
Robotic Hand Development Kit

Description

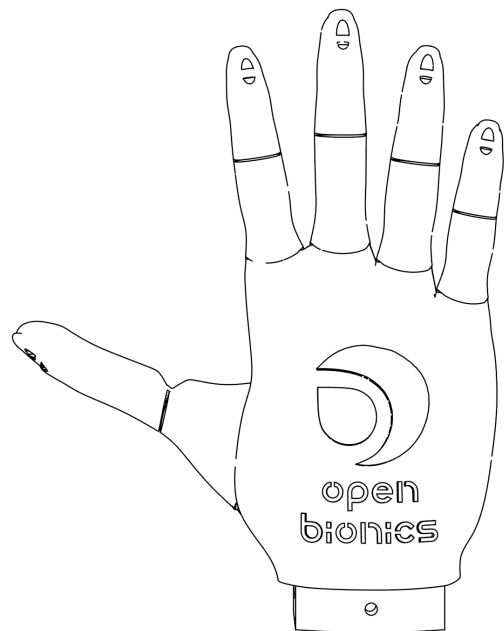
The Ada Hand is a robotic hand from Open Bionics. It comes as a kit and can be assembled in around 1 hour using standard tools. The Ada hand houses all of the actuators required to move the fingers as well as its own custom control printed circuit board (PCB), the Almond V1.2. The PCB is based around the ATMEGA2560 microcontroller.

Features

- 5 degrees of freedom
- Open source
- Arduino IDE compatible
- USB Programmable

Key specifications

- Mass: 380 g
- Major dimensions: 215 x 178 x 58 mm
- Operating voltage: 12V

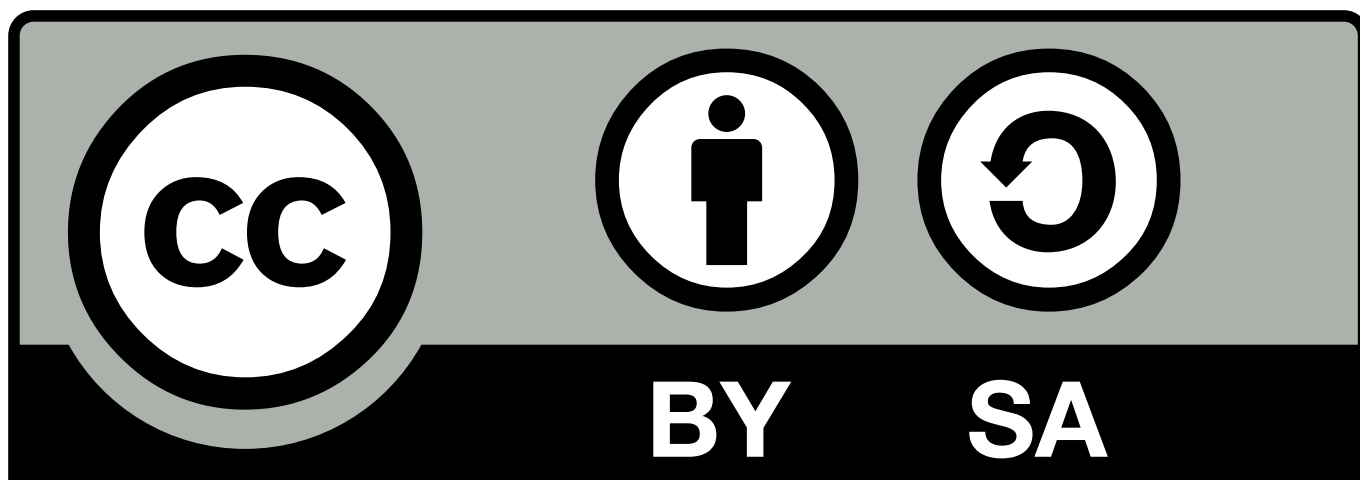


Applications

Perfect for the scientist, researcher, roboticist, educator or hobbyist. For example uses, please see the User Project section of our forum at www.openbionics.lefora.com

This is not a medical device.

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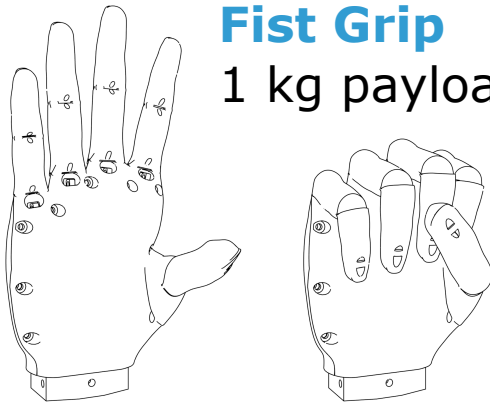
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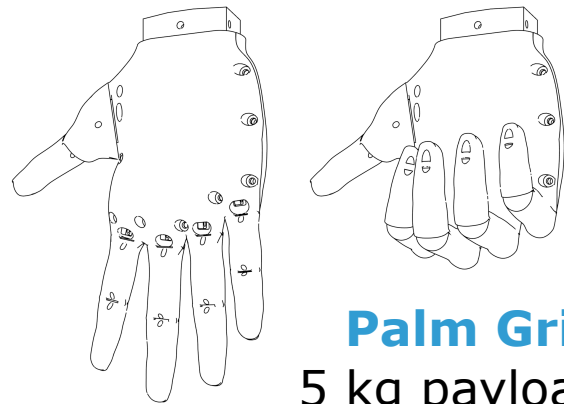
Fist Grip

1 kg payload



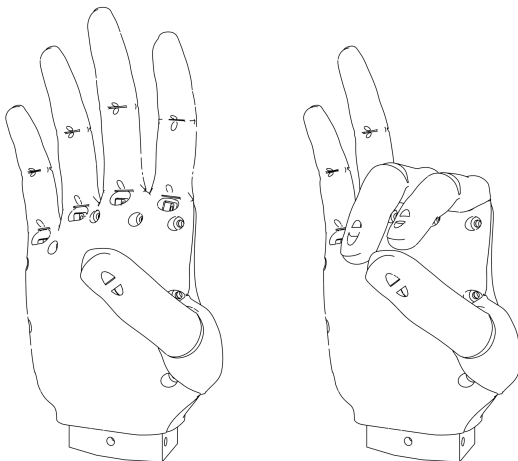
Palm Grip

5 kg payload



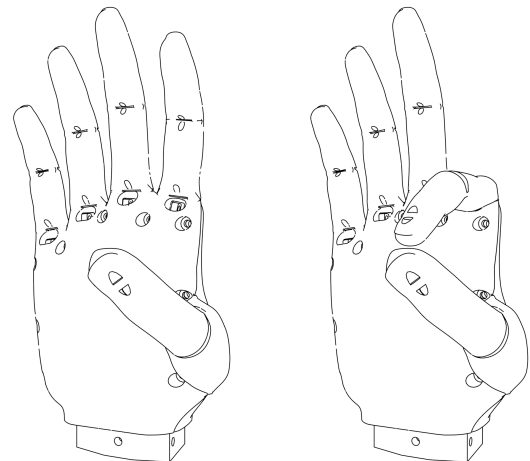
Tripod Grip

0.7 kg payload

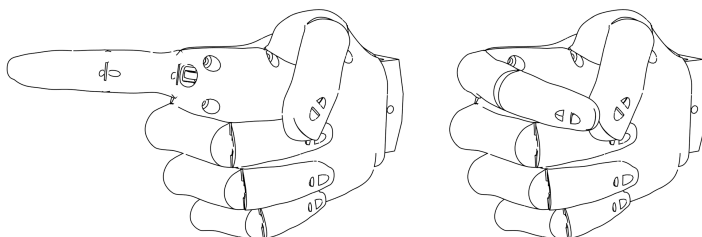


Pinch Grip

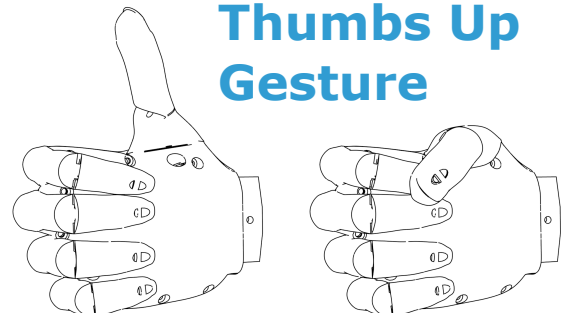
0.4 kg payload



Point Gesture

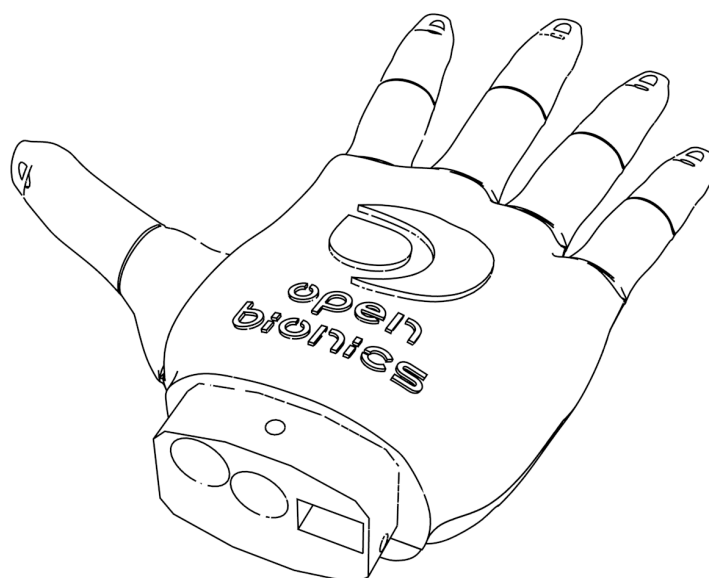
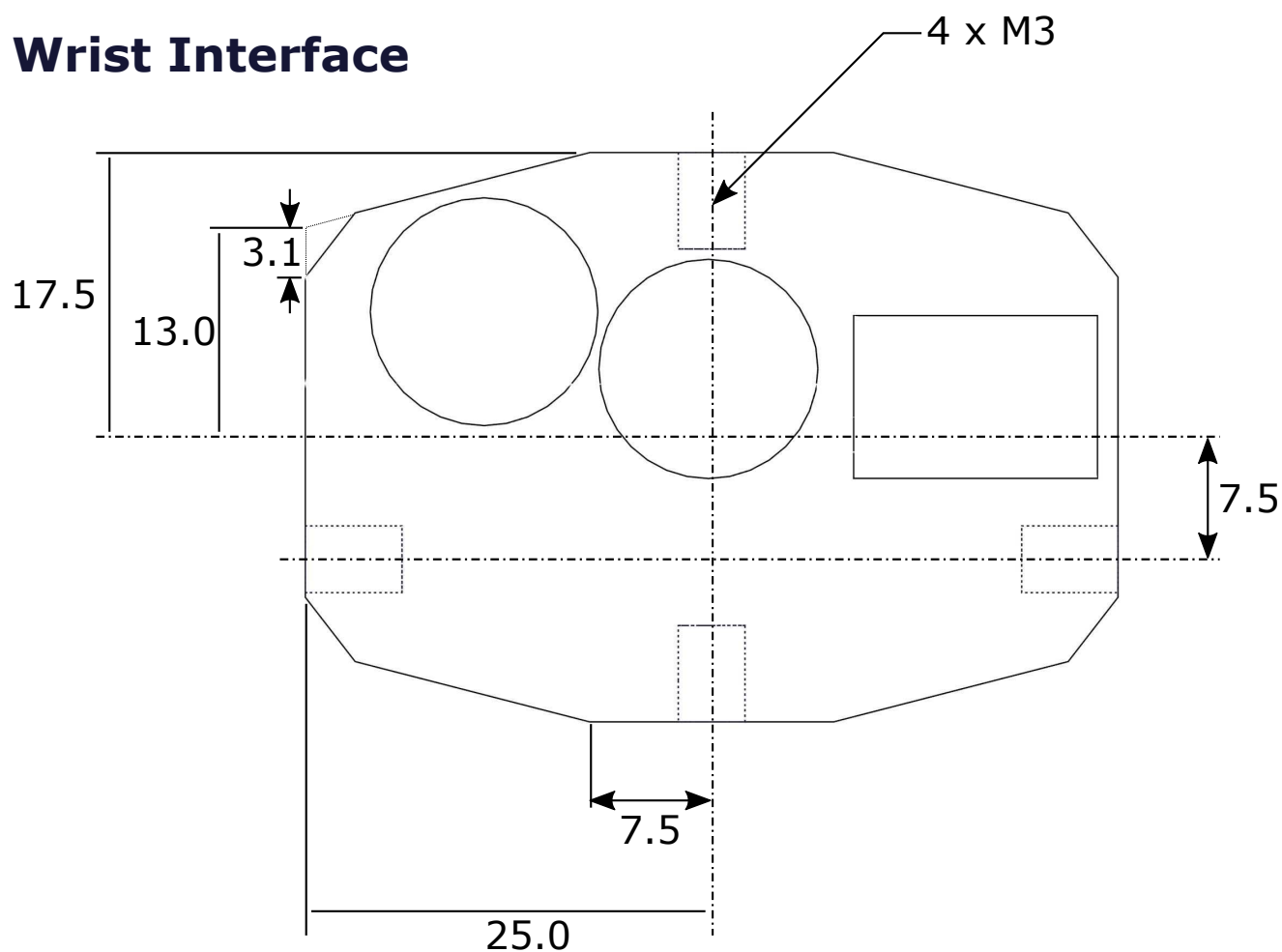


Thumbs Up Gesture



Payloads are approximate and assume use of silicone fingertips

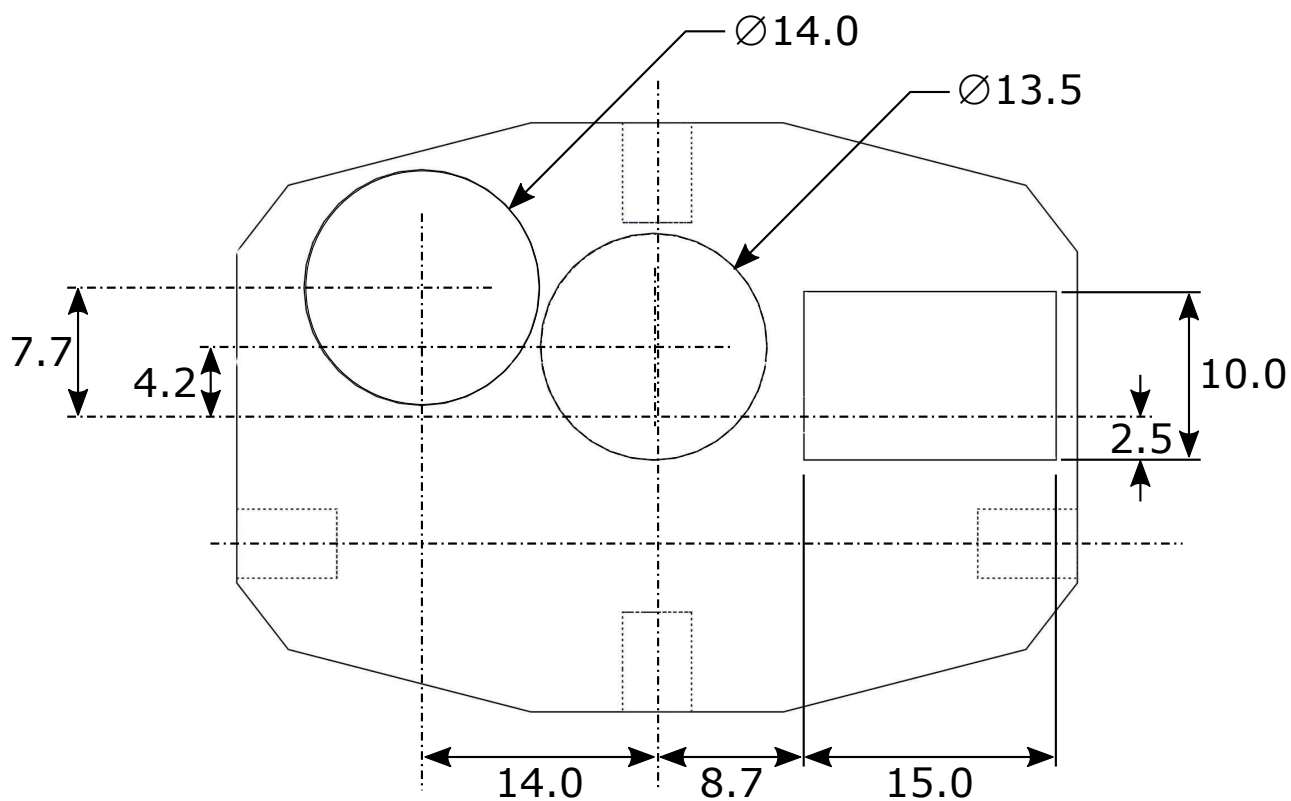
Wrist Interface



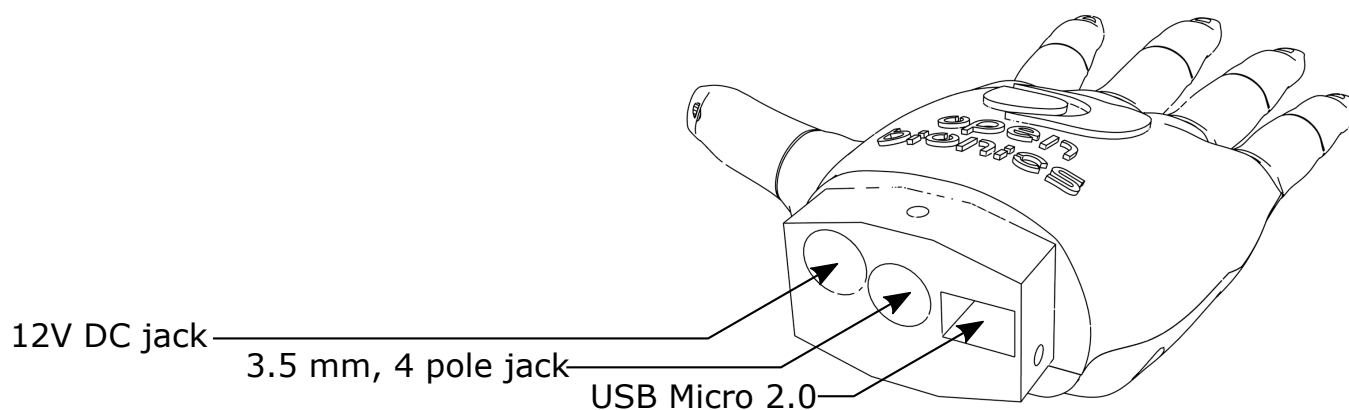
Wrist connector depth: 15 mm

All units in mm

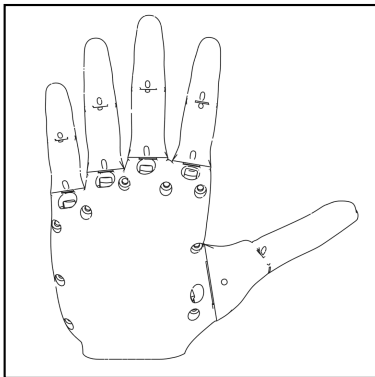
Wrist Cabling



All units in mm



Components



Palm

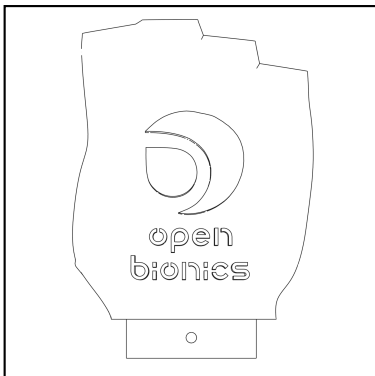
Material: Ninjaflex

Mass: 160 g

Mass with support: 200 g

Print time: 26 hours

Bounding box: 180 x 200 x 45 mm



Back Cover

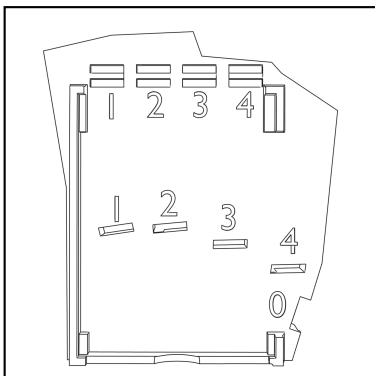
Material: PLA or ABS

Mass: 57 g

Mass with support: 70 g

Print time: 6 hours

Bounding box: 130 x 95 x 40 mm



PCB Tray - Upper

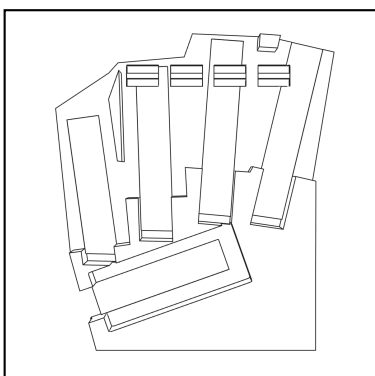
Material: PLA or ABS

Mass: 6 g

No support required

Print time: 40 minutes

Bounding box: 80 x 70 x 10 mm



PCB Tray - Lower

Material: PLA or ABS

Mass: 10 g

No support required

Print time: 40 minutes

Bounding box: 80 x 70 x 10 mm