

DESCRIPTION

number of output		3, coaxial
output angle	hour	2°
	minute	2°
	second	6°
steps per turn	hour	180
	minute	180
	second	60
Main plate material		Plastic
Gears		Metal, Soptec

Prepared	RC
Checked	BS
Version	2.2
Date	21.06.2017

SPECIFICATIONS

Description	symbole	Unit	Minimum	Nominal	Maximum
pulse width	T ₀	ms	-	2.9	-
Time between pulses	T ₁	ms	16.6	-	Infinite
motor step frequency	M _{fréq}	Hz	0	-	60
voltage	U ₀	V	-	3	-
Motor start voltage	U _{start}	V	-	2.2	2.6
Motor average consumption (1 step)	I _{mot}	μAs	-	3.8	4.2
Motor peak consumption	I _{peak}	mA	-	2	2.5
Coils resistor	R _{coil}	Ohm	1480	1600	1720
Motor torque 2°	M _{ti}	μNm	20	-	40
Motor torque 6°	M _{ti}	μNm	10	-	18
Motor positioning torque 2°	MPT	μNm	-	90	-
Motor positioning torque 6°	MPT	μNm	-	30	-
Total Angular play	∠	°	-	-	2°

Hands specifications

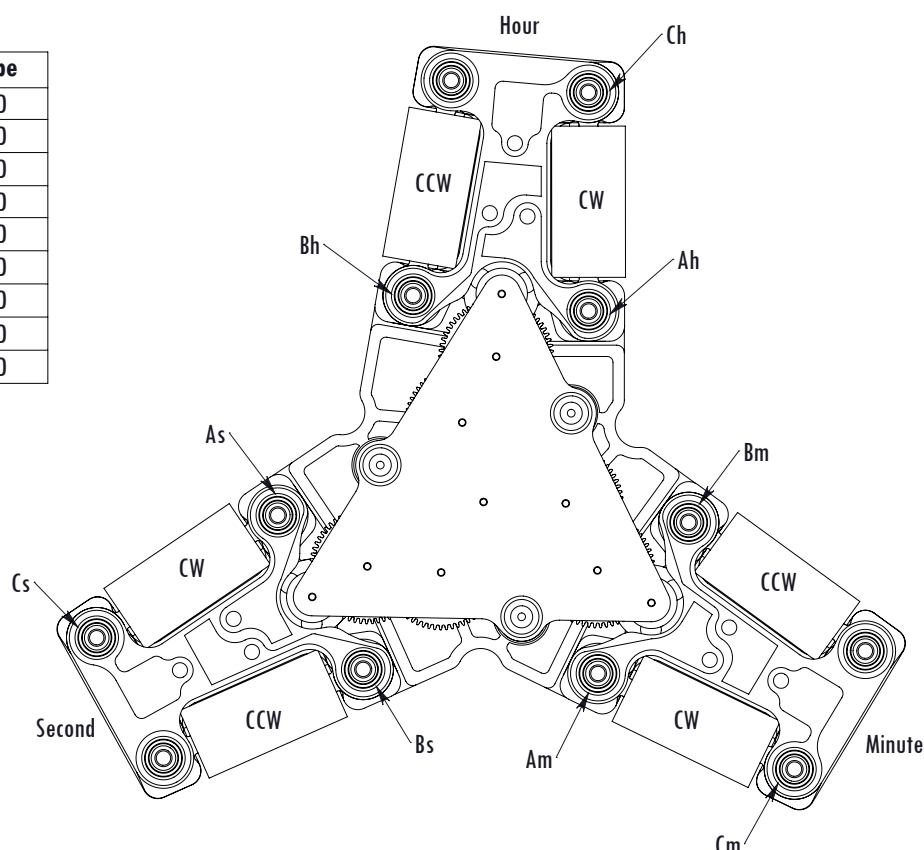
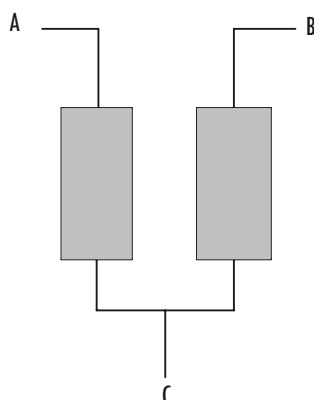
Unbalance (μNm)	0.3	0.3	0.1
Inertia (gmm ²)	0.7	0.7	0.3
F. Max (N)	40	40	25

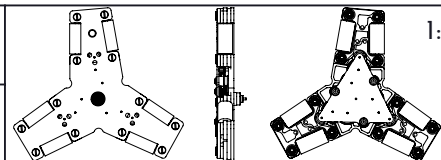
Unbalance is given for a linear shock resistance up to 300G perpendicular to the hand direction.
For higher values, please contact us.

ELECTRICAL PRINCIPLE

Pin configuration

Motor	Pin description	Symbol	Type
Minute	Coil CW	Am	I/O
	Coil CCW	Bm	I/O
	Common	Cm	I/O
Hour	Coil CW	Ah	I/O
	Coil CCW	Bh	I/O
	Common	Ch	I/O
Second	Coil CW	As	I/O
	Coil CCW	Bs	I/O
	Common	Cs	I/O

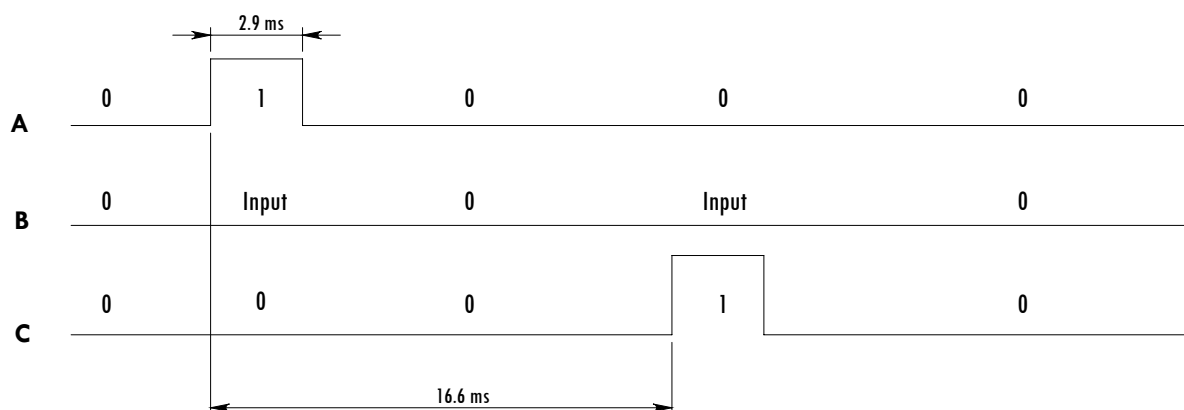




ELECTRICAL PRINCIPLE

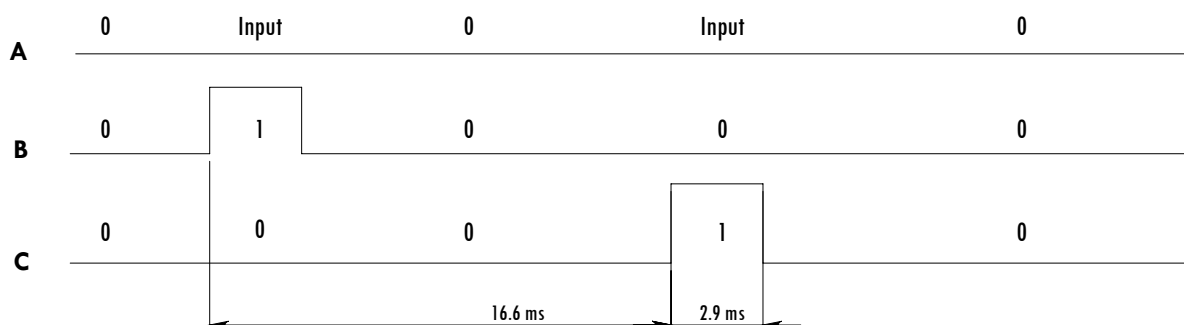
Step Clockwise

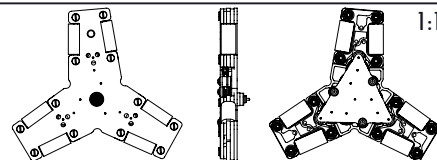
Description	Pin A		Pin B		Pin C	
	Direction	Output	Direction	Output	Direction	Output
Init	Output	'0'	Output	'0'	Output	'0'
Step 1	Output	'1'	Input	'0'	Output	'0'
Between the steps	Output	'0'	Output	'0'	Output	'0'
Step 2	Output	'0'	Input	'0'	Output	'1'
End	Output	'0'	Output	'0'	Output	'0'



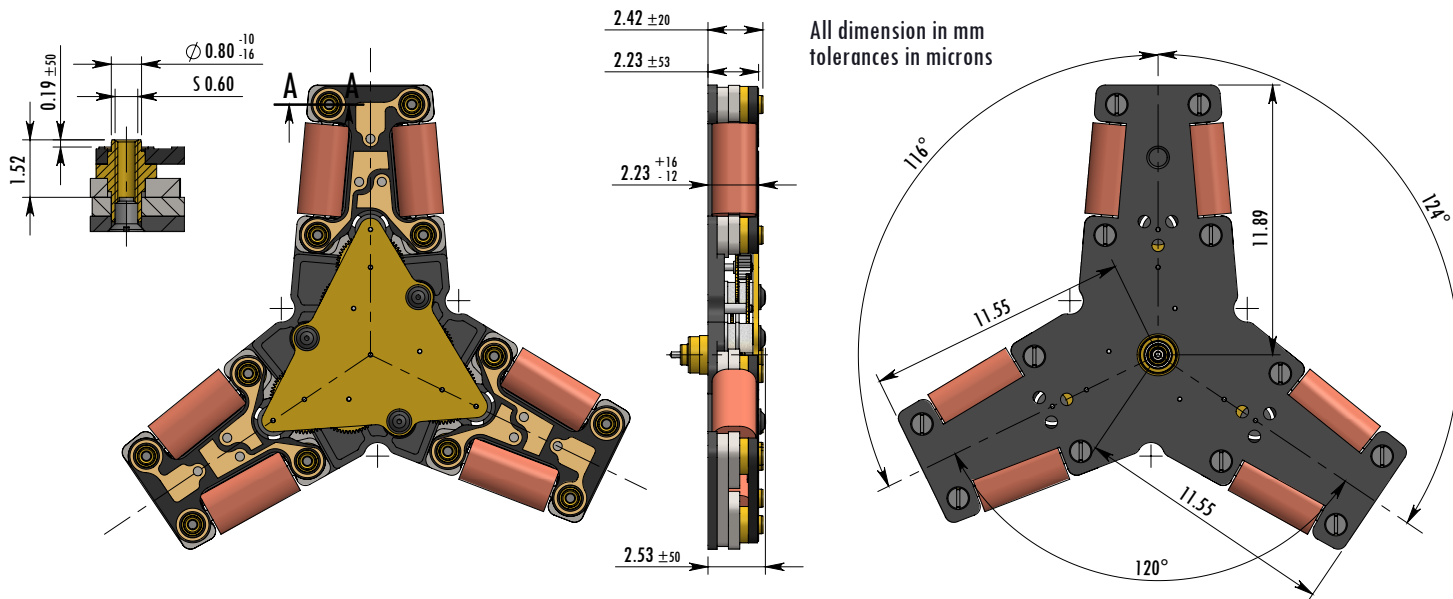
Step Counterclockwise

Description	Pin A		Pin B		Pin C	
	Direction	Output	Direction	Output	Direction	Output
Init	Output	'0'	Output	'0'	Output	'0'
Step 1	Input	'0'	Output	'1'	Output	'0'
Between the steps	Output	'0'	Output	'0'	Output	'0'
Step 2	Input	'0'	Output	'0'	Output	'1'
End	Output	'0'	Output	'0'	Output	'0'

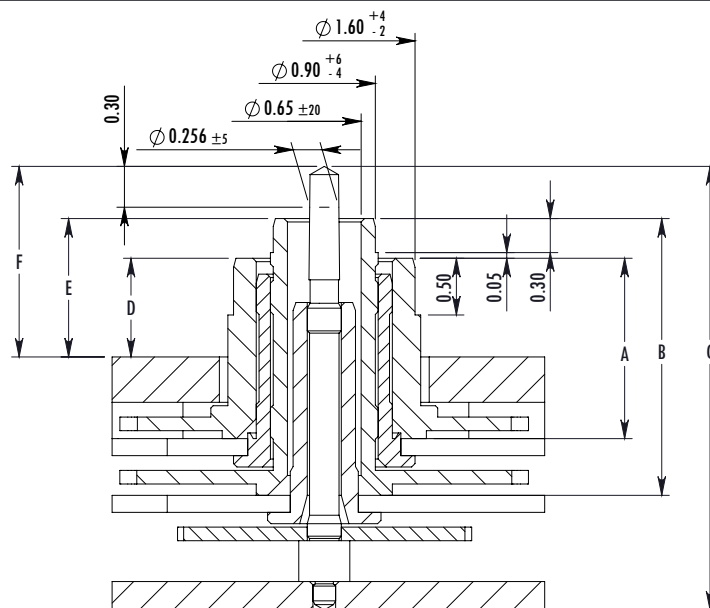




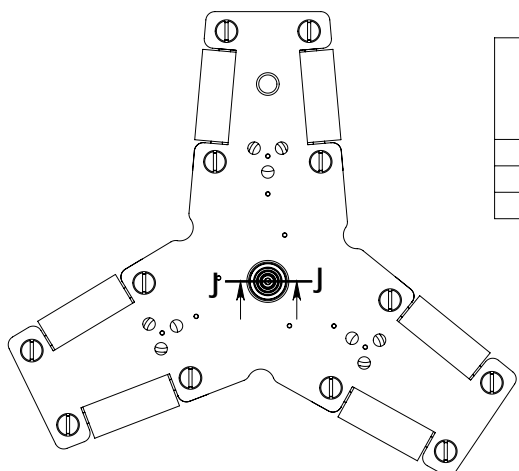
DIMENSIONS



HAND FITTING

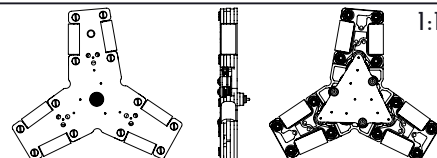


Support mandatory for the hand press in

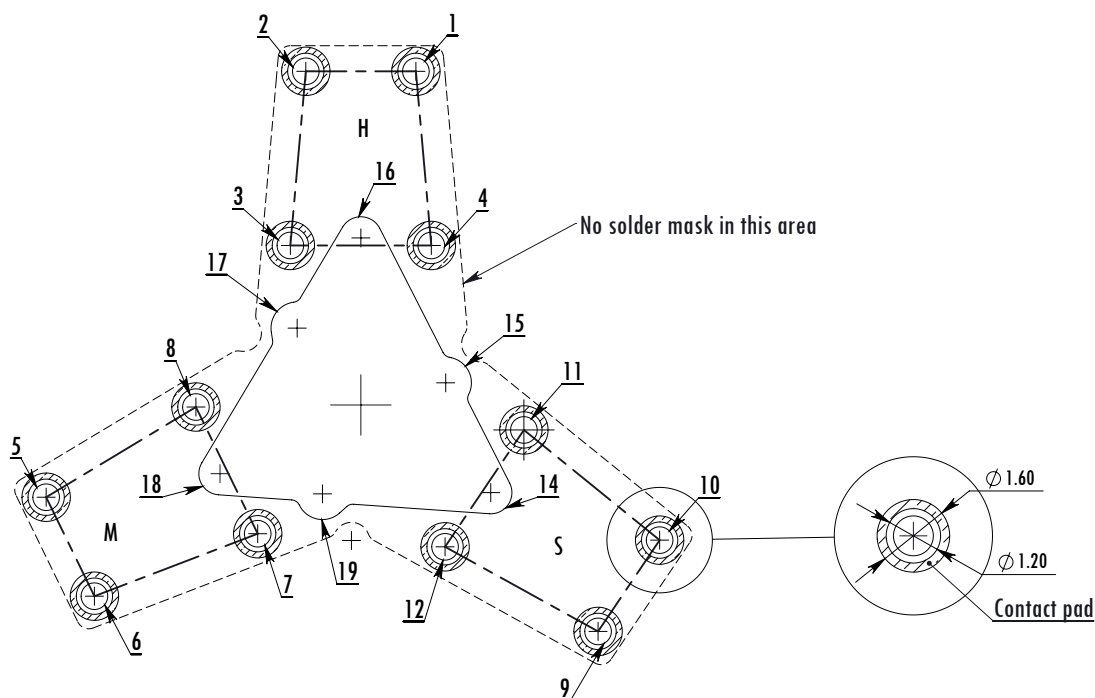


Hand fitting	Lenght			Height over dial seat		
	A	B	C	D	E	F
	Hour	Minute	Second	Hour	Minute	Second
H1	1.59	2.44	3.91	0.87	1.22	1.68
H4	2.34	3.19	4.66	1.62	1.97	2.43
H6	2.84	3.69	5.16	2.12	2.47	2.93

Other heights on demand



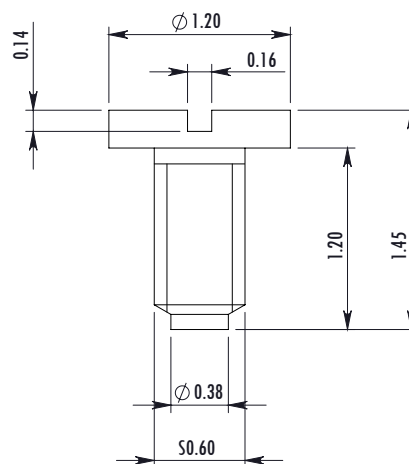
PCB LAYOUT



Connection pad location \oplus 90 XY

REP.	X	Y	Size	TOL. [μ m]	Note
1	1.820	11.031	\emptyset 0.88	± 20	not connected
2	-1.820	11.031			Ch
3	-2.330	5.273			Ah
4	2.330	5.273			Bh
5	-10.404	-3.049			not connected
6	-8.808	-6.321			Cm
7	-3.410	-4.255			Am
8	-5.453	-0.067			Bm
9	7.843	-7.485			not connected
10	9.878	-4.468			Cs
11	5.390	-0.825			As
12	2.784	-4.689			Bs

Connection to main board is ensured trough S0.60 Screws
Soprod reference: 500.001 for PCB from 0.40 to 0.60 mm thick.



Milling coordinates \square 200

14	4.295	-2.897	R 0.70		
15	2.806	0.733	R 0.85		
16	0.000	5.523	R 0.70		
17	-2.105	2.541	R 0.85		
18	-4.656	-2.271	R 0.70		
19	-1.269	-2.938	R 0.85		