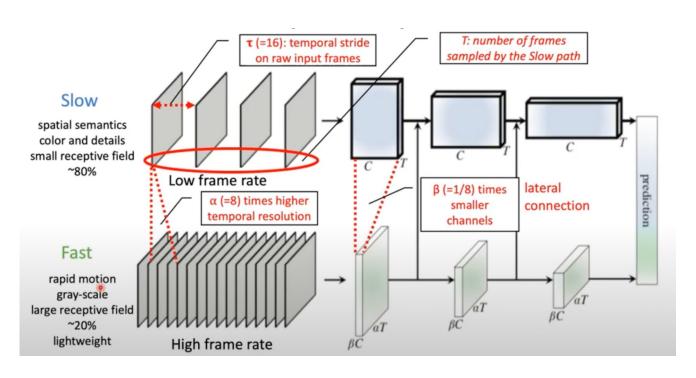
GxLabs

Abstract

- This method [SlowFast] is partially inspired by biological studies on the retinal ganglion cells in the primate visual system.
- Model involves a Slow pathway and Fast pathway
 - Slow pathway
 - Low frame rate
 - Capturing spatial semantics
 - Fast pathway
 - High frame rate
 - Capturing motion information



Lateral Connections

- Attach one lateral connection for every "stage"
 - Right after ResNet pool₁, res₂, res₃, res₄
 - Unidirectional
- Global average pooling is performed on each pathway's output
 - o Then, Concat -> fully-connected classifier layer
- Feature shape
 - Slow pathway: {T, S², C}
 - Fast pathway: {αT, S², βC}

Lateral Connections

- Feature shape
 - \circ Slow pathway: {T, S², C}
 - Fast pathway: $\{aT, S^2, \beta C\}$



- Time-to-channel: reshape and transpose
 - \circ {aT, S², β C} -> {T, S², a β C}
- Time-strided sampling
 - \circ {aT, S², β C} -> {T, S², β C}
- Time-strided convolution
 - \circ 3D conv with 5 \times 1² kernel
 - $2\beta C$ output channels, stride = α



The output is fused into the Slow pathway by summation or concatenation

Accuracy/complexity tradeoff

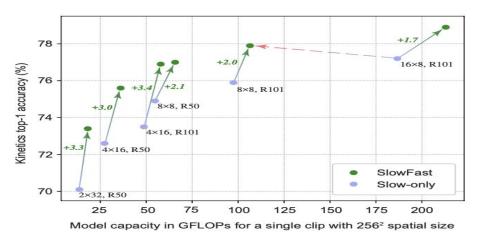


Figure 2. Accuracy/complexity tradeoff on Kinetics-400 for the SlowFast (green) vs. Slow-only (blue) architectures. SlowFast is consistently better than its Slow-only counterpart in all cases (green arrows). SlowFast provides higher accuracy and lower cost than temporally heavy Slow-only (e.g. red arrow). The complexity is for a single 256² view, and accuracy are obtained by 30-view testing.

Conclusion

- The time axis is a special dimension
- The SlowFast architecture design focuses on contrasting the speed along the temporal axis
- SlowFast & Two-Stream networks treat space and time differently and share motivation from neuroscience