COMP 445
Data Communications & Computer networks
Winter 2022

Learning objectives

- To understand principles behind network control plane:
  - traditional routing algorithms
  - SDN controllers
  - network management, configuration
- To verify the application of routing principles in the actual implementation of Internet protocols: OSPF, BGP
- To understand the implementation of the control plane using OpenFlow

Network Layer – Control plane

- ✓ Introduction
- ✓ Routing algorithms
- ✓ Intra-ISP routing: OSPF
- ✓ Routing among ISPs: BGP
- ✓ SDN control plane
- ✓ Internet Control Message Protocol

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Network-layer functions

- routing: determine route taken by packets from source to destination

control plane

- forwarding: move packets from router's input to appropriate router output

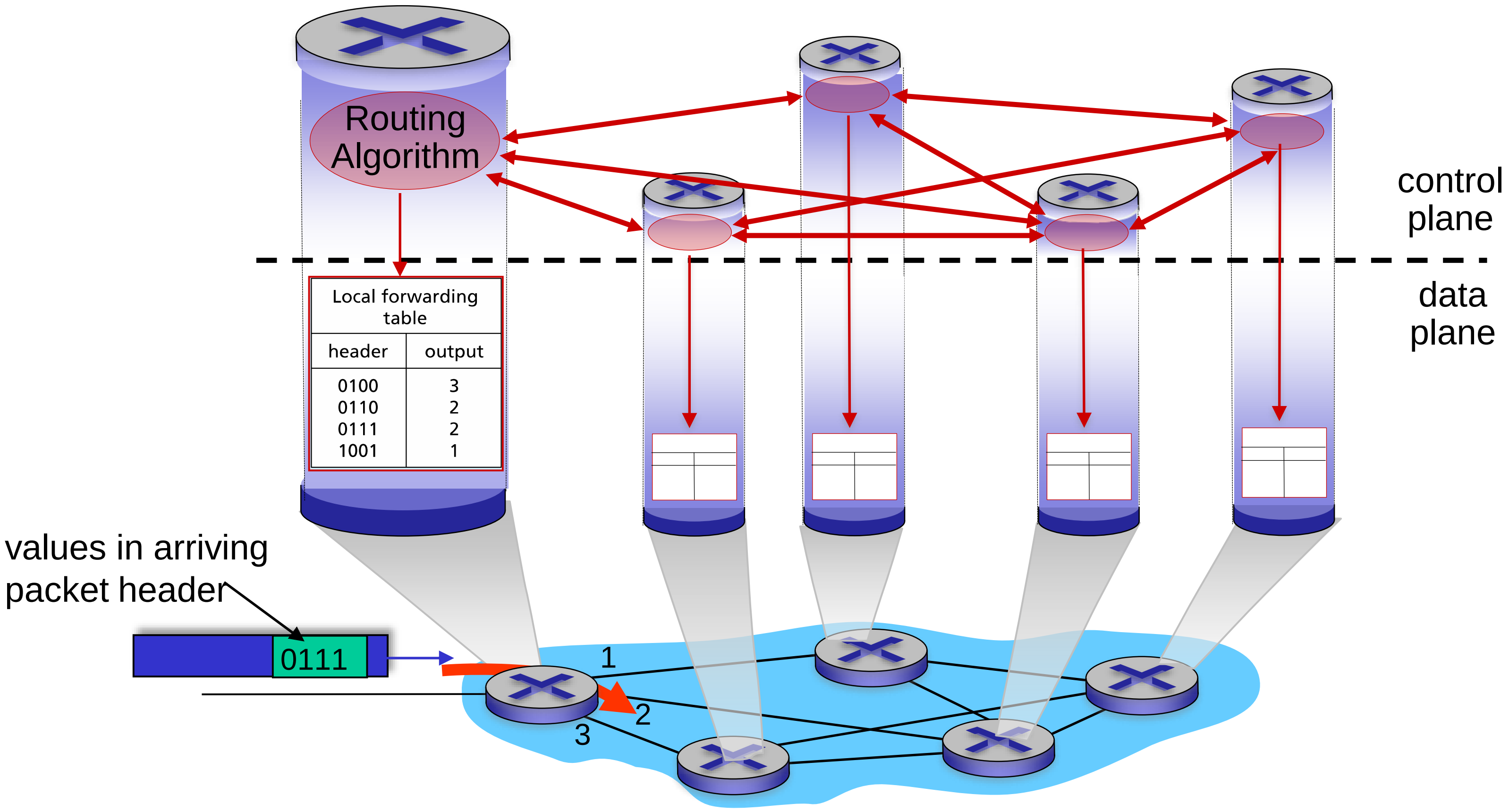
data plane

Two approaches to structuring network control plane:

- per-router control (traditional)
- logically centralized control (software defined networking)

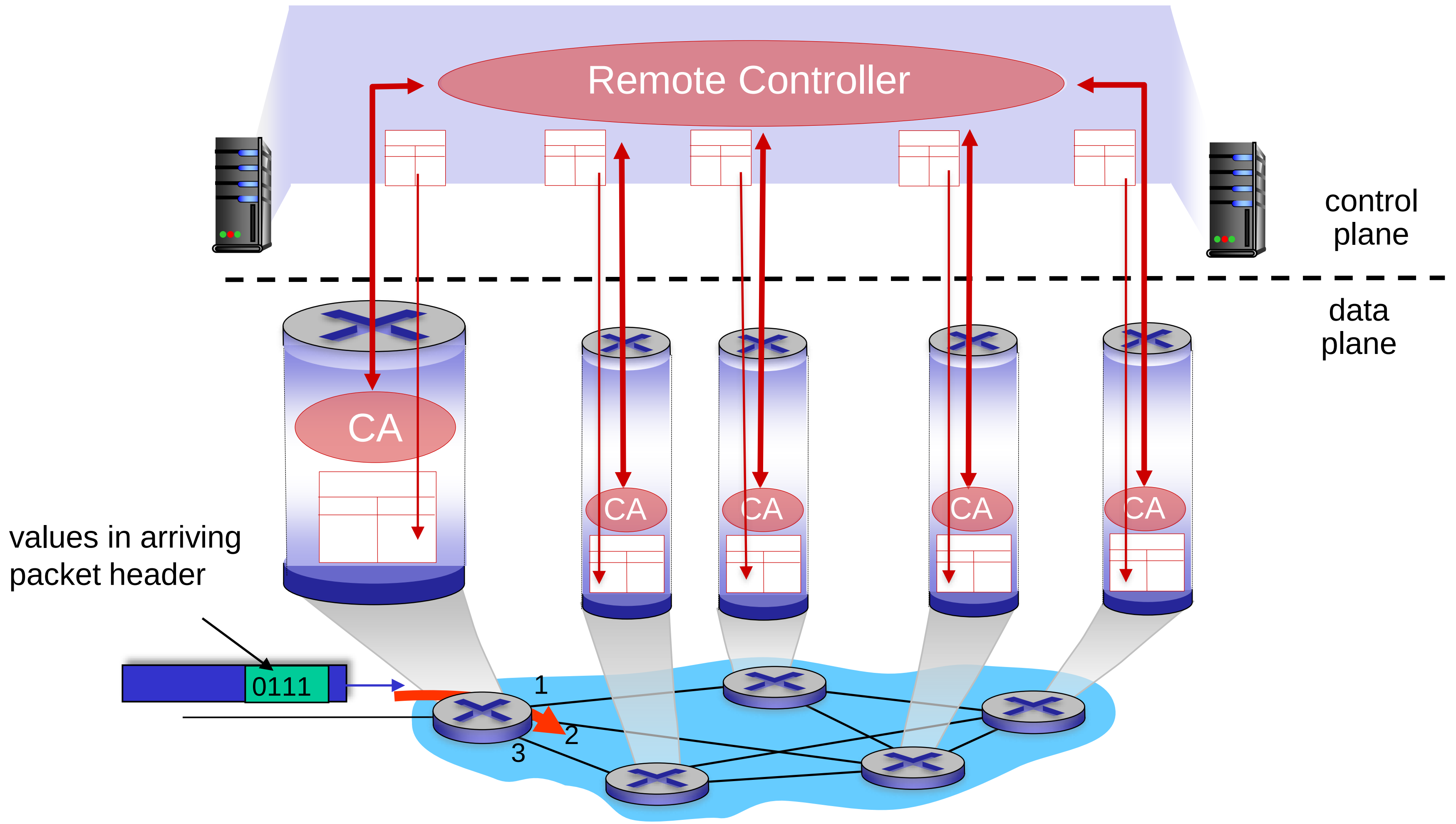
Per-router control plane

Individual routing algorithm components *in each and every router* interact in the control plane

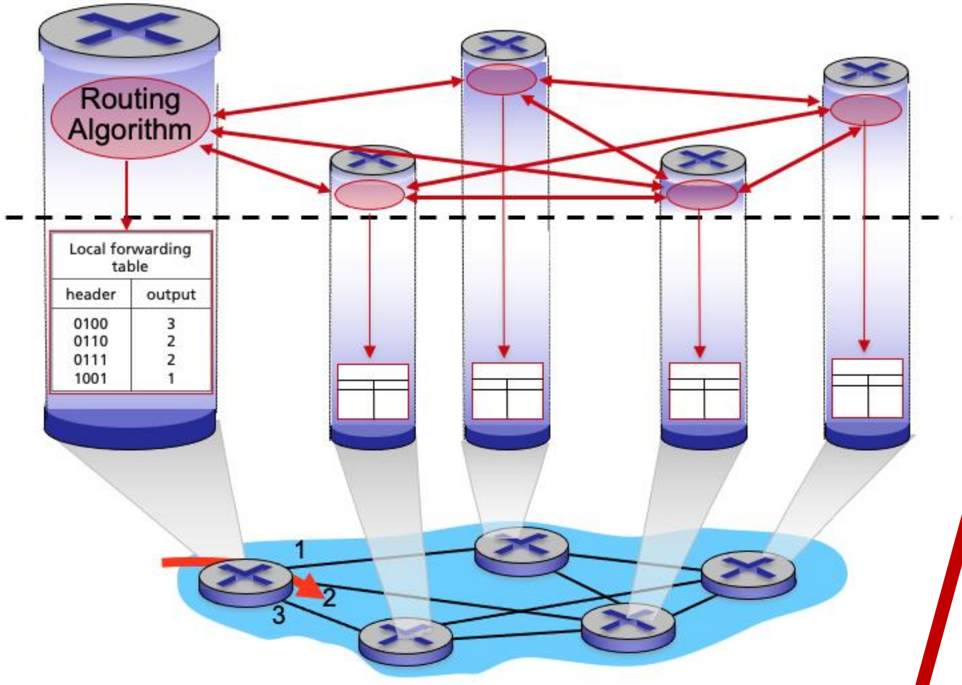


Software-Defined Networking (SDN) control plane

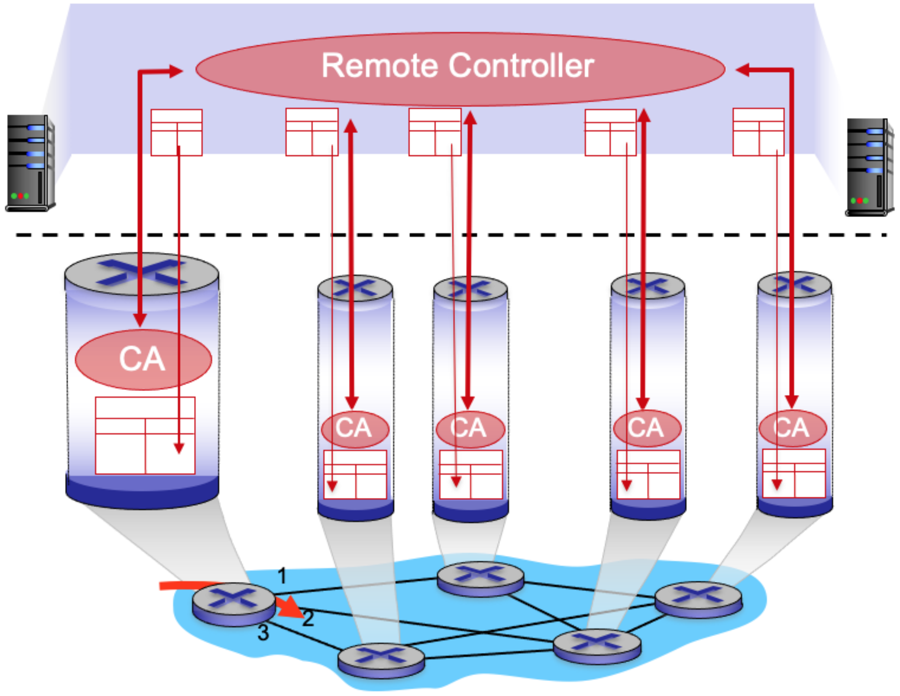
Remote controller computes, installs forwarding tables in routers



Per-router control plane



SDN control plane



Network Layer – Control plane

- ✓ Introduction
- ✓ Routing algorithms
- ✓ Intra-ISP routing: OSPF
- ✓ Routing among ISPs: BGP
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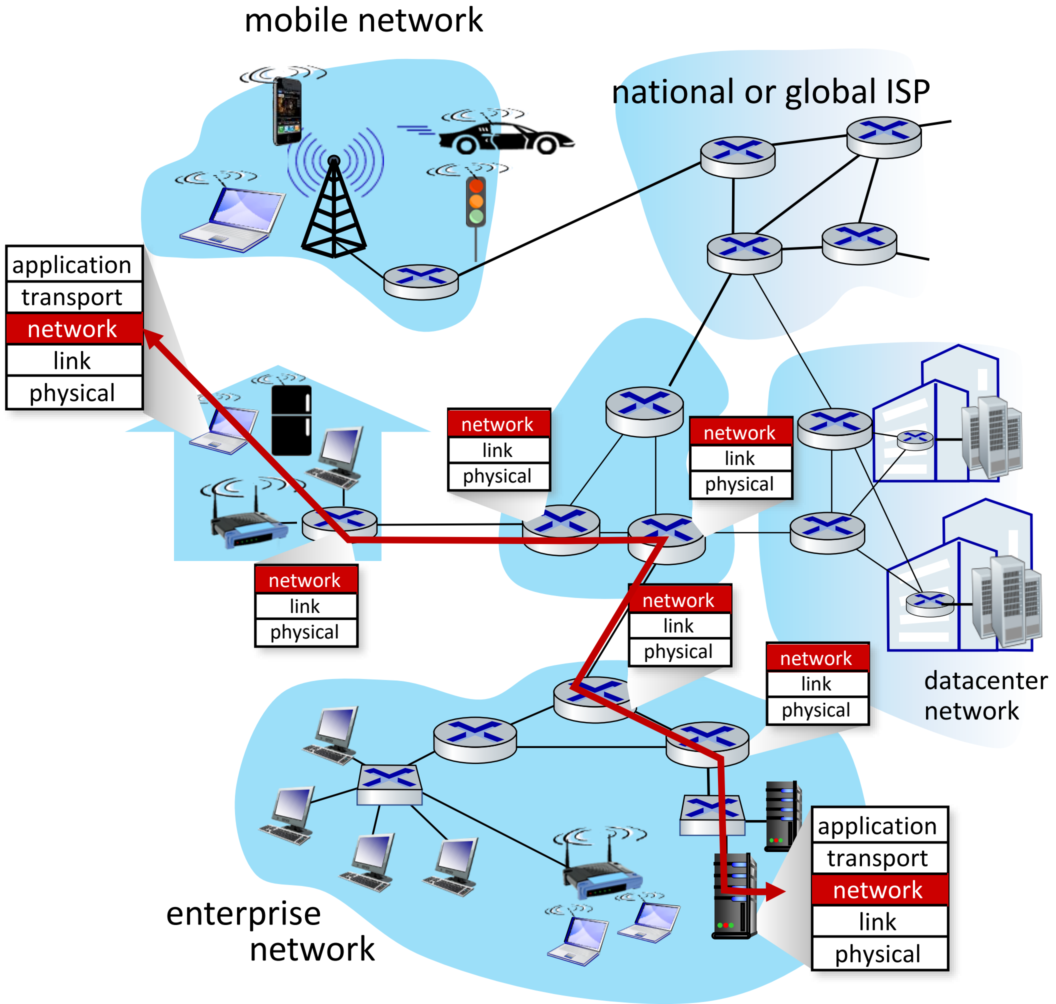
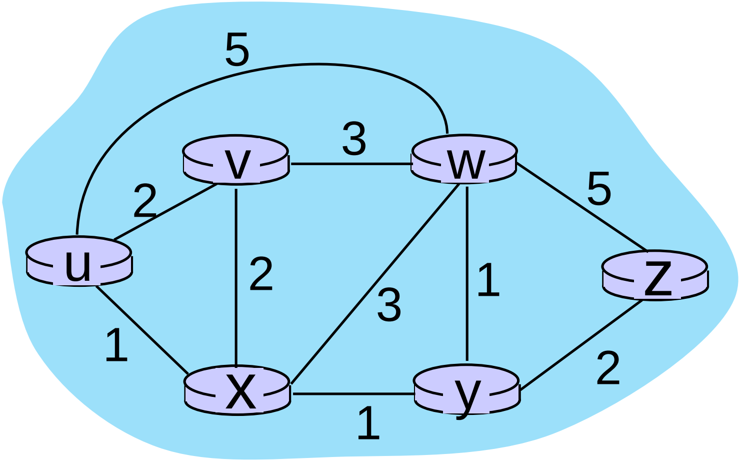
Routing algorithm

Routing algorithm goal: determine "good" paths (equivalently, routes), from sending hosts to receiving host, through network of routers

- path: sequence of routers packets traverse from given initial source host to final destination host
- "good": least "cost", "fastest", "least congested"
- routing: a "top-10" networking challenge!



Graph abstraction: link costs



$c_{a,b}$: cost of *direct* link connecting *a* and *b*

e.g., $c_{w,z} = 5$, $c_{u,z} = \infty$

cost defined by network operator: could always be 1, or inversely related to bandwidth, or related to congestion

graph: $G = (N,E)$

N: set of routers = { u, v, w, x, y, z }

E: set of links ={ $(u,v), (u,x), (v,x), (v,w), (x,w), (x,y), (w,y), (w,z), (y,z)$ }

Routing algorithm classification

global: all routers have *complete* topology, link cost info
- "link state" algorithms

How fast do routes change?

static: routes change slowly over time

dynamic: routes change more quickly
- periodic updates or in response to link cost changes

decentralized: iterative process of computation, exchange of info with neighbors
- routers initially only know link costs to attached neighbors
- "distance vector" algorithms

global or decentralized information?

Dijkstra's link-state routing algorithm

- centralized: network topology, link costs known to *all* nodes
  - accomplished via "link state broadcast"
  - all nodes have same info
- computes least cost paths from one node ("source") to all other nodes
  - gives *forwarding table* for that node
- iterative: after *k* iterations, know least cost path to *k* destinations

notation

- $C_{a,b}$: direct link cost from node *a* to *b*; = ∞ if not direct neighbors
- *D(a)*: *current* estimate of cost of least-cost-path from source to destination *a*
- *p(a)*: predecessor node along path from source to *a*
- *N'*: set of nodes whose least-cost-path *definitively* known

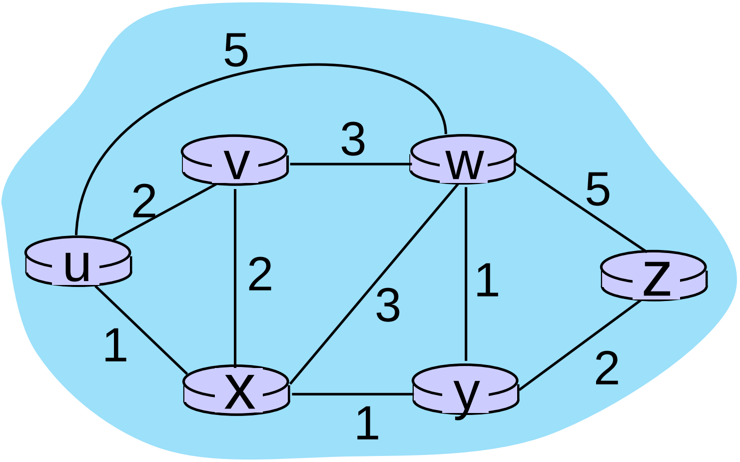
Dijkstra's link-state routing algorithm

Initialization:
  $N' = \{u\}$ /* compute least cost path from u to all other nodes */
  for all nodes a
    if a adjacent to u /* u initially knows direct-path-cost only to direct neighbors */
      then $D(a) = c_{u,a}$ /* but may not be *minimum* cost! */
    else $D(a) = \infty$

Loop
  find a not in N' such that $D(a)$ is a minimum
  add a to N'
  update $D(b)$ for all b adjacent to a and not in N' :
    $\mathbf{D(b) = \min(\, D(b),\; D(a) + c_{a,b}\,)}$
  /* new least-path-cost to b is either old least-cost-path to b or known
  least-cost-path to a plus direct-cost from a to b */
until all nodes in N'

Dijkstra’s algorithm: an example

Step	N'	v D(v),p(v)	w D(w),p(w)	x D(x),p(x)	y D(y),p(y)	z D(z),p(z)
0	u	2,u	5,u	1,u	∞	∞
1						
2						
3						
4						
5						

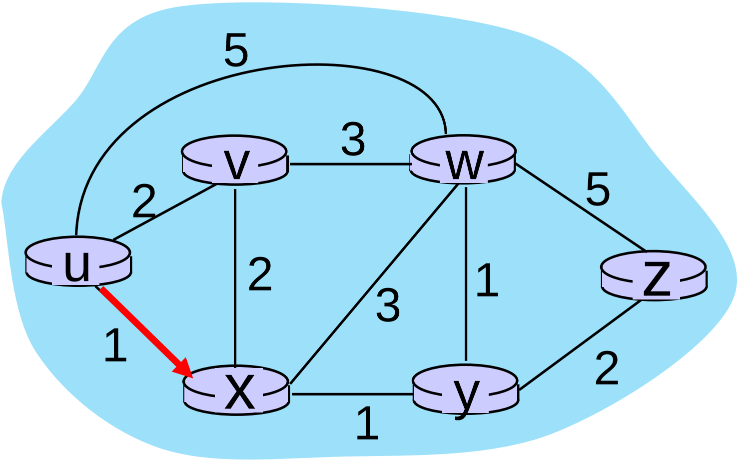


Initialization (step 0):

For all *a*: if *a* adjacent to *u* then $D(a) = c_{u,a}$

Dijkstra’s algorithm: an example

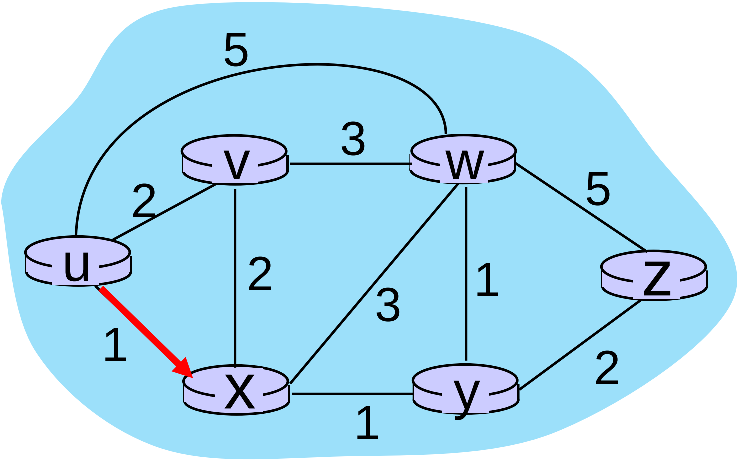
Step	N'	v D(v),p(v)	w D(w),p(w)	x D(x),p(x)	y D(y),p(y)	z D(z),p(z)
0	u	2,u	5,u	1,u	∞	∞
1	ux					
2						
3						
4						
5						



Loop
  find *a* not in *N'* such that *D(a)* is a minimum
  add *a* to *N'*

Dijkstra's algorithm: an example

Step	N'	v D(v),p(v)	w D(w),p(w)	x D(x),p(x)	y D(y),p(y)	z D(z),p(z)
0	u	2,u	5,u	1,u	∞	∞
1	ux	2,u	4,x		2,x	∞
2						
3						
4						
5						



8 *Loop*

9 find *a* not in *N'* such that *D(a)* is a minimum

10 add *a* to *N'*

11 update *D(b)* for all *b* adjacent to *a* and not in *N'* :

$D(b) = \min (D(b), D(a) + c_{a,b})$

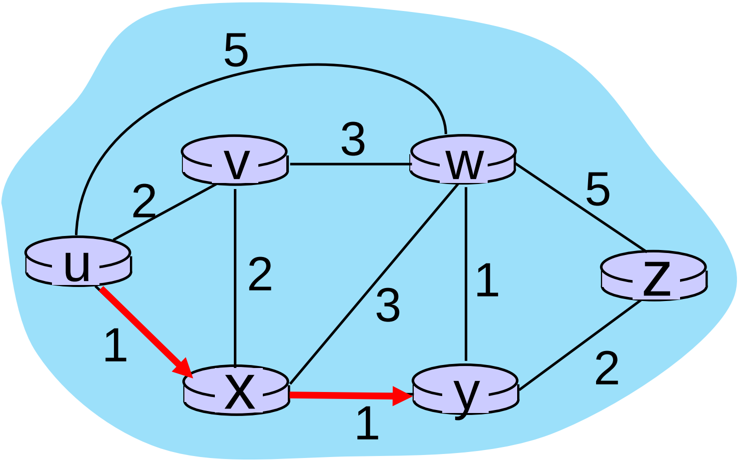
$D(v) = \min (D(v), D(x) + c_{x,v}) = \min(2, 1+2) = 2$

$D(w) = \min (D(w), D(x) + c_{x,w}) = \min (5, 1+3) = 4$ NEW!

$D(y) = \min (D(y), D(x) + c_{x,y}) = \min(inf,1+1) = 2$ NEW!

Dijkstra's algorithm: an example

Step	N'	v D(v),p(v)	w D(w),p(w)	x D(x),p(x)	y D(y),p(y)	z D(z),p(z)
0	u	2,u	5,u	1,u	∞	∞
1	ux	2,u	4,x		2,x	∞
2	uxy					
3						
4						
5						



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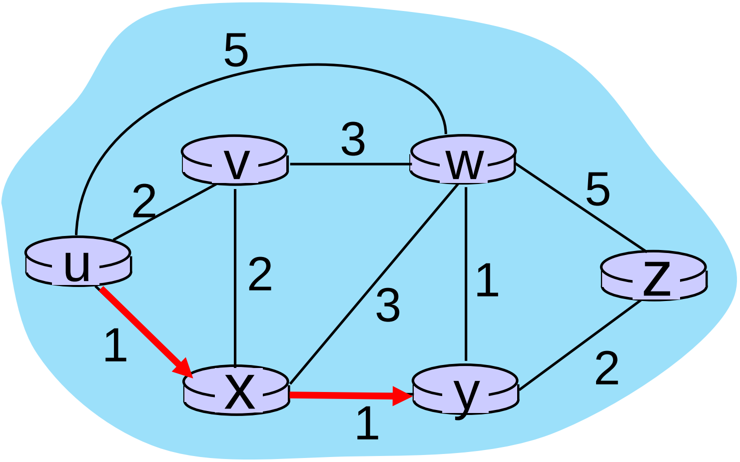
0	u	2,u	5,u	1,u	∞	∞
1	ux	2,u	4,x		2,x	∞
2	uxy	2,u	3,y			4,y
3						
4						
5						



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$D(b) = \min(D(b), D(a) + c_{a,b})$

$D(w) = \min(D(w), D(y) + c_{x,w}) = \min(4, 2+1) = 3$ NEW!

$D(z) = \min(D(z), D(y) + c_{y,x}) = \min(inf, 2+2) = 4$ NEW!

Dijkstra's algorithm: an example

Step	N'	v D(v),p(v)	w D(w),p(w)	x D(x),p(x)	y D(y),p(y)	z D(z),p(z)
0	u	2,u	5,u	1,u	∞	∞
1	ux	2,u	4,x		2,x	∞
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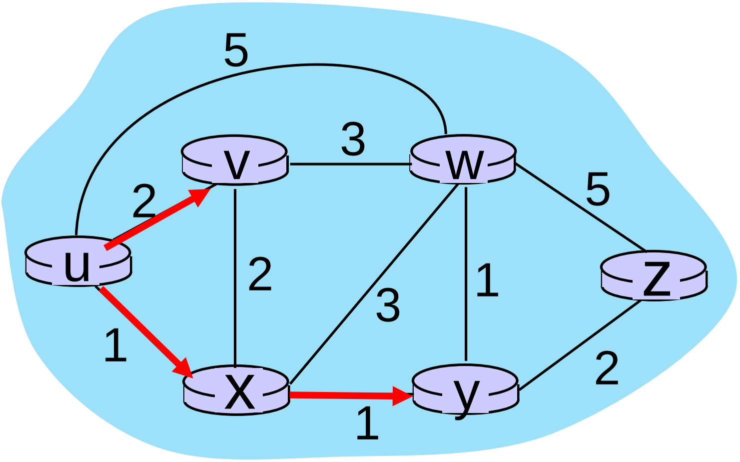
3	uxyv					
4						
5						



Loop

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add *a* to *N'*

Dijkstra's algorithm: an example

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3	uxyv		3,y			4,y
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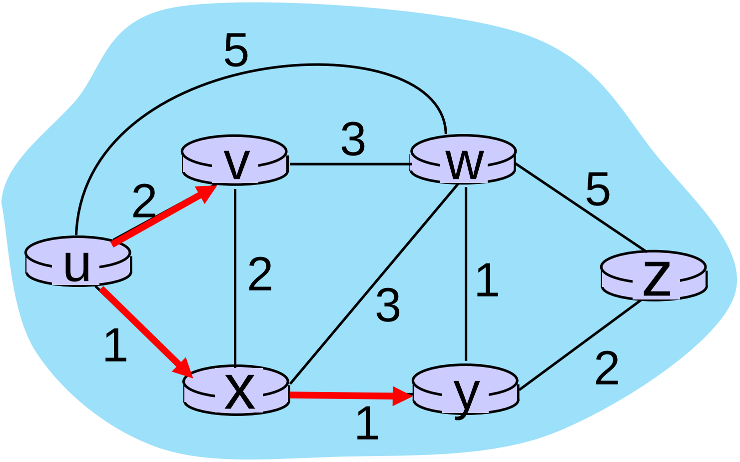
5						



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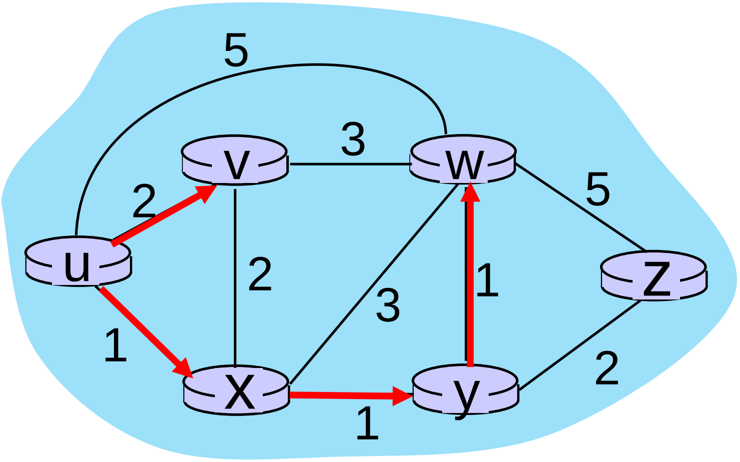
0	u	2,u	5,u	1,u	∞	∞
1	ux	2,u	4,x		2,x	∞
2	uxy	2,u	3,y			4,y
3	uxyv		3,y			4,y
4	uxyvw					
5						



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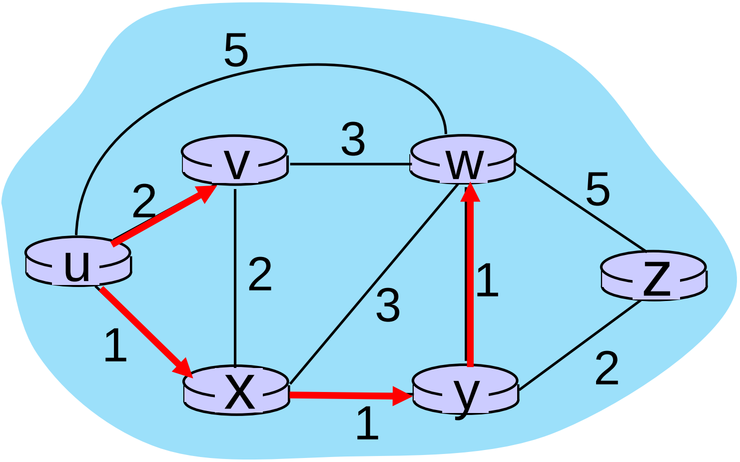
0	u	2,u	5,u	1,u	∞	∞
1	ux	2,u	4,x		2,x	∞
2	uxy	2,u	3,y			4,y
3	uxyv		3,y			4,y
4	uxyvw					4,y
5						



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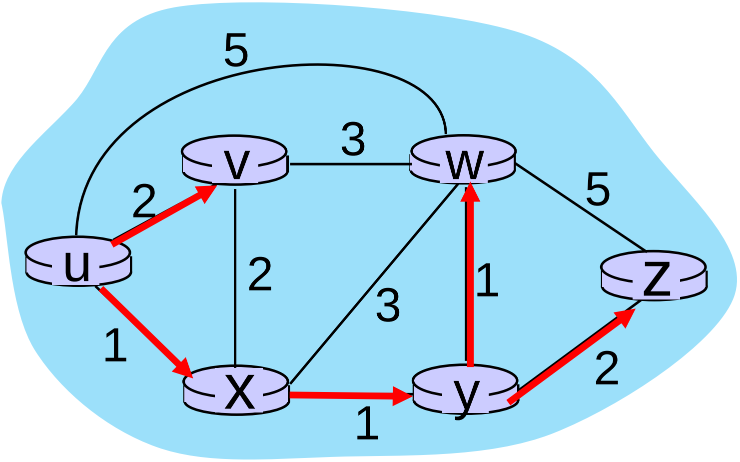
3	uxyv		3,y			4,y
4	uxyvw					4,y
5	uxyvwz					



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Dijkstra's algorithm: an example

		v	w	x	y	z
Step	N'	D(v),p(v)	D(w),p(w)	D(x),p(x)	D(y),p(y)	D(z),p(z)
0	u	2,u	5,u	1,u	∞	∞
1	ux	2,u	4,x		2,x	∞
2	uxy	2,u	3,y			4,y
3	uxyv		3,y			4,y
4	uxyvw					4,y
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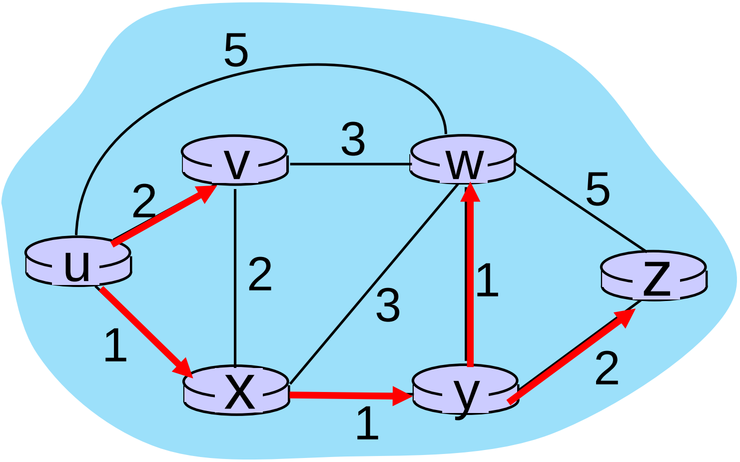

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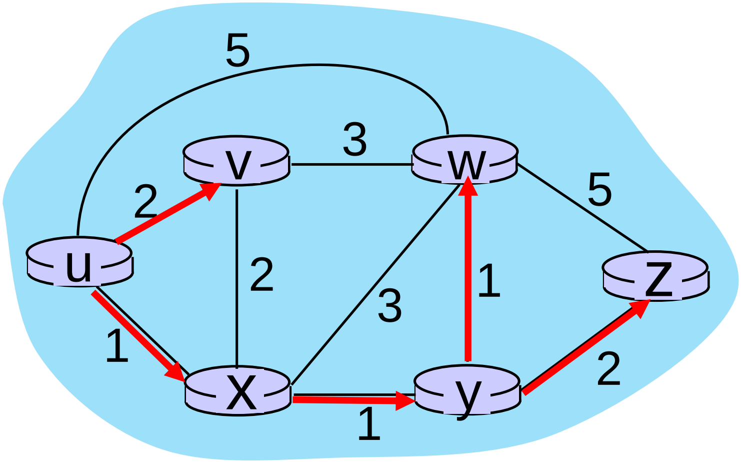
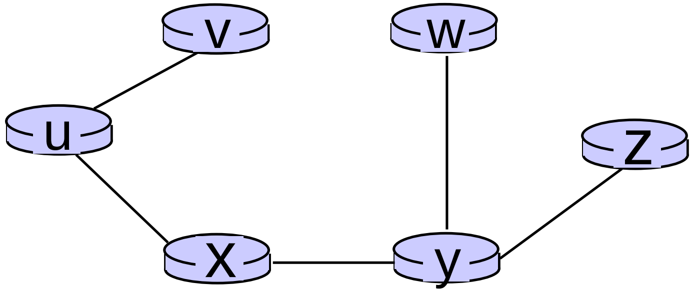
Dijkstra's algorithm: an example



resulting least-cost-path tree from u:



resulting forwarding table in u:

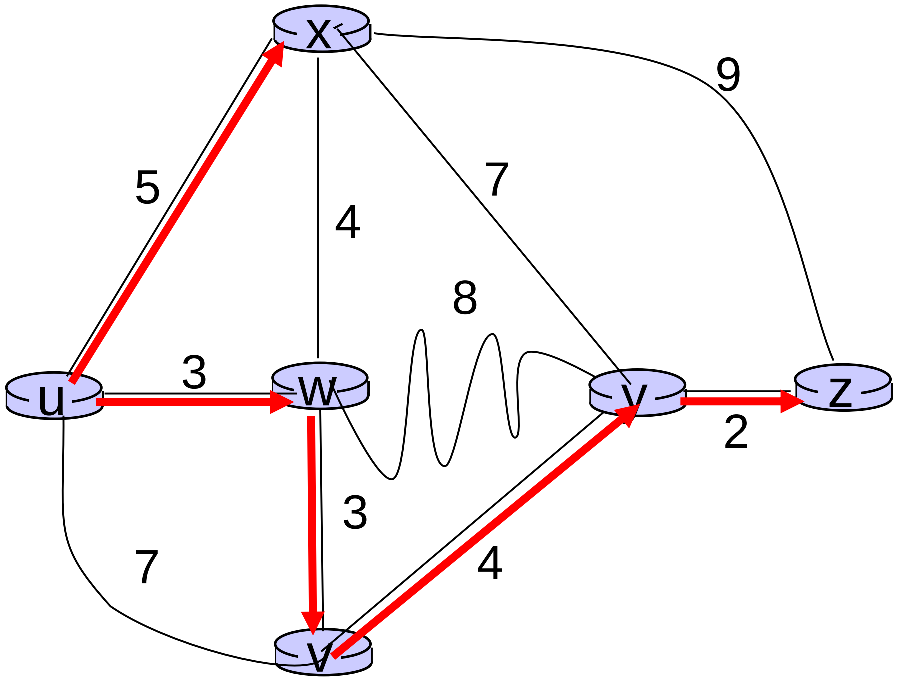
destination	outgoing link
v	(u,v)
x	(u,x)
y	(u,x)
w	(u,x)
z	(u,x)

route from *u* to *v* directly

route from u to all other destinations via *x*

Dijkstra's algorithm: another example

Step	N'	D(v), p(v)	D(w), p(w)	D(x), p(x)	D(y), p(y)	D(z), p(z)
0	u	7,u	3,u	5,u	∞	∞
1	uw	6,w		5,u	11,w	∞
2	uwx	6,w			11,w	14,x
3	uwxv				10,v	14,x
4	uwxvy					12,y
5	uwxvyz					



notes:

- construct least-cost-path tree by tracing predecessor nodes
- ties can exist (can be broken arbitrarily)

Dijkstra's algorithm: discussion

algorithm complexity: *n* nodes

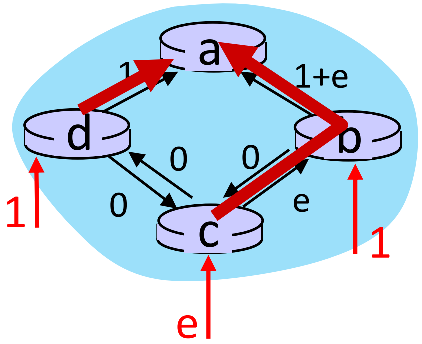
- each of *n* iteration: need to check all nodes, *w*, not in *N*
- $n(n+1)/2$ comparisons: $O(n^2)$ complexity
- more efficient implementations possible: $O(n\log n)$

message complexity:

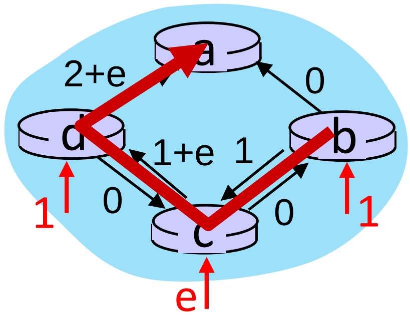
- each router must *broadcast* its link state information to other *n* routers
- efficient (and interesting!) broadcast algorithms: $O(n)$ link crossings to disseminate a broadcast message from one source
- each router's message crosses $O(n)$ links: overall message complexity: $O(n^2)$

Dijkstra’s algorithm: oscillations possible

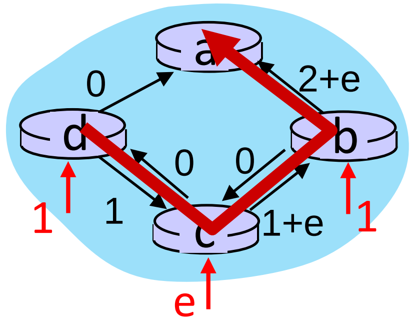
- when link costs depend on traffic volume, route oscillations possible
- sample scenario:
  - routing to destination a, traffic entering at d, c, e with rates 1, e (<1), 1
  - link costs are directional, and volume-dependent



initially



given these costs,
find new routing….
resulting in new costs



given these costs,
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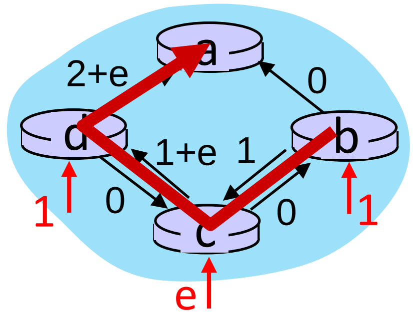


given these costs,
find new routing….
resulting in new costs

Distance vector algorithm

Based on *Bellman-Ford* (BF) equation (dynamic programming):

Bellman-Ford equation

Let $D_x(y)$: cost of least-cost path from x to y.

Then:

$$D_x(y) = \min_v \{ c_{x,v} + D_v(y) \}$$

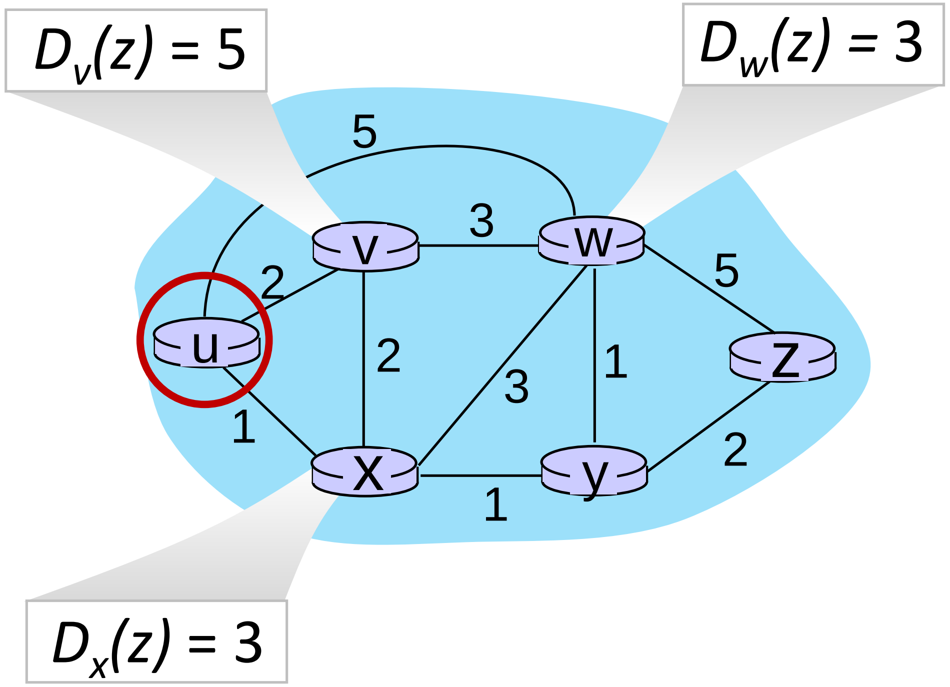
v's estimated least-cost-path cost to y

min taken over all neighbors v of x

direct cost of link from x to v

Bellman-Ford Example

Suppose that *u*'s neighboring nodes, *x,v,w,* know that for destination *z*:



Bellman-Ford equation says:

$$
\begin{aligned}
D_u(z) &= \min \{ c_{u,v} + D_v(z), \\
&\qquad c_{u,x} + D_x(z), \\
&\qquad c_{u,w} + D_w(z) \} \\
&= \min \{2 + 5, \\
&\qquad 1 + 3, \\
&\qquad 5 + 3\} = 4
\end{aligned}
$$

node achieving minimum (x) is next hop on estimated least-cost path to destination (z)

Distance vector algorithm

key idea:

- from time-to-time, each node sends its own distance vector estimate to neighbors
- when x receives new DV estimate from any neighbor, it updates its own DV using B-F equation:

$$D_x(y) \leftarrow \min_v\{c_{x,v} + D_v(y)\} \text{ for each node } y \in N$$

- under minor, natural conditions, the estimate $D_x(y)$ *converge to the actual least cost* $d_x(y)$

Distance vector algorithm:

each node:

wait for (change in local link cost or msg from neighbor)

↓

recompute my DV estimates using DV received from neighbor

↓

if my DV to any destination has changed, *send my new DV* my neighbors, else do nothing.

iterative, asynchronous: each local iteration caused by:

- local link cost change
- DV update message from neighbor

distributed, self-stopping: each node notifies neighbors *only* when its DV changes

- neighbors then notify their neighbors – *only if necessary*
- no notification received, no actions taken!

$$D_x(y) = \min\{c(x,y) + D_y(y),\ c(x,z) + D_z(y)\} = \min\{2+0\ ,\ 7+1\} = 2$$

$$D_x(z) = \min\{c(x,y) + D_y(z),\ c(x,z) + D_z(z)\} = \min\{2+1\ ,\ 7+0\} = 3$$

node x table

from \ cost to	x	y	z
x	0	2	7
y	∞	∞	∞
z	∞	∞	∞

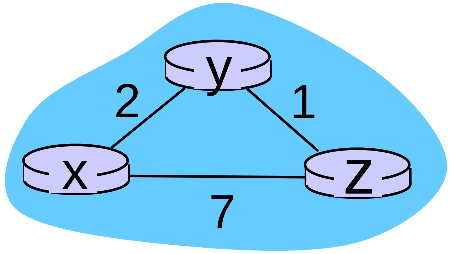
from \ cost to	x	y	z
x	0	2	3
y	2	0	1
z	7	1	0

node y table

from \ cost to	x	y	z
x	∞	∞	∞
y	2	0	1
z	∞	∞	∞

node z table

from \ cost to	x	y	z
x	∞	∞	∞
y	∞	∞	∞
z	7	1	0



time

$D_x(y) = \min\{c(x,y) + D_y(y), c(x,z) + D_z(y)\}$
$= \min\{2+0 , 7+1\} = 2$

$D_x(z) = \min\{c(x,y) +$
$D_y(z), c(x,z) + D_z(z)\}$
$= \min\{2+1 , 7+0\} = 3$

node x table

from \ cost to	x	y	z
x	0	2	7
y	∞	∞	∞
z	∞	∞	∞

from \ cost to	x	y	z
x	0	2	3
y	2	0	1
z	7	1	0

from \ cost to	x	y	z
x	0	2	3
y	2	0	1
z	3	1	0

node y table

from \ cost to	x	y	z
x	∞	∞	∞
y	2	0	1
z	∞	∞	∞

from \ cost to	x	y	z
x	0	2	7
y	2	0	1
z	7	1	0

from \ cost to	x	y	z
x	0	2	3
y	2	0	1
z	3	1	0

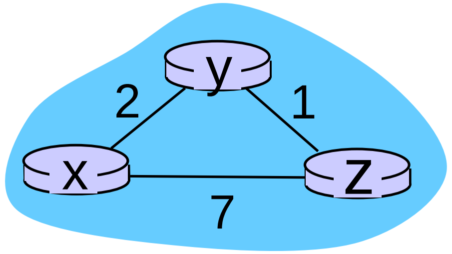
node z table

from \ cost to	x	y	z
x	∞	∞	∞
y	∞	∞	∞
z	7	1	0

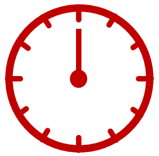
from \ cost to	x	y	z
x	0	2	7
y	2	0	1
z	3	1	0

from \ cost to	x	y	z
x	0	2	3
y	2	0	1
z	3	1	0

time



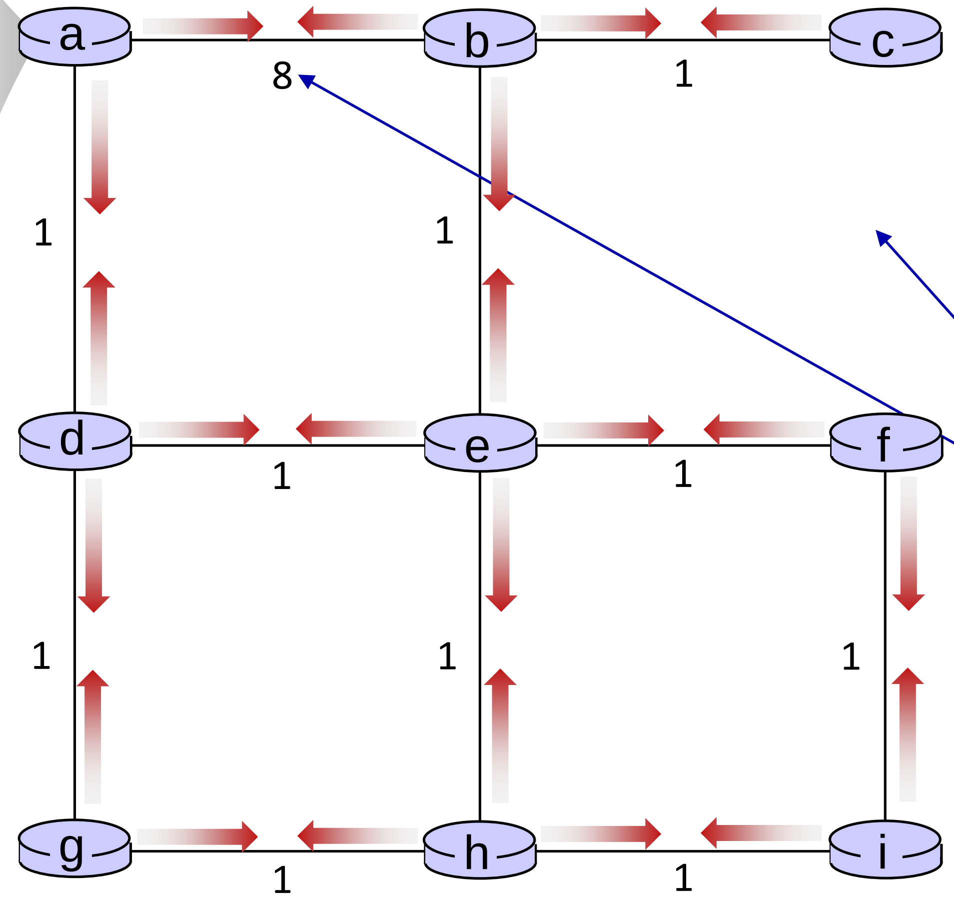
Distance vector: another example



t=0

- All nodes have distance estimates to nearest neighbors (only)
- All nodes send their local distance vector to their neighbors

DV in a:
$D_a(a)=0$
$D_a(b) = 8$
$D_a(c) = \infty$
$D_a(d) = 1$
$D_a(e) = \infty$
$D_a(f) = \infty$
$D_a(g) = \infty$
$D_a(h) = \infty$
$D_a(i) = \infty$

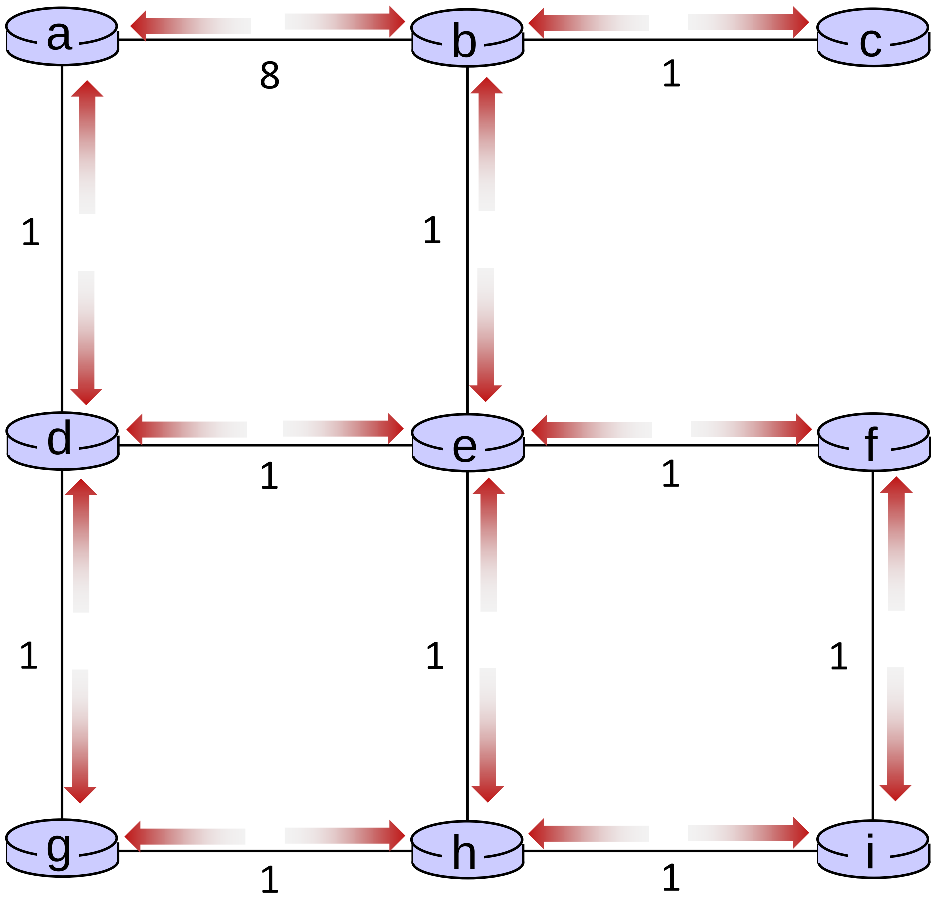


A few asymmetries:
- missing link
- larger cost

Distance vector example: iteration

t=1

All nodes:
- receive distance vectors from neighbors
- compute their new local distance vector
- send their new local distance vector to neighbors

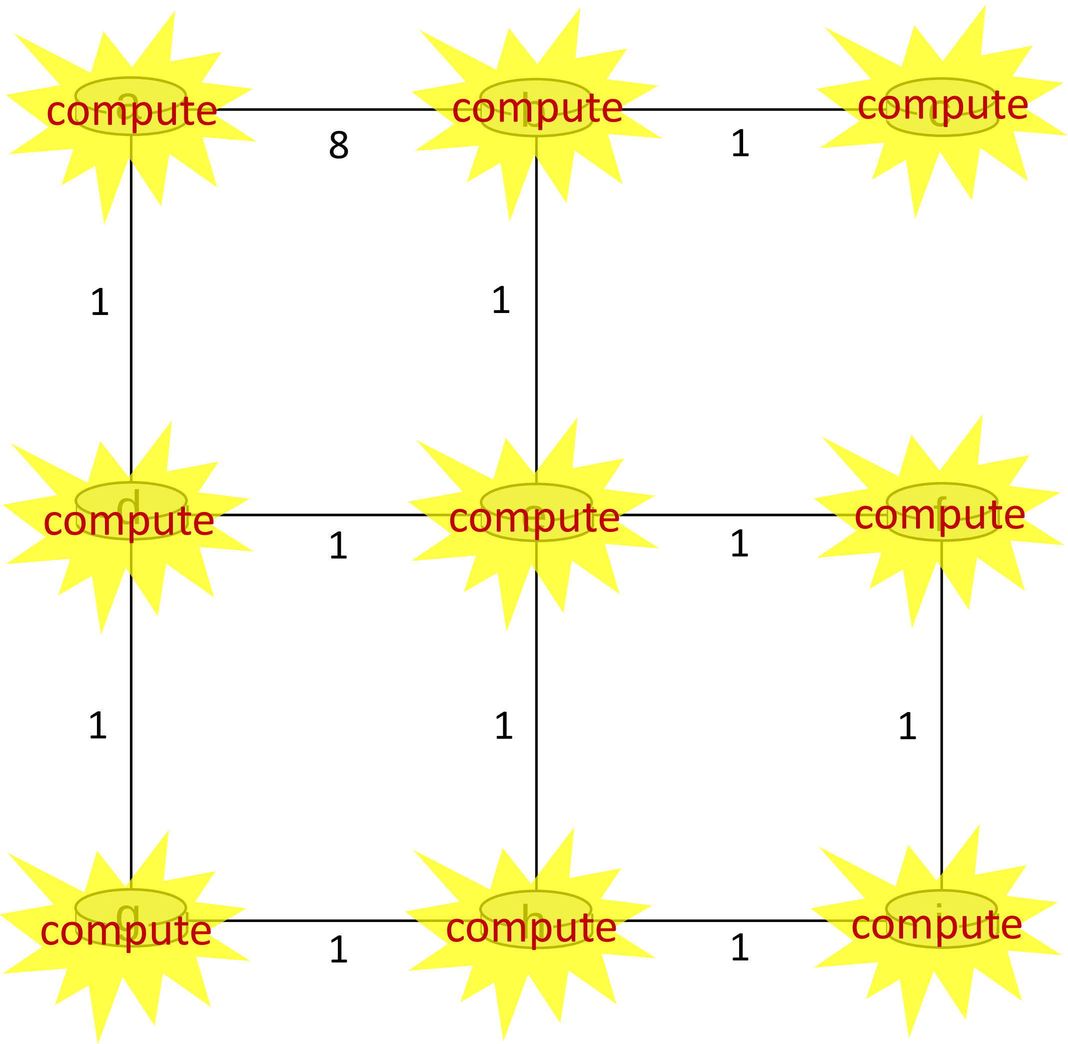


Distance vector example: iteration

t=1

All nodes:

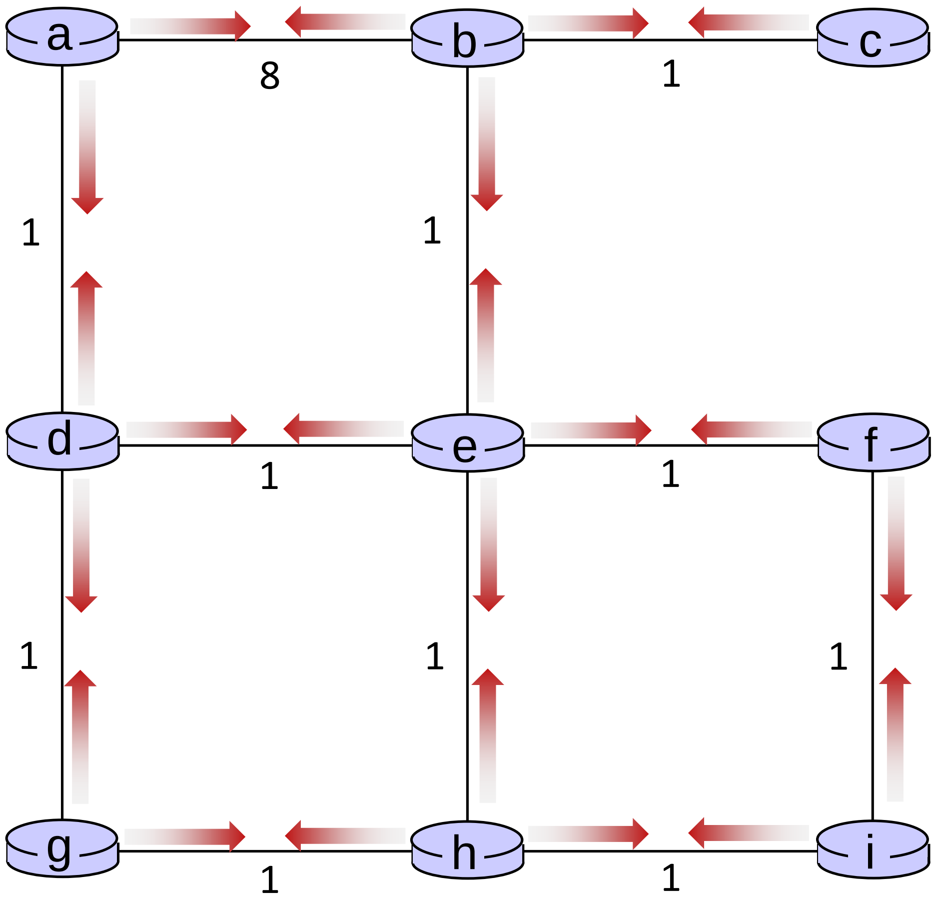
- receive distance vectors from neighbors
- compute their new local distance vector
- send their new local distance vector to neighbors



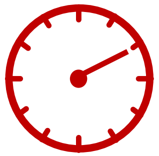
Distance vector example: iteration

t=1

All nodes:
- receive distance vectors from neighbors
- compute their new local distance vector
- send their new local distance vector to neighbors



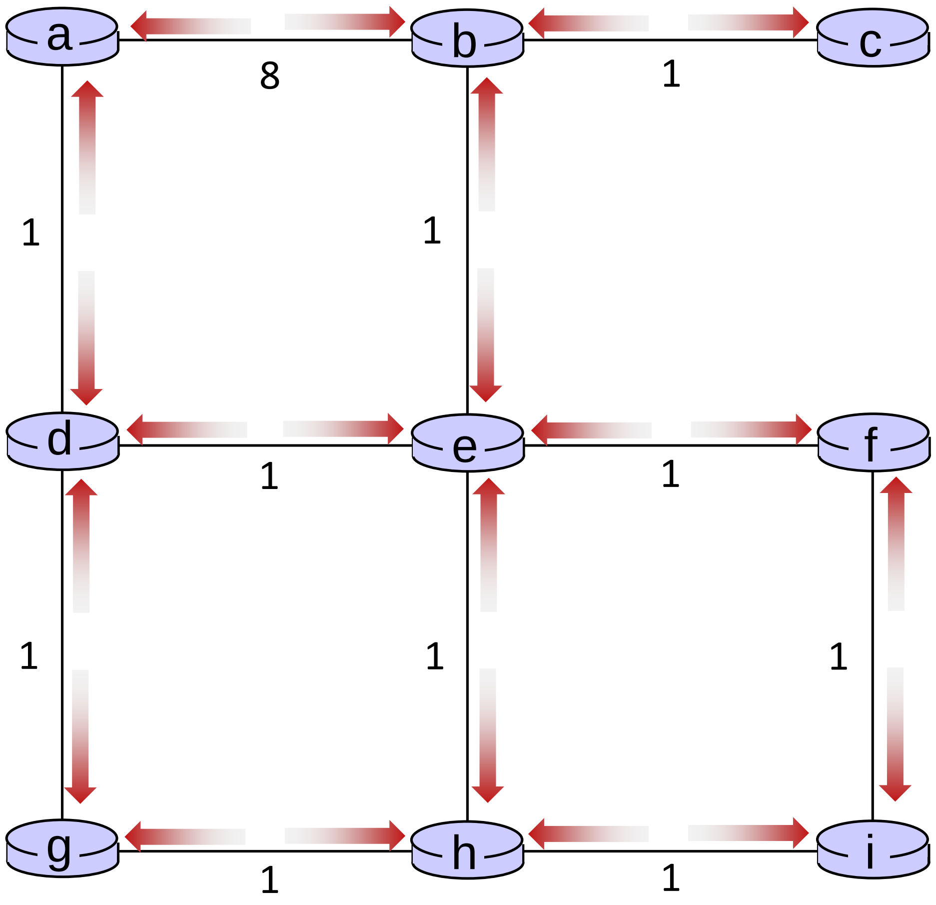
Distance vector example: iteration



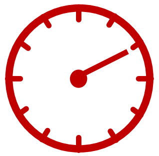
t=2

All nodes:

- receive distance vectors from neighbors
- compute their new local distance vector
- send their new local distance vector to neighbors



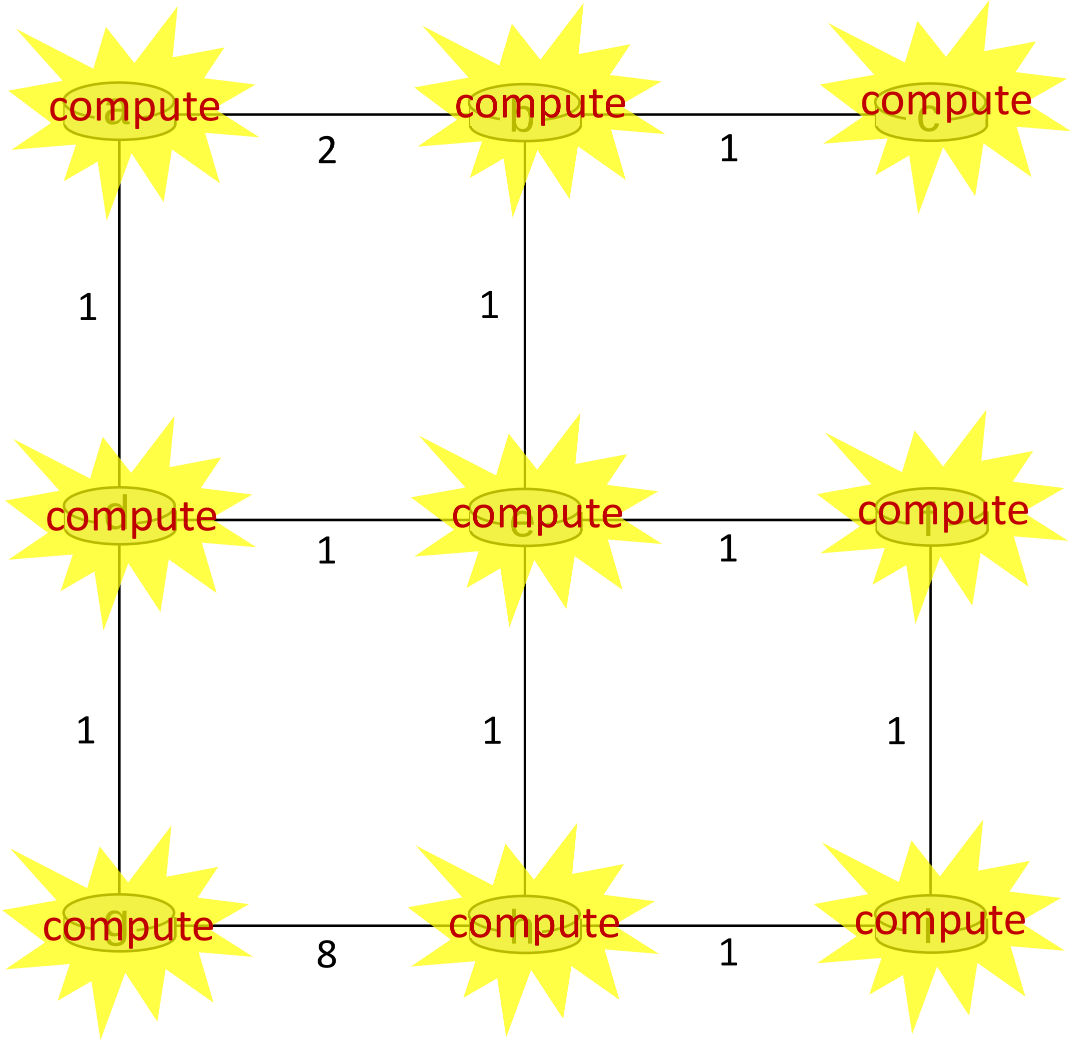
Distance vector example: iteration



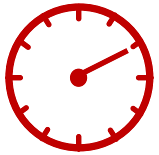
t=2

All nodes:

- receive distance vectors from neighbors
- compute their new local distance vector
- send their new local distance vector to neighbors

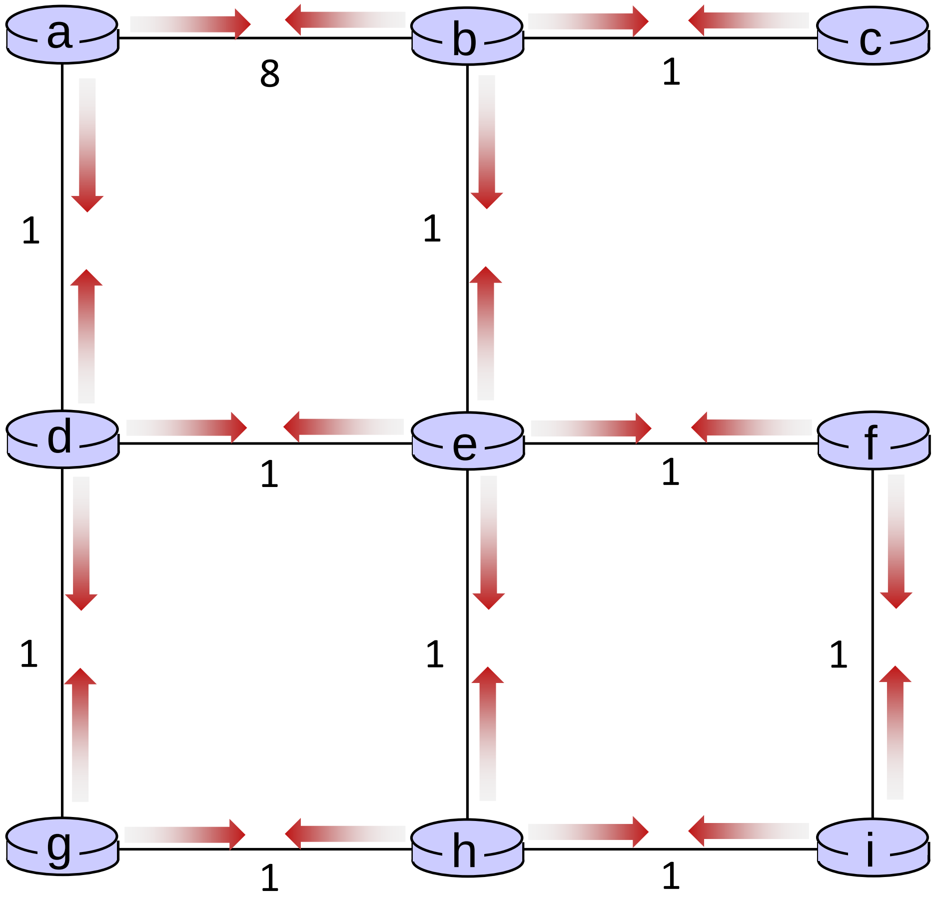


Distance vector example: iteration



t=2

All nodes:
- receive distance vectors from neighbors
- compute their new local distance vector
- send their new local distance vector to neighbors



Distance vector example: iteration

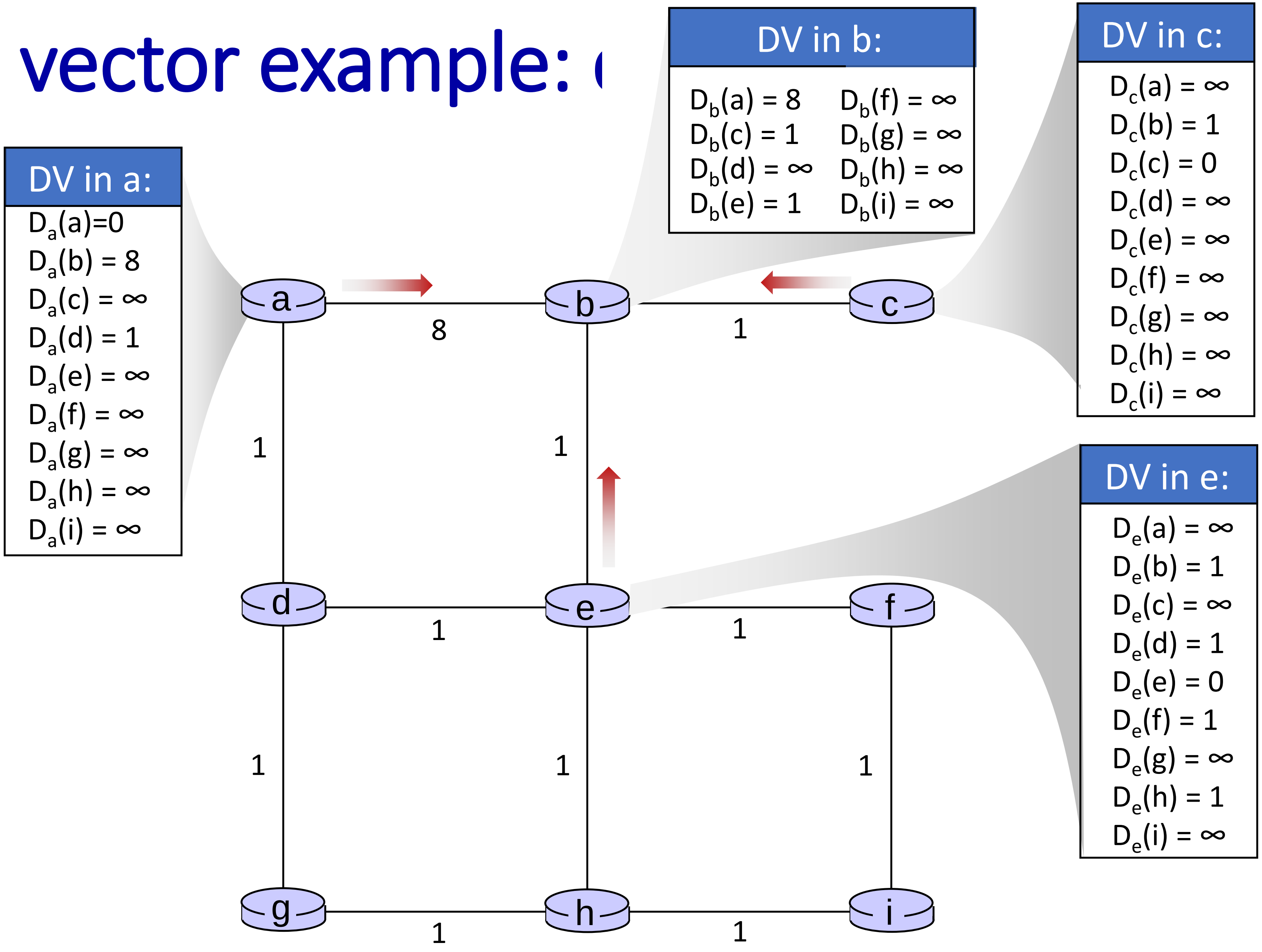
…. and so on

Let’s next take a look at the iterative *computations* at nodes

Distance vector example:

t=0

- b receives DVs from a, c, e



Distance vector example:

DV in a:

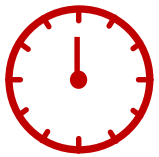
$D_a(a)=0$
$D_a(b) = 8$
$D_a(c) = \infty$
$D_a(d) = 1$
$D_a(e) = \infty$
$D_a(f) = \infty$
$D_a(g) = \infty$
$D_a(h) = \infty$
$D_a(i) = \infty$

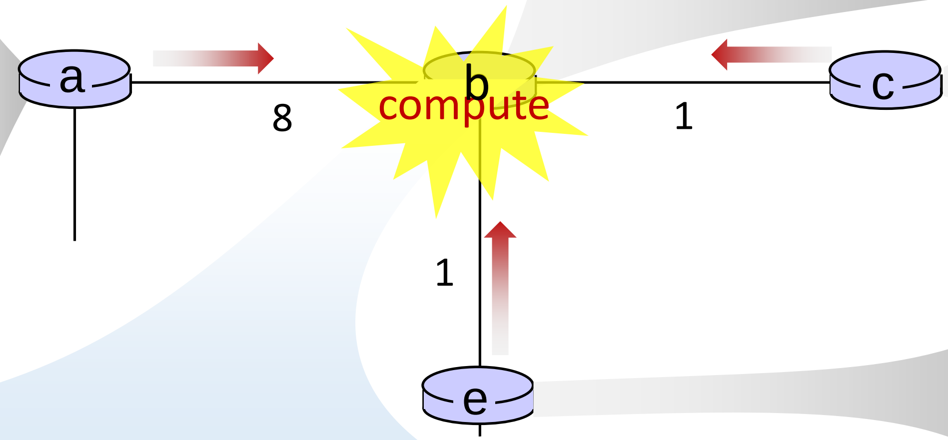
DV in b:

$D_b(a) = 8$	$D_b(f) = \infty$
$D_b(c) = 1$	$D_b(g) = \infty$
$D_b(d) = \infty$	$D_b(h) = \infty$
$D_b(e) = 1$	$D_b(i) = \infty$

DV in c:

$D_c(a) = \infty$
$D_c(b) = 1$
$D_c(c) = 0$
$D_c(d) = \infty$
$D_c(e) = \infty$
$D_c(f) = \infty$
$D_c(g) = \infty$
$D_c(h) = \infty$
$D_c(i) = \infty$





t=1

- b receives DVs from a, c, e, computes:

$D_b(a) = \min\{c_{b,a}+D_a(a),\ c_{b,c}+D_c(a),\ c_{b,e}+D_e(a)\} = \min\{8,\infty,\infty\} = 8$

$D_b(c) = \min\{c_{b,a}+D_a(c),\ c_{b,c}+D_c(c),\ c_{b,e}+D_e(c)\} = \min\{\infty,1,\infty\} = 1$

$D_b(d) = \min\{c_{b,a}+D_a(d),\ c_{b,c}+D_c(d),\ c_{b,e}+D_e(d)\} = \min\{9,2,\infty\} = 2$

$D_b(e) = \min\{c_{b,a}+D_a(e),\ c_{b,c}+D_c(e),\ c_{b,e}+D_e(e)\} = \min\{\infty,\infty,1\} = 1$

$D_b(f) = \min\{c_{b,a}+D_a(f),\ c_{b,c}+D_c(f),\ c_{b,e}+D_e(f)\} = \min\{\infty,\infty,2\} = 2$

$D_b(g) = \min\{c_{b,a}+D_a(g),\ c_{b,c}+D_c(g),\ c_{b,e}+D_e(g)\} = \min\{\infty, \infty, \infty\} = \infty$

$D_b(h) = \min\{c_{b,a}+D_a(h),\ c_{b,c}+D_c(h),\ c_{b,e}+D_e(h)\} = \min\{\infty, \infty, 2\} = 2$

$D_b(i) = \min\{c_{b,a}+D_a(i),\ c_{b,c}+D_c(i),\ c_{b,e}+D_e(i)\} = \min\{\infty, \infty, \infty\} = \infty$

DV in e:

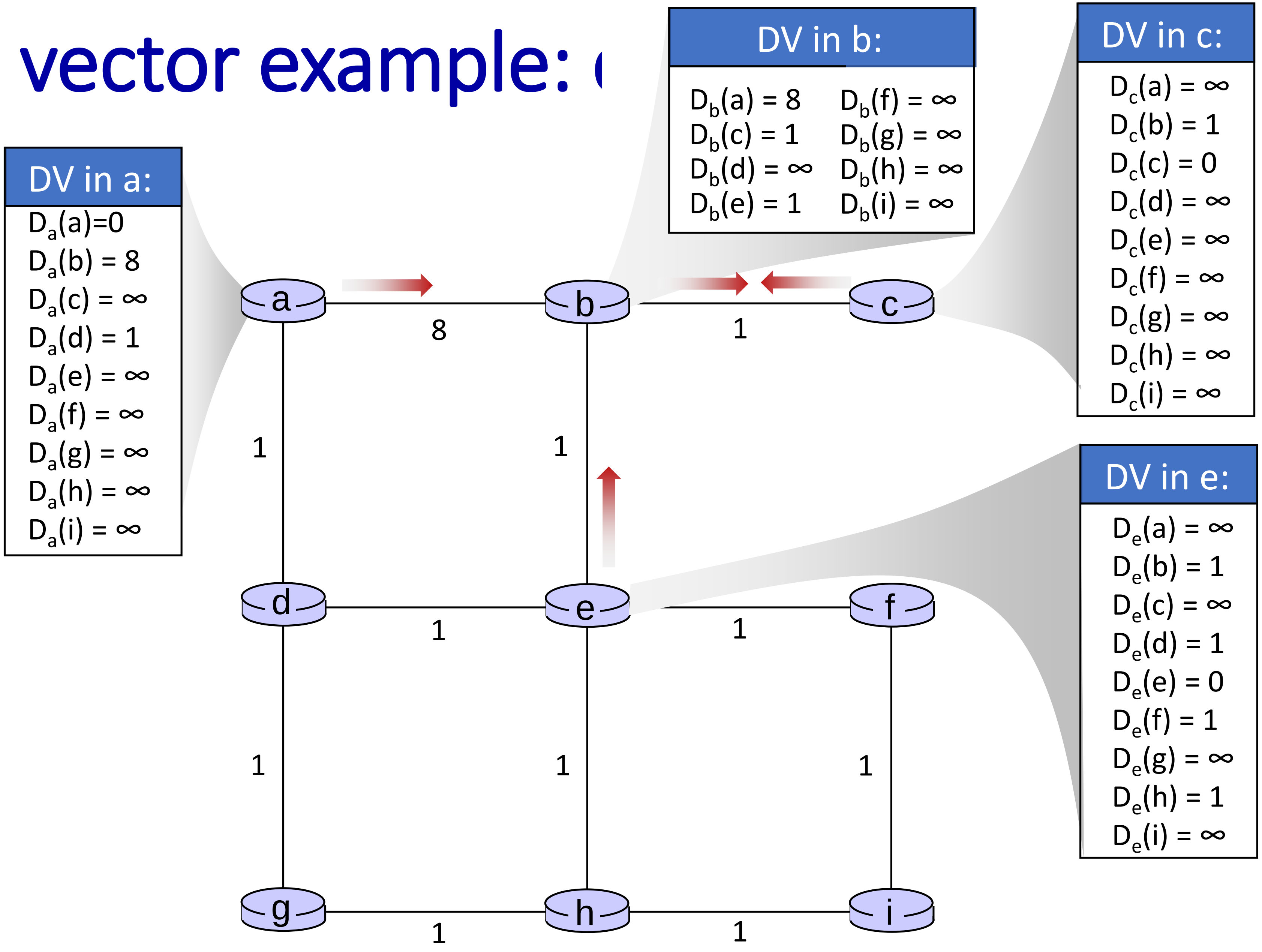
$D_e(a) = \infty$
$D_e(b) = 1$
$D_e(c) = \infty$
$D_e(d) = 1$
$D_e(e) = 0$
$D_e(f) = 1$
$D_e(g) = \infty$
$D_e(h) = 1$
$D_e(i) = \infty$

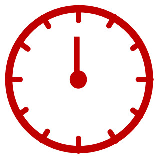
New DV in b

DV in b:

$D_b(a) = 8$	$D_b(f) = 2$
$D_b(c) = 1$	$D_b(g) = \infty$
$D_b(d) = 2$	$D_b(h) = 2$
$D_b(e) = 1$	$D_b(i) = \infty$

Distance vector example:



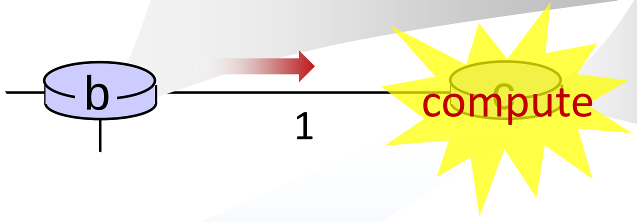

t=1

- c receives DVs from b

Distance vector example:

DV in b:

$D_b(a) = 8$ $\quad D_b(f) = \infty$
$D_b(c) = 1$ $\quad D_b(g) = \infty$
$D_b(d) = \infty$ $\quad D_b(h) = \infty$
$D_b(e) = 1$ $\quad D_b(i) = \infty$



DV in c:

$D_c(a) = \infty$
$D_c(b) = 1$
$D_c(c) = 0$
$D_c(d) = \infty$
$D_c(e) = \infty$
$D_c(f) = \infty$
$D_c(g) = \infty$
$D_c(h) = \infty$
$D_c(i) = \infty$

t=1

- c receives DVs from b computes:

$D_c(a) = \min\{c_{c,b}+D_b(a)\} = 1 + 8 = 9$

$D_c(b) = \min\{c_{c,b}+D_b(b)\} = 1 + 0 = 1$

$D_c(d) = \min\{c_{c,b}+D_b(d)\} = 1+ \infty = \infty$

$D_c(e) = \min\{c_{c,b}+D_b(e)\} = 1 + 1 = 2$

$D_c(f) = \min\{c_{c,b}+D_b(f)\} = 1+ \infty = \infty$

$D_c(g) = \min\{c_{c,b}+D_b(g)\} = 1+ \infty = \infty$

$D_c(h) = \min\{c_{bc,b}+D_b(h)\} = 1+ \infty = \infty$

$D_c(i) = \min\{c_{c,b}+D_b(i)\} = 1+ \infty = \infty$

New DV in c

DV in c:

$D_c(a) = 9$
$D_c(b) = 1$
$D_c(c) = 0$
$D_c(d) = \infty$
$D_c(e) = 2$
$D_c(f) = \infty$
$D_c(g) = \infty$
$D_c(h) = \infty$
$D_c(i) = \infty$

Distance vector example: (

t=1

- e receives DVs from b, d, f, h

DV in d:

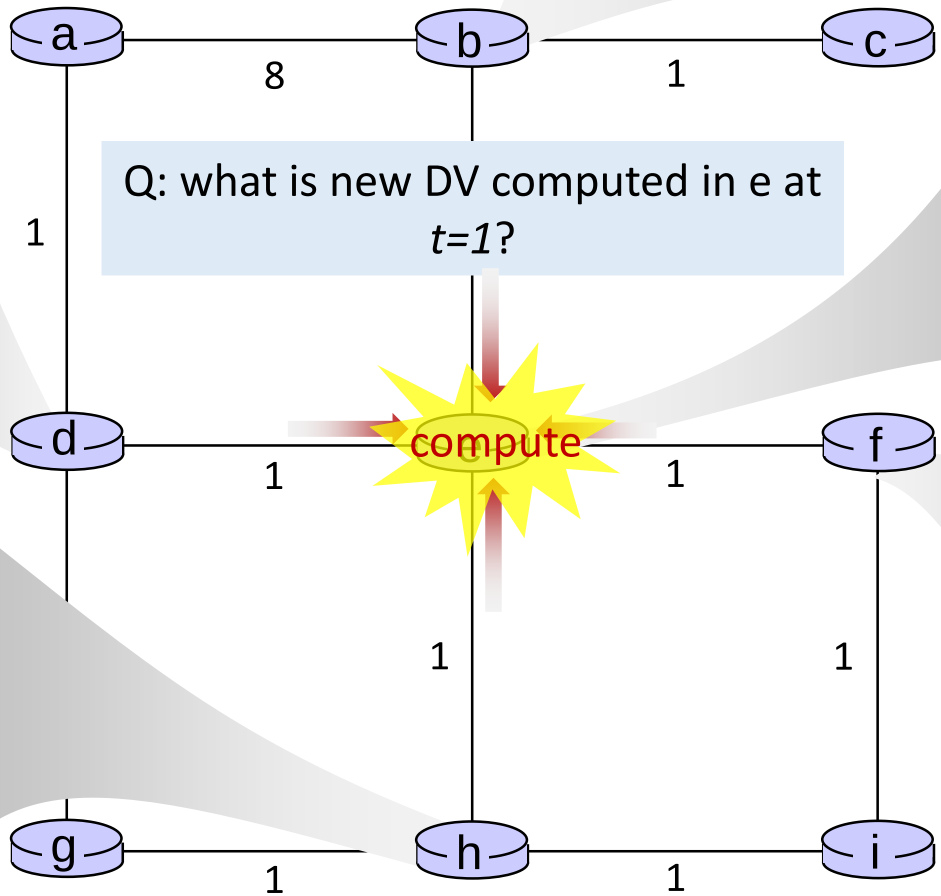
$D_c(a) = 1$
$D_c(b) = \infty$
$D_c(c) = \infty$
$D_c(d) = 0$
$D_c(e) = 1$
$D_c(f) = \infty$
$D_c(g) = 1$
$D_c(h) = \infty$
$D_c(i) = \infty$

DV in b:

$D_b(a) = 8$ $D_b(f) = \infty$
$D_b(c) = 1$ $D_b(g) = \infty$
$D_b(d) = \infty$ $D_b(h) = \infty$
$D_b(e) = 1$ $D_b(i) = \infty$

DV in e:

$D_e(a) = \infty$
$D_e(b) = 1$
$D_e(c) = \infty$
$D_e(d) = 1$
$D_e(e) = 0$
$D_e(f) = 1$
$D_e(g) = \infty$
$D_e(h) = 1$
$D_e(i) = \infty$



DV in h:

$D_c(a) = \infty$
$D_c(b) = \infty$
$D_c(c) = \infty$
$D_c(d) = \infty$
$D_c(e) = 1$
$D_c(f) = \infty$
$D_c(g) = 1$
$D_c(h) = 0$
$D_c(i) = 1$

DV in f:

$D_c(a) = \infty$
$D_c(b) = \infty$
$D_c(c) = \infty$
$D_c(d) = \infty$
$D_c(e) = 1$
$D_c(f) = 0$
$D_c(g) = \infty$
$D_c(h) = \infty$
$D_c(i) = 1$

Distance vector: state information diffusion

Iterative communication, computation steps diffuses information through network:

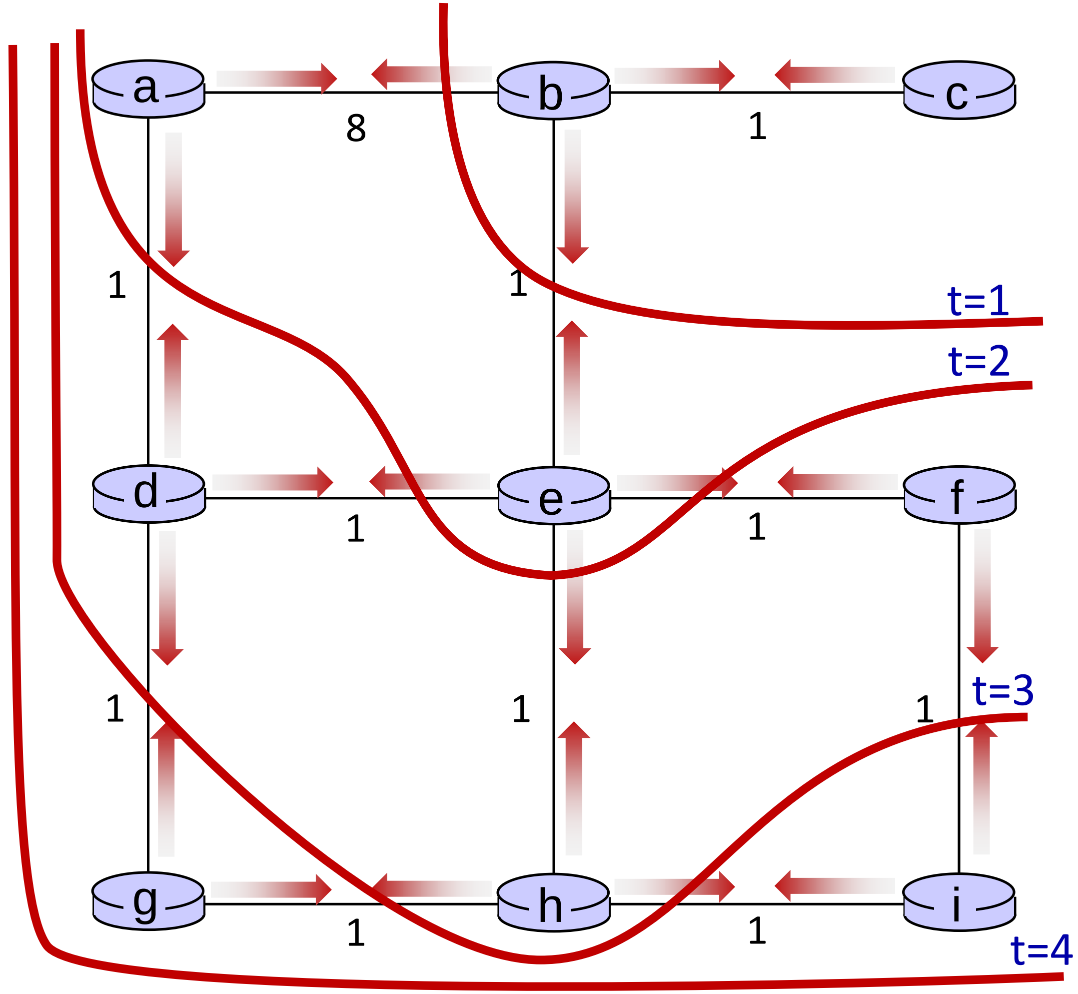
t=0 c's state at t=0 is at c only

t=1 c's state at t=0 has propagated to b, and may influence distance vector computations up to **1** hop away, i.e., at b

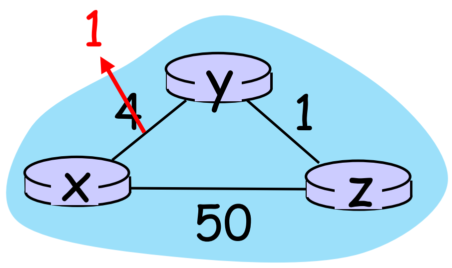
t=2 c's state at t=0 may now influence distance vector computations up to **2** hops away, i.e., at b and now at a, e as well

t=3 c's state at t=0 may influence distance vector computations up to **3** hops away, i.e., at d, f, h

t=4 c's state at t=0 may influence distance vector computations up to **4** hops away, i.e., at g, i



Distance vector: link cost changes



link cost changes:

- node detects local link cost change
- updates routing info, recalculates local DV
- if DV changes, notify neighbors

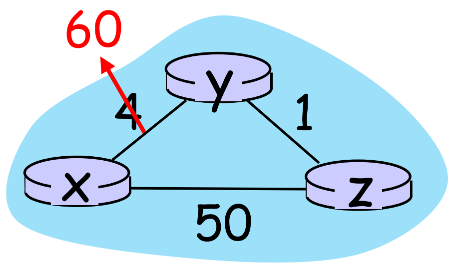
"good news travels fast"

t_0 : *y* detects link-cost change, updates its DV, informs its neighbors.

t_1 : *z* receives update from *y*, updates its DV, computes new least cost to *x* , sends its neighbors its DV.

t_2 : *y* receives *z*'s update, updates its DV. *y*'s least costs do *not* change, so *y* does *not* send a message to *z*.

Distance vector: link cost changes



link cost changes:

- node detects local link cost change
- "bad news travels slow" – count-to-infinity problem:
  - *y* sees direct link to *x* has new cost 60, but z has said it has a path at cost of 5. So *y* computes "my new cost to x will be 6, via z); notifies *z* of new cost of 6 to *x*.
  - *z* learns that path to *x* via *y* has new cost 6, so *z* computes "my new cost to *x* will be 7 via y), notifies *y* of new cost of 7 to *x*.
  - *y* learns that path to *x* via *z* has new cost 7, so *y* computes "my new cost to *x* will be 8 via y), notifies *z* of new cost of 8 to *x*.
  - *z* learns that path to *x* via *y* has new cost 8, so *z* computes "my new cost to *x* will be 9 via y), notifies *y* of new cost of 9 to *x*.

    …
- see text for solutions. *Distributed algorithms are tricky!*

Comparison of LS and DV algorithms

message complexity

LS: n routers, $O(n^2)$ messages sent

DV: exchange between neighbors; convergence time varies

speed of convergence

LS: $O(n^2)$ algorithm, $O(n^2)$ messages

- may have oscillations

DV: convergence time varies

- may have routing loops
- count-to-infinity problem

robustness: what happens if router malfunctions, or is compromised?

LS:

- router can advertise incorrect *link* cost
- each router computes only its *own* table

DV:

- DV router can advertise incorrect *path* cost (“I have a *really* low-cost path to everywhere”): *black-holing*
- each router’s DV is used by others: error propagate thru network

References

Figures and slides are taken/adapted from:

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