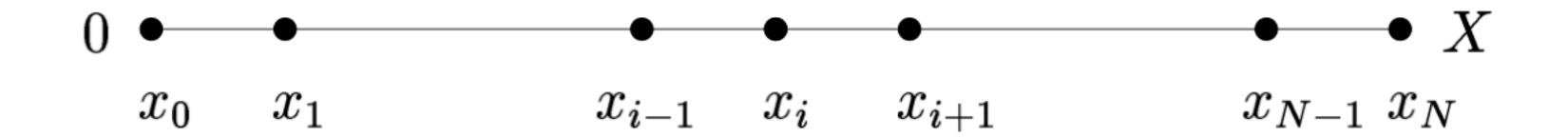
Finite difference methods

Principle: derivatives in the partial differential equation are approximated by linear combinations of function values at the grid points

1D:
$$\Omega = (0, X), \quad u_i \approx u(x_i), \quad i = 0, 1, ..., N$$

grid points $x_i = i\Delta x$ mesh size $\Delta x = \frac{X}{N}$

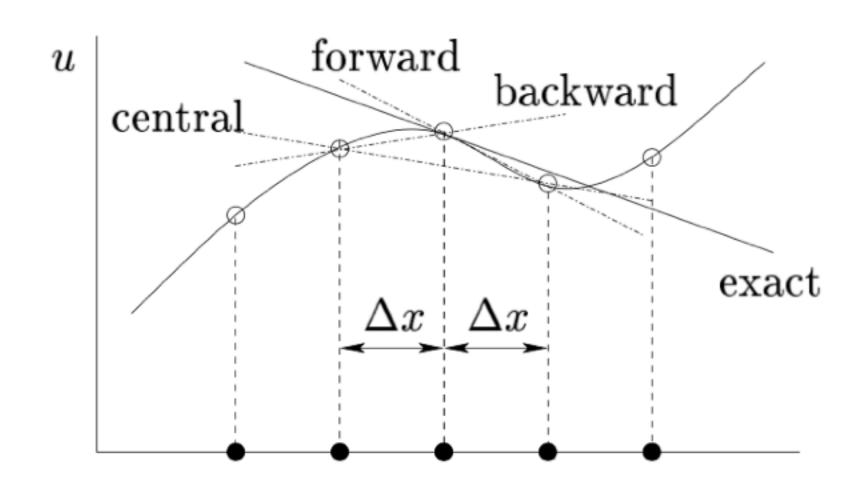


First-order derivatives

$$\frac{\partial u}{\partial x}(\bar{x}) = \lim_{\Delta x \to 0} \frac{u(\bar{x} + \Delta x) - u(\bar{x})}{\Delta x} = \lim_{\Delta x \to 0} \frac{u(\bar{x}) - u(\bar{x} - \Delta x)}{\Delta x}$$
$$= \lim_{\Delta x \to 0} \frac{u(\bar{x} + \Delta x) - u(\bar{x} - \Delta x)}{2\Delta x} \quad \text{(by definition)}$$

Approximation of first-order derivatives

Geometric interpretation



$$\left(\frac{\partial u}{\partial x}\right)_i pprox rac{u_{i+1}-u_i}{\Delta x}$$

forward difference

$$\left(\frac{\partial u}{\partial x}\right)_i pprox rac{u_i - u_{i-1}}{\Delta x}$$

backward difference

$$\left(rac{\partial u}{\partial x}
ight)_i pprox rac{u_{i+1} - u_{i-1}}{2\Delta x}$$

central difference