows and UNIX slashes?]

[Developers should provide default names to all files.]

output filename This has to be relative path. The path will be prefixed by the path given at command line through the parameter -o. In some cases the path will be also postfixed by extension of particular file format.

formula Expression that will be parsed and evaluated runtime. Documentation of particular key should provide variables which can appear in the expression, however in general it can be function of the space coordinates $x,\ y,\ z$ and possibly also function of time t. For full specification of expression syntax see documentation of FParser library: http://warp.povusers.org/FunctionParser/fparser.html# literals

text string Just text without particular meaning.

Record types

A record type like particular definition of a class (e.g. in C++). One record type serves usually for initialization of one particular class. From this point of view one record type is set of keys that corresponding class can read.

For purpose of this manual the record type is given by specification of record's keys, their types, default values and meanings. In the next two sections, we describe all record types that forms input capabilities of Flow123d. Description of a record type has form of table. Table heading consists of the name of the record type. Then for every key we present name, type of the value, default value and text description of key meaning. Type of the value can be record type, array of record types, double, integer, enum or string type. Default value specification can be:

none No default value given, but input is mandatory. You get an error if you don't set this key.

null null value. No particular default value, but you need not to set the key. Usually means feature turned off.

explicit value For keys of type: string, double, integer, or enum, the default value is explicit value of this type.

type defaults For keys of some record type we let that record to set its default values.

[? polymorphic record types]

2.2 Record types for input of data fields

In this section we describe record types used to describe general time-space scalar, vector, or tensor fields and records for prescription of boundary conditions. Since one possibility how to prescribe input data fields is by discrete function spaces on computational mesh, we begin with mesh setting.

2.2.1 Mesh type

The mesh record and should provide a mesh consisting of points, lines, triangles and tetrahedrons in 3D space and further definition of boundary segments and element connectivity.

record type: Mesh

file = < input filename >

DEFAULT: mesh.msh

The file with computational mesh in the ASCII GMSH format.

http://geuz.org/gmsh/doc/texinfo/gmsh.html#MSH-ASCII-file-format

 $\verb|boundary_segments| = < array of boundary segments| > DEFAULT: null optional$

The set of 0,1, or 2 dimensional boundary faces of the mesh should be partitioned into boundary segments in order to prescribe unique boundary condition on every boundary face. The segments numbers are assigned to boundary faces by iterating through the array. Initially every boundary face has segment number 0. Every record in the array use "auxiliary" physical domains, elements or direct face specification to specify some set of boundary faces. The new segment number is assigned to each face in the set, possibly overwriting previous value.

Physical domains or its parts that appears in the boundary segment definitions are removed form the computational mesh, however, the element numbers of removed elements are stored in the corresponding boundary face and can be used to define face-wise approximations of functions with support on the boundary.

neighbouring = <input file name>

DEFAULT: neigbours.flw

This should be removed as soon as we integrate ngh functionality into flow.

record type: Boundary segment

index = < integer>

DEFAULT: index in outer array

The index of boundary segment can be used later to prescribe particular type of boundary condition on it. Indices must be greater or equal to 1 and should form more or less continuous sequence. The zero boundary segment is reserved for remaining part of the boundary. By default we assign indices to boundary segments according to the order in their array in mesh, i.e. index (counted form 0) plus 1.

physical_domains = <array of integers>

DEFAULT: null optional

Numbers of physical domains which form the boundary segment. All elements of these physical domains will be removed from actual computational mesh.

elements = < array of integers>

DEFAULT: null optional

The array contains element numbers which should be removed from computational mesh and added to boundary segment.

sides = < array of integer pairs>

DEFAULT: null optional

The array contains numbers of elements which outer faces will be added to the boundary segment or pairs [element, side_on _element] identifying individual faces that will be added to the boundary segment.

2.2.2 Time-space field type

A general time and space dependent, scalar, vector, or tensor valued function is given by array of *steady field data*, i.e. time slices. The time slice contains array of *space functions* for individual materials. Then, the *space function* can by either analytical (given by formula) or numerical, given by type of discrete space and array of *elemental functions*. *Elemental function* is just array of values for every degree of freedom on one element.

The function described by this type is tensor values in general and dimensions of this tensor should be specified outside of the function data. For example in description of Transport record type you should specify that function for initial condition is vector valued with vector size equal to number of substances. It is like template for Timespace field type parametrized by shape of the value tensor given by number of lines N and columnes N.

record type: Steady field data

 $time = \langle double \rangle$ DEFAULT: -Inf

Start time for the spatial filed data.

time_interpolation = < enum> DEFAULT: constant

time interpolation enum cases:

constant=0 Keeps constant data until next time cut.

linear=1 Linear interpolation between current time cut and the next one.

materials = < array of Steady spatial functions> DEFAULT: null optional

record type: **Space function**

material = <integer> DEFAULT: 0

Material filter. The function has nonzero value only on elements with given material number. Function with filter 0 takes place for all materials where no function is set.

analytic = < multi-array of function formulas > DEFAULT: null optional

The shape of the multi-array is given by rank of the value of the function. Since formula parser can deal only with scalar functions, we have to specify individual members of resulting tensor. Formulas can contain variables x, y, z, and t. The formula is used until the next time slice and is evaluated for every solved time step (can depend on equation).

Instead of constant formulas one can use double values. Usage of formulas or doubles need not to be uniform over the tensor.

numeric_type = < enum>
DEFAULT: None

FE space enum cases:

None=0 Use analytic function.

P0=1 Zero order polynomial on element.

Currently we support only P0 base functions for data.

```
numeric = <array of element functions>
```

DEFAULT: empty array

Usually, this element-wise array should by included from an external file through INCLUDE_ARRAY construct.

record type: Element function

```
element_id = <integer>
```

DEFAULT: null optional

Element ID in the mesh. By default the element is identified by the index in the array of element function.

```
values = < multi-array of doubles>
```

DEFAULT: null mandatory

Values for degrees of freedom of the base functions on the element. Currently we support only P0 functions which are given by value in the barycenter of the element. In general the value can be tensor, i.e. array of arrays of doubles. However, in accordance to simplification rules, you can use only array of doubles for vector functions or mere double for scalar functions.

[tensor/vector valued element function should be given also as simple array of DOF values. But we have to provide ordering of tensor products of FE spaces]

[As follows from next examples, there is no way how to simply set simply tensors. We can introduce automatic conversion form scalar to vector (constant vector) and vector to tensor (diagonal tensor).]

[we should also allow 'in place' array includes to simplify material tables etc.]

[How to allow parallel input of field data?]

[Should be there explicit mesh reference in the field specification?]

Examples:

```
constant_scalar_function = 1.0
# is same as
constant_scalar_function = {
  time = -Inf,
  time_interpolation= constant,
  materials = [
    {
      rank=0
      numeric_type=None
      analytic=1.0
                        # the only key withou default value
    }
}
conductivity_tensor =
  [{ material = 1,
     rank = 2,
     analytic = [[1.0, 0.0, 0.0], [0.0, 1.0, 0.0], [0.0, 0.0, 1.0]]
   },
```

```
{ material = 2,
  rank = 2,
  analytic = [[10.0, 0.0, 0.0], [0.0, 10.0, 0.0], [0.0, 0.0, 10.0]]
}
```

2.2.3 Boundary conditions

Input of boundary conditions is similar to the Time-space fields. For description of one time slice we have type *steady boundary data*. This contains array of *boundary conditions* for individual boundary segments. *Boundary condition* is given by type and parameters that are analytic or numeric functions. However, numeric functions are considered only on boundary elements.

record type: steady boundary data

time = < double >

DEFAULT: 0.0

Time when the BC should be applied.

 $bc = \langle array \ of \ boundary \ conditions \rangle$

DEFAULT: empty

record type: boundary condition

boundary_segment = < integer>

DEFAULT: 0

Boundary segment where the boundary condition will be applied.

 $bc_type = \langle enum \rangle$

DEFAULT: dirichlet

Currently there are just three types of boundary condition common to all equations, but some equations can implement some specific boundary conditions. Common boundary condition types are **BC types** enum cases:

dirichlet=0

neumann=1

newton=2 (also known as Robin boundary condition)

value = < space function>

DEFAULT: type defaults

Prescribed value for Dirichlet boundary condition and Newton boundary condition, the normal flux for the Neumann boundary condition. Key material of space function is irrelevant.

mean_value = <scalar or vector constant>

DEFAULT: 0

Prescribes flux for Neumann boundary condition by total flux over the boundary segment. If both *value* and *mean_value* keys are set, we use only *value* key. [How this interact with fracture opening?]

 $newton_coef = \langle scalar \ space \ function \rangle$

DEFAULT: type defaults

Coefficient that appears in the Newton boundary condition. Key material of space function is irrelevant.

E.g. denoting u the unknown scalar or vector field and $\partial_n u$ density of the normal flux of this field, the meaning of keys value and newton_coef is following: $\mathbf{v} \nabla v$

u := value for Dirichlet boundary $A\nabla u \cdot \boldsymbol{n} := value$ for Neumann boundary $A\nabla u \cdot \boldsymbol{n} := newton_coef(u-value)$ for Newton boundary

Specific interpretation of the boundary conditions should be described in particular equations.

[How to allow both analytic and numerical functions here?]

[In order to allow changing BC type in time, the structure has to be: time array of BC segments array of BC type with data alternatively we can have just one array of BC patches, where one patch has: time, BC segment, BC type, BC data patches with non monotone time will be scratched]

[need vector valued Dirichlet (and Neuman, and Newton) for Transport boundary conditions]

[More examples...]

2.3 Other record types recognized by Flow123d

2.3.1 Record types not related to equations

record type: Root record

system = < system type> DEFAULT: type defaults

Record with application setting.

problem = problem type>
DEFAULT: null mandatory

Record with numerical problem to solve.

material = <input filename> DEFAULT: material.flw

Old material file still used for initialization of data fields in equations. This should be replaced by material database type. Then certain input data fields in equations can be constructed from material informations. Main obstacle are various adsorption algorithms depending on material number.

Only these keys are recognized directly at main level, however you can put here your own keys and then reference to them. For example mesh is part of problem type record, but you can put it on the main level and use reference inside problem.

[Should we put problem record to the main level?]

[Should we provide "material database"? Possibility to specify properties of individual materials and use them to construct field data for equations.]

record type: **System**

```
pause\_after\_run = < bool >
                                                  DEFAULT: no
      Wait for press of Enter after run. Good for Windows users, but dangerous for
      batch computations. Should be rather an command-line option.
verbosity = < bool >
                                                  DEFAULT: no
      Turns on/off more verbose mode.
output\_streams = < output stream >
                                                  DEFAULT: null optional
      One or more output data streams. There are two predefined output streams:
      vtk ascii stream:
₹
  name="dafault_vtk_ascii"
  file="flow_output"
  type="vtk_ascii"
}
      GMSH ascii stream:
  name="dafault_gmsh_ascii"
  file="flow_output"
  type="gmsh_ascii"
}
Possibly here could be variables for check-pointing, debugging, timers etc.
record type: Output stream
name = \langle string \rangle
                                                  DEFAULT: null mandatory
      Name of the output stream. This is used to set output stream for individual
      output data.
file = < output filename string>
                                                  DEFAULT: stream name
      File name of the output file for the stream. The file name should be without
      extension, the correct extension will be appended according to the format type.
                                                  DEFAULT: vtk_ascii
format = \langle enum \rangle
      output format enum cases:
      vtk_ascii=0
      gmsh_ascii=1
                                                  DEFAULT: 8
precision = < integer>
      Number of valid decadic digits to output floating point data into the ascii file
      formats.
```

copy_file = < output filename string>

DEFAULT: null optional

Optionally one can set copy file to output data into to different file formats.

 $copy_format = \langle enum \rangle$

copy_precision = <integer> DEFAULT: 8

2.3.2 Equation related record types

Up to now there is only one problem type: TYPE=sequential_coupling, but in near future we should introduce full coupling e.g. for density driven flow.

The sequential coupling problem has following keys:

record type: Sequential coupling implements Problem type

 $description = \langle string \rangle$

DEFAULT: null optional

DEFAULT: null optional

Short text description of solved problem. Now it is only reported on the screen, but could be written into output files or used somewhere else.

 $mesh = \langle mesh \ type \rangle$

DEFAULT: type defaults

The computational mesh common for both coupled equations.

 $time_governor = < time\ governor\ type>$

DEFAULT: type defaults

Common time governor setting. [Future: allow different setting for each equation]

 $primary_equation = < darcy flow type >$

DEFAULT: type defaults

Independent equation.

 $secondary_equation = \langle transport \ type \rangle$

DEFAULT: null optional

Equation with some data dependent on the primary equation.

record type: Time governor

 $init_time = < double >$

DEFAULT: 0.0

Time when an equation starts its simulation.

 $time_step = < double>$

DEFAULT: 1.0

Initial time step.

 $end_time = < double>$

DEFAULT: 1.0

End time for an equation.

This record type should initialize TimeGovernor class, but there are still questions about steady TimeGovernor and if we allow user setting for other parameters.

There are three subtypes steady saturated MH, unsteady saturated MH, unsteady saturated LMH The common keys are:

record type: **Darcy flow**(abstract type)

 $TYPE = \langle enum \rangle$ DEFAULT:

There are three implementations of Darcy flow. Most keys are common but unsteady solvers accept some extra keys. **darcy flow type** enum cases:

steady_MH=0

unsteady_LMH=1

unsteady_MH=2

 $sources = \langle time\text{-}space \ field \rangle$

DEFAULT: 0

Density of water sources. Scalar valued field (1x1 tensor).

sources_file = <input file name>

DEFAULT: null optional

File with sources in old format. (OBSOLETE)

coef_tensor = < tensor steady field>

DEFAULT: 1.0

Conductivity 3x3 tensor. [Should be always 3x3 and then restricted on 2d and 1d fractures.]

boundary_condition = <array of steady boundary data> DEFAULT: null mandatory New scheme for setting boundary conditions.

boundary_file = <input file name>

DEFAULT: null mandatory

File with boundary conditions in old format. (OBSOLETE)

 $solver = \langle solver \ type \rangle$

DEFAULT: type defaults

n_schurs = <integer>

DEFAULT: 2

Number of Schur complements to make. Valid values are 0,1,2.

output = < darcy flow output type>

DEFAULT: typ defaults

This is just sub record to separate output setting.

 $initial = \langle steady \ data \ type \rangle$

DEFAULT: null mandatory

Initial condition. Scalar valued field (1x1 tensor). (for unsteady only)

initial_file = <input file name>

DEFAULT: null mandatory

File with initial condition in old format. (OBSOLETE)

 $storativity = \langle steady \ data \ type \rangle$

DEFAULT: null mandatory

Storativity coefficient. Scalar valued field (1x1 tensor). (for unsteady only)

record type: Darcy flow output

 $save_step = < double>$

DEFAULT: null optional

Time step between outputs.

output_times = < array of doubles>

DEFAULT: null optional

Force output in prescribed times. Can be combined with regular otuptu given by save_step.

velocity_p0 = < output stream name>

DEFAULT: default_vtk_ascii

pressure_p0 = < output stream name>

DEFAULT: default_vtk_ascii

2.3.3 Solver type

record type: **Solver type** (abstract)

 $TYPE = \langle enum \rangle$ DEFAULT: petsc

solver types enum cases:

petsc=0 Use any PETSc solver for MPIAIJ matrices.

bddc=1 Use BDDC solver (need not to work with every equation).

 $accuracy = \langle double \rangle$ DEFAULT: solvers defaults

Absolute residual tolerance.

 $max_it = \langle integer \rangle$ DEFAULT: 1000

Maximum number of outer iterations.

parameters = < string> DEFAULT: null optional

String with options for PETSc solvers.

export_to_matlab = < bool> DEFAULT: no

Save every solved system in matlab format. Useful for debugging and numerical experiments.

2.3.4 Transport type

record type: Transport type

 $sorption = \langle bool \rangle$ DEFAULT: no

 ${\tt dual_porosity} = <bool> \\ {\tt DEFAULT: no}$

 $transport_reactions = < bool>$ DEFAULT: no

What kind of reactions is this? Age of water?

reactions = < reaction type> DEFAULT: null optional

Currently only Semchem is supported. [Interface to Phreaq ...]

 $decays = \langle array \ of \ decays \rangle$ DEFAULT: null optional

substances = < array of strings> DEFAULT: null mandatory

Names for transported substances. Number of substances is given implicitly by size of the array.

initial = < steady data type> DEFAULT: null mandatory

Vector valued initial condition for mobile phase of all species.

initial_others = < steady data type> DEFAULT: null optional

Tensor valued initial condition for immobile, mobile-sorbed, immobile-sorbed phases and all species. (3 x n_substances). [alternatively have separate key for each phase]

initial_file = <input file name>

DEFAULT: null mandatory

File with initial condition in old format. (OBSOLETE)

 $\label{eq:condition} \mbox{boundary of steady boundary data} > \mbox{DEFAULT: null mandatory}$ New scheme for setting boundary conditions.

boundary_file = <input file name>

DEFAULT: null mandatory

File with boundary condition in old format. (OBSOLETE) For time dependent boundary conditions, the filename is postfixed with number of time level.

 $bc_times = < array \ of \ doubles>$

DEFAULT: null optional

Times for changing boundary conditions. If you set this variable, you have to prepare a separate file with boundary conditions for every time in the list. Filenames for individual time level are formed from BC filename by appending underscore and three digits of time level number, e.g. transport_bcd_000, transport_bcd_001, etc. (OBSOLETE)

output = <transport output>

DEFAULT: type defaults

record type: Transport output

 ${\tt save_step} = <\! double\!\! >$

DEFAULT: null optional

Time step between outputs.

output_times = <array of doubles>

DEFAULT: null optional

Force output in prescribed times. Can be combined with regular otuptu given by save_step.

mobile_p0 = < output stream name>

DEFAULT: default_vtk_ascii

immobile_p0 = < output stream name>

DEFAULT: default_vtk_ascii

mobile_sorbed_p0 = < output stream name>

DEFAULT: default_vtk_ascii

immobile_sorbed_p0 = <output stream name>

DEFAULT: default_vtk_ascii

mobile_p1 = < output stream name>

DEFAULT: default_vtk_ascii

immobile_p1 = <output stream name>

DEFAULT: default_vtk_ascii

mobile_sorbed_p1 = < output stream name>

DEFAULT: default_vtk_ascii

immobile_sorbed_p1 = < output stream name>

DEFAULT: default_vtk_ascii

record type: Reaction

record type: **Decay chain**

substance_ids = < array of integers>

DEFAULT: empty

Sequence of N ids of transported substances describing the order of isotopes in the decay chain.

half_lives = < array of doubles>

DEFAULT: empty

This array of N-1 half-lives of individual decays. If there are no bifurcation key specified, the decay chain is linear $1 \to 2 \to 3$. If there is the bifurcation key, the decay chain is branched $1 \to 2, 1 \to 3$.

 $bifurcation = \langle array \ of \ double \rangle$

DEFAULT: null optional

Contains N-1 probabilities for individual branches of the bifurcation decay. They should sum to one.

Chapter 3

File formats

3.1 Flow123D ini file format

In this section we briefly descripte every option you can use in global INI-file. Options marked (NOT IMPLEMENTED) are not implemented in current version, but probably will be reimplemented in near future. Options marked (NOT SUPPORTED) has not been tested since they are obsolete and will be soon replaced by similar functionality.

Section: [Global]

| seedien: [Glesar] | | | |
|-------------------|--------|-----------|---|
| KEY | TYPE | DEFAULT | DESCRIPTION |
| Problem_type | int | NULL | Type of solved problem. Currently supported: 1 = steady saturated flow 2 = unsteady saturated flow using MH method 4 = unstedy saturated flow using Lumped MH method |
| Description | string | undefined | Short description of solved problem - any text. |
| ${	t Stop_time}$ | double | 1.0 | Time interval of the whole problem.[time units] |
| Time_step | double | 1.0 | Time step for unstedy water flow solver. [time units] |
| Save_step | double | 1.0 | The output with transport is written every Save_step. [time units] |

Section: [Input]

| KEY | TYPE | DEFAULT | DESCRIPTION |
|-----------------|-------------------------|---------|--|
| Mesh | string | NULL | Name of file containing definition of the mesh for the problem. (see Section 3.2.1) |
| Material | string | NULL | Name of file with hydraulical properties of the elements. (see Section 3.2.3) |
| Boundary | string | NULL | Name of file with boundary condition data. (see Section $3.2.4$) |
| Neighbouring | string | NULL | Name of file describing topology of the mesh. (see Section 3.2.2) |
| Initial | string | NULL | Name of file with initial condition for preasure head [length]. (see Section 3.2.6) |
| Sources | string | NULL | Name of file with definition of fluid sources. This is optional file, if this key is not defined, calculation runs without sources. (see Section 3.2.6) |
| sources_formula | string | NULL | Expression for sources as function of space coordinates x, y, z . See documentation of FParser library: http://warp.povusers.org/FunctionParser/fparser.html# literals |

Section: [Run]

| KEY | TYPE | DEFAULT | DESCRIPTION |
|------------------|--------|---------|---|
| Screen_verbosity | int | 0 | Nonzero value turn on a more verbose mode (more messages on screen), however everything is in the log file. |
| Pause_after_run | YES/NO | NO | Wait for Enter after end of progam in order to keep output screen open. |

Section: [Transport]

| KEY | TYPE | DEFAULT | DESCRIPTION |
|-----------------------|-------------------------|-----------|--|
| Transport_on | YES/NO | NO | If set "YES" program compute transport too. |
| Sorption | YES/NO | NO | If set "YES" program include sorption too. |
| Dual_porosity | YES/NO | NO | If set "YES" program include dual porosity too. |
| Reactions | YES/NO | NO | If set "YES" program include reactions too. |
| Concentration | string | NULL | Name of file with initial condition for concentrations of individual substances. (see Section 3.2.6) |
| Transport_BCD | string | NULL | Name of file with boundary condition for transport. (see Section 3.2.5) |
| Sources | string | undefined | Name of file with sources of species for transport. (see Section 3.2.6) |
| Transport_out | string | NULL | Name of transport output file. |
| Transport_out_im | string | NULL | (NOT IMPLEMENTED IN 1.6.5) Name of transport immobile output file. |
| Transport_out_sorp | string | NULL | (NOT IMPLEMENTED IN 1.6.5) Name of transport sorbed output file. |
| Transport_out_im_sorp | string | NULL | (NOT IMPLEMENTED IN 1.6.5) Name of transport sorbed immobile output file. |
| N_substances | int | -1 | Number of substances. |
| Substances | string | undefined | Names of the substances separated by commas. |
| bc_times | list of doubles | NULL | Times for changing boundary conditions. If you set this variable, you have to prepare a separate file with boundary condintions for every time in the list. Filenames for individual time level are formed from BC filename by appending underscore and three digits of time level number, e.g. transport_bcd_000, transport_bcd_001, etc. |

Section: [Solver]

| KEY | TYPE | DEFAULT | DESCRIPTION |
|-------------------|-------------------------|---------|---|
| Use_last_solution | YES/NO | NO | If set to "YES", uses last known solution for chosen solver. |
| Solver_name | string | petsc | Type of linear solver. Supported solvers are: petsc, petsc_matis (experimental) |
| Solver_params | ${f string}$ | NULL | PETSc options to override default choice of iterative solver and preconditioner (use with care). In particular to use UMFPACK sequantial direct solver set: Solve_params = "-ksp preonly -pc_type lu -pc_factor_mat_solver_package umfpack" To use parallel direct solver MUMPS use: Solve_params = "-ksp preonly -pc_type lu -pc_factor_mat_solver_package mumps -mat_mumps_icntl_14 5" |
| Keep_solver_files | YES/NO | NO | (NOT SUPPROTED IN 1.6.5) If set to "YES", files for solver are not deleted after the run of the solver. |
| Manual_solver_run | YES/NO | NO | (NOT SUPPROTED IN 1.6.5) If set to "YES", programm stops after writing input files for solver and lets user to run it. |
| Use_control_file | YES/NO | NO | (NOT SUPPROTED IN 1.6.5) If set to "YES", programm do not create control file for solver, it uses given file. |
| Control_file | string | NULL | (NOT SUPPROTED IN 1.6.5) Name of control file for situation, when Use_control_file YES. |
| NSchurs | int | 2 | Number of Schur complements to use. Valid values are 0,1,2. The last one should be the fastest. |
| Solver_accuracy | double | 1e-6 | When to stop solver run - value of residum of matrix. Useful values from 1e-4 to 1e-10. Bigger number = faster run, less accuracy. |
| max_it | int | 200 | Maximum number of iteration of linea solver. |

Section: [Output]

| KEY | TYPE | DEFAULT | DESCRIPTION |
|-------------------|-------------------------|---------|--|
| Write_output_file | YES/NO | NO | If set to "YES", writes output file. |
| output_piezo_head | YES/NO | NO | If set to "YES", output also piezometric head into flow output files. |
| Output_file | string | NULL | Name of the output file for water flow output. |
| Output_file_2 | string | NULL | (NOT IMPLEMENTED IN 1.6.5) Name of the output file (type 2). |
| Output_digits | int | 6 | (NOT IMPLEMENTED IN 1.6.5) Number of digits used for floating point numbers in output file. |
| Output_file_type | int | 1 | (NOT IMPLEMENTED IN 1.6.5) Type of output file 1 - GMSH like format 2 - Flow data file 3 - both files (two separate names) |
| Pos_format | string | ASCII | Output file format. One can use: ASCII, BIN, or VTK_SERIAL_ASCII |
| balance_output | string | NULL | Name of file for output of water boundary fluxes and balnace of sources over material subdomains. |

Section: [Semchem_module]

| KEY | TYPE | DEFAULT | DESCRIPTION |
|---------------------------|-------------|------------|--|
| Compute_reactions | Yes/No | "No" | NO = transport without chemical reactions YES = transport influenced by chemical reactions |
| Output_precission | int | 1 | Number of decimal places written to output file created by Semchem_module. |
| Number_of_further_species | $_{ m int}$ | 0 | Concentrations of these species are not computed, because they are ment to be unexplaustible. |
| Temperature | double | 0.0 | Temperature, one of state variables of the system. |
| Temperature_Gf | double | 0.0 | Temperature at which Free Gibbs Energy is specified. |
| Param_Afi | double | 0.0 | Parameter of the Debuy-Hückel equation for activity coeficients computation. |
| Param_b | double | 0.0 | Parameter of the Debuy-Hückel equation for activity coefficients computation. |
| Epsilon | double | 0.0 | Epsilon specifies relative norm of residuum estimate to stop numerical algorithms used by Semchem_module. |
| Time_steps | int | 1 | Number of transport step subdivisions for Semchem_module. |
| Slow_kinetics_substeps | int | 0 | Number of substeps performed by Runge-Kutta method used for slow kinetics simulation. |
| Error_norm_type | string | "Absolute" | Through wich kind of norm the error is measured. |
| Scalling | boolean | "No" | Type of the problem preconditioning for better convergence of numerical method. |

Section: [Aqueous_species]

| KEY TYPE DEFAULT | | DEFAULT | DESCRIPTION | |
|------------------|--------|---------|---|--|
| El_charge int 0 | | 0 | Electric charge of an Aqueous_specie particleunder consideration. | |
| dGf | double | 0.0 | Free Gibbs Energy valid for TemperatureGf. | |
| dHf | double | 0.0 | Enthalpy | |
| Molar_mass | double | 0.0 | Molar mass of Aqueous_species. | |

 ${\bf Section:} \ [{\bf Further_species}]$

| KEY | TYPE | DEFAULT | DESCRIPTION | |
|-----------------------|--------|---------|---|--|
| Specie_name string "" | | 17 77 | Name belonging to Further_specie under consideration. | |
| dGf | double | 0.0 | Free Gibbs Energy valid for TemperatureGf. | |
| dHf | double | 0.0 | Enthalpy | |
| Molar_mass | double | 0.0 | Molar mass of Further_species. | |
| Activity | double | 0.0 | Activity of Further_species. | |

 $Section: \ [\textbf{Reaction_i}]$

| KEY | TYPE | DEFAULT | DESCRIPTION |
|----------------------|--------|-----------|--|
| Reaction_type | string | "unknown" | Type of considered reaction (Equilibrium, Kinetics, Slow_kinetics). |
| Stoichiometry | int | 0 | Stoichiometric coeficients of species taking part in i -th reaction. |
| Kinetic_constant | double | 0.0 | Kinetic constant for determination of reaction rate. |
| Order_of_reaction | int | 0 | Order of kinetic reaction for participating species. |
| Equilibrium_constant | double | 0.0 | Equilibrium constant defining i-th reaction. |

 ${\bf Section:} \ [{\bf Reaction_module}]$

| KEY | TYPE | DEFAULT | DESCRIPTION |
|--------------------|--------|---------|---|
| Compute_decay | Yes/No | "No" | It enables to switch on simulation of radioactive decay or first order reactions. |
| Nr_of_decay_chains | int | 0 | How many decay chains are considered. |
| Nr_of_FoR | int | 0 | How many first order reactions are defined. |

Section: $[\mathbf{Decay}_{-\mathbf{i}}]$

| KEY | TYPE | DEFAULT | DESCRIPTION |
|------------------------|--------------------|---------|--|
| Nr_of_isotopes | int | 0 | It defines the number of isotopes which does the current section [Decay_i] work with. |
| Substance_ids | array of int | NULL | Sequence of ids describing the order of isotopes in decay chain. |
| Half_lives | array of double | NULL | Contain half-lives belonging to isotopes defined by ids. |
| ${	t Bifurcation_on}$ | Yes/No | "No" | It makes it possible to define branches in current [Decay_i]. |
| Bifurcation | array of double | NULL | It defines a percentage, which is the first isotope in current [Decay_i] decaying to products. |

Section: [FoReact_i]

| KEY | TYPE | DEFAULT | DESCRIPTION |
|------------------|-----------------|--|---|
| Kinetic_constant | double | 0.0 | It defines kinetic constant which is the corresponding half-life computed from. |
| Substance_ids | array of int | NULL It containes a couple of indices of substances which are taking part in first order reactions described in current section FoReact_i. | |

3.2 Other input files

3.2.1 Mesh file format version 2.0

The only supported format for the computational mesh is MSH ASCII format produced by the GMSH software. You can find its documentation on:

http://geuz.org/gmsh/doc/texinfo/gmsh.html#MSH-ASCII-file-format

Comments concerning Flow123d:

- Every inconsistency of the file stops the calculation. These are:
 - Existence of nodes with the same *node-number*.
 - Existence of elements with the same *elm-number*.
 - Reference to non-existing node.
 - Reference to non-existing material (see below).
 - Difference between *number-of-nodes* and actual number of lines in nodes' section.
 - Difference between *number-of-elements* and actual number of lines in elements' section.
- By default Flow123d assumes meshes with number-of-tags = 3.

tag1 is number of material (reference to .MTR file) in the element.

tag2 is number of geometry region in which the element lies.

tag3 is partition number (CURRENTLY NOT USED).

In accordance with specification of GMSH mesh format.

- Currently, line (type = 1), triangle (type = 2) and tetrahedron (type = 4) are the only supported types of elements. Existence of an element of different type stops the calculation.
- Wherever possible, we use the file extension .MSH. It is not required, but highly recomended.
- This file format can be used also for storing simple dicrete scalar or vector fields. We support output into this format (see Section 3.3)

3.2.2 Neighbouring file format, version 1.0

The file is divided in two sections, header and data. The extension .NGH is highly recomended for files of this type.

\$NeighbourFormat
1.0 file-type data-size
\$EndNeighbourFormat
\$Neighbours

```
number-of-neighbours
neighbour-number type <type-specific-data>
...
$EndNeighbours
```

where

file-type int — is equal 0 for the ASCII file format.

data-size int — the size of the floating point numbers used in the file. Usually data-size = sizeof(double).

number-of-neighbours int — Number of neighbouring defined in the file.

neighbour-number int — is the number (index) of the n-th neighbouring. These numbers do not have to be given in a consecutive (or even an ordered) way. Each number has to be given only onece, multiple definition are treated as inconsistency of the file and cause stopping the calculation.

type int — is type of the neighbouring.

<type-specific-data> — format of this list depends on the type.

Types of neighbouring and their specific data

type = 10 — "Edge with common nodes", i.e. sides of elements with common nodes. (Possible many elements)

type = 11 — "Edge with specified sides", i.e. sides of the edge are explicitly defined. (Possible many elements)

type = 20 — "Compatible", i.e. volume of an element with a side of another element. (Only two elements)

type = 30 — "Non-compatible" i.e. volume of an element with volume of another element. (Only two elements)

| type | type-specific-data | Description |
|------|--|---|
| 10 | $n_{-}elm\ eid1\ eid2\dots$ | number of elements and their ids |
| 11 | $n_sid\ eid1\ sid1\ eid2\ sid2\ldots$ | number of sides, their elements and local ids |
| 20 | eid1 eid2 sid2 coef | Elm 1 has to have lower dimension |
| 30 | eid1 eid2 coef | Elm 1 has to have lower dimension |

coef is of the double type, other variables are ints.

Comments concerning Flow123d:

- Every inconsistency or error in the .NGH file causes stopping the calculation. These are especially:
 - Multiple usage of the same *neighbour-number*.

- Difference between *number-of-neighbours* and actual number of data lines.
- Reference to nonexisting element.
- Nonsence number of side.
- The variables *sid?* must be nonegative and lower than the number of sides of the particular element.

3.2.3 Material properties file format, version 1.0

The file is divided in two sections, header and data. The extension .MTR is highly recomended for files of this type.

```
$MaterialFormat
1.0 file-type data-size
$EndMaterialFormat
$Materials
number-of-materials
material-number material-type < material-type-specific-data > [text]
$EndMaterials
$Storativity
material-number < storativity-coefficient> [text]
$EndStorativity
$Geometry
material-number geometry-type < geometry-type-specific-coefficient> [text]
$EndGeometry
$Sorption
material-number substance-id sorption-type <sorption-type-specific-data> [text]
$EndSorption
$SorptionFraction
material-number < sorption-fraction-coefficient> [text]
$EndSorptionFraction
$DualPorosity
material-number < mobile-porosity-coefficient> < immobile-porosity-coefficient>
< nonequillibrium-coefficient-substance(0)>
\dots<nonequilibrium-coefficient-substance(n-1)> [text]
. . .
$EndDualPorosity
$Reactions
reaction-type < reaction-type-specific-coefficient> [text]
$EndReactions
```

where:

- file-type int is equal 0 for the ASCII file format.
- data-size int the size of the floating point numbers used in the file. Usually data-size = sizeof(double).
- number-of-materials int Number of materials defined in the file.
- material-number int is the number (index) of the n-th material. These numbers do not have to be given in a consecutive (or even an ordered) way. Each number has to be given only onece, multiple definition are treated as inconsistency of the file and cause stopping the calculation (exception \$Sorption section).
- material-type int is type of the material, see table.
- < material-type-specific-data > format of this list depends on the material type.
- <storativity-coefficient> double coefficient of storativity
- geometry-type int type of complement dimension parameter (only for 1D and 2D material), for 1D element is supported type 1 cross-section area, for 2D element is supported type 2 thickness.
- <geometry-type-specific-coefficient> double cross-section for 1D element or thickness for 2D element.
- substance-id int refers to number of transported substance, numbering starts on θ .
- sorption-type int type 1 linear sorption isotherm, type 2 Freundlich sorption isotherm, type 3 Langmuir sorption isotherm.
- <sorption-type-specific-data > format of this list depends on the sorption type, see table.
 - Note: Section \$Sorption is needed for calculation only if *Sorption* is turned on in the *ini* file.
- <sorption-fraction-coefficient> double ratio of the "mobile" solid surface in the contact with "mobile" water to the total solid surface (this parameter (section) is needed for calculation only if Dual_porosity and Sorption is together turned on in the ini file).
- <mobile-porosity-coefficient> double ratio of the mobile pore volume to the total volume (this parameter is needed only if Transport_on is turned on in the ini file).
- <immobile-porosity-coefficient> double ratio of the immobile pore volume to the total pore volume (this parameter is needed only if Dual_porosity is turned on in the ini file).
- <nonequilibrium-coefficient-substance(i)> double nonequilibrium coefficient for substance i, $\forall i \in \langle 0, n-1 \rangle$ where n is number of transported substances (this parameter is needed only if $Dual_porosity$ is turned on in the ini file).
- reaction-type int type 0 zero order reaction

< reaction-type-specific-data > — format of this list depends on the reaction - type, see table.

| material-type | material-type-specific-data | Description | |
|---------------|--|--|--|
| 11 | k | $\mathbf{K} = (k)$ | |
| -11 | a | $\mathbf{A} = \mathbf{K}^{-1} = (a)$ | |
| 21 | k | $\mathbf{K} = \left(\begin{array}{cc} k & 0 \\ 0 & k \end{array}\right)$ | |
| 22 | $egin{bmatrix} k_x & k_y \end{bmatrix}$ | $\mathbf{K} = \left(\begin{array}{cc} k_x & 0 \\ 0 & k_y \end{array}\right)$ | |
| 23 | k_x k_y k_{xy} | $\mathbf{K} = \begin{pmatrix} 0 & k_y \\ k_x & k_{xy} \\ k_{xy} & k_y \end{pmatrix}$ | |
| -21 | a | $\mathbf{A} = \mathbf{K}^{-1} = \left(\begin{array}{cc} a & 0 \\ 0 & a \end{array}\right)$ | |
| -22 | $a_x a_y$ | $\mathbf{A} = \mathbf{K}^{-1} = \left(\begin{array}{cc} a_x & 0\\ 0 & a_y \end{array}\right)$ | |
| -23 | $\begin{bmatrix} a_x & a_y & a_{xy} \end{bmatrix}$ | $\mathbf{A} = \mathbf{K}^{-1} = \left(egin{array}{cc} a_x & a_{xy} \ a_{xy} & a_y \end{array} ight)$ | |
| 31 | $igg _k$ | $\mathbf{K} = \left(\begin{array}{ccc} k & 0 & 0 \\ 0 & k & 0 \\ 0 & 0 & k \end{array}\right)$ | |
| 33 | $k_x k_y k_z$ | $\mathbf{K} = \begin{pmatrix} 0 & 0 & k \\ k_x & 0 & 0 \\ 0 & k_y & 0 \\ 0 & 0 & k_z \end{pmatrix}$ $\mathbf{K} = \begin{pmatrix} k_x & k_{xy} & k_{xz} \\ k_{xy} & k_y & k_{yz} \\ k_{xz} & k_{yz} & k_z \end{pmatrix}$ | |
| 36 | | $\mathbf{K} = \begin{pmatrix} k_x & k_{xy} & k_{xz} \\ k_{xy} & k_y & k_{yz} \\ k_{xz} & k_{yz} & k_z \end{pmatrix}$ | |
| -31 | a | $\mathbf{A} = \mathbf{K}^{-1} = \begin{pmatrix} a & 0 & 0 \\ 0 & a & 0 \\ 0 & 0 & a \end{pmatrix}$ | |
| -33 | $\begin{bmatrix} a_x & a_y & a_z \end{bmatrix}$ | $\mathbf{A} = \mathbf{K}^{-1} = \left(egin{array}{ccc} a_x & 0 & 0 \\ 0 & a_y & 0 \\ 0 & 0 & a_z \end{array} ight)$ | |
| -36 | $\begin{bmatrix} a_x & a_y & a_z & a_{xy} & a_{xz} & a_{yz} \end{bmatrix}$ | $\mathbf{A} = \mathbf{K}^{-1} = \begin{pmatrix} a_x & a_{xy} & a_{xz} \\ a_{xy} & a_y & a_{yz} \\ a_{xz} & a_{yz} & a_z \end{pmatrix}$ | |

Note: all variables (k, k_x , k_y , k_z , k_{xy} , k_{xz} , k_{yz} , a, a_x , a_y , a_z , a_{xy} , a_{xz} , a_{yz}) are of the double type.

| sorption-type | $sorption\-type\-specific\-data$ | Description |
|---------------|--|---------------------------------------|
| 1 | $k_D[1]$ | $s = k_D c$ |
| 2 | | $s = k_F c^{\alpha}$ |
| 3 | $K_L[L^3 \cdot M^{-1}] s^{max}[L^{-3} \cdot M^1]$ | $s = \frac{K_L s^{max} c}{1 + K_L c}$ |

Note: all variables ($k_D,\,k_F,\,\alpha,\,K_L,\,s^{max}$) are of the double type.

| reaction-type | $reaction\-type\-specific\-data$ | Description |
|---------------|--|---|
| 0 | $substance-id[1] \qquad k[M\cdot L^{-3}\cdot T]$ | $\begin{bmatrix} -1 \end{bmatrix} \begin{bmatrix} \frac{\partial c_m^{[substance-id]}}{\partial t} = k \end{bmatrix}$ |

Where $c_m^{[substance-id]}$ is mobile concentration of substance with id substance-id and

 Δt is the internal transport time step defined by CFL condition.

text char[] — is a text description of the material, up to 256 chars. This parameter is optional.

Comments concerning Flow123d:

• If *number-of-materials* differs from actual number of material lines in the file, it stops the calculation.

3.2.4 Boundary conditions file format, version 1.0

The file is divided in two sections, header and data.

```
$BoundaryFormat

1.0 file-type data-size
$EndBoundaryFormat
$BoundaryConditions
number-of-conditions
condition-number type < type-specific-data> where < where-data> number-of-tags
<tags> [text]
...
$EndBoundaryConditions
```

where

file-type int — is equal 0 for the ASCII file format.

data-size int — the size of the floating point numbers used in the file. Usually data-size = sizeof(double).

number-of-conditions int — Number of boundary conditions defined in the file.

condition-number int — is the number (index) of the n-th boundary condition. These numbers do not have to be given in a consecutive (or even an ordered) way. Each number has to be given only onece, multiple definition are treated as inconsistency of the file and cause stopping the calculation.

type int — is type of the boundary condition. See below for definitions of the types.

- <type-specific-data> format of this list depends on the type. See below for specification of the type-specific-data for particular types of the boundary conditions.
- where int defines the way, how the place for the contidion is prescribed. See below for details.
- <where-data> format of this list depends on where and actually defines the place for the condition. See below for details.

number-of-tags int — number of integer tags of the boundary condition. It can be zero.

< tags > number-of-tags*int — list of tags of the boundary condition. Values are separated by spaces or tabs. By default we set number-of-tags=1, where tag1 defines group of boundary conditions, "type of water" in our jargon. This can be used to calculate total fluxes through the boundary group.

[text] char[] — arbitrary text, description of the fracture, notes, etc., up to 256 chars. This is an optional parameter.

Types of boundary conditions and their data

type = 1 — Boundary condition of the Dirichlet's type

type = 2 — Boundary condition of the Neumann's type

type = 3 — Boundary condition of the Newton's type

| type | type-specific-data | Description |
|------|--------------------|---|
| 1 | scalar | Prescribed value of pressure (in meters [m]) |
| 2 | flux | Prescribed value of flux through the boundary |
| 3 | scalar sigma | Scalar value and the σ coefficient |

scalar, flux and sigma are of the double type.

Ways of defining the place for the boundary condition

where = 1 — Condition on a node

where = 2 — Condition on a (generalized) side

where = 3 — Condition on side for element with only one external side.

| where | <pre><where-data></where-data></pre> | Description |
|-------|--------------------------------------|--|
| 1 | node-id | Node id number, according to .MSH file |
| 2 | elm-id sid-id | Elm. id number, local number of side |
| 3 | elm-id | Elm. id number |

The variables node-id, elm-id, sid-id are of the int type.

Comments concerning Flow123d:

- We assume homegemous Neumman's condition as the default one. Therefore we do not need to prescribe conditions on the whole boundary.
- If the condition is given on the inner edge, it is treated as an error and stops calculation.
- Any inconsistence in the file stops calculation. (Bad number of conditions, multiple definition of condition, reference to non-existing node, etc.)

- At least one of the conditions has to be of the Dirichlet's or Newton's type. This is well-known fact from the theory of the PDE's.
- Local numbers of sides for where = 2 must be lower than the number of sides of the particular element and greater then or equal to zero.
- The element specified for where = 3 must have only one external side, otherwise the program stops.

3.2.5 Transport boundary conditions file format, version 1.0

The file is divided in two sections, header and data.

```
$Transport_BCDFormat

1.0 file-type data-size

$EndTransport_BCDFormat

$Transport_BCD

number-of-conditions

transport-condition-number boundary-condition-number value1 value2 ...

$EndTransport_BCD
```

where

file-type int - is equal 0 for the ASCII file format.

data-size int - the size of the floating point numbers used in the file. Usually data-size = sizeof(double)

number-of-conditions int - Number of conditions defined in the file.

transport-condition-number int - is the number (index) of the n-th transport condition. These numbers do not have to be given in a consecutive (or even an ordered) way. Each number has to be given only once, multiple definition are treated as inconsistency of the file and cause stopping the calculation.

boundary-condition-number int - id number of the boundary-condition where transport boundary condition is prescribed.

valueN double - prescribed boundary concentration of substance N (should be from interval [0,1]).

Comments concerning FLOW123d: Number of transport boundary conditions has to be same as number of boundary conditions. Program stops computation in the other case.

3.2.6 Element data file format, version 1.0

Several input data fields are given as constant scalars on every element. In particular this is used for water sources, initial condition of pressure, initial condition for concentrations and substance sources in transport. Common file format of these files is:

\$FieldName

```
number-of-lines
eid value1 value2 ...
```

\$EndFieldName

where

\$FieldName — Unique name of the input field. Since all field data are enclosed by \$FieldName and \$EndFieldName one can even have different fields in one common file.

number-of-sources int — Number of data lines that has to match number of elements in the mesh.

eid int — is id-number of the element (in the input mesh file).

value N double — list of field values. Number of values is specific for each particular type of input.

Description of individual input fields.

water sources FieldName=Sources, there is only one value per line — the density of water source on the element.

pressure initial condition FieldName=PressureHead, there is only one value per line — the initial pressure value on the element.

substance sources FieldName=TransportSources, number of values is 3 times number of substances. The density of one substance source is given by formula:

$$f = d + \sigma(c - c_N)$$

where f is total source, the first term is fixed Neuman-like source density d. The second term is Newton-like source density, where σ is transmisitvity, c is actual concentration, and c_N is prescribed concentration. For every substance there is triplet of three parameters: d, σ , c_N . The order of substances is same as in the main INI file.

concentration initial conditions FieldName=Concentrations, number of values equal to number of transported substances, the order of substances is same as in the main INI file.

Comments concerning Flow123d:

- Every inconsistency or error in the .SRC file causes stopping the calculation. These are especially:
 - Difference between *number-of-lines* and actual number of data lines.
 - Reference to nonexisting element.

3.3 Output files

Flow123d support output of scalar and vaector data fields into two formats. First one can use native fromat of program GMSH (usualy with extension msh) which contains computational mesh and then various datafields for squence of time levels. For second we support output into XML version of VTK files. These files can be viewed and postprocessed by several vizualization softwares. However, our primal goal is to support data transfer into Paraview vizualization software. See key Pos_format.

3.3.1 Output data fields of water flow module

Water flow module provides output of four data fields.

- **pressure on elements** Pressure head in length units [L] piecewise constant on every element. This field is directly produced by the MH method and thus contains no postprocessing error.
- pressure in nodes Same pressure head field, but interpolated into P1 continuous scalar field. Namely you lost discontinuities on fractures.
- **velocity on elements** Vector field of water flux volume unit per time unit $[L^3/T]$. For every element we evaluate discrete flux field in barycenter.
- piezometric head on elements Piezometric head in length units [L] piecewise constant on every element. This is just pressure on element plus z-coordinate of the barycenter. This field is produced only on demand (see key output_piezo_head).

3.3.2 Output data fields of transport

Transport module provides output only for concentrations (in mobile phase) as a field piecewise constant over elements. There is one field for every substance and names of those fields contain names of substances given by key Substances. The physical unit is mass unit over volume unit $[M/L^3]$.

3.3.3 Auxiliary output files

Profiling information

On every run we collect some bacis profilling informations. After all computations these data are written into the file profiler%y%m%d_%H.%M.%S.out where %y, %m, %d, %H, %M, %S are two digit numbers representing year, month, day, hour, minute, and second of the program start time.

Water flux information

File contains water flow balance, total inflow and outflow over boundary segments. Further there is total water income due to sources (if they are present).

Raw water flow data file

You can force Flow123d to write raw data about results of MH method. The file format is:

Chapter 4

Mathematical models

4.0.4 Advection-Diffusion equation

Solute transport is governed by advection equation which can be written in the form

$$\frac{\partial c}{\partial t} + \mathbf{v} \frac{\partial c}{\partial x} = 0, \tag{4.1}$$

where c is concentration $[M^3 \cdot L^{-3}]$, t is time [T], v is velocity $[L \cdot T^{-1}]$, and x is coordinate in cartesian system [L]. Assuming solution which is constant on every element (cell centered finite volume method) and integrating equation (4.1) we get

$$\int_{e_i} \frac{\partial c}{\partial t} dV + \int_{e_i} \boldsymbol{v} \frac{\partial c}{\partial x} dV = 0.$$

After some rearrangements we obtain on *i*-th element (e_i)

$$\frac{\partial c_i}{\partial t} V_i + c \int_{\partial e_i} \mathbf{v} \, \mathbf{dS} = 0, \tag{4.2}$$

where c_i is average concentration in e_i and V_i its volume, c will be specified later (there are two main possibilities - c_i or concentration from neighbouring element). Term $\frac{\partial c}{\partial t}$ we approximate by explicit Euler difference

$$\frac{\partial c}{\partial t} \approx \frac{c_i^{n+1} - c_i^n}{\Delta t}.$$
(4.3)

Where Δt is a time step and upper index at c_i means values in the discrete time steps n+1 and n. We assume that all elements have piecewise smooth element boundary ∂e with outwards directed normal. Inside the area Ω we introduce internal flows. With respect to e_i , we define internal flow intake U_{ij}^- (from element e_j) and internal flow drain U_{ij}^+ (to element e_j) as follows

$$U_{ij}^{-} = \min(\int_{\partial e_i \cap \partial e_j, i \neq j} \boldsymbol{v} \, \mathbf{dS}, 0),$$

$$U_{ij}^{+} = \max(\int_{\partial e_i \cap \partial e_j, i \neq j} \boldsymbol{v} \, \mathbf{dS}, 0).$$
(4.4)

Those flows realizes solute transport in the area Ω . On the $\partial\Omega$ we define external flows which will be important for transport Dirichlet boundary conditions. In the same way as for internal flows we assume (with respect to element e_i) external flow intake U_{ij}^{e-} (from $\partial\Omega$) and external flow drain U_{ij}^{e+} (to $\partial\Omega$).

$$U_{ik}^{e-} = \min(\int_{\partial e_i \cap \partial \Omega} \boldsymbol{v} \, d\mathbf{S}, 0),$$

$$U_{ik}^{e+} = \max(\int_{\partial e_i \cap \partial \Omega} \boldsymbol{v} \, d\mathbf{S}, 0).$$

$$(4.5)$$

Direction of the velocity v, which affects sign of the U-terms is significant for the construction solution. For the solution stability it is suitable to use an upwind scheme, which can by written for finite difference on simple 1D geometry in the form

$$v > 0: \frac{\partial c}{\partial \mathbf{x}} \approx \frac{c_i^n - c_{i-1}^n}{\Delta x},$$

$$v < 0: \frac{\partial c}{\partial \mathbf{x}} \approx \frac{c_{i+1}^n - c_i^n}{\Delta x}.$$
(4.6)

This scheme can be interpreted as well as in finite volume method - in convection term one can get c value opposite the flow of the quantity v direction. For every e_i we introduce itemsets $\mathcal{N}_i, \mathcal{B}_i$ which contains indexes of neighbourging elements, local boundary conditions respectivelly. Assuming upwind scheme, using (4.4), (4.5), and (4.3) we can write solution of the equation (4.2) (relation between two consecutive time steps) on e_i in the form

$$c_i^{n+1} = c_i^n - \frac{\Delta t}{V_i} \left[\sum_{j \in \mathcal{N}_i} \left[U_{ij}^+ c_i + U_{ij}^- c_j \right] + \sum_{k \in \mathcal{B}_i} \left[U_{ik}^{e+} c_i + U_{ik}^{e-} c_{B_{ik}} \right] \right]. \tag{4.7}$$

Where $c_{B_{ik}}$ are values of Dirichlet boundary conditions which belong to e_i . Formula (4.7) can be rewritten into the matrix notation

$$\mathbf{c}^{n+1} = (\mathbf{I} + \Delta t \mathbf{A}) \cdot \mathbf{c}^n + \Delta t \mathbf{B} \cdot \mathbf{c_B}^n$$
(4.8)

Where \mathbf{c} is vector of c_i^{n+1} , \mathbf{A} is a square matrix composed from $\frac{U_{ij}^+}{V_i}$, $\frac{U_{ij}^-}{V_i}$, and $\frac{U_{ij}^{e^+}}{V_i}$. \mathbf{B} is in general rectangular matrix composed from $\frac{U_{ij}^{e^-}}{V_i}$ and $\mathbf{c}_{\mathbf{B}}^n$ is vector of Dirichlet boundary conditions.matrix definition. There is one stability condition for time step which is called Courant-Friedrich-Levy condition. For the problem without sources/sinks it can be written as

$$\Delta t_{max} = \min_{i} \left(\frac{V_i}{\sum_{j} U_{ij}^+ + \sum_{k} U_{ik}^{e+}} \right) = \min_{i} \left(\frac{V_i}{\sum_{j} |U_{ij}^-| + \sum_{k} |U_{ik}^{e-}|} \right). \tag{4.9}$$

This condition has a physical interpretation, which can be understood as conservation law - volume that intakes/drains to/from element e_i can not be higher then element volume V_i . From algebraical point of view this condition can be seen as a condition which bounds norm of the evolution operator as follows

$$\|\mathbf{I} + \Delta t \mathbf{A} \quad \Delta t \mathbf{B}\| \le 1. \tag{4.10}$$

4.0.5 Generalization

This approach can be used as well as for more general element connections – for compatible/non-compatible element interconnection, if we know the flow integral values $(U_{ij}^+ \text{ or } U_{ij}^-)$. The most general case of connection is relation among n elements like

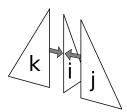


Figure 4.1: Edge with 3 elements

in figure (4.1). For this case we define edge element indexset \mathcal{G}_l that contains all the indexes of elements which sides make l-th edge (g_l) , so that $\mathcal{G}_l = \{i, j, k\}$. For \mathcal{G}_l we introduce its subsets \mathcal{G}_{ij} , \mathcal{G}_{ji} , \mathcal{G}_{ki} , \mathcal{G}_{kj} , and \mathcal{G}_{jk} , where $\mathcal{G}_{ij} = \mathcal{G}_{ik} = \mathcal{G}_l \setminus i = \{j, k\}$, $\mathcal{G}_{ji} = \mathcal{G}_{jk} = \mathcal{G}_l \setminus j = \{i, k\}$, and $\mathcal{G}_{ki} = \mathcal{G}_{kj} = \mathcal{G}_l \setminus k = \{i, j\}$. It can be written in the same way for any edge g with more than 3 elements, it is hold $|\mathcal{G}_g| - 1 = |\mathcal{G}_{ab}|$; $\forall a, b \in \mathcal{G}_g$. For l-th edge (g_l) we can define total edge flow U_{g_l} eg. as

$$U_{g_{l}} = \sum_{m \in \mathcal{G}_{ji}} \left[U_{mj}^{+} + \frac{U_{jm}^{+}}{|\mathcal{G}_{ji}|} \right] = \sum_{m \in \mathcal{G}_{jk}} \left[U_{mj}^{+} + \frac{U_{jm}^{+}}{|\mathcal{G}_{jk}|} \right]$$

$$= \sum_{m \in \mathcal{G}_{ij}} \left[U_{mi}^{+} + \frac{U_{im}^{+}}{|\mathcal{G}_{ij}|} \right] = \sum_{m \in \mathcal{G}_{ik}} \left[U_{mi}^{+} + \frac{U_{im}^{+}}{|\mathcal{G}_{ik}|} \right]$$

$$= \sum_{m \in \mathcal{G}_{ki}} \left[U_{mk}^{+} + \frac{U_{km}^{+}}{|\mathcal{G}_{ki}|} \right] = \sum_{m \in \mathcal{G}_{kj}} \left[U_{mk}^{+} + \frac{U_{km}^{+}}{|\mathcal{G}_{kj}|} \right], \tag{4.11}$$

 U_{g_l} with respect to any e_m ; $m \in \mathcal{G}_l$ has to have the same value because continuity equation, for assumed incompresible flow, has to be fulfilled in every edge. Edges with more than two elements and two and more nonzero intakes to edge realize an ideal mixing (to an average concentration) with weights which will be specified later. This fact modifies equation (4.7) on the general mesh into the form

$$c_{i}^{n+1} = c_{i}^{n} - \frac{\Delta t}{V_{i}} \left[\sum_{j \in \mathcal{N}_{i}} \left[U_{ij}^{+} c_{i} + \frac{U_{ij}^{-}}{\sum_{k \in \mathcal{G}_{ij}} \left[U_{ki}^{+} + \frac{U_{ik}^{+}}{|\mathcal{G}_{ij}|} \right]} \sum_{k \in \mathcal{G}_{ij}} U_{ki}^{+} c_{k} \right] + \sum_{k \in \mathcal{B}_{i}} \left[U_{ik}^{e+} c_{i} + U_{ik}^{e-} c_{B_{ik}} \right] \right].$$

$$(4.12)$$

The edges with total edge flow $U_{g_l} = 0$ can occur breakdown in the equation (4.12) via term $\sum_{k \in \mathcal{G}_{ij}} \left[U_{ki}^+ + \frac{U_{ik}^+}{|\mathcal{G}_{ij}|} \right] = 0$. This fact implies as well as numerator $U_{ij}^- = 0$. In order to avoid dividing by zero we have to assume computation only for nonzero flows. Concentrations c_k , $k \in \mathcal{G}_{ij}$ that may intakes into element e_i are weighted with weights

$$\alpha_k = \frac{U_{ki}^+}{\sum_{k \in \mathcal{G}_{ij}} \left[U_{ki}^+ + \frac{U_{ik}^+}{|\mathcal{G}_{ij}|} \right]},\tag{4.13}$$

so that the ideal mixing in this edge leads to the average concentration

$$c_{av} = \frac{\sum_{k \in \mathcal{G}_{ij}} U_{ki}^{+} c_{k}}{\sum_{k \in \mathcal{G}_{ij}} \left[U_{ki}^{+} + \frac{U_{ik}^{+}}{|\mathcal{G}_{ij}|} \right]}.$$
 (4.14)

Matrix notation is the same as in (4.8). Finally ...

4.0.6 Radioactive Decay and First Order Reactions

Lets consider to have a narrow decay chain without branches. This kind of decay chain can be described by following equation

$$A \xrightarrow{t_{1/2},A} B \xrightarrow{t_{1/2},B} C \xrightarrow{t_{1/2},C} D \xrightarrow{t_{1/2},D} E,$$

where letters $\{A, \ldots, E\}$ denotes isotopes contained in considered decay chain and $t_{1/2}, i, i \in \{A, \ldots, E\}$ is a symbol for a halflife of *i*-th isotope. For a simulation of radioactive decay and first order reactions matrix multiplication based approach has been developed. It has been based on an arrangement of all the data to matrices. The matrix \mathbf{C}^k contains the information about concentrations of all species (s) in all observed elements (e). The upper index k denotes k-th time step. The matrix \mathbf{C}^k has the dimension $e \times s$ ($rows \times columns$). The transport simulation is realized by matrix multiplication

$$\mathbf{T} \cdot \mathbf{C}^k = \mathbf{C}^{k+1},$$

where \mathbf{T} is a square, block-diagonal matrix, representing a set of algebraic equations constructed from a set of partial differential equations. When the simulation of the radioactive decay or first order reaction is switched on, one step of simulation changes to

$$\mathbf{T} \cdot \mathbf{C}^k \cdot \mathbf{R} = \mathbf{C}^{k+1},$$

where ${\bf R}$ is a square matrix with the dimension $(s\times s)$. It is much easier to construct and to use ${\bf R}$, than to include chemical influence to the transport matrix ${\bf T}$, because the matrix ${\bf R}$ has usually a simple structure and s is much smaller than e. In the most simple case, when the order of identification numbers of isotopes in considered decay chain is the same as the order of identifiers of species transported by groundwater, then just two diagonals are engaged and the matrix ${\bf R}$ looks as follows:

Every single j-th column, except the first one, includes the contribution $1 - \left(\frac{1}{2}\right)^{\frac{\Delta t}{t_{1/2,j}}}$, $j \in \{A, \ldots, E\}$ from (j-1)-th isotope with its half-life $t_{1/2,j-1}$. The term $\left(\frac{1}{2}\right)^{\frac{\Delta t}{t_{1/2,j}}}$ describes concentration decrease caused by the radioactive decay of j-th isotope itself. In general

cases the matrix \mathbf{R} can have much more complicated structure, especially when the considered decay chain has more branches. The implementation of the radioactive decay in Flow123D does not firmly include standard natural decay chain. Instead of that it is possible for a user to define his/her decay chain.

It is also possible to simulate decay chains with branches as picture 4.2 shows.

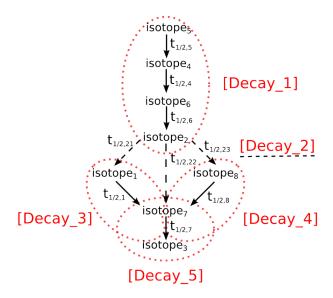


Figure 4.2: Decay chain with branches.

When it comes to a simulation of first order reactions, the kinetic constant is given as an input. The description of a kinetic chemical reaction has obviously two following forms

$$A \xrightarrow{k_1} B,$$

$$\frac{dc^A}{dt} = -k_1 \cdot c^A.$$

The first one description is a standard chmical one. The second equation describes temporal decrease in amount of concentrations of the specie c^A . The constant k_1 is so called kinetic constant and for the case of a first order reactions it is equal to so called reaction rate. The order of reaction with just one reactant is equal to the power of c^A in partial differential reaction.

For an inclusion of first order reaction into a reaction matrix a half-live need to be computed from the corresponding kinetic constant k_i . The derivation follows

$$\begin{array}{l} A \xrightarrow{k} B \\ \frac{dc^{A}}{d\tau} = -k \cdot c_{A} \\ \frac{dc^{A}}{c^{A}} = -k \cdot d\tau \\ \int\limits_{c_{0}^{A}/2}^{c_{0}^{A}} \frac{dc^{A}}{c^{A}} = -k \cdot \int\limits_{t_{1/2,A}}^{0} d\tau \\ \left[\ln c^{A} \right]_{c_{0}^{A}/2}^{c_{0}^{A}} = -[k\tau]_{t_{1/2,A}}^{0} \\ \ln c_{0}^{A} - \ln \frac{c_{0}^{A}}{2} = k \cdot t_{1/2,A} \\ \ln 2 = k \cdot t_{1/2,A} \\ t_{1/2,A} = \frac{\ln 2}{k_{1}} \end{array}$$

The matrix **R** is constructed in the same way as for the radioactive decay.

4.0.7 General Chemical Reactions

For a simulation of general chemical reactions as a part of reactive transport simulation, an application Semchem has been merged together with Flow123D. It enables to simulate following types of reactions:

- Chemical equilibrium (solved using iterative Newtons method) mathematical description $K^{(r)} = \prod_i c_i^{\alpha_i^{(r)}}$,
- Slow evolving chemical kinetics (solved using Runge-Kutta method) mathematical description $\frac{dc_i}{dt} = -k^{(r)} \prod_j c_j^{\beta_j^{(r)}}$,
- Fast evolving chemical kinetics (discretized using implicit Eulerova method and solved using Newtons method)

mathematical description
$$\frac{c_i^{(T+1)}-c_i^T}{\Delta t}=-k^{(r)}\prod_j c_j^{\beta_j^{(r),(T+1)}},$$

• Radioactive decay can be simulated as a special case of first order reaction.

Further informations can be found in "Snizeni poctu nelinearnich rovnic popisujicich chemicke reakce".