

Extended Testing using GMock

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Summary of Testing

- Testing small units of Code
- Simple tests expressing the expected behaviour
- Automated test execution to catch regressions
- Integration of the tests to the build process (catkin, rostest)

Interface: Definition

Definition: Specification

Specification is used to describe the functionality of a piece of software without any implementational detail. It can either be done in written form, in pseudo-code or even in a mathematical form.

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Definition: Interface

An interface is transformation of a (part of) specification in a concrete machine readable description. It defines the access points of a functional unit regarding ingoing and outgoing data as well as control.

Flavours of Interfaces

Class Interface : Collection of methods and members the class provides to other parts of the program

Library Interface : Collection of static functions and statically defined variables.

Communication Interface : Definition of data in a specific format usable to be transmitted byte by byte through a network connection.

User-Interface : Collection of user-interactable fields and switches.

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Commonality

Interfaces define the possible interaction between entities. One entity may only use the features of another entity through the interface as specified.

Examples

A Class Interface

```
1 class RoadInterface {  
2     public:  
3         enum class Cell { Free, Blocked, Car };  
4         virtual ~RoadInterface() {}  
5         virtual Cell readCell( unsigned int y,  
6                                 unsigned int x ) const =0;  
7         virtual void writeCell( unsigned int y,  
8                                 unsigned int x, Cell cell ) =0;  
9     };
```

A ROS Network Interface

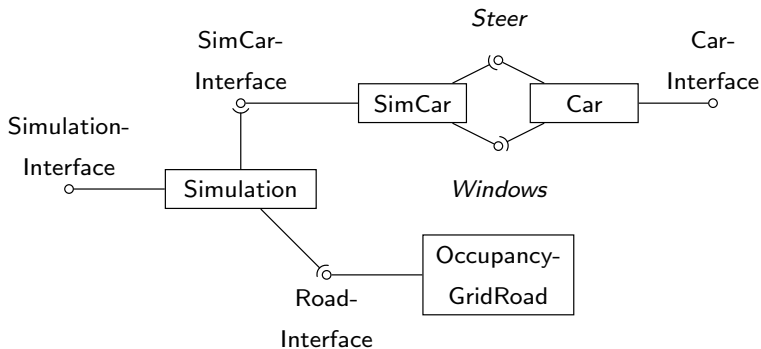
```
1 Header header  
2 int32 cmd  
3  
4 int32 Straight = 0  
5 int32 Left     = -1  
6 int32 Right    = 1
```


Component-based Software Design

Definition: Software Component

A software component is a functional unit with clearly specified incoming and outgoing interfaces. The incoming interfaces need to be fulfilled by other components for this component to be used.

Component structure of the ROS Testing Example



Benefits of Software Components

Decoupled Devopment : Developers may focus on a single piece of software. Limits the effects of software changes to the connections between the components.

Reusage of Components : A developed component may be used in any context as long as the interface specifications are fulfilled.

Easier Testing : Each component may be tested individually against the specification of its interface, without using any other component

How to test

The Problem

How can the dependency of a software component be fulfilled without using another component fulfilling the interface.

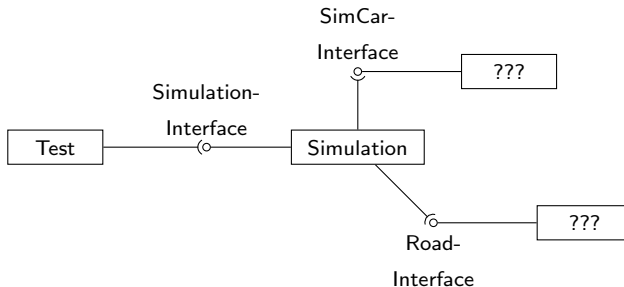


Figure: ROS Example Simulation Testing Challenge

Solutions

Definition: Fake Object

Fake objects have working implementations, but usually take some shortcut (perhaps to make the operations less expensive), which makes them not suitable for production. An in-memory file system would be an example of a fake.¹

¹GMock for Dummies:

<https://code.google.com/p/googlemock/wiki/ForDummies>

Solutions

Definition: Fake Object

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Definition: Mock Object

Mocks are objects pre-programmed with expectations, which form a specification of the calls they are expected to receive.¹

¹GMock for Dummies:

<https://code.google.com/p/googlemock/wiki/ForDummies>

Expectations in Value

EXPECT_CALL declares a Mock Method to be expected to be called

Lt is a *Matcher* comparing provided arguments to be
Lower than a reference.

_ is the wildcard *Matcher* stating all arguments should
be matched.

Expecations on Value Example

```
1  using ::testing::Lt;  
2  using ::testing::_;  
3  
4  EXPECT_CALL(road, isFree(Lt(road.maxY()),  
5                      Lt(road.maxX()  
6                      ));  
7  EXPECT_CALL(road, writeCell(_, _,  
8                      RoadInterface::Cell::Car  
9                      ));
```


Expectations in Time

`.Times()` declares the expected number of calls to a mock method with the specified arguments

`AtLeast()` declares a minimum amount

Expectations on Time Example

```
1 using ::testing::AtLeast;
2
3 Test(SimulationTest, carCreationTest) {
4     MockRoad road(10, 10);
5
6     EXPECT_CALL(road, isFree(_, _))
7         .Times(AtLeast(1))
8     EXPECT_CALL(road, writeCell(_, _, _))
9         .Times(1);
10
11     Simulation<MockCar> sim(road);
12     sim.createCar("TestCar");
13 }
```

Returning Values

`.WillOnce()` : Modifies the Mock Method to do an **Action** a single time

`.WillRepeatedly()` : Modifies the Mock Method to do an **Action** all the time

`Return()` : return the specifies value as the **Action**

Example of a Return Action

```
1  using ::testing::Return;
2  MockRoad mRoad(10, 10);
3  EXPECT_CALL(road, isFree(Lt(road.maxY()),
4                      Lt(road.maxX()))
5      .Times(AtLeast(1))
6      .WillOnce(Return(true))
7      .WillRepeatedly(Return(false));
```

Side Effects

`Assign(T* ptr, T v)` : assigns `v` to the address `ptr` as the methods action

Example of a Side-Effect Action

```
1 class MockCar : public SimCarInterface {
2     public:
3         MOCK_METHOD1(x, void(unsigned int x));
4
5         MockCar(const string& numberPlate, Dir dir,
6                 unsigned int y, unsigned int x)
7             : SimCarInterface(numberPlate, dir, 1, 1) {
8             EXPECT_CALL(*this, x(2))
9                 .Times(AtLeast(1))
10                .WillRepeatedly(Assign(&mX, 2));
11        }
12    };
```

⁰Many more actions and receipes can be found in the cookbook:

<https://code.google.com/p/googlemock/wiki/CookBook>

Catkin Integration

No Default Catkin Integration

Unfortunately; there is currently no GMock integration within catkin available. Therefore, a workaround needs to be used.

GMock Catkin Integration Workaround

```
1  if(CATKIN_ENABLE_TESTING)
2
3      # Create a gmock target to be used as a dependency
4      # by test programs
5      add_library(gmock IMPORTED STATIC GLOBAL)
6      set_property(TARGET gmock PROPERTY IMPORTED_LOCATION
7                   /usr/lib/libgmock.so)
8
9      # Add gtest based cpp test target and link libraries
10     catkin_add_gtest(${PROJECT_NAME}-mock src/Mock.cpp)
11     target_link_libraries(${PROJECT_NAME}-mock
12                           ${catkin_LIBRARIES} cars gmock)
13
14 endif()
```

VCS History

Rewriting History

Reverting and Blaming

Left Overs

- Runtime Testing using `Ros::SelfTest`