

# FUNDAMENTALS

## COURSE INTRODUCTION

Riccardo M.G. Ferrari

April 22<sup>nd</sup>, 2025



# OVERVIEW

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1. Pre-requisites

2. Course description

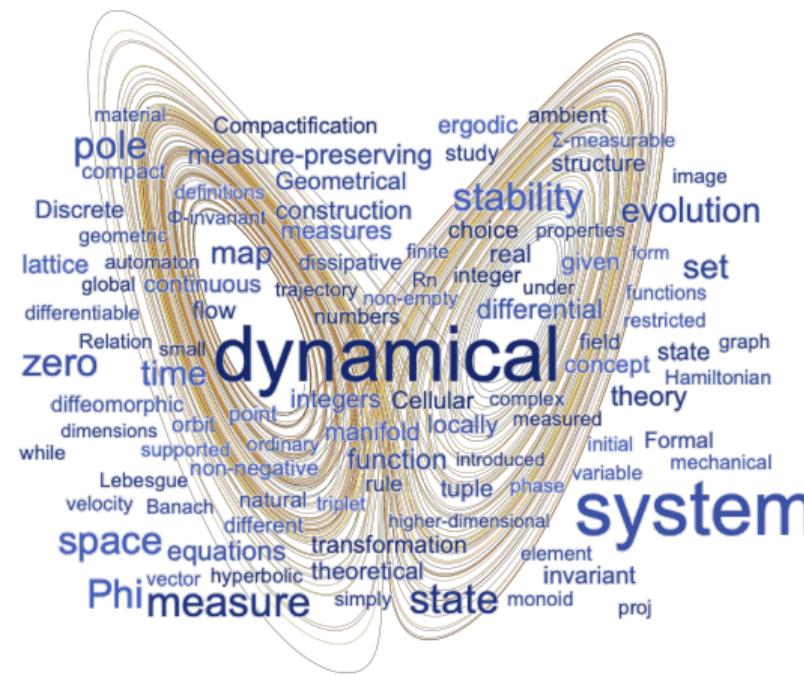
3. Resources and tools

4. Conclusion

# PRE-REQUISITES

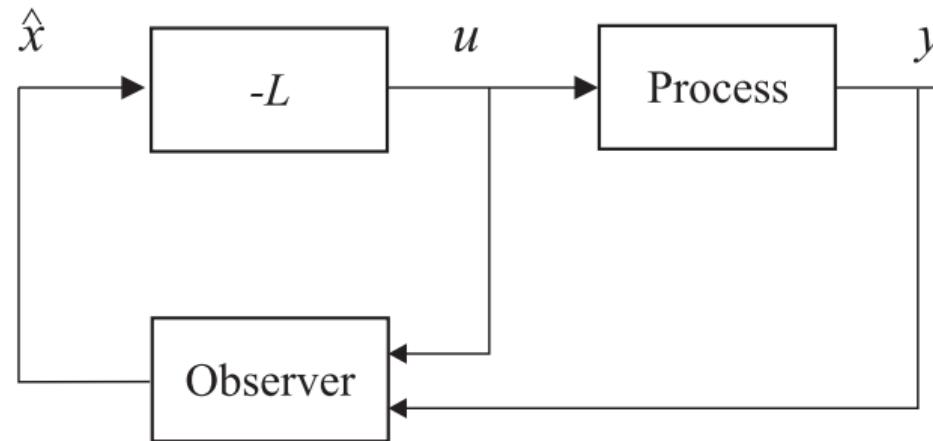
# PRE-REQUISITES

## DYNAMICAL SYSTEMS THEORY



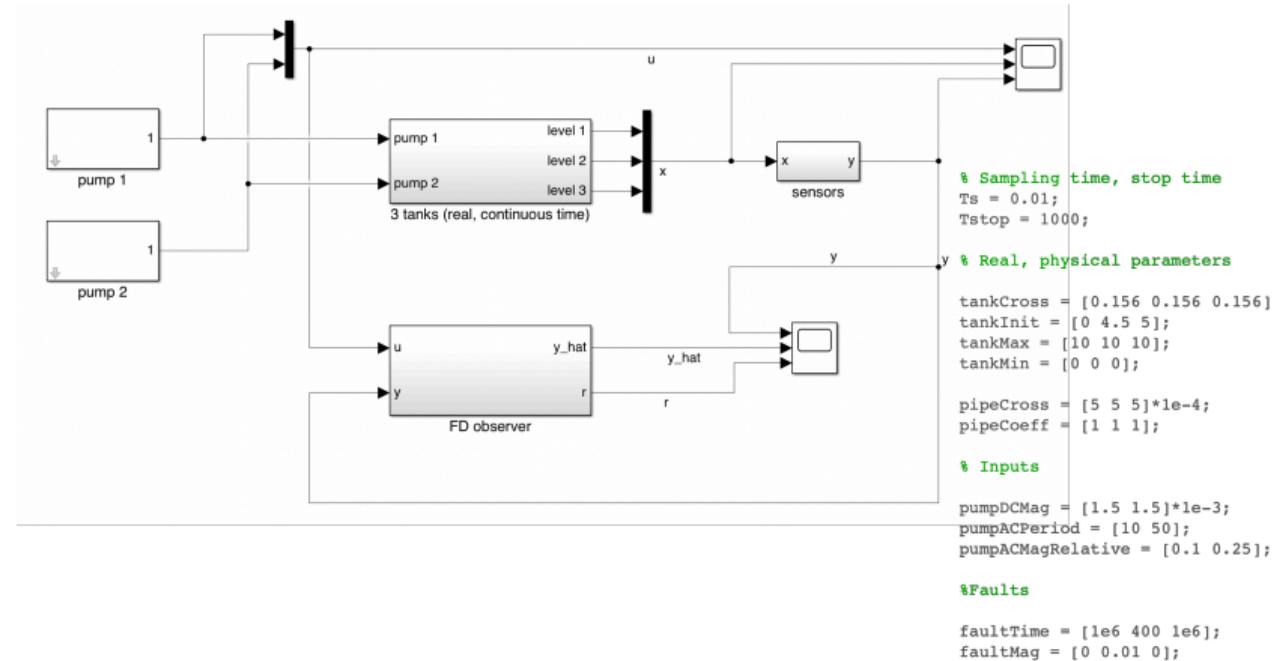
# PRE-REQUISITES

## OBSERVERS AND CONTROL SYSTEMS DESIGN



# PRE-REQUISITES

## MATLAB+SIMULINK OR PYTHON CODING AND SIMULATION OF DYNAMICAL SYSTEMS



# PRE-REQUISITES

## USEFUL RESOURCES TO INTEGRATE/BUILD UP KNOWLEDGE

### ► Books

- ▶ Stephen Lynch. *Dynamical Systems with Applications using MATLAB*. Springer, 2014, Ch. 1 to 3
- ▶ Karl Johan Åström and Richard M Murray. *Feedback systems: an introduction for scientists and engineers*. Princeton university press, 2021
- ▶ Dingyü Xue and Yang Chen. *System simulation techniques with MATLAB and Simulink*. John Wiley & Sons, 2013, Ch. 1 to 6

### ► Courses

- ▶ Control Theory (SC42015)
- ▶ Modeling of Dynamical Systems (SC42155)
- ▶ Integration Project Systems and Control (SC42035)

## COURSE DESCRIPTION

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## MOTIVATION

- ▶ Making control systems and plants **fault tolerant**
- ▶ Examples of **lack of fault tolerance** (check videos here)

### Delta II rocket



# COURSE DESCRIPTION

## MOTIVATION

- ▶ Making control systems and plants **fault tolerant**
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Delta II rocket



CaughtOnTapeTV

Mississippi bridge



# COURSE DESCRIPTION

## MOTIVATION

- ▶ Making control systems and plants **fault tolerant**
- ▶ Examples of **lack of fault tolerance** (check videos here)

Delta II rocket



Mississippi bridge



Helicopter hydraulics



# COURSE DESCRIPTION

## LEARNING GOALS

Goal	Description	Bloom's level
G1	analyse the structure of a system, carry out a Fault Tree and a Fault Modes and Effects Analysis	analyze (4)
G2	analyse and model anomalies that can occur in a given dynamical system	analyze (4)
G3	design an algorithm for detecting, isolate and identify them	create (6)
G4	design a policy for reconfiguring the control system in order to accommodate them	create (6)

# COURSE DESCRIPTION

## ORGANIZATION

- ▶ 8 weeks of lectures, **in person**
- ▶ Theory plus in-class active learning
- ▶ **Group assignment** every Thu, deadline on Tue

Day	Mon	Tue	Wed	Thu	Fri
Classes		L1		L2	
Assignment		→		→	

⇒ **enroll on Brightspace!**

# COURSE DESCRIPTION

## TOPICS

Week	Date	Module	Description	Lecture number	Instructor	Duration [h:mm]
<b>17 (4.2)</b>		<b>M1</b>	<b>Fundamentals</b>			<b>03:00</b>
	apr 22		Course Introduction	L1.1a	Rick	00:15
			Faults and failures in dynamical systems	L1.1b	Rick	00:45
			Fault diagnosis and fault tolerance	L1.2	Rick	00:30
<b>self-study ONLINE</b>	apr 24		Graphs and finite state machines	L2.1a	Rick	00:20
			Components and Services Model	L2.1b	Rick	00:40
			IN CLASS	C2.1	Rick	00:30
	apr 24		Homework	A1		
<b>18 (4.3)</b>		<b>M2</b>	<b>Structural Analysis</b>			<b>01:30</b>
	apr 29		FTA and FMEA	L2.2	Bart+Ivo	00:20
			IN CLASS	C2.2	Bart+Ivo	00:30
		<b>M3</b>	<b>Change detection algorithms</b>			<b>03:00</b>
	mag 01		Fundamentals	L3.1a	Rick	00:15
			Basic Probabilistic tests	L3.1b	Rick	00:45
			IN CLASS	C3.1	Rick	00:30
	mag 01		Homework	A2		
<b>19 (4.4)</b>						
	mag 06		Advanced probabilistic tests	L3.2	Rick	01:00
			IN CLASS	C3.2	Rick	00:30
		<b>M4</b>	<b>Signal-based fault diagnosis</b>			<b>03:00</b>
	mag 08		Time and Frequency analysis	L4.1a	Rick	00:20
			PCA	L4.1b		00:30
			Matrix Profile	L4.1c	Rick	00:20
			IN CLASS	C4.1	Rick	00:20
	mag 08		Homework	A3		

# COURSE DESCRIPTION

## TOPICS

<b>20 (4.5)</b>					
	mag 13		AI & ML for signal-based detection IN CLASS (bring your laptop)	L4.2 C4.2	Bart+Ivo Bart+Ivo
		<b>MS</b>	<b>Model-based fault diagnosis</b>		<b>03:00</b>
	mag 15		Filtering approaches Observer-based detection IN CLASS	L5.1 L5.2 C5.1	Rick Rick Rick
		mag 15	Homework	A4	
<b>21 (4.6)</b>					
	mag 20		Robust thresholds Fault isolation and learning	L5.2 L5.3	Rick Rick
			IN CLASS	C5.2	Rick
		<b>M6</b>	<b>Fault tolerant control</b>		<b>06:00</b>
	mag 22		Introduction to Fault Tolerant Control Model matching IN CLASS	L6.1 Rick C6.1	Rick Rick Rick
		mag 22	Homework	A5	
<b>22 (4.7)</b>					
	mag 27		Virtual sensors Virtual actuators	L6.2	Bart Bart
			IN CLASS	C6.2	Bart
		mag 29			
		mag 29	Homework	A6.1	

# COURSE DESCRIPTION

## TOPICS

23 (4.8)					
	giu 03	Learning-based Methods and Control Allocation for FTC	L6.3	Rick	00:20
		IN CLASS	C6.3	Rick	01:10
	giu 05	Recent advancements on adaptive methods	L6.4	Rick	00:45
		IN CLASS	C6.4		00:45
	giu 05	Homework	A6.2		

24 (4.9)	M7	Extra topics			03:00
	giu 10	ML&AI for FDI and FTC	L6.5a	Rick	00:45
		IN CLASS	C6.4		00:45
	giu 12	Cybersecurity for Industrial Control Systems		all	01:30

# COURSE DESCRIPTION

## ASSESSMENT

Element	Weight
Homework (group assignments)	30%
Final exam (written, individual test)	70%

## RESOURCES AND TOOLS

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## BOOKS

- ▶ Mogens Blanke et al. *Diagnosis and fault-tolerant control*. Vol. 2. Springer, 2006
- ▶ Rolf Isermann. *Fault-diagnosis systems: an introduction from fault detection to fault tolerance*. Springer Science & Business Media, 2006
- ▶ Michele Basseville, Igor V Nikiforov, et al. *Detection of abrupt changes: theory and application*. Vol. 104. prentice Hall Englewood Cliffs, 1993
- ▶ Jie Chen and Ron J Patton. *Robust model-based fault diagnosis for dynamic systems*. Vol. 3. Springer Science & Business Media, 2012
- ▶ Steven X Ding. *Model-based fault diagnosis techniques: design schemes, algorithms, and tools*. Springer Science & Business Media, 2008
- ▶ George J Vachtsevanos et al. *Intelligent fault diagnosis and prognosis for engineering systems*. Vol. 456. Wiley Hoboken, 2006

# RESOURCES AND TOOLS

## SOFTWARE AND TOOLS

- ▶ Coding and simulation
  - ▶ Matlab and Simulink
- ▶ Material dissemination, news, assignments
  - ▶ Brightspace
- ▶ Online collaboration
  - ▶ Microsoft Teams

<https://teams.microsoft.com/l/team/19%3ANx4HYIHLf05fQcLtQHmQ00PxI80shJJKvs2FTM6o0hg1%40thread.tacv2/conversations?groupId=49107539-c634-4f20-9012-495b83cdc3aa&tenantId=096e524d-6929-4030-8cd3-8ab42de0887b>

# RESOURCES AND TOOLS

## STAFF



**Course Responsible Instructor:** Dr. Riccardo Ferrari

**Email:** r.ferrari@tudelft.nl

**Teaching on:** Tuesdays + Thursdays  
(some)



**Teaching Assistants:** Bart Wolleswinkel,  
Ivo van Straalen

**Email:** B.Wolleswinkel@tudelft.nl,  
i.vanstraalen@tudelft.nl

**Teaching on:** Thursdays

# CONCLUSION

# CONCLUSION

## IN THIS LECTURE WE COVERED

- ▶ Pre-requisites
- ▶ Course **description**
- ▶ Learning goals
- ▶ Structure and dates
- ▶ Assessment
- ▶ Resources and tools
- ▶ Staff and support

# CONCLUSION

THANK YOU FOR YOUR ATTENTION!

For further information:

Course page on [Brightspace](#)

or

our [MS Team](#)

# REFERENCES |

-  Karl Johan Åström and Richard M Murray. *Feedback systems: an introduction for scientists and engineers*. Princeton university press, 2021.
-  Mogens Blanke et al. *Diagnosis and fault-tolerant control*. Vol. 2. Springer, 2006.
-  Michele Basseville, Igor V Nikiforov, et al. *Detection of abrupt changes: theory and application*. Vol. 104. prentice Hall Englewood Cliffs, 1993.
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# REFERENCES II

-  Rolf Isermann. *Fault-diagnosis systems: an introduction from fault detection to fault tolerance*. Springer Science & Business Media, 2006.
-  Stephen Lynch. *Dynamical Systems with Applications using MATLAB*. Springer, 2014.
-  George J Vachtsevanos et al. *Intelligent fault diagnosis and prognosis for engineering systems*. Vol. 456. Wiley Hoboken, 2006.
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