#### Formulation

The goal is to express quantum mechanics in a new way with geometric algebra in order to get an understanding for space and spin.

The wavefunction can be expressed as

$$\Psi = \sum_i rac{1}{\sqrt{2}} (e_i + J f_i) (\mathfrak{R} \psi_i + J \, \mathfrak{I} \psi_i)$$

where  $e_i, f_i$  are orthonormal vectors which square to +1,  $J=e_0f_0$  is an independent bivector, and  $\psi_i$  are the complex valued components of the wave vector. This makes the wave function an odd-grade multivector.

For a spin-1/2 particle space coordinates will come out as

$$egin{aligned} X &= rac{1}{2}(e_1f_2 + e_2f_1) \ Y &= rac{1}{2}(e_1e_2 + f_1f_2) \ Z &= rac{1}{2}(e_2f_2 - e_1f_1) \end{aligned}$$

which means that space rotations can be derived in this basis.

# Observation in quantum mechanics

The probability  $P=|\langle \psi_1|\psi_2\rangle|^2$  to measure a state  $\psi_1$  in a state  $\psi_2$  can be calculated from

$$egin{aligned} P(1
ightarrow2) &= \langle (1-\Psi_1\Psi_1^\dagger)(1-\Psi_2\Psi_2^\dagger)
angle \ &= \langle \Psi_1\Psi_1^\dagger\Psi_2\Psi_2^\dagger
angle -1 \end{aligned}$$

which is an inner product between two state multivectors of the form  $\Psi\Psi^{\dagger}.$ 

# Unitary transformation

A unitary transformation of the wavefunction can be represented as a rotor in geometric algebra. Note that the same rotor can be applied to  $\Psi$  or  $\Psi\Psi^{\dagger}$ .

# Single spin

The wavefunction for a single spin-up in a direction given by Euler angles  $\theta, \phi$  is usually written as

$$\psi = egin{pmatrix} \cosrac{ heta}{2} \ \sinrac{ heta}{2}e^{i\phi} \end{pmatrix}$$

up to an arbitrary phase.

Written in geometric algebra this is

$$egin{aligned} J\Psi\Psi^\dagger &= J + e_1f_1\cos^2rac{ heta}{2} + e_2f_2\sin^2rac{ heta}{2} \ &+ (e_1f_2 + e_2f_1)\cosrac{ heta}{2}\sinrac{ heta}{2}\cos\phi \ &+ (e_1e_2 + f_1f_2)\cosrac{ heta}{2}\sinrac{ heta}{2}\sin\phi \end{aligned}$$

(see derivation in appendix).

$$egin{aligned} J\Psi\Psi^{\dagger} &= J + e_1 f_1 rac{1 - \cos heta}{2} + e_2 f_2 rac{1 + \cos heta}{2} \ &+ (e_1 f_2 + e_2 f_1) rac{1}{2} \sin heta\cos\phi \ &+ (e_1 e_2 + f_1 f_2) rac{1}{2} \sin heta\sin\phi \ &= J + rac{1}{2} (e_1 f_1 + e_2 f_2) \ &+ rac{1}{2} (e_2 f_2 - e_1 f_1) \cos heta \ &+ rac{1}{2} (e_1 f_2 + e_2 f_1) \sin heta\cos\phi \ &+ rac{1}{2} (e_1 e_2 + f_1 f_2) \sin heta\sin\phi \end{aligned}$$

Remembering that we have Euler angles, we can identify the multivectors for space coordinates from this expression for a single spin

$$egin{aligned} X &= rac{1}{2}(e_1f_2 + e_2f_1) \ Y &= rac{1}{2}(e_1e_2 + f_1f_2) \ Z &= rac{1}{2}(e_2f_2 - e_1f_1) \end{aligned}$$

They are orthogonal (e.g.  $\langle XY \rangle = 0$ ) and obey

$$With\$z_i=\Re\psi_i+J\Im\psi_i\$$$

### \begin{align

\Psi\Psi^\dagger&=\frac{1}{2}\sum{ij}(e\_i+Jf\_i)z\_iz\_j^\dagger(e\_j-Jf\_j)\

&=\sum\_i (1-e\_if\_iJ)z\_iz\_i^\dagger\

&\quad+\frac{1}{2}\sum{i<j}\left((ei+Jf\_i)(e\_j-Jf\_j)z\_iz\_j^\dagger+(e\_j+Jf\_j)(e\_i-

Jf\_i)z\_jz\_i^\dagger\right)\

&=\sum i(1-e if iJ)z iz i^\dagger\

 $\& \quad + \frac{1}{2} \cdot \frac{1}{2} \cdot \frac{j^{-(e_if_j + e_jf_i)J \cdot right)z_iz_j^{dagger \cdot e_if_j + e_jf_i)J \cdot right)z_iz_j^{dagger \cdot e_if_j + e_jf_i}}{2}$ 

&\quad+\frac{1}{2}\sum{i<j}\left(e\_je\_i+f\_jf\_i-(e\_jf\_i+e\_if\_j)J\right)z\_jz\_i^\dagger

\end{align}

#### With the real and imaginary parts

### \begin{align

R{ij}&=\frac{1}{2}(z\_iz\_j^\dagger+z\_jz\_i^\dagger)\

JI{ij}&=\frac{1}{2}(ziz\_j^\dagger-z\_jz\_i^\dagger)\

 $z_iz_j^{\adjustering} = R\{ij\} + J_i\{ij\}^{\adjustering}$ 

z\_jz\_i^\dagger&=R{ij}-J,I\_{ij}

\end{align}

# $where \$R_{ij}, I_{ij}\$ are scalars this becomes$

### \begin{align

\Psi\Psi^\dagger&=\sumi (1-e if iJ)z iz i^\dagger\

&\quad+\frac{1}{2}\sum{i<j}\left(eie\_j+f\_if\_j-(e\_if\_j+e\_jf\_i)J\right)(R{ij}+J,I{ij})\

 $\alpha + \frac{1}{2}\sum_{i=1}^{n} \left( \frac{1}{2}\sum_{i=1}^{$ 

&=\sum i z iz i^\daaaer-\sum i e if iJz iz i^\daaaer\

&\quad-\sum{i<j}(eif\_j+e\_jf\_i)JR{ij}\

&\quad+\sum{i<j}(e ie j+f if j)J,I{ij}

\end{align}

#### For normalized wave vectors

 $\label{langle PsiPsi^dagger} \$ 

### Therefore

### \begin{align

J\Psi\Psi^\dagger&=J+\sumi e\_if\_iz\_iz\_i^\dagger+\sum{i<j}(eif\_j+e\_jf\_i)R{ij}

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