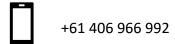
Global Navigation Satellite Systems

An very short introduction to Global Navigation Satellite Systems (GNSS)

FRJNTIER<mark>S</mark>>

Rupert Brown rbrown@frontiersi.com.au

FrontierSI
December 2021

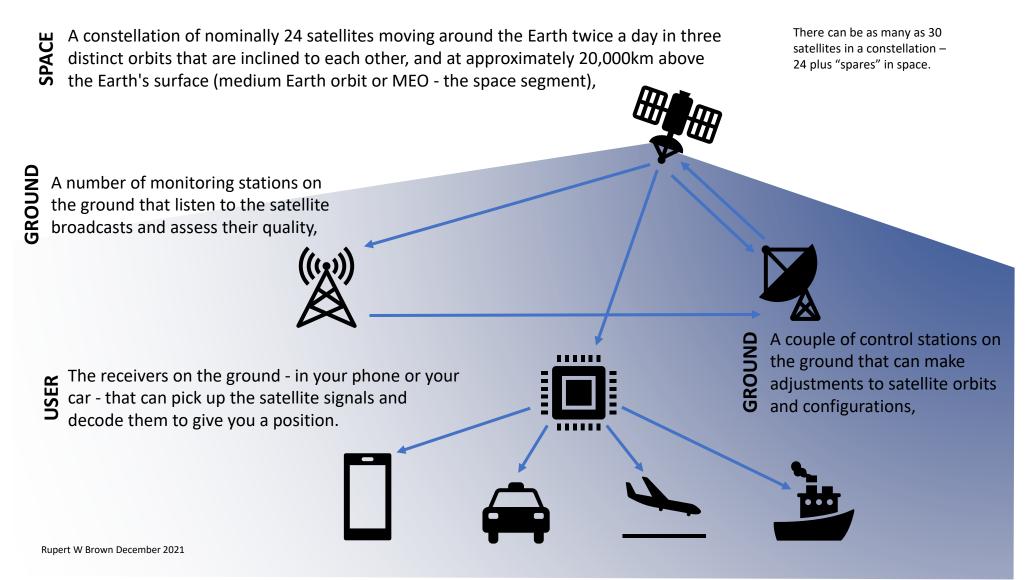






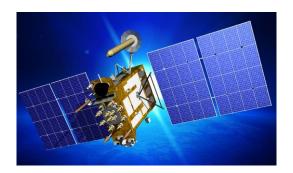
Global Navigation Satellite Systems

A global navigation satellite system consists of:

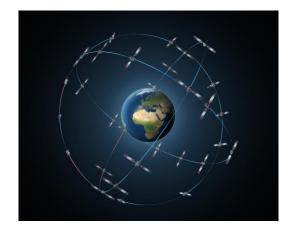


GNSS Components

SPACE



A Russian GLONASS GNSS satellite



The Galileo GNSS satellite constellation

GROUND



An Australian GNSS monitoring station



A GPS Control Station

USER



A GNSS car navigation system



A GNSS enabled drone autopilot

These symbols represent parameters that define a satellite's orbit.

Argument of the ascending node (Aries)

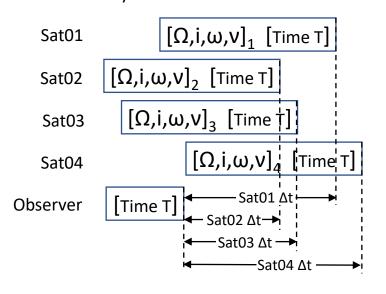
Angle of inclination

W Argument of perigee

V True anomaly

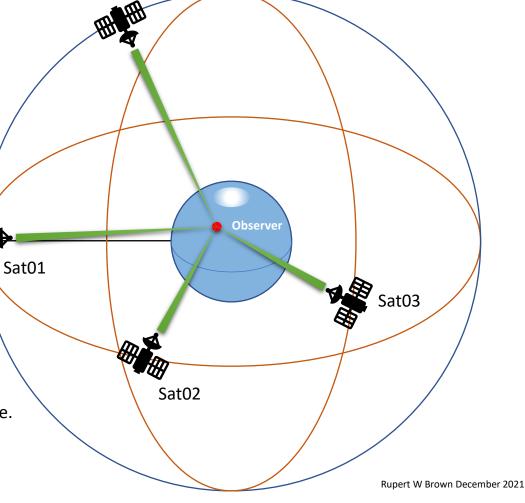
Position: determining a position on Earth using GNSS radio signals

Position and time messages sent from the satellites are received by the Observer at different times.



Messages sent at the same time by the satellites are received at different times by the Observer because the signals have to travel different distances. These time differences can be used to calculate those distances. With a knowledge of the satellites' positions and their distance from the Observer, the Observer can calculate its position on the Earth's surface.

The messages are complex in nature and transmitted on several frequencies including the three L bands: L1 (1575.42 Mhz), L2 (1227.60 MHz) and L5 (1176.45 MHz).

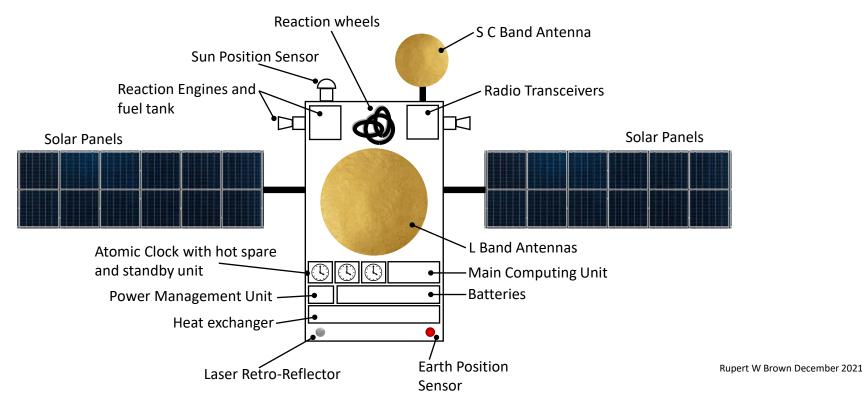


Sat04

GNSS Constellations – with signal frequencies Earth Axis of Rotation **GLONASS GPS** L1 L2 L5 G1 G2 G3/L5 L1: 1574.42 MHz G1: 1600.995 MHz L2: 1227.60 MHz G2: 1248.06 MHz L5: 1176.45 MHz G3: 1202.25 MHz Earth Mass Centre B1: 1561.098 MHz E1: 1575.42 MHz B3: 1268.52 MHz E6: 1278.75 MHz B2b: 1207.14 MHz E5b: 1207.14 MHz B2a: 1176.45 MHz E5a: 1176.45 Equator · @ . **B1 E1** GALILEO **B2 E6** B3 **E**5 **GALILEO BEIDOU** Rupert W Brown December 2021

The space segment - satellite

A representation – not an accurate depiction – of a GNSS satellite.



Electrical power is generated by the **Solar Panels**. The **Power Management Unit** controls the distribution of power to onboard systems and the **Batteries**. The **Batteries** ensure that the satellite continues to operate when the solar panels are not in sunlight. The **Sun Position Sensor** identifies the direction of the Sun.

The **Reaction Engines** are used to maintain the satellite's position in orbit as part of a constellation. A satellite typically carries a finite amount of fuel which is depleted over time and restricts the satellite's useful working life. The **Reaction Wheels** use angular momentum to adjust the satellite's orientation.

A Radio Transceiver creates the L Band signals – the positioning signals – which are broadcast via the L Band Antennas. The fully redundant Atomic Clocks provide vital timing data to create the positioning signals. The Earth Position Sensor ensures that the positioning signals are pointed at the Earth.

The Main Computing Unit, working with the S and/or C Band Antenna receives and processes telemetry, tracking and command data to keep the satellite working correctly and in the right place. The Laser Retro-Reflector is used by ground based ranging lasers to determine the satellite's position and latitude.

