Introduction
Project Recon
Recognition Techniques
Communication
Summary

Ju-Jutsu Training Kinect Application

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Summary

- Introduction
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- Project Recon
 - Architecture
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 - Project Requirements
- Recognition Techniques
 - Glyphs Method
 - Joint Positions Lists
 - MCS UK
- Communication
 - Communication to the Interface
 - Demonstration



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Ju-Jutsu

- Ju Jutsu is a Japanese martial art.
- Like most martail arts, it includes Thai Pad training.







- Different sensors include:
 - PlayStation EyeToy.
 - Microsoft Kinect.
- Applications supporting activities:
 - Ubisoft's Just Dance.
- However, there are no contact sports fitness related applications.





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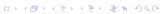


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Project Impact



- Embedded systems project
- Multiple inputs from a practitioner during a workout session through different input sources
- Main monitor will be used as the interface and to display sessions
- Website: http://georgjung.github.io/Impact/





Input Sources and Different Components

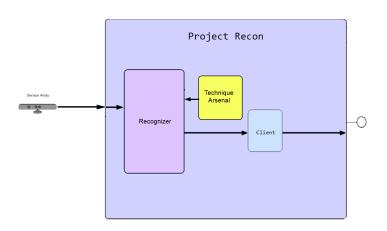
- Seismic sensor equipped Thai Pads
- Kinect sensor (Project Recon)
- Optional input
 - Pulse rates
 - Lactic acid levels
 - Respiration rates
 - and any similar measurement . . .



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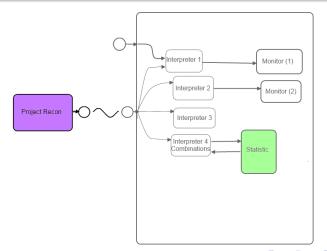
Project Recon Architecture







Project Recon Architecture







Kinect

- Four components
 - Infrared grid projector
 - Infrared sensor
 - Color camera
 - Microphone
- Four different streams
 - Depth stream
 - Color stream
 - Audio stream
 - Skeleton stream







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XNA



- Framework based on .NET Compact framework
- Created by Microsoft to support game development
- Basic platform for the indie games on XBOX Live
- Language used is C[‡]



Kinect SDK

KINECT for Windows

- Is the official SDK for the Kinect system
- Manages data streams





Socket Programming

- Enables Processes to communicate
- Used to connect between Project Recon and the Interface
- Uses client-server model





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Project Requirements

- Real time recognition
- Robust and dynamic
- Plug in to interface





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The Challenges in Kinect

- The user always faces the Kinect
- Kinect does not differentiate between facing and not facing
- Solution:
 - Normalize the skeleton of the user (Always ends up facing)





Normal Vector

• Create normal between vectors \vec{r} , \vec{c} , and \vec{l}

$$\vec{N} = (\vec{r} - \vec{c}) \times (\vec{l} - \vec{c})$$

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Glyphs Method

- Rotates the skeleton of the user
- Draws the path joints take and stores it in an image
- Each joint will have its own exclusive color



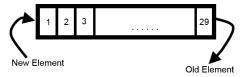


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Joint Positions Lists

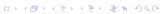
- Creates a list (n=30)
- The list stores object types StoreGesture (Position, Time Stamp)







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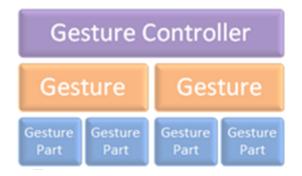
MCS UK

- Microsoft Consultant Services UK
- Gesture service for Kinect for Windows
- The gesture service is written in C[‡]
- Similar to the JPL in a manner.





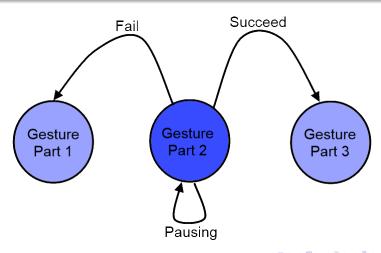
Architecture







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Communication to the Interface

- Connection is attempted once Kinect is plugged and ready
- The interface listens for gestures
- User sends gestures with their timestamps
- Once connection to the interface falls, program terminates





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Demonstration

Please Hold for a Demonstration! [this will only take few minutes]





Demonstration

Please Hold for a Demonstration!
[this will only take few minutes]
...I lied





Summary

- Real time recognition was accomplished by Kinect's fast streaming.
- The Robust and Dynamic requirement was not fully possible as Kinect has a lot of limitations.
- Plugging in to the interface, was possible through Socket programming.
- Outlook
 - Differentiation between facing and not facing(Solved in the new Kinect).
 - Detecting minor movements.





Q&A

Thank you for listening, floor is open for Q & A

