

2η ΕΡΓΑΣΤΗΡΙΑΚΗ ΑΣΚΗΣΗ

ΓΙΑ ΤΟ ΜΑΘΗΜΑ

"Εργαστήριο Μικροϋπολογιστών"

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2.1 (Assembly)

```
;
; microlab2_1.asm
;
; Created: 10/27/2020 7:07:39 PM
; Author : georg
;
; Replace with your application code
.INCLUDE "m16def.inc"

.def input = r18
.def temp = r19
.def temp2=r17
.def A = r20
.def B = r21
.def C = r22
.def D = r23
.def F0 = r24
.def F1 = r25
main:
    clr temp
    out DDRC ,temp
    ser temp
    out DDRB,temp
```

in input , PINC ; take the input from the PINC

mov A,input

andi A,0x01 ; mask the lsb

mov B,input

andi B,0x02 ; mask the 2nd lsb

ror B ; move it to the 1 position

mov C,input

andi C,0x04 ; mask the 2nd lsb

ror C ; move it to the 1 position

ror C

mov D,input

andi D,0x08 ; mask the 4th lsb

ror D ; move it to the 1 position

ror D

ror D

mov temp2,B

com temp2 ; create the B'

andi temp2,0x01 ;temp2=B'

mov temp,A

com temp ; create the A'

andi temp,0x01; temp=A'

and temp,B ; temp=A'B

and temp2,C ; temp2=B'C

and temp2,D ; temp2= B'CD

or temp,temp2 ; temp=A'B+B'CD

mov F0,temp

mov temp,A

```

and temp,C ; temp =AC

mov temp2,B
or temp2,D ; temp2 = B+D
and temp,temp2 ; temp =(AC)(B+D)
mov F1,temp
clc
rol F1 ; move it to the 2nd position
com F0 ; create the F0'
andi F0,0x01 ; mask the first position
add F0,F1
out PORTB,F0 ; show it to the PORTB
rjmp main

end:

```

(C)

```

/*
 * GccApplication1.cpp
 *
 * Created: 10/28/2020 6:42:12 PM
 * Author : georg
 */
#include <avr/io.h>

unsigned char A,B,C,D,NOTA,NOTB,F0,F1;

int main(void){
    DDRC=0x00; // C= input
    DDRB=0xff; // B= output
    while(1){
        A = PINC &0x01; // mask the lsb
        B = PINC &0x02; // mask the 2 position
        B = B >> 1; // move it to the 1 position
    }
}

```

```

        C = PINC & 0x04; // mask the 3 position
        C = C >> 2; // move it to the 1 position
        D = PINC & 0x08; //mask the 4 position
        D = D >> 3; // move it to the 1 position
        NOTA = A ^ 0x01; // xor with 1 so we came out with A' and B'
        NOTB = B ^ 0x01;
        F0 = (NOTA & B) | (NOTB & C & D);
        F0 = F0 ^ 0x01; // F0'
        F1 = (A & C) & (B | D);
        F1 = F1 << 1; // move it to the second position
        F0 = F0 + F1;
        PORTB = F0; // output to the port B
    }
}

```

2.2

```

;
; AssemblerApplication1.asm
;
; Created: 10/28/2020 4:20:49 PM
; Author : georg
;
; Replace with your application code
.include "m16def.inc"

```

```

.org 0x0
rjmp RESET
.org 0x4
rjmp ISR1

```

```

RESET:
    .def temp = r20
    .def input =r21

```

```
.def interrupt_counter=r22
```

```
.def timer_counter=r26
```

```
clr interrupt_counter
```

```
clr timer_counter
```

```
ldi temp,LOW(RAMEND)
```

```
out SPL,temp
```

```
ldi temp,HIGH(RAMEND)
```

```
out SPH,temp
```

```
ldi r24,(1<<ISC11)|(1<<ISC10) ; mask the MCUCR for the positive edge of the interrupt1
```

```
out MCUCR,r24
```

```
ldi r24,(1<<INT1)
```

```
out GICR,r24 ; mask the GICR of the interrupt1
```

```
sei ; enable interrupts
```

```
ser temp
```

```
out DDRC,temp ; DDRC output
```

```
loop:
```

```
out PORTC,timer_counter ; show the timer_counter
```

```
;ldi r24,low(100)
```

```
;ldi r25,high(100)
```

```
;rcall wait_msec
```

```
inc timer_counter ; increace the timer_counter
```

```
rjmp loop ; go again
```

```
ISR1:
```

```
cli
```

```
in temp, SREG ; save the System Register
```

```
push temp
```

```
clr temp
```

```

out DDRA,temp ; A= input

ser temp

out DDRB,temp ; B = output

inc interupt_counter ; increace the interupt_counter

in input,PINA ; check A if you have to show it or not

cpi input,0xC0

brne dont_display_the_interupt_counter

```

display_the_interupt_counter:

```

out PORTB,interupt_counter

;ldi r24,low(100)

;ldi r25,high(100)

;rcall wait_msec

pop temp

out SREG,temp

reti

```

dont_display_the_interupt_counter:

```

;ldi r24,low(100)

;ldi r25,high(100)

;rcall wait_msec

pop temp

out SREG,temp

reti

```

2.3

```

/*

* GccApplication1.cpp

*

* Created: 10/28/2020 6:42:12 PM

* Author : georg

*/

```

```

#include <avr/io.h>

#include <avr/interrupt.h>

unsigned char A,B,temp;

char x,c;

volatile int flag=1;

ISR(INT0_vect){

    //pd2 routine

    cli();

    if((PINA & 0x04) == 0x04){

        x=0x00;

        if((PINB & 0x01) == 0x01) x++;

        if((PINB & 0x02) == 0x02) x++;

        if((PINB & 0x04) == 0x04) x++;

        if((PINB & 0x08) == 0x08) x++;

        if((PINB & 0x10) == 0x10) x++;

        if((PINB & 0x20) == 0x20) x++;

        if((PINB & 0x40) == 0x40) x++;

        if((PINB & 0x80) == 0x80) x++; //count the pins of B

        c=0x00;

        while(x>0){

            c=c<<1;

            c=c+1;

            x=x-1;

        }

        PORTC=c; // open so many leds of the C starting from the lsb as the count of B

    }

    else{

```

```

        x=0x00;

        if((PINB &0x01) == 0x01) x++;
        if((PINB &0x02) == 0x02) x++;
        if((PINB &0x04) == 0x04) x++;
        if((PINB &0x08) == 0x08) x++;
        if((PINB &0x10) == 0x10) x++;
        if((PINB &0x20) == 0x20) x++;
        if((PINB &0x40) == 0x40) x++;
        if((PINB &0x80) == 0x80) x++; //count the pins of B

        PORTC=x; // output them on binary form
    }
    sei();
}

int main(){

    GICR=(1<<INT0); // be ready for the interrupt0
    MCUCR = (1<<ISC01|1<<ISC00); // wait on the positive edge of the interrupt0
    sei();

    DDRA = 0x00; // A input
    DDRB = 0x00; // B input
    DDRC = 0xff; // C output
    while(1){
        PORTC=0x00; // wait for the interrupt0
    }
}

```