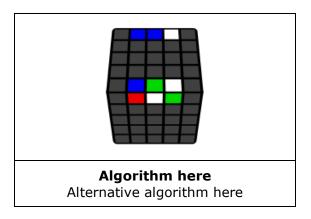


## 5x5 L2E Algorithms (Last Two Edges)

Images sourced from Conrad Rider's VisualCube - <a href="http://cube.crider.co.uk/visualcube.php">http://cube.crider.co.uk/visualcube.php</a>

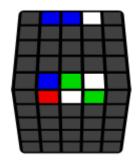
## **Algorithm Presentation Format**



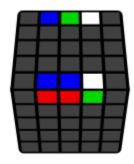
For some cases shown, algorithms are given for alternative angles. [L2E on top, and L2E on front]

Round brackets are used to segment algorithms to assist memorisation and group move triggers.

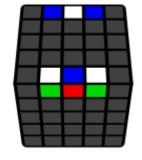
## **No Parity Cases**



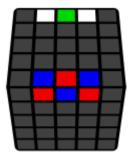
**Rw' U' R' U (R' F R F') Rw** [z' y'] Uw' (R U R' F R' F' R) Uw



**3Lw U' R' U (R' F R F') Rw'** [z' y'] 3Dw (R U R' F R' F' R) Uw'

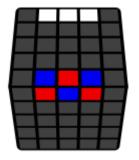


Rw2' F2 U2' Rw2' U2' F2 Rw2

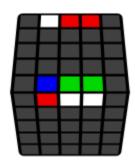


**Rw' Lw U' R' U (R' F R F') Rw Lw'** [z' y'] Uw' Dw (R U R' F R' F' R) Uw Dw'

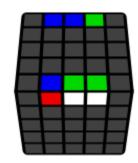
## **Parity Cases**



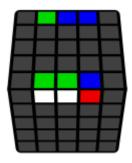
Rw U2 x Rw U2 Rw U2' Rw' U2 Lw U2 3Rw' U2' Rw U2 Rw' U2' Rw'



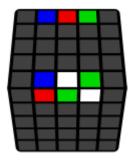
Rw U2 Rw U2' x U2 Rw U2' 3Rw' U2 Lw U2' Rw2



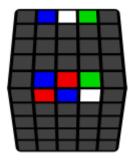
F2 Rw U2 Rw U2' Rw' F2 Rw' U2 Rw' U2' Rw U2 Rw' U2' Rw2



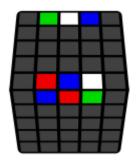
U2' Rw' U2 Rw U2' Rw2



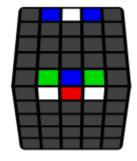
B2 Rw' U2 Rw' U2' Rw B2 Rw U2 Rw Rw U2 Rw2 U2' Rw' U2 Rw U2' Rw' U2 Rw' U2' Rw2 U2' Rw U2' Rw U2' Rw Rw2 U2' Rw



U2' Rw2 U2' Rw'



Rw' U2 Rw U2' 3Lw' U2 Rw U2 Rw U2' Rw' U2 Rw U2' Rw2



Rw2 B2 Rw' U2 Rw' U2' x' U2 Rw' U2' Rw U2 Rw' U2' Rw2