

Introduction to Approximate Message Passing with Application to LASSO

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- The optimization problem we're dealing with is:

$$\hat{x} = \arg \min_x g(x) + \phi(x)$$

- **Proximal Operator:**

$$\text{Prox}_f(y, \alpha) = \arg \min_x f(x) + \frac{1}{2\alpha} \|y - x\|_2^2$$

- The ISTA procedure for solving the optimization problem is:

$$\begin{aligned}r_k &= x_k - \alpha \nabla g(x_k) \\ x_{k+1} &= \text{Prox}_\phi(r_k, \alpha)\end{aligned}$$

- The original optimization problem could be relaxed to:

$$\begin{aligned} \min_x & g(x) + \phi(y) \\ \text{s.t.} & x = y \end{aligned}$$

- The augmented Lagrangian is:

$$L(x, y; s, \alpha) = g(x) + \phi(y) + \alpha s^T(x - y) + \frac{\alpha}{2} \|x - y\|_2^2$$

- The **ADMM** procedure goes as followed:

$$x_{k+1} = \text{Prox}_g(y_k - s_k, \alpha^{-1})$$

$$y_{k+1} = \text{Prox}_\phi(x_{k+1} + s_k, \alpha^{-1})$$

$$s_{k+1} = s_k + x_{k+1} - y_{k+1}$$

- The LASSO problem here is formulated as:

$$\hat{x} = \arg \min_x \frac{1}{2} \|y - Ax\|_2^2 + \lambda \|x\|_1$$

where $y \in \mathbb{R}^n$ and $x \in \mathbb{R}^N$

- Soft threshold function is defined as, let $h(x) = \|x\|_1$:

$$\eta(x, b) = \text{sign}(x)(|x| - b)_+ = \text{Prox}_h(x, b)$$

- Given the soft-thresholding function aforementioned, the **ISTA** procedure for LASSO is:

$$\begin{aligned} r_k &= x_k + \alpha A^T(y - Ax_k) \\ x_{k+1} &= \arg \min_x \lambda \|x\|_1 + \frac{1}{2\alpha} \|x - r_k\|_2^2 \\ &= \eta(r_k, \lambda\alpha) \end{aligned}$$

- Let $g(x) = \frac{1}{2}\|y - Ax\|_2^2$ and $h(x) = \lambda\|x\|_1$, the **ADMM** procedure for LASSO is:

$$\begin{aligned}x_{k+1} &= \text{Prox}_g(z_k - s_k, \alpha^{-1}) \\ &= (A^T A + \alpha I)^{-1}(A^T y + \alpha(z_k - s_k))\end{aligned}$$

$$\begin{aligned}z_{k+1} &= \text{Prox}_h(x_{k+1} + s_k, \alpha^{-1}) \\ &= \eta(x_{k+1} + s_k; \frac{\lambda}{\alpha})\end{aligned}$$

$$s_{k+1} = s_k + x_{k+1} - y_{k+1}$$

- The LASSO problem here is formulated as:

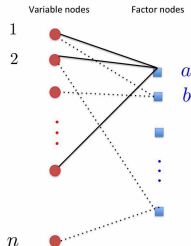
$$\hat{s} = \arg \min_s \frac{1}{2} \|y - As\|_2^2 + \lambda \|s\|_1$$

- From simulated annealing, set up the probability density for x :

$$f(s) = \frac{1}{Z_\beta} \exp(-\beta [\frac{1}{2} \|y - As\|_2^2 + \lambda \|s\|_1])$$

- $f(s)$ is most dense around \hat{s} and will concentrate on \hat{s} as $\beta \rightarrow \infty$

Belief Propagation on Factor Graph



- $f(x) = \frac{1}{Z} \prod_{j=1}^m f_j(x_{S_j}) \prod_{i=1}^n g_i(x_i)$
- j are the factor nodes, i are the variable nodes, S_j are the set of variable nodes which are neighbours of factor node j

Belief Propagation on Factor Graph

- $\partial(x_i)$ be the set of factor nodes that are neighbours of variable x_i
- **Belief from factor node j to variable node i :**

$$v_{j \rightarrow i}(x_i) \simeq \int_{x_{S_j}/x_i} f_j(x_{S_j}) \prod_{i' \neq i} d\hat{v}_{i' \rightarrow j}(x_{i'})$$

- **Belief from variable node i to factor node j :**

$$\hat{v}_{i \rightarrow j}(x_i) \simeq g_i(x_i) \prod_{b \in \partial(x_i)/j} v_{b \rightarrow i}(x_i)$$

- The products of the beliefs would be the marginal distribution.

Belief Propagation on Factor Graph

- In most cases, bipartite graphs are loopy, beliefs could not be obtained easily.
- **Belief from factor node j to variable node i :**

$$v_{j \rightarrow i}^{t+1}(x_i) \simeq \int_{x_{S_j}/x_i} f_j(x_{S_j}) \prod_{i' \neq i} d\hat{v}_{i' \rightarrow j}^t(x_{i'})$$

- **Belief from variable node i to factor node j :**

$$\hat{v}_{i \rightarrow j}^{t+1}(x_i) \simeq g_i(x_i) \prod_{b \in \partial(x_i)/j} v_{b \rightarrow i}^t(x_i)$$

Approximate Message Passing for LASSO

- Density Set-up for LASSO:

$$f(s) \propto \prod_{i=1}^N \exp(-\beta\lambda|s_i|) \prod_{a=1}^n \exp(-\frac{\beta}{2}(y_a - (As)_a)^2)$$

- Belief from factor node a to variable node i :

$$v_{a \rightarrow i}^{t+1}(x_i) \simeq \int \exp(-\frac{\beta}{2}(y_a - (As)_a)^2) \prod_{j \neq i} d\hat{v}_{j \rightarrow a}^t(x_j)$$

- Belief from variable node i to factor node j :

$$\hat{v}_{i \rightarrow a}^{t+1}(x_i) \simeq \exp(-\beta\lambda|s_i|) \prod_{b \in \partial(x_i)/a} v_{b \rightarrow i}^t(x_i)$$

Approximate Message Passing for LASSO

- Let $x_{j \rightarrow a}^t$ and $\tau_{j \rightarrow a}^t$ be the mean and variance of $\hat{v}_{j \rightarrow a}^t$
- Let $z_{a \rightarrow i}^t = y_a - \sum_{j \neq i} A_{aj} x_{j \rightarrow a}^t$ and $\hat{\tau}_{a \rightarrow i}^t = \sum_{j \neq i} A_{aj}^2 \tau_{j \rightarrow a}^t$
- Define the density function $\phi_{a \rightarrow i}^t(s_i)$ as:

$$\phi_{a \rightarrow i}^t(s_i) = \sqrt{\frac{\beta A_{ai}^2}{2\pi(1+\hat{\tau}_{a \rightarrow i}^t)}} \exp\left(-\frac{\beta}{2(1+\hat{\tau}_{a \rightarrow i}^t)}(A_{ai} - z_{a \rightarrow i}^t)^2\right)$$

Theorem (Donoho.D.L et.al. 2009)

There exists a constant C_t such that the KS distance between $\phi_{a \rightarrow i}^t$ and $v_{a \rightarrow i}^t$ satisfies:

$$\sup_{s_i \in \mathbb{R}} |\phi_{a \rightarrow i}^t(s_i) - v_{a \rightarrow i}^t(s_i)| \leq \frac{C_t}{N(\hat{\tau}_{a \rightarrow i}^t)^{3/2}}$$

Approximate Message Passing for LASSO

- Define the family of distributions $f_\beta(s; x, b)$ as:

$$f(s; x, b) \propto \exp(-\beta|s| - \frac{\beta}{2b}(s - x)^2)$$

- $F_\beta(x; b)$ and $G_\beta(x; b)$ are defined as the mean and variance of the distribution above
- The bounds on the KS distance between $\phi_{a \rightarrow i}^t(s_i)$ and $v_{a \rightarrow i}^t(s_i)$ suggests that we could replace the mean and variance of the latter distribution by the previous one, which gives rise to the following message passing algorithm:

Approximate Message Passing for LASSO

Algorithm 1: Message Passing for LASSO

for $0 \leq t \leq n - 1$ **do**

$$x_{i \rightarrow a}^{t+1} = \frac{1}{\lambda} F_{\beta}(\lambda \sum_{b \neq a} A_{bi} z_{b \rightarrow i}^t; \lambda^2(1 + \hat{\tau}^t));$$

$$\hat{\tau}^{t+1} = \frac{\beta}{\lambda^2 n} \sum_{i=1}^N G_{\beta}(\lambda \sum_b A_{bi} z_{b \rightarrow i}^t; \lambda^2(1 + \hat{\tau}^t));$$

$$z_{a \rightarrow i}^{t+1} = y_a - \sum_{j \neq i} A_{aj} x_{j \rightarrow a}^{t+1}$$

end

Approximate Message Passing for LASSO

- Recall the definition for the soft-thresholding function $\eta(x, b)$:

$$\lim_{\beta \rightarrow \infty} F_{\beta}(x, b) = \eta(x, b)$$
$$\lim_{\beta \rightarrow \infty} \beta G_{\beta}(x, b) = b\eta'(x, b)$$

- With these two limits
above, let $\delta = n/N$ we could improve the message passing algorithm as:

Algorithm 2: Message Passing for LASSO with large β limits

for $0 \leq t \leq n - 1$ **do**

$$x_{i \rightarrow a}^{t+1} = \eta\left(\lambda \sum_{b \neq a} A_{bi} z_{b \rightarrow i}^t; \lambda(1 + \hat{\tau}^t)\right);$$

$$\hat{\tau}^{t+1} = \frac{1 + \hat{\tau}^t}{N\delta} \sum_{i=1}^N \eta'\left(\lambda \sum_b A_{bi} z_{b \rightarrow i}^t; \lambda(1 + \hat{\tau}^t)\right);$$

$$z_{a \rightarrow i}^{t+1} = y_a - \sum_{j \neq i} A_{aj} x_{j \rightarrow a}^{t+1}$$

end

Approximate Message Passing for LASSO

- The Message Passing Algorithm is still computationally expensive, if we further assume that:

$$\begin{aligned}x_{i \rightarrow a}^t &= x_i^t + \delta x_{i \rightarrow a}^t + \mathcal{O}(1/N) \\ z_{a \rightarrow i}^t &= z_a^t + \delta z_{a \rightarrow i}^t + \mathcal{O}(1/N)\end{aligned}$$

where $\delta x_{i \rightarrow a}^t$ and $\delta z_{a \rightarrow i}^t$ are both of order $\mathcal{O}(1/\sqrt{N})$

- $x_{i \rightarrow a}^t$ and $z_{a \rightarrow i}^t$ could be approximate by one step from x_i^t and z_a^t

Approximate Message Passing for LASSO

Let $\gamma^t = \lambda \hat{\tau}^t$ and $\langle \cdot \rangle$ be the averaging operator:

Algorithm 3: Approximate Message Passing for LASSO

for $0 \leq t \leq n - 1$ **do**

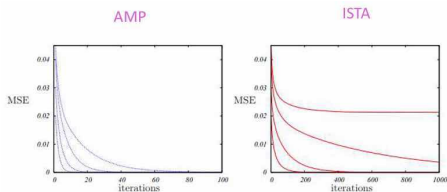
$$x^{t+1} = \eta(x^t + A^* z^t; \lambda + \gamma^t);$$

$$\gamma^{t+1} = \frac{\lambda + \gamma^t}{\delta} \langle \eta'(Az^t + x^t; \lambda + \gamma^t) \rangle;$$

$$z^{t+1} = y - Ax^{t+1} + \frac{1}{\delta} z^t \langle \eta'(Az^t + x^t; \lambda + \gamma^t) \rangle$$

end

Empirical Results



- For the synthesized dataset $N = 8000$, $n = 1600$, and A_{ai} is sampled from $N(0, 1/N)$, AMP converge with much fewer iterations compared to ISTA

- AMP algorithm is unstable
- No theoretical guarantees yet
- Generalization to other sparse learning problems

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Graphical Models and Belief Propagation