

Trilinear Coordinate System

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1 Introduction

Given a fixed triangle, we can define a coordinate system called *trilinear coordinate system* to the Euclidean plane – with respect to the triangle. Such a coordinate system is useful in triangle geometry because it adapts the shape of the given triangle.

Trilinear coordinate system was introduced by *Plücker* in 1835. The point on the Euclidean plane is represented by homogeneous coordinates $(x : y : z)$ or (x, y, z) , where the latter has different meaning than the homogeneous coordinates in projective geometry.

Before introducing the trilinear coordinate system, we first need to introduce the concept of *signed distance*, which is a generalization of the distance from a point to a line.

Definition 1. (Signed Distance)

Let

$$px + qy + r = 0$$

represent a line L in the Euclidean plane. Let $P = (x_0, y_0)$ be a point. Then the *signed distance* of P to the line L is defined to be

$$\text{dist}(P, L) = \frac{px_0 + qy_0 + r}{\sqrt{p^2 + q^2}}.$$

We make two remarks on the signed distance. First, $|\text{dist}(P, L)|$ is the distance of the point to the line by analytic geometry. Second, the signed distance depends not only on the point and the line, but also on the *orientation* of the line. Both $ax + by + c = 0$ and $-ax - by - c = 0$ represent the same line, but the corresponding signed distances differ by a negative sign.

Definition 2. (Trilinear Coordinate System)

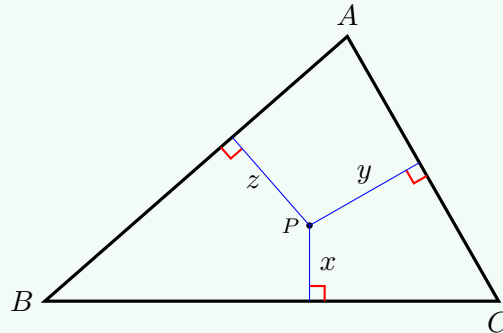
Let $\triangle ABC$ be a fixed triangle. We shall choose the orientations of the lines BC, CA, AB so that any point in the interior of the triangle would have *positive* signed distances to all three sides.

Let P be any point in the plane. The *trilinear coordinates* of P are the *ratios* of its signed distances to the three sides BC, CA, AB .

In the following picture, P is an interior point of $\triangle ABC$. Let (x, y, z) be the distances

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(=signed distances) of P to BC, CA, AB , respectively. Then, the trilinear coordinates of P is given by (x, y, z) , or $(x : y : z)$.



2 Basic Properties of the Trilinear Coordinate System

The definition in the last section leaves a theoretical question whether trilinear coordinates are well-defined or not.

Theorem 1

Trilinear coordinate system is indeed a coordinate system. For homogeneous coordinates (x, y, z) and (x_1, y_1, z_1) , if there is a non-zero number k such that $x = kx_1, y = ky_1, z = kz_1$, then (x, y, z) and (x_1, y_1, z_1) represent the same point.

Proof. We use the picture in Definition 2. Let a, b, c be the lengths of BC, CA, AB , respectively. Let $\tilde{x}, \tilde{y}, \tilde{z}$ be the signed distances to BC, CA, AB , respectively. We claim that

$$a\tilde{x} + b\tilde{y} + c\tilde{z} = 2\Delta, \quad (1)$$

where Δ is the area of $\triangle ABC$.

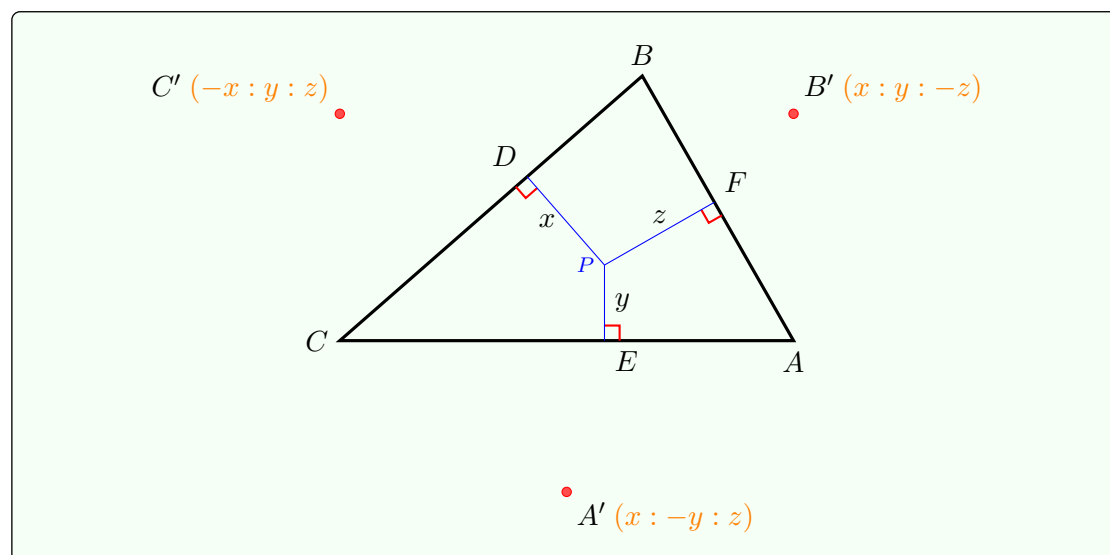
To prove the above identity, we observe that the signed distances $\tilde{x}, \tilde{y}, \tilde{z}$ are linear functions of P , hence so is $a\tilde{x} + b\tilde{y} + c\tilde{z}$. When P is an interior point of $\triangle ABC$, we then have

$$a\tilde{x} + b\tilde{y} + c\tilde{z} = 2S_{\triangle PBC} + 2S_{\triangle PCA} + 2S_{\triangle PAB} = 2\Delta.$$

Therefore, such a linear function must be equal to the constant 2Δ . This proves the claim.

By (1), we conclude that if $(x, y, z) = k(\tilde{x}, \tilde{y}, \tilde{z})$, then k must be positive. Thus (x, y, z) and (x_1, y_1, z_1) represent the same point. ■

Remark It is impossible for all three trilinear coordinates to be non-positive.



- The coordinates of vertices A , B , and C of the triangle are $(1 : 0 : 0)$, $(0 : 1 : 0)$, and $(0 : 0 : 1)$, respectively.
- The **positive** and **negative** signs of the *trilinear coordinate* components can be determined according to the following rules:
 - The component x of a point P is positive if it is on the same side of the edge BC as vertex A , and negative when P and vertex A are on opposite sides of BC .
 - The component y of a point P is positive if it is on the same side of the edge CA as vertex B , and negative when P and vertex B are on opposite sides of CA .
 - The component z of a point P is positive if it is on the same side of the edge AB as vertex C , and negative when P and vertex C are on opposite sides of AB .

🔗 **External Link.** Here is the introduction of the Trilinear Coordinate System in [Wikipedia](#).

3 The Trilinear Coordinates of the Five Triangle Centers

Theorem 2

Given a triangle $\triangle ABC$ with three vertices A , B , and C , each vertex corresponds to its opposite side length a , b and c , respectively.

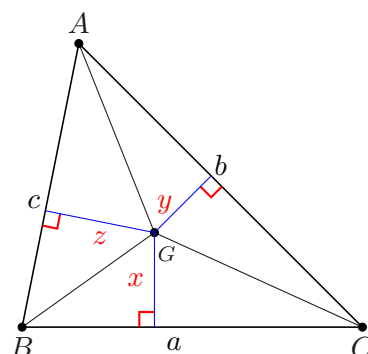
The *trilinear coordinates* of the five triangle centers:

- The trilinear coordinates for the *incenter* is $(1 : 1 : 1)$; and three *excenters* are $(-1 : 1 : 1)$, $(1 : -1 : 1)$, and $(1 : 1 : -1)$, respectively.
- The trilinear coordinates for the *centroid* is $(\csc(A) : \csc(B) : \csc(C))$ or $(a^{-1} : b^{-1} : c^{-1})$.
- The trilinear coordinates for the *circumcenter* is $(\cos(A) : \cos(B) : \cos(C))$.
- The trilinear coordinates for the *orthocenter* is $(\sec(A) : \sec(B) : \sec(C))$.

Proof. It is well known that the (signed) distances of the incenter to the three sides are equal. Therefore the trilinear coordinates of the incenter is $(1, 1, 1)$.

Similarly, the distances of any excenters to the three sides are equal as well. However, one of the signed distances is negative. Thus the coordinates of the excenters are $(-1 : 1 : 1)$, $(1 : -1 : 1)$, and $(1 : 1 : -1)$, respectively.

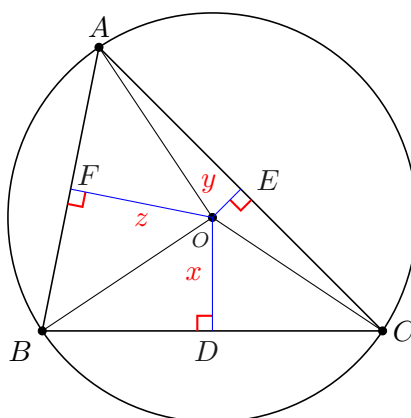
Let G be the centroid of $\triangle ABC$ in the following picture. Let x, y, z be the distances to the three sides BC, CA and AB , respectively. By the property of the centroid, the area of $\triangle BGC$ = the area of $\triangle AGC$ = the area of $\triangle AGB$, which implies $ax = by = cz$.



Therefore, the trilinear coordinate for the centroid of $\triangle ABC$ is

$$(x : y : z) = (a^{-1} : b^{-1} : c^{-1}) = (\csc(A) : \csc(B) : \csc(C)).$$

Now we turn to the circumcenter. In the following picture, let O be the circumcenter.



By definition, the circumcenter is the center of the circumcircle, which is the circle passing through the three vertices A, B , and C . Since $\angle BAC$ is an inscribed angle, we have

$$\angle A = \frac{1}{2} \angle BOC = \angle BOD.$$

Therefore,

$$x = R \cos A,$$

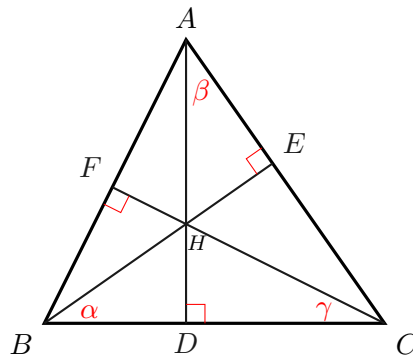
where R is the radius of the circumcircle. Similarly, we have

$$y = R \cos B, \quad z = R \cos C.$$

Thus, the *trilinear coordinates* of the circumcenter of $\triangle ABC$ are

$$(\cos A : \cos B : \cos C).$$

Finally, we turn to the orthocenter. In the following picture, let H be the orthocenter of $\triangle ABC$.



Let $\angle EBC = \alpha$, $\angle CAD = \beta$ and $\angle FCB = \gamma$. Then

$$\begin{aligned} HD &= BD \tan \alpha = BD \cot C \\ &= AB \cos B \cot C = \frac{2R \cos B \cos C \cos A}{\cos A} \\ &= 2R \cos B \cos C. \end{aligned}$$

Similarly, we have

$$HE = 2R \cos A \cos C, \quad FH = 2R \cos A \cos B$$

Therefore, the *trilinear coordinates* of H are

$$(R \cos B \cos C : R \cos A \cos C : R \cos A \cos B) = (\sec A : \sec B : \sec C).$$



4 Converting Between Cartesian and Trilinear Coordinates

In this section, we prove a transformation formula between *Trilinear coordinates* and *Cartesian coordinates*.

Theorem 3

Let a, b, c be the side lengths of $\triangle ABC$, respectively, and let $(x : y : z)$ be the trilinear coordinates of a point P . Let $\vec{A}, \vec{B}, \vec{C}$ be the vector representations of vertexes A, B, C ,

respectively. Then we have

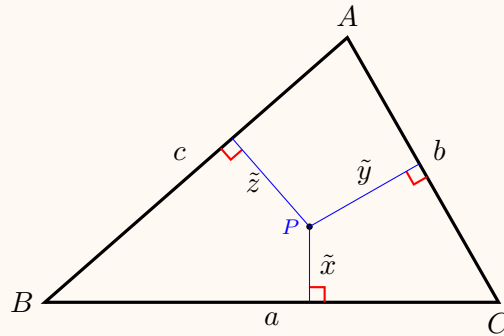
$$\vec{P} = \frac{ax}{ax+by+cz}\vec{A} + \frac{by}{ax+by+cz}\vec{B} + \frac{cz}{ax+by+cz}\vec{C},$$

where \vec{P} is the vector representation of P . Conversely, let

$$\vec{P} = k_1\vec{A} + k_2\vec{B} + k_3\vec{C},$$

where k_1, k_2, k_3 are real numbers such that $k_1 + k_2 + k_3 = 1$. Then the trilinear coordinates of P are given by

$$(a^{-1}k_1 : b^{-1}k_2, c^{-1}k_3).$$



Proof. We make the following observation regarding to the signed distance. Let ℓ be the equation of a line L and let P be a point. Then by Definition 1, the signed distance of P to the line is given by $c(\ell)\ell(\vec{P})$, where $c(\ell)$ is a constant depending only on ℓ .

Let $\tilde{x}, \tilde{y}, \tilde{z}$ be the signed distances of P to BC, CA and AB , respectively, and let $\ell_{BC} = 0$ be the equations of the line BC . Then

$$\tilde{x} = c(\ell_{BC})\ell_{BC}(\vec{P}).$$

Writing $\vec{P} = k_1\vec{A} + k_2\vec{B} + k_3\vec{C}$, with $k_1 + k_2 + k_3 = 1$, we have

$$\tilde{x} = k_1c(\ell_{BC})\ell_{BC}(\vec{A})$$

because $\ell_{BC}(\vec{B}) = \ell_{BC}(\vec{C}) = 0$. Let h_1 be the height of $\triangle ABC$ over the side BC . Then $h_1 = c(\ell_{BC})\ell_{BC}(\vec{A})$ and hence $\tilde{x} = k_1h_1$. Similarly, we have $\tilde{y} = k_2h_2$ and $\tilde{z} = k_3h_3$, where h_2, h_3 are the heights over CA, AB , respectively.

Let $(x : y : z)$ be the trilinear coordinates of P . Then

$$\frac{ax}{ax+by+cz} = \frac{a\tilde{x}}{a\tilde{x}+b\tilde{y}+c\tilde{z}}.$$

Since $a\tilde{x} + b\tilde{y} + c\tilde{z} = 2\Delta$ by (1), we have

$$\frac{ax}{ax+by+cz} = k_1.$$

Similarly, we have

$$\frac{by}{ax+by+cz} = k_2, \quad \frac{cz}{ax+by+cz} = k_3.$$

This proves the first part of the theorem. For the second part, we just need to observe that

$$h_1 : h_2 : h_3 = a^{-1} : b^{-1} : c^{-1}.$$

Thus

$$(\tilde{x} : \tilde{y} : \tilde{z}) = (k_1 h_1 : k_2 h_2 : k_3 h_3) = (a^{-1} k_1 : b^{-1} k_2, c^{-1} k_3).$$



5 Example

Theorem 4. (Euler Line)

*In any non-equilateral triangle, the orthocenter, the centroid, and the circumcenter are collinear. The line is called the **Euler Line**.*

Proof. We first remark that three points P_i ($i = 1, 2, 3$) with trilinear coordinates $(x_i : y_i : z_i)$ ($i = 1, 2, 3$), respectively, are collinear if and only if

$$\det \begin{bmatrix} x_1 & y_1 & z_1 \\ x_2 & y_2 & z_2 \\ x_3 & y_3 & z_3 \end{bmatrix} = 0.$$

By Theorem 2, in order to prove the theorem, we only need to prove

$$\det \begin{bmatrix} \sec(A) & \sec(B) & \sec(C) \\ \csc(A) & \csc(B) & \csc(C) \\ \cos(A) & \cos(B) & \cos(C) \end{bmatrix} = 0.$$

Multiplying the 1st row by $(\cos A \cos B \cos C)$ and the 2nd row by $(\sin A \sin B \sin C)$, we get

$$\sigma \stackrel{\text{def}}{=} \det \begin{bmatrix} \sin(B) \sin(C) & \sin(C) \sin(A) & \sin(A) \sin(B) \\ \cos(B) \cos(C) & \cos(C) \cos(A) & \cos(A) \cos(B) \\ \cos(A) & \cos(B) & \cos(C) \end{bmatrix}.$$

Subtracting the first row by the second row, we get

$$\sigma = \begin{bmatrix} -\cos(B+C) & -\cos(C+A) & -\cos(A+B) \\ \cos(B) \cos(C) & \cos(C) \cos(A) & \cos(A) \cos(B) \\ \cos(A) & \cos(B) & \cos(C) \end{bmatrix}.$$

Since $\angle A + \angle B + \angle C = 180^\circ$, we have

$$\cos(A) = -\cos(B+C), \cos(B) = -\cos(C+A), \cos(C) = -\cos(A+B).$$

Thus

$$\sigma = \begin{bmatrix} \cos(A) & \cos(B) & \cos(C) \\ \cos(B) \cos(C) & \cos(C) \cos(A) & \cos(A) \cos(B) \\ \cos(A) & \cos(B) & \cos(C) \end{bmatrix} = 0,$$

completing the proof of the theorem. ■

6 Barycentric Coordinate System

There is a similar coordinate system, called

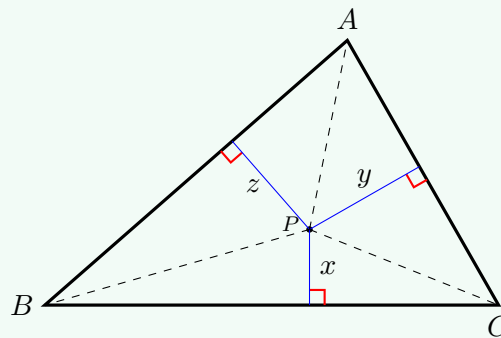
Definition 3. (Barycentric Coordinate System)

Let $\triangle ABC$ be a fixed triangle. We shall choose the orientations of the lines BC, CA, AB so that any point in the interior of the triangle would have **positive** signed distances to all three sides.

The **signed** area of $\triangle PBC$ is defined as $\frac{1}{2}BC \cdot x$, where x is the signed distance from P to BC . The signed area of $\triangle PCA$ and $\triangle PAB$ can be defined in a similar way.

Let P be any point in the plane. The **barycentric coordinates** of P are the **ratios** of the signed areas of $\triangle PBC, \triangle PCA$ and $\triangle PAB$.

In the following picture, P is an interior point of $\triangle ABC$. Let $BC = a, CA = b$ and $AB = c$. Let (x, y, z) be the distances (=signed distances) of P to BC, CA, AB , respectively. Then, the barycentric coordinates of P is given by (ax, by, cz) , or $(ax : by : cz)$.



Using the above definition, the following theorem is straightforward.

Theorem 5

Let (x, y, z) be the trilinear coordinates of a point P with respect to a triangle $\triangle ABC$ with side lengths a, b, c , respectively. Then the barycentric coordinates of P is given by (ax, by, cz) .