

MONASH BUSINESS SCHOOL

# ETC3550/ETC5550 Applied forecasting

Ch9. ARIMA models
OTexts.org/fpp3/



#### **ARIMA models**

**AR**: autoregressive (lagged observations as inputs)

I: integrated (differencing to make series stationary)

MA: moving average (lagged errors as inputs)

An ARIMA model is rarely interpretable in terms of visible data structures like trend and seasonality. But it can capture a huge range of time series patterns.

# **Stationarity**

#### **Definition**

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Transformations help to **stabilize the variance**. For ARIMA modelling, we also need to **stabilize the mean**.

# Differencing

- Differencing helps to stabilize the mean.
- First differencing: *change* between consecutive observations:  $y'_t = y_t y_{t-1}$ .
- Seasonal differencing change between years

# **Automatic differencing**

## Using unit root tests for first differencing

- Augmented Dickey Fuller test: null hypothesis is that the data are non-stationary and non-seasonal.
- 2 Kwiatkowski-Phillips-Schmidt-Shin (KPSS) test: null hypothesis is that the data are stationary and non-seasonal.

## Seasonal strength

STL decomposition:  $y_t = T_t + S_t + R_t$ Seasonal strength  $F_s = \max \left(0, 1 - \frac{\operatorname{Var}(R_t)}{\operatorname{Var}(S_t + R_t)}\right)$ 

#### Random walk model

If differenced series is white noise with zero mean:

$$y_t - y_{t-1} = \varepsilon_t$$
 or  $y_t = y_{t-1} + \varepsilon_t$ 

where  $\varepsilon_t \sim NID(0, \sigma^2)$ .

- Model behind the naïve method.
- Forecast are equal to the last observation (future movements up or down are equally likely).

## Random walk with drift model

If differenced series is white noise with non-zero mean:

$$y_t - y_{t-1} = c + \varepsilon_t$$
 or  $y_t = c + y_{t-1} + \varepsilon_t$ 

where  $\varepsilon_t \sim NID(0, \sigma^2)$ .

- c is the average change between consecutive observations.
- Model behind the **drift method**.