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# ETC3550/ETC5550 Applied forecasting

## Ch9. ARIMA models

`af.numbat.space`



# ARIMA models

- AR:** autoregressive (lagged observations as inputs)
- I:** integrated (differencing to make series stationary)
- MA:** moving average (lagged errors as inputs)

An ARIMA model is rarely interpretable in terms of visible data structures like trend and seasonality. But it can capture a huge range of time series patterns.

# Stationarity

## Definition

If  $\{y_t\}$  is a stationary time series, then for all  $s$ , the distribution of  $(y_t, \dots, y_{t+s})$  does not depend on  $t$ .

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Transformations help to **stabilize the variance**.

For ARIMA modelling, we also need to **stabilize the mean**.

## Differencing

- Differencing helps to **stabilize the mean**.
- First differencing: *change* between consecutive observations:  $y'_t = y_t - y_{t-1}$ .
- Seasonal differencing: *change* between years:

# Automatic differencing

## Using unit root tests for first differencing

- 1 Augmented Dickey Fuller test: null hypothesis is that the data are non-stationary and non-seasonal.
- 2 Kwiatkowski-Phillips-Schmidt-Shin (KPSS) test: null hypothesis is that the data are stationary and non-seasonal.

## Seasonal strength

STL decomposition:  $y_t = T_t + S_t + R_t$

Seasonal strength  $F_s = \max\left(0, 1 - \frac{\text{Var}(R_t)}{\text{Var}(S_t + R_t)}\right)$

If  $F_s > 0.64$ , do one seasonal difference

# Random walk model

If differenced series is white noise with zero mean:

$$y_t - y_{t-1} = \varepsilon_t \quad \text{or} \quad y_t = y_{t-1} + \varepsilon_t$$

where  $\varepsilon_t \sim NID(0, \sigma^2)$ .

- Model behind the **naïve method**.
- Forecast are equal to the last observation (future movements up or down are equally likely).

# Random walk with drift model

If differenced series is white noise with non-zero mean:

$$y_t - y_{t-1} = c + \varepsilon_t \quad \text{or} \quad y_t = c + y_{t-1} + \varepsilon_t$$

where  $\varepsilon_t \sim NID(0, \sigma^2)$ .

- $c$  is the **average change** between consecutive observations.
- Model behind the **drift method**.