

# FUNDAMENTALS — FAULT DIAGNOSIS AND FAULT TOLERANCE —

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*Lecture 1.2*  
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# LECTURE SUMMARY

What are we going to talk about today ?

- > A taxonomy of different kind of **FD approaches**
- > A taxonomy of different kind of **FT approaches**

# FAULT DIAGNOSIS

An overview of different approaches

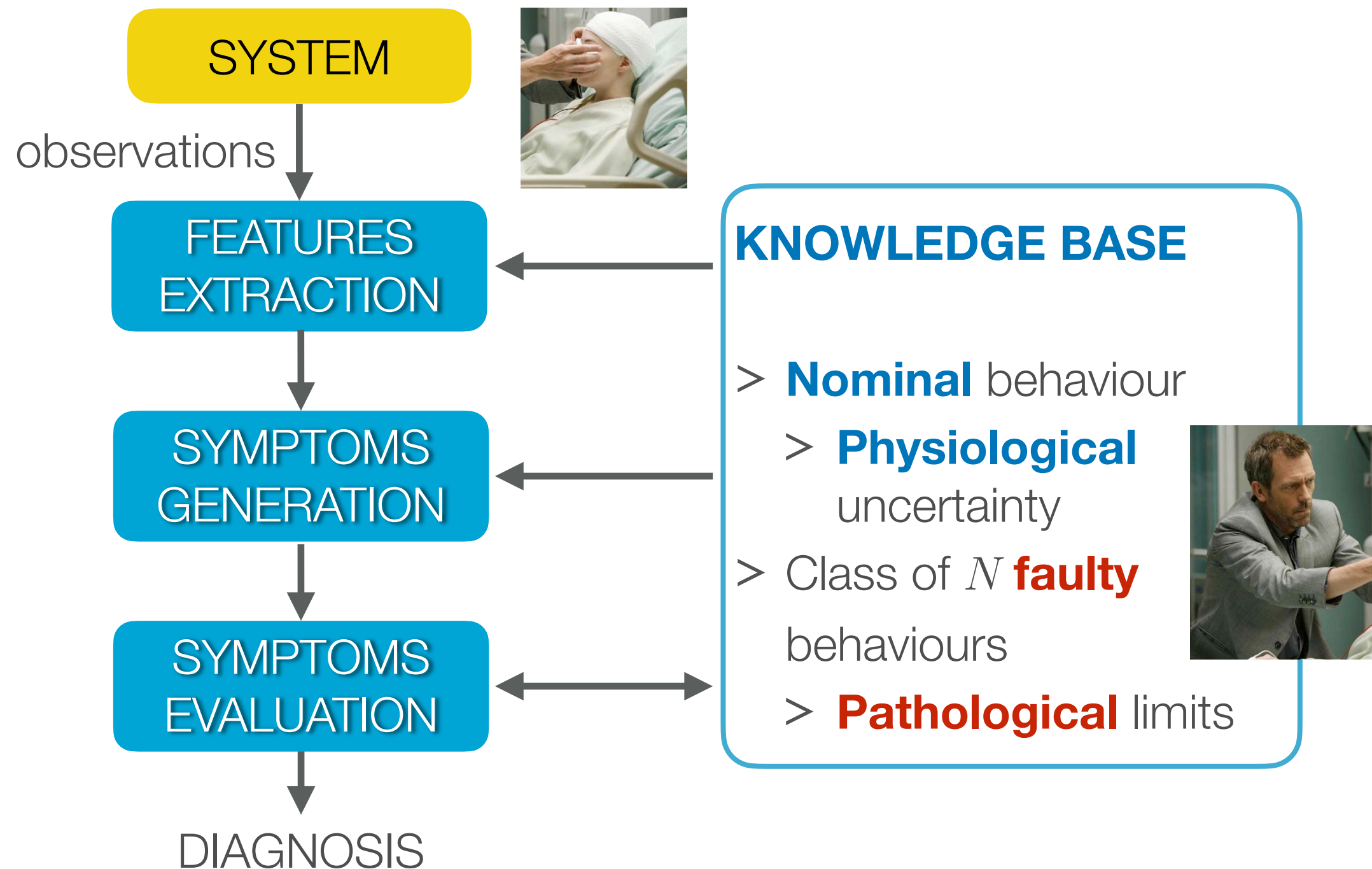
# FAULT DIAGNOSIS

It is not that much different from medical diagnosis!



# FAULT DIAGNOSIS

Whatever approach you use, this is the common structure of FD



# FAULT DIAGNOSIS

Feature extraction is different according to the FD approach

Signal based

Model based

# FAULT DIAGNOSIS

Feature extraction is different according to the FD approach

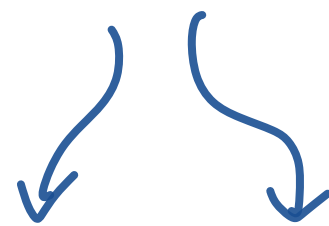
## Signal based

- Raw signal
- Mean or std over moving window
- Peak values
- Fourier transform, STFT, Wavelet, ...
- Cepstrum
- Cuntosis
- ...

## Model based

- (Kalman) observer estimation error
- Parity relations error
- Model parameters estimate

E.g.  $\ddot{x} = -\underline{k}x - \underline{b}\dot{x}$



# FAULT DIAGNOSIS

## Symptoms generation

- > From Wikipedia (sorry, but they actually have a good definition)

“A **symptom** (from Greek σύμπτωμα, "accident, misfortune, that which befalls", [...]) is a **departure** from **normal** function or feeling”

- > In FD, a **symptom** is a measure of the **difference** between **actual** value of **features** extracted from observations, and **nominal** ones

Signal based

Model based



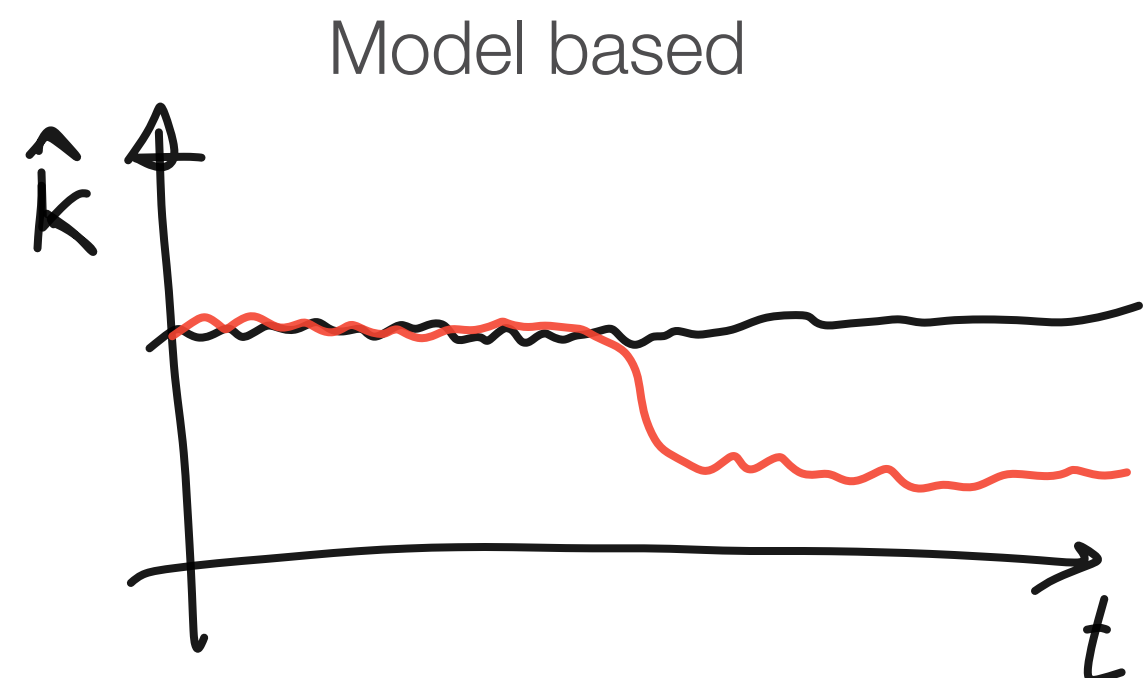
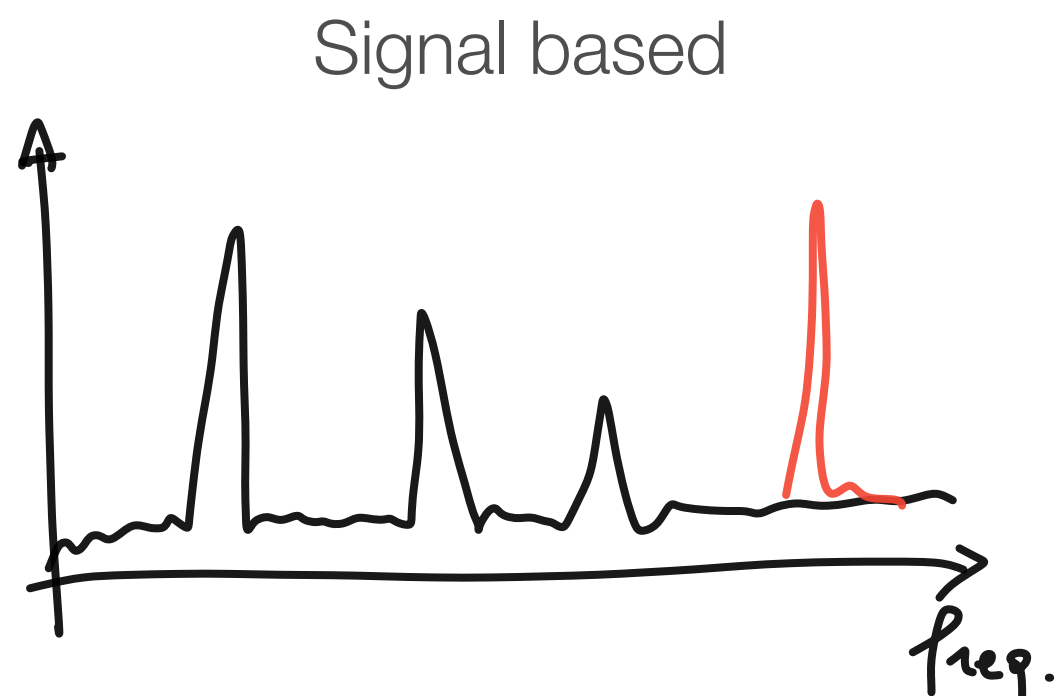
# FAULT DIAGNOSIS

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# FAULT DIAGNOSIS

## Symptoms evaluation

- > **Physiological** changes shall be **ignored**, but **pathological** changes are **evaluated** in the next step
- > A **measure** of a **symptom** is so **compared** against a known **pathological threshold**
- > In general, this is a **change detection problem** (more in upcoming lectures)

# FAULT DIAGNOSIS

Once symptoms evaluation is done, diagnosis entails:

> STEP 1: **DETECTION**

> Testing the **null hypothesis**:

$\mathcal{H}_0$ : “Is the system behaving in a **nominal** way?”

> STEP 2: **ISOLATION**

> Testing  $N$  **faulty hypotheses**:

$\mathcal{H}_i$ : “Is the system behaving as if the ***i*-th fault** is present?”

> STEP 3: **IDENTIFICATION/ESTIMATION**

> If  $\mathcal{H}_0$  and every but one  $\mathcal{H}_i$  are falsified  $\Rightarrow$  **estimate** parameters of  $i$ -th fault

> If  $\mathcal{H}_0$  and every  $\mathcal{H}_i$  are falsified  $\Rightarrow$  **identify** model of a new fault

# FAULT TOLERANCE



# FAULT TOLERANCE

## Different approaches to fault tolerance

By design

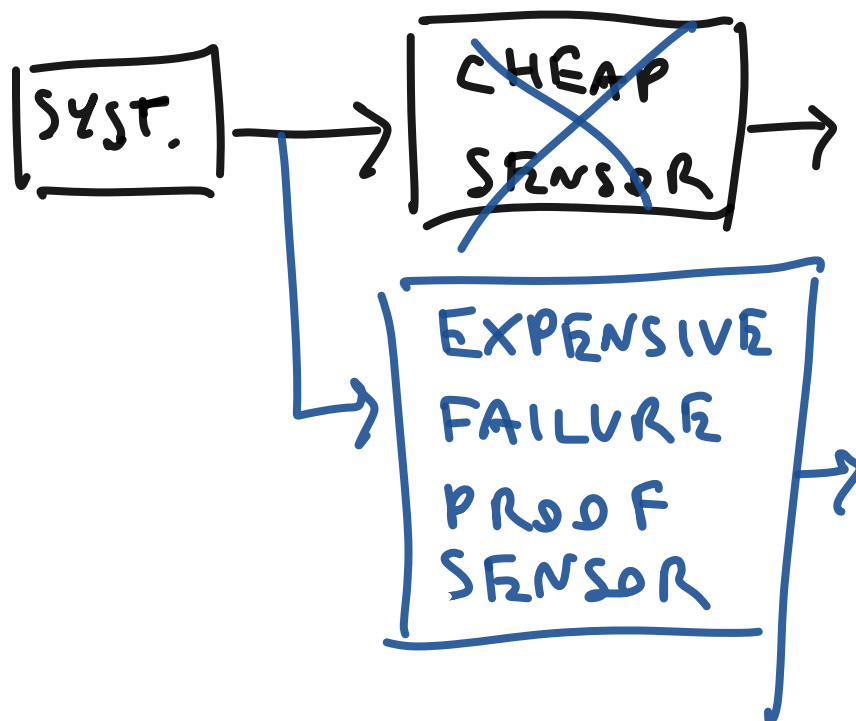
Switching

Adaptive

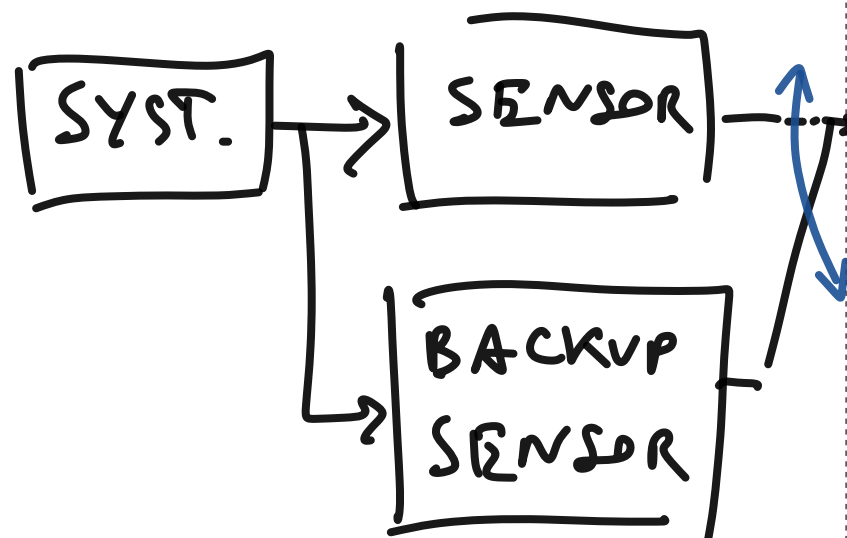
# FAULT TOLERANCE

## Different approaches to fault tolerance

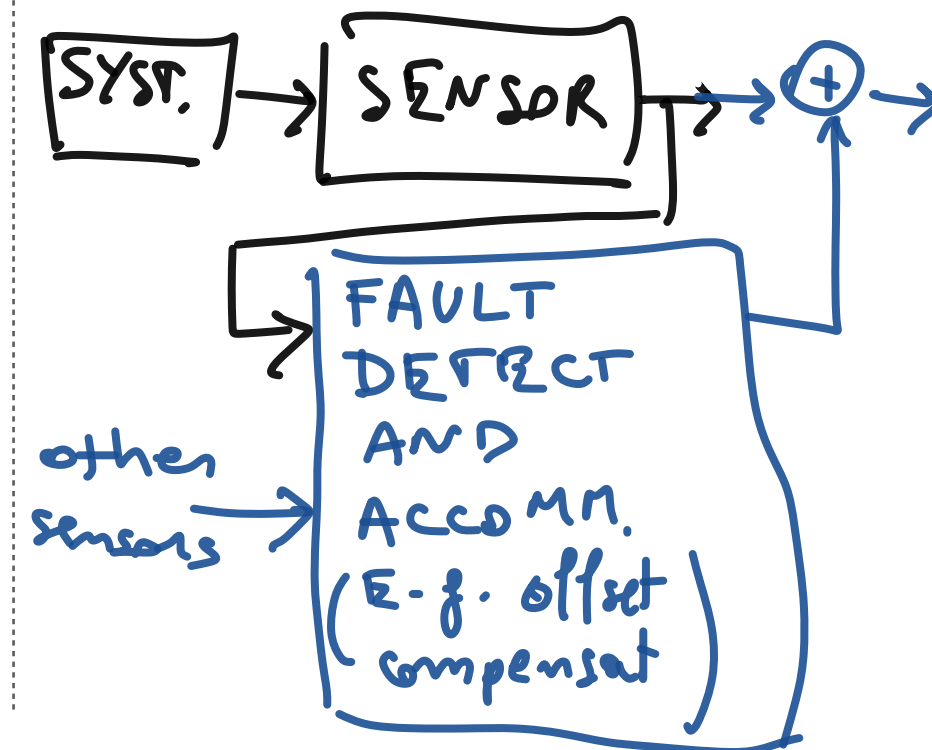
By design



Switching



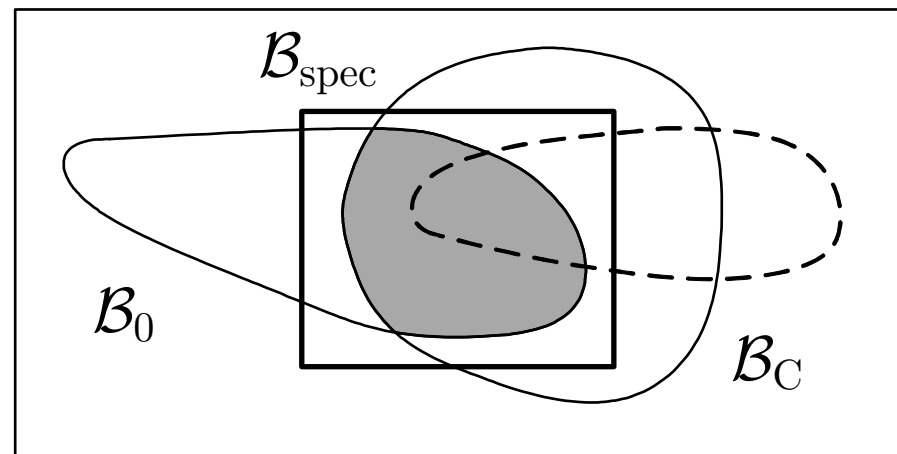
Adaptive



# FAULT TOLERANCE

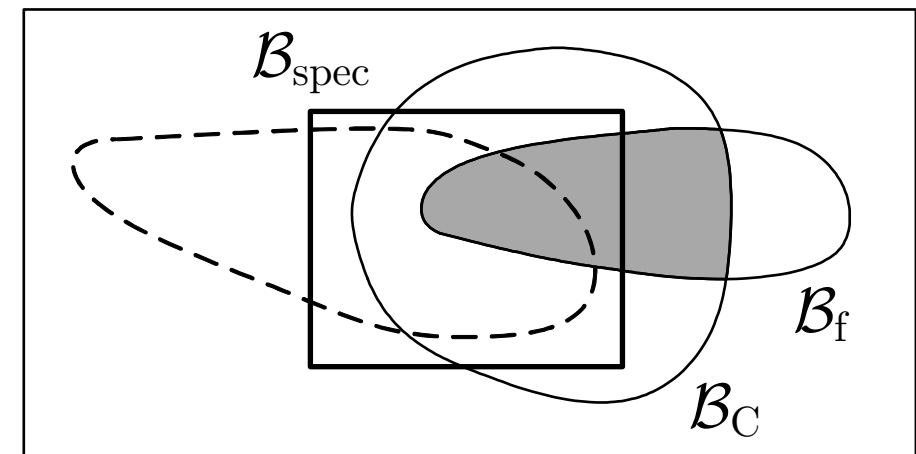
Fault accommodation: remember the behaviour diagram?

Control of the faultless system

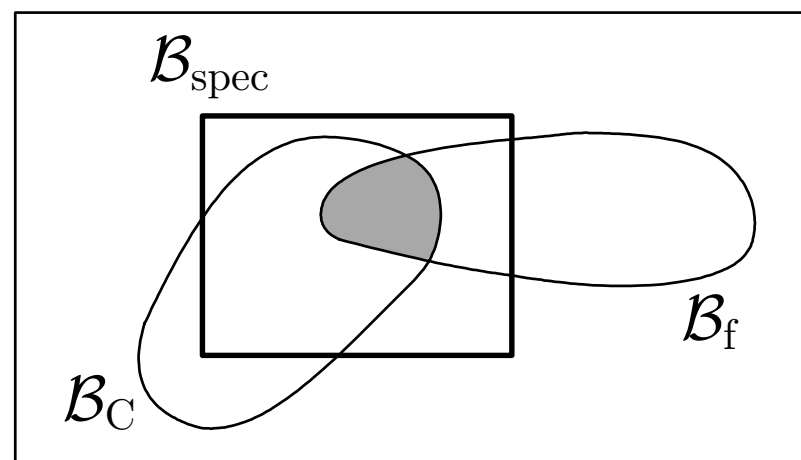


FAULT

Control of the faulty system



ACCOMMODATION



# CONCLUSION

Recap of this lecture and plan for next

## > **TODAY**

- > We introduced an **overview** of FD and FT
- > We introduced **definitions**
- > We provided some **taxonomy** of existing approaches

## > **TOMORROW**

- > **System structural analysis and components and services model**



# CONCLUSION

Thank you for your attention !

For further information:

Course page on Brightspace

or

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