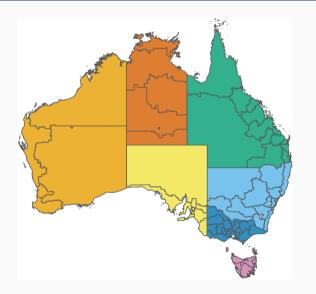
Forecast Linear Augmented Projection (FLAP)

Fin Yang, George Athanasopoulos, Rob J Hyndman, Anastasios Panagiotelis

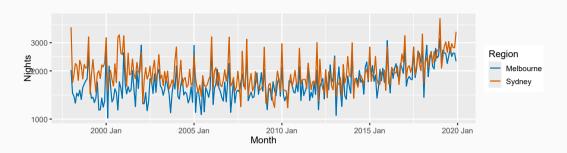


Australian tourism regions

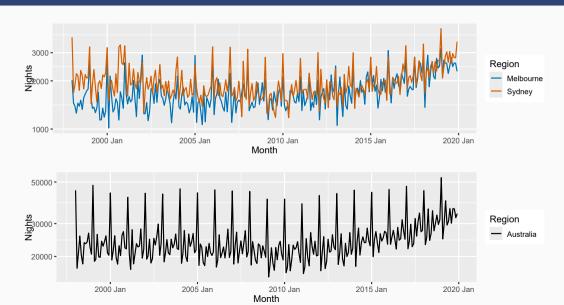


- **■** Visitor Nights
- Monthly time series
- **1998 2019**
- 77 regions

Regions V Aggregate



Regions V Aggregate



FLAP Intuition

We have multivariate times series:

- which share similar patterns;
- with a better signal-noise ratio in the linear combination.

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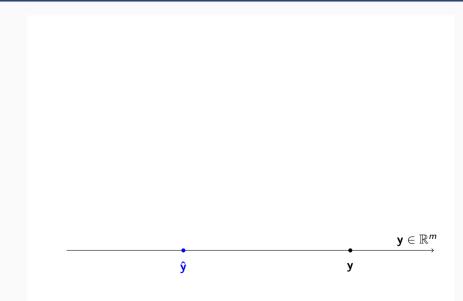
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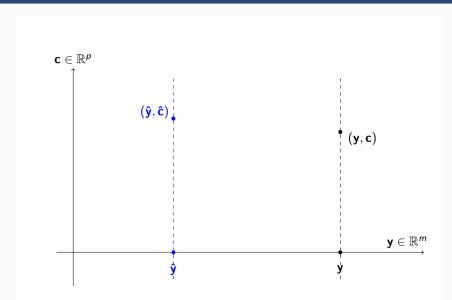
Can we find components that:

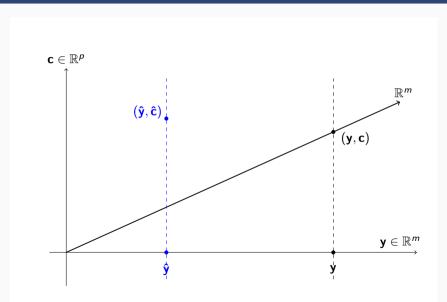
- are easy to forecast (or easier than the original series);
- can capture possible common signals;
- can improve forecast of original series.

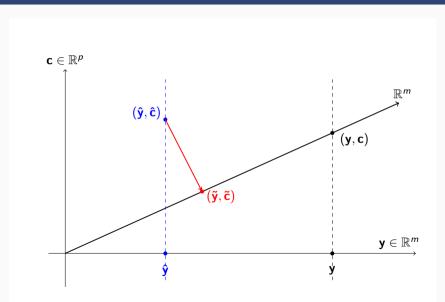
Outline of FLAP Implementation

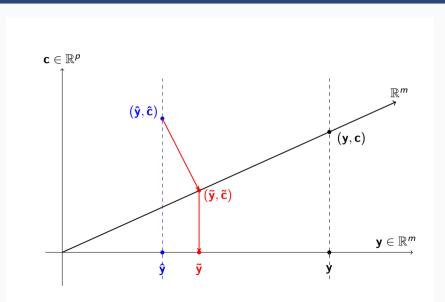
- We want to forecast a multivariate series $\mathbf{y}_t \in \mathbb{R}^m$.
- Construct many linear combinations $\mathbf{c}_t = \Phi \mathbf{y}_t \in \mathbb{R}^p$ of the multivariate series.
- Produce univariate forecasts of all series $\hat{\mathbf{y}}_{t+h}$ and all linear combinations $\hat{\mathbf{c}}_{t+h}$.
- Project forecasts onto the \mathbb{R}^m coherent subspace, resulting in $\tilde{\mathbf{y}}_{t+h}$.











FLAP Projection

$$\mathbf{z}_{t} = \begin{bmatrix} \mathbf{y}_{t} \\ \mathbf{c}_{t} \end{bmatrix}, \qquad \hat{\mathbf{z}}_{t+h} = \begin{bmatrix} \hat{\mathbf{y}}_{t+h} \\ \hat{\mathbf{c}}_{t+h} \end{bmatrix}, \qquad \tilde{\mathbf{z}}_{t+h} = \mathbf{M}\hat{\mathbf{z}}_{t+h}$$

where M is a projection matrix onto the \mathbb{R}^m coherent subspace

$$\mathbf{M} = \mathbf{I}_{m+p} - \mathbf{W}_h \mathbf{C}' (\mathbf{C} \mathbf{W}_h \mathbf{C}')^{-1} \mathbf{C}$$

$$\mathbf{C} = \begin{bmatrix} -\Phi & \mathbf{I}_p \end{bmatrix}$$

$$\mathbf{W}_h = \text{Var}(\mathbf{z}_{t+h} - \hat{\mathbf{z}}_{t+h})$$

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$$\mathbf{W}_{h} = \text{Var}(\mathbf{z}_{t+h} - \hat{\mathbf{z}}_{t+h})$$

$$\tilde{\mathbf{y}}_{t+h} = \mathbf{G}\hat{\mathbf{z}}_{t+h} = \mathbf{J}\mathbf{M}\hat{\mathbf{z}}_{t+h}$$

$$\mathbf{J} = \begin{bmatrix} \mathbf{I}_m & \mathbf{O}_{m \times p} \end{bmatrix}$$

Forecast error variance reduction

- The variance reduction $Var(\mathbf{y}_{t+h} \hat{\mathbf{y}}_{t+h}) Var(\mathbf{y}_{t+h} \tilde{\mathbf{y}}_{t+h})$ is positive semi-definite.
- The diagonal elements of $Var(\mathbf{y}_{t+h} \hat{\mathbf{y}}_{t+h}) Var(\mathbf{y}_{t+h} \tilde{\mathbf{y}}_{t+h})$ are non-decreasing as the number of components increases.

Minimum variance of individual series

The projection is equivalent to the mapping

$$\tilde{\mathbf{y}}_{t+h} = \mathbf{G}\hat{\mathbf{z}}_{t+h},$$

where $G = [g_1 \ g_2 \ \dots \ g_m]' \in \mathbb{R}^{m \times (m+p)}$ is the solution to arg min $\operatorname{tr}(GW_hG')$ s.t. GS = I

or

$$\underset{\boldsymbol{g}_{i}}{\operatorname{arg\,min}}\;\boldsymbol{g}_{i}'\boldsymbol{W}_{h}\boldsymbol{g}_{i}\qquad \text{s.t. }\boldsymbol{g}_{i}'\boldsymbol{s}_{j}=\mathbf{1}(i=j),$$

where
$$\mathbf{S} = \begin{vmatrix} \mathbf{I}_m \\ \mathbf{\Phi} \end{vmatrix} = [\mathbf{s}_1 \cdots \mathbf{s}_m].$$

Key results

- The forecast error variance is reduced with FLAP.
- The forecast error variance **monotonically** decreases with increasing number of components.
- The forecast projection is **optimal** to achieve minimum forecast error variance of each series.

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In practice, we need to:

- Estimate W_h = Var($\mathbf{z}_{t+h} \hat{\mathbf{z}}_{t+h}$). (Use in-sample residuals, shrink variances to their median, covariances to zero.)
- \blacksquare Construct the components, Φ .

Construction of Φ

Principal component analysis (PCA)

Finding the weights matrix Φ so that the resulting components maximise variance

Simulation

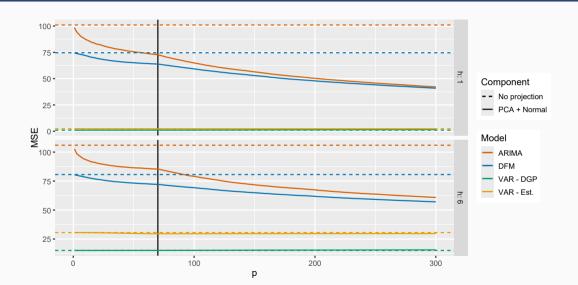
Generating values of Φ from a random distribution and normalising them to unit vectors

- Normal distribution
- Uniform distribution
- Orthonormal matrix

Simulation

- Data generating process: VAR(3) with m = 70 variables
- Innovations $\sim N(0, I_m)$
- Sample size: *T* = 400
- Number of repeated samples: 220
- Base forecasts:
 - ARIMA models using AICc (auto.arima() in forecast package).
 - DFM structure using BIC (different model for each horizon).

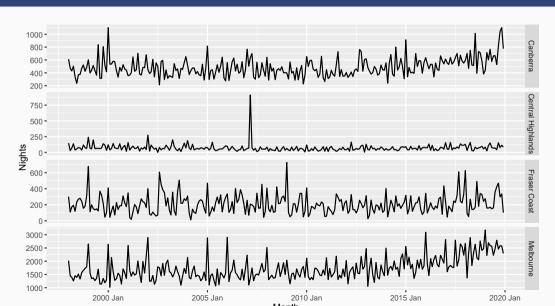
Simulation



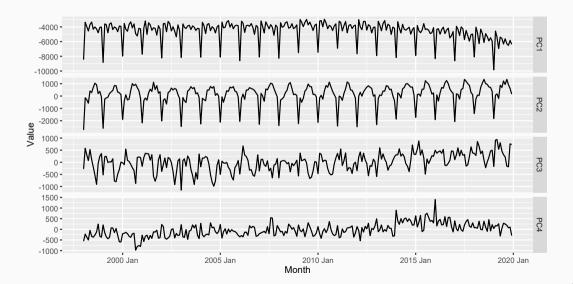
Monthly Australian regional tourism

- Monthly Australian tourism data by region giving 77 series, from Jan 1998 to Dec 2019
- Use expanding window time series cross-validation with T = 84 observations in first training set, and forecast horizons h = 1, 2, ..., 12.
- Estimate ets() models using the forecast package.

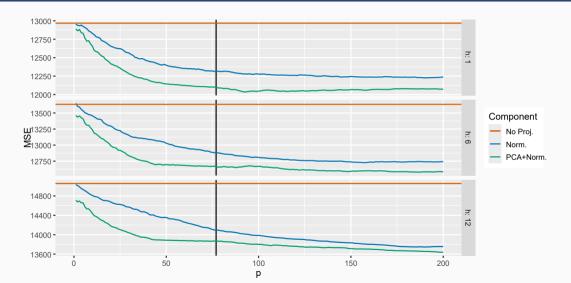
Monthly Australian regional tourism



Monthly Australian regional tourism



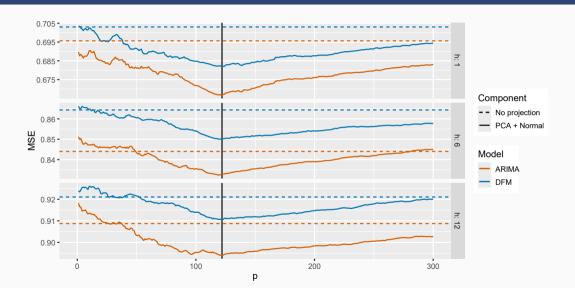
Monthly Australian regional tourism - ets()



FRED-MD

- Monthly data of macroeconomic variables (McCracken and Ng, 2016).
- Data from Jan 1959 Sep 2023. 777 observations on 122 series.
- Same cleaning process as per McCracken and Ng (2016).
- All series scaled to have mean 0 and variance 1.
- Expanding time series cross-validation with initial size of 25 years and forecast horizon 12 months.

FRED-MD



Future research directions

- Investigate why PCA performs better than random weights
- Find other components that are better than PCA
- \blacksquare Find optimal components by minimising forecast error variance with respect to Φ
- Use forecast projection and forecast reconciliation together

Working Paper and R Package

YF Yang, G Athanasopoulos, RJ Hyndman, and A Panagiotelis (2024). "Forecast Linear Augmented Projection (FLAP): A free lunch to reduce forecast error variance". Department of Econometrics and Business Statistics, Monash University, Working Paper Series 13/24. URL: https://www.monash.edu/business/ebs/research/publications/ebs/2024/wp13-2024.pdf

You can install the stable version from CRAN

```
## CRAN.R-project.org/package=flap
install.packages("flap")
```

or the development version from Github

```
## github.com/FinYang/flap
# install.packages("remotes")
remotes::install_github("FinYang/flap")
```



rch/publications/ebs/2024/wp13-2024.pdf.