

Mooooorrrr:

```
library IEEE;
```

```
use IEEE.STD_LOGIC_1164.ALL;
```

```
entity FSM is
```

```
    port(
```

```
        Clk          : in  STD_LOGIC;
```

```
        Reset       : in   STD_LOGIC;
```

```
        Up          : in   STD_LOGIC;
```

```
        Dn          : in   STD_LOGIC;
```

```
        SensorUp    : in   STD_LOGIC;
```

```
        SensorDn    : in   STD_LOGIC;
```

```
        State       : out   STD_LOGIC_VECTOR(3 downto 0);
```

```
        MoveUp      : out   STD_LOGIC;
```

```
        MoveDn      : out   STD_LOGIC
```

```
    );
```

```
end FSM;
```

```
architecture Behavioral of FSM is
```

```
    type STATE_TYPE is (S0, S1, S2, S3, S4);
```

```
    signal CurrentState, NextState : STATE_TYPE;
```

```
begin
```

```
MEM:
```

```
    -- Блок памет на състоянието
```

```
    process (Reset, Clk)
```

```
    begin
```

```
        if (Reset = '1') then
```

```
            CurrentState <= S0;
```

```
        elsif (falling_edge(Clk)) then
```

```
            CurrentState <= NextState;
```

```
        end if ;
```

```
    end process MEM;
```

NEXT_STATE_LOGIC:

-- Логика за определяне на следващото състояние

process (CurrentState, Up, Dn, SensorUp, SensorDn)

begin

NextState <= CurrentState;

MoveUp <= '0';

MoveDn <= '0';

case CurrentState is

when S0=>

if (Up = '1') then

NextState <= S1;

end if;

when S1=>

if (SensorUp = '1') then

NextState <= S2;

end if;

when S2=>

if (Dn = '1') then

NextState <= S3;

end if;

when S3 =>

if (SensorDn = '1') then

NextState <= S0;

end if;

when others=>

NextState <= S0;

end case;

end process NEXT_STATE_LOGIC;

-- Логика (изходи)

MoveUp <= '1' when CurrentState = S1 else '0';

MoveDn <= '1' when CurrentState = S3 else '0';

```

-- Извеждане на състоянието
with CurrentState select
    State <= "0000" when S0,
            "0001" when S1,
            "0010" when S2,
            "0011" when S3,
            "0100" when S4,
            "1111" when others;

end Behavioral;

```

Mealy:

```

library IEEE;
use IEEE.STD_LOGIC_1164.ALL;

entity FSM is
    port(
        Clk          : in  STD_LOGIC;
        Reset        : in   STD_LOGIC;
        Up           : in   STD_LOGIC;
        Dn           : in   STD_LOGIC;
        SensorUp     : in   STD_LOGIC;
        SensorDn     : in   STD_LOGIC;
        State        : out   STD_LOGIC_VECTOR(3 downto 0);
        MoveUp       : out   STD_LOGIC;
        MoveDn       : out   STD_LOGIC
    );
end FSM;

```

```

architecture Behavioral of FSM is
    type STATE_TYPE is (S0, S1, S2, S3, S4);
    signal CurrentState, NextState : STATE_TYPE;

```

```
signal asdaf: LOGIC_VECTOR(3 downto 0);
```

```
begin
```

```
MEM:
```

```
-- Блок памет на състоянието
```

```
process (Reset, Clk)
```

```
begin
```

```
    if (Reset = '1') then
```

```
        CurrentState <= S0;
```

```
    elsif (falling_edge(Clk)) then
```

```
        CurrentState <= NextState;
```

```
    end if ;
```

```
end process MEM;
```

```
NEXT_STATE_LOGIC:
```

```
-- Логика за определяне на следващото състояние
```

```
process (CurrentState, Up, Dn, SensorUp, SensorDn)
```

```
begin
```

```
NextState <= CurrentState;
```

```
MoveUp <= '0';
```

```
MoveDn <= '0';
```

```
case CurrentState is
```

```
    when S0=>
```

```
        if (Up = '1') then
```

```
            NextState <= S1;
```

```
            MoveUp <= '1';
```

```
            MoveDn <= '0';
```

```
        end if;
```

```
    when S1=>
```

```
        if (SensorUp = '1') then
```

```
            NextState <= S2;
```

```
            MoveUp <= '0';
```

```
            MoveDn <= '0';
```

```

        end if;
    when S2=>
        if (Dn = '1') then
            NextState <= S3;

            MoveUp <= '0';
            MoveDn <= '1';
        end if;
    when S3 =>
        if (SensorDn = '1') then
            NextState <= S0;

            MoveUp <= '0';
            MoveDn <= '0';
        end if;
    when others=>
        NextState <= S0;
    end case;

end process NEXT_STATE_LOGIC;
-- Извеждане на състоянието
with CurrentState select
    State <= "0000" when S0,
             "0001" when S1,
             "0010" when S2,
             "0011" when S3,
             "0100" when S4,
             "1111" when others;
end Behavioral;

```

