

Ju-Jutsu Training Kinect Application

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Outline

- 1 Introduction
 - Motivation
 - Project Impact
- 2 Project Recon
 - Architecture
 - Tools
 - Project Requirements
- 3 Recognition Techniques
 - Glyphs Method
 - Joint Positions Lists
 - MCS UK
- 4 Communication
 - Communication to the Interface
 - Demonstration



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Ju-Jutsu

- Ju Jutsu is a Japanese martial art.
- Like most martial arts, it includes Thai Pad training.



Increase of Ubiquitous Technology

Motion Sensors...

- Different sensors include:
 - PlayStation EyeToy.
 - Microsoft Kinect.
- Applications supporting activities:
 - Karate, Judo, Jujitsu Training.
 - Children's Arts Lessons.
- However, there are no contact sports fitness related applications.



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 - Judo and Jujitsu Training
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Project Impact



- Embedded systems project
- Multiple inputs from a practitioner during a workout session through different input sources
- Main monitor will be used as the interface and to display sessions



Input Sources and Different Components

- Seismic sensor equipped Thai Pads
- Kinect sensor (Project Recon)
- Optional input
 - Pulse rates
 - Lactic acid levels
 - Respiration rates
 - and any similar measurement ...

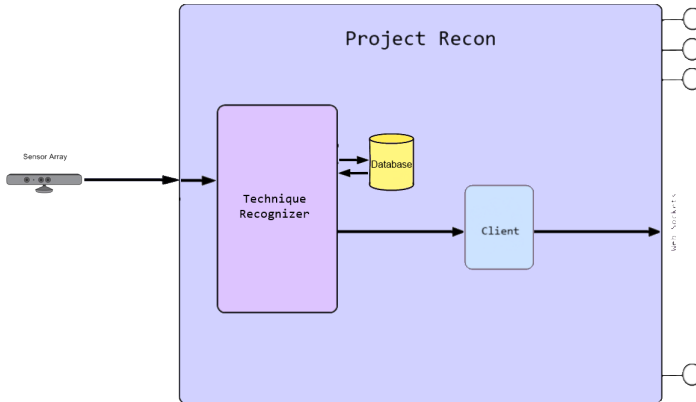


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Project Recon Architecture



Kinect

- Four components
 - Infrared emitter
 - Infrared sensor
 - Color camera
 - Microphone
- Four different streams
 - Depth stream
 - Color stream
 - Skeleton stream
 - Audio stream

KINECT™



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XNA



- Framework based on .NET Compact framework
- Created by Microsoft to support game development
- Basic platform for the indie games on XBOX Live
- Language used is C#



Kinect SDK

KINECT™ for Windows®

- Is the official SDK for the Kinect system
- Manages data streams



Socket Programming

- Enables Processes to communicate
- Used to connect between Project Recon and the Interface
- Uses client-server model



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Project Requirements

- Real time recognition
- Robust and Dynamic
- Plug in to interface



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The Challenges in Kinect

- The user always faces the Kinect
- Kinect does not differentiate between facing and not facing
- Solution:
 - Normalize the skeleton of the user (Always ends up facing)



Normal Vector

- Create normal between vectors \vec{r} , \vec{c} , and \vec{l}

$$\vec{N} = (\vec{r} - \vec{c}) \times (\vec{l} - \vec{c})$$



Normal Vector

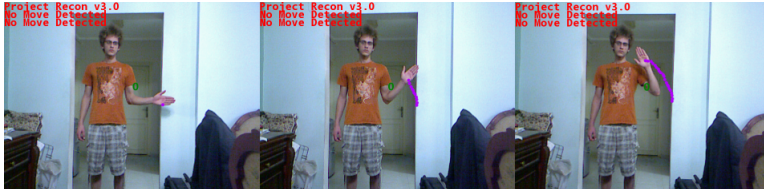
- Create normal between vectors \vec{r} , \vec{c} , and \vec{l}

$$\vec{N} = (\vec{r} - \vec{c}) \times (\vec{l} - \vec{c})$$



Glyphs Method

- Rotates the skeleton of the user
- Draws the path joints take and stores it in an image
- Each joint will have its own exclusive color



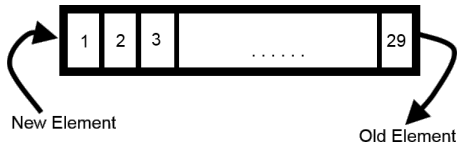
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Joint Positions Lists

- Creates a list ($n=30$)
- The list stores object types StoreGesture (Position, Time Stamp)



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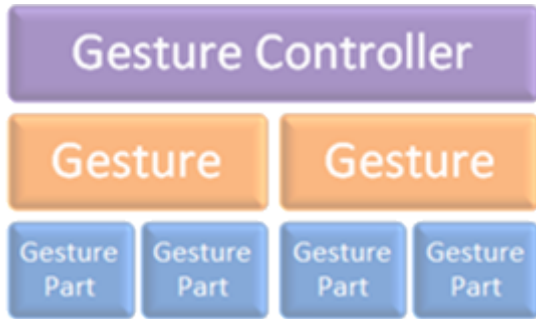


MCS UK

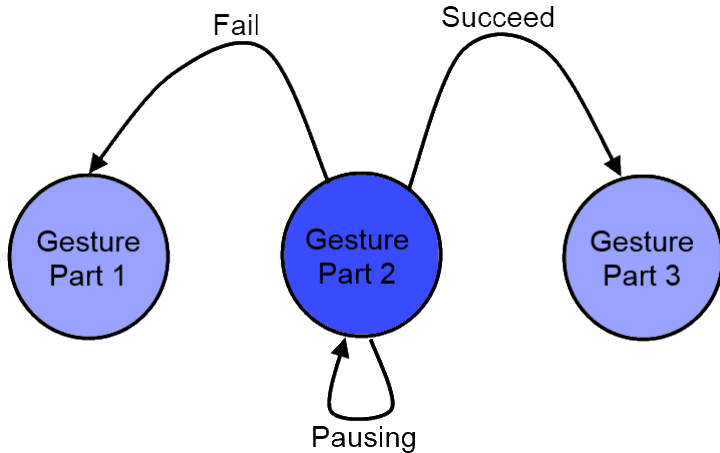
- Microsoft Consultant Services UK
- Gesture service for Kinect for Windows
- The gesture service is written in C#
- Similar to the JPL in a manner.



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Communication to the Interface

- Connection is attempted once Kinect is plugged and ready
- The interface listens for gestures
- User sends gestures with their timestamps
- Once connection to the interface falls, program terminates



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Demonstration

Please Hold for a Demonstration!
[this will only take few minutes]
... I lied



Demonstration

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[this will only take few minutes]
... I lied



Summary

- **Real time recognition** was accomplished by Kinect's fast streaming.
- The **Robust and Dynamic** requirement was not fully possible as Kinect has a lot of limitations.
- **Plugging in to the interface**, was possible through Socket programming.
- Outlook
 - Differentiation between facing and not facing (Solved in the new Kinect).
 - Detecting minor movements.



Q&A

Thank you for listening,
floor is open for Q & A

