A

```
> restart: with(plots): with(plottools):
> Jacobi2d:=(r)->LinearAlgebra[Determinant](<diff~(r(u,v)[1],u),
   diff^{(v)}(r(u,v)[2],u) | diff^{(v)}(r(u,v)[1],v), diff^{(v)}(r(u,v)[2],v) >) :
   Jacobi3d:=(r)->expand(simplify(LinearAlgebra[Norm](LinearAlgebra
   [CrossProduct] (\langle diff \sim (r(u,v)[1],u), diff \sim (r(u,v)[2],u), diff \sim (r(u,v)[2],u)
   v)[3],u)>,<diff~(r(u,v)[1],v),diff~(r(u,v)[2],v),diff~(r(u,v)[3],
   v) > (2) assuming 0 < u):
   JacobiRum:=(r)->LinearAlgebra[Determinant](<diff~(r(u,v,w)[1],u),</pre>
   diff^{(r(u,v,w)[2],u)}, diff^{(r(u,v,w)[3],u)}, diff^{(r(u,v,w)[1],v)},
   diff^{(r(u,v,w)[2],v)}, diff^{(r(u,v,w)[3],v)}, diff^{(r(u,v,w)[1],w)},
   diff^{(v)}(r(u,v,w)[2],w), diff^{(v)}(r(u,v,w)[3],w)>):
\rightarrow hoved:=plot3d(<7.68*cos(v),7.68*sin(v),u>,u=0..34.8,v=0..2*Pi,
   color=gold):
> top:=plot3d(<3*\cos(v), 3*\sin(v), u>, u=34.9..34.9+4, v=0..2*Pi, color=
   aquamarine):
> skive:=plot3d(\langle u*cos(v), u*sin(v), 34.9 \rangle, u=3..7.68, v=0..2*Pi, color=
   khaki):
> obs:=plot3d(<sin(u)*3*cos(v), sin(u)*3*sin(v), cos(u)*3+34.8+4>, u=
   0..Pi/2,v=0..2*Pi,color=green):
> display(hoved, top, skive, obs, view=[-10..10,-10..10,0..50], scaling=
   constrained):
```

B

L

```
\mathbf{C}
> with(LinearAlgebra):
> s:=v->(3*cos(v*faktor),3*sin(v*faktor),v)
                      s := v \mapsto (3 \cdot \cos(v \cdot faktor), 3 \cdot \sin(v \cdot faktor), v)
                                                                                       (3.1)
> diff(s(v)[1],v)
                            -4.224900465 \sin(1.408300155 v)
                                                                                       (3.2)
> K:=sqrt((diff(s(v)[1],v))^2+(diff(s(v)[2],v))^2+(diff(s(v)[3],v))
      K := \sqrt{17.84978394 \sin(1.408300155 v)^2 + 17.84978394 \cos(1.408300155 v)^2 + 1}
                                                                                       (3.3)
> simplify(K(v))
     \sqrt{17.84978394 \sin(1.408300155 v)(v)^2 + 17.84978394 \cos(1.408300155 v)(v)^2 + 1}
                                                                                       (3.4)
> længde:=int(K,v=0..34.8)
                                 længde := 151.0888558
                                                                                       (3.5)
> fundet stigning:=34.8/længde
                            fundet \ stigning := 0.2303280399
                                                                                       (3.6)
> 0.33+0.10:
   rigtig stigning := %/2
                             rigtig \ stigning := 0.2150000000
                                                                                       (3.7)
  forskel=fundet stigning/rigtig stigning
                                  forskel = 1.071293209
                                                                                       (3.8)
```

L D

$$f := x \rightarrow a * x + b$$

$$f := x \mapsto a \cdot x + b$$

$$[> b := 0.5]$$
(4.1)

$$b := 0.5 \tag{4.2}$$
> $f(34, 8) = 0.4$

34.8 a + 0.5 = 0.4 (4.3)

> solve(f(34.8)=0.4,{a})

$${a=-0.002873563218}$$
 (4.4)

> h:=z->(subs((4.4), f(z))):
h(z)
$$-0.002873563218 z + 0.5$$
 (4.5)

> g:=(u,v,w)-><r(u,v)[1],r(u,v)[2],r(u,v)[3]+h(v)*w>: > g(u,v,w)

$$\begin{bmatrix} u \cos(1.408300155 v) \\ u \sin(1.408300155 v) \\ v + (-0.002873563218 v + 0.5) w \end{bmatrix}$$
(4.6)

> masse:=2*% masse := 2 rumfang = 736.7683512 (4.8)

> forskel=masse/5914
$$forskel = \left(\frac{rumfang}{2957} = 0.1245803773\right)$$
 (4.9)