

STRUCTURAL ANALYSIS

COMPONENTS AND SERVICES MODEL

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LECTURE SUMMARY

1. Components and Services Model

2. Conclusions

COMPONENTS AND SERVICES MODEL

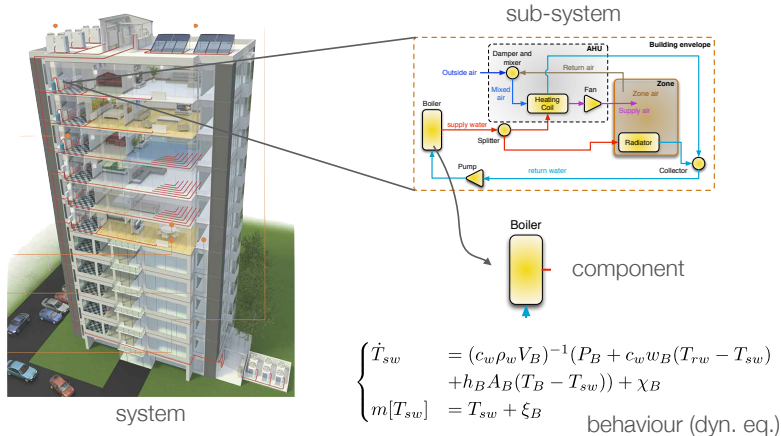
COMPONENTS AND SERVICES MODEL

WHY DO WE NEED THE COMPONENTS AND SERVICES MODELS?

- ▶ To **organise knowledge** of the system (nominal behaviour) in a **hierarchical** way
- ▶ To allow for **fault propagation** and **effects**, and **root causes analysis** (see next lecture)

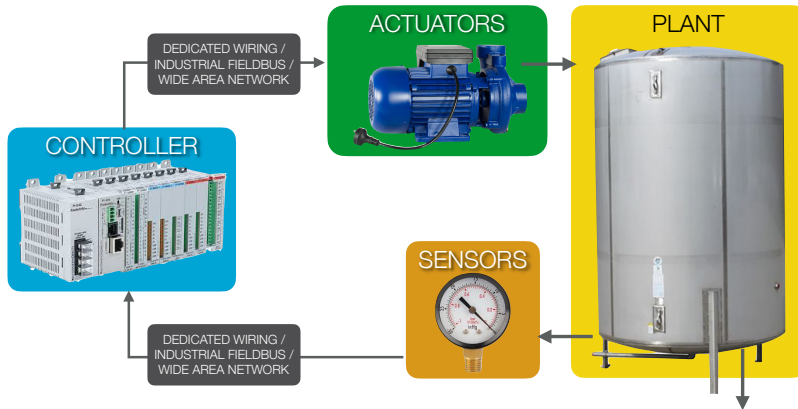
COMPONENTS AND SERVICES MODEL

AN EXAMPLE FROM SMART BUILDINGS



COMPONENTS AND SERVICES MODEL

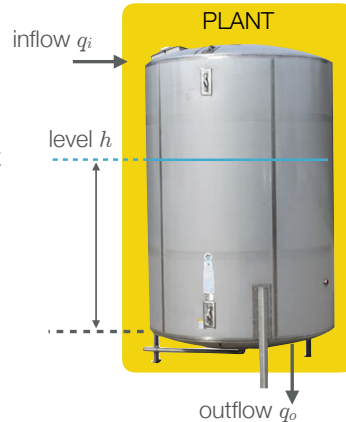
LET US RECALL THE TANK EXAMPLE



COMPONENTS AND SERVICES MODEL

THE TANK ITSELF IS A COMPONENT

- ▶ **Components** provide **services**
- ▶ A **tank integrates** inflow minus outflow to **produce** a stored mass \Rightarrow a level h
- ▶ It **requires**: a vessel, an input and an output pipe
- ▶ A tank will **always provide** such service, if required resources are connected and healthy (i.e. no electric power or control commands needed)



COMPONENTS AND SERVICES MODEL

THE TANK ITSELF IS A COMPONENT

- ▶ A **service** s is described by a **6-tuple**

$$s = (\text{cons}, \text{prod}, \text{proc}, \text{rqst}, \text{enable}, \text{res})$$

$$\text{cons} = \{q_i, q_o\}$$

$$\text{prod} = \{h\}$$

$$\text{proc} = \left\{ \dot{h} = q_i - q_o, h = \int \dot{h} dt \right\}$$

$$\text{rqst} = \{1\}$$

$$\text{enable} = \{1\}$$

$$\text{res} = \{\text{vessel}, \text{pipes}\}$$



COMPONENTS AND SERVICES MODEL

SERVICES COME IN DIFFERENT VERSIONS

- ▶ For example, an **electric multimeter** offers different **voltage measurement services**
- ▶ They differ according to measurable **range**, **resolution** and **accuracy**



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AVAILABILITY OF SERVICES DEPENDS ON COMPONENT USE MODE

- For example, a wireless speaker can have the following use modes:

{ off, disconnected, pairing, connected }

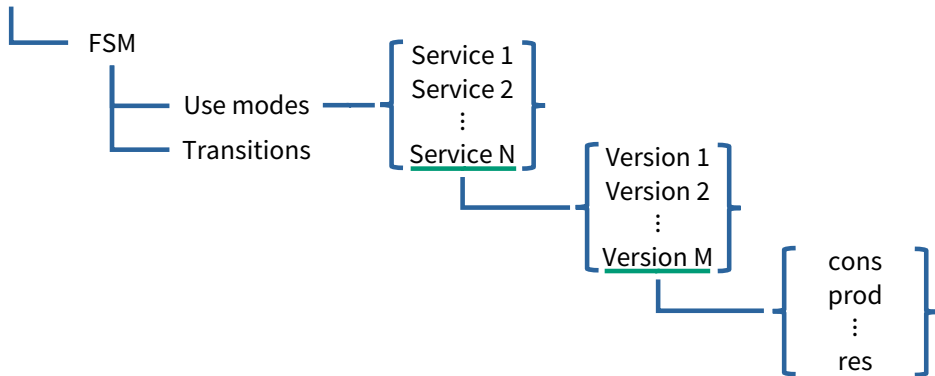
- The service *playing music* is available only in *connected* mode




COMPONENTS AND SERVICES MODEL

GENERAL COMPONENT MODEL

COMPONENT



 Mogens Blanke et al. *Diagnosis and fault-tolerant control*. Vol. 2. Springer, 2006, Ch.4

COMPONENTS AND SERVICES MODEL

GENERAL COMPONENT MODEL

$\langle \text{component } k \rangle ::= \langle \text{state transition graph } G(M(k), \tau(k), m^0(k)) \rangle$

$\langle M(k) \rangle ::= \langle \text{set of use-modes } \{m_i(k), i \in I_m(k)\} \rangle$

$\langle \tau(k) \rangle ::= \langle \text{set of transitions } \{\tau_{ij}(k), i, j \in I_m(k)\} \rangle$

$\langle m^0(k) \rangle ::= \langle \text{initial use-mode} \rangle$

$\langle \text{use-mode } m_i(k) \rangle ::= \langle \text{set of services } S_i(k) \subseteq S(k) \rangle$

$\langle \text{service } s_l(k) \rangle ::= \langle \text{pre-ordered versions}$

$\left\{ s_l^j(k), j \in J(s_l(k)) \right\} \rangle$

$\langle \text{version } s_l^j(k) \rangle ::= \langle \text{consumed vars } cons_l^j(k),$
 $\text{produced vars } prod_l(k),$
 $\text{procedures } proc_l^j(k), \text{ request } rqst_l(k),$
 $\text{activation cond. } activ_l^j(k),$
 $\text{hardware and software resources } res_l^j(k) \rangle$

$\langle \text{transition } \tau_{ij}(k) \rangle ::= \langle \text{condition } c_{ij}(k), \text{ origin } m_i(k),$
 $\text{destination } m_j(k) \rangle .$

 Mogens Blanke et al. *Diagnosis and fault-tolerant control*. Vol. 2. Springer, 2006, Ch.4

COMPONENTS AND SERVICES MODEL

HOW DO WE USE COMPONENTS AND SERVICES MODELS?

- ▶ For **fault diagnosis**
 - ▶ Assuming components can be either **healthy** or **faulty** \Rightarrow **root cause analysis** and **propagation analysis**
 - ▶ See next lecture on FTA and FMEA
- ▶ For **fault accommodation** via **switching** of hardware redundant components
- ▶ Remember the example from the Mars landing from lecture 1?

CONCLUSIONS

CONCLUSIONS

IN THIS LECTURE WE COVERED

- Components and services model

Next lecture: **FTA (Fault Tree Analysis) and FMEA (Fault Modes and Effects Analysis)**

CONCLUSIONS

THANK YOU FOR YOUR ATTENTION!

For further information:
Course page on [Brightspace](#)
or
our [MS Team](#)