## CSC 211: Computer Programming

Sorting Algorithms, Binary Search, Big-O

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Fall 2024



# Basic Sorting Algorithms

#### Administrative Announcements

- MC05 due 11/08
- Exam#02 ~ Tuesday, November 12th
  - ✓ Same time / place as lecture
  - ✓ One 11x8 notes sheet
  - √ No calculator
  - √ Weeks 6 10
- A04 due 11/17

## Sorting and Searching

- Two fundamental problems in CS
  - ✓ Sorting and Searching

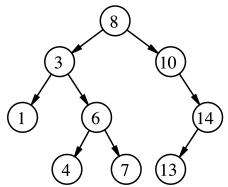
## Sorting

- Given an input sequence of **n** elements that can be compared to each other according to a **total order** relation
  - we want to rearrange them in non-increasing/non-decreasing order
- Example (sorting in non-decreasing order):
  - **input**: array  $A = [k_0, k_1, ..., k_{n-1}]$
  - **output**: array B (permutation of A), s.t.  $B[0] \leq ... \leq B[n-1]$

Central problem in computer science

## Searching

Given some data structure S, determine if some key
 K exists



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## Efficiency

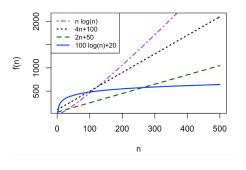
- We'll talk about efficiency in CSC 212. Why do we care?
- Computers are fast, but they can still take time to do complex actions.
- A major goal of computer scientists is not just to make algorithms that work, but algorithms that work efficiently.

#### **Function Families**

- When we count the actions taken by algorithms, we don't really care about one-off operations; we care about actions that are related to the size of the input.
- In math, a **function family** is a set of equations that all grow at the same rate as their inputs grow. (linearly v.s quadratically)
- When determining which equation family represents the actions taken by an algorithm, we say that n is the size of the input.

#### **Function Families**

As n grows, the two linear functions become larger than the log(n) function, and then the n log(n) function becomes larger than both linear functions, regardless of the constants.



## **Big-O Notation**

• When we determine an equation's function family, we ignore constant factors and smaller terms. All that matters is the dominant term (the highest power of n). That is the idea of Big-O notation.

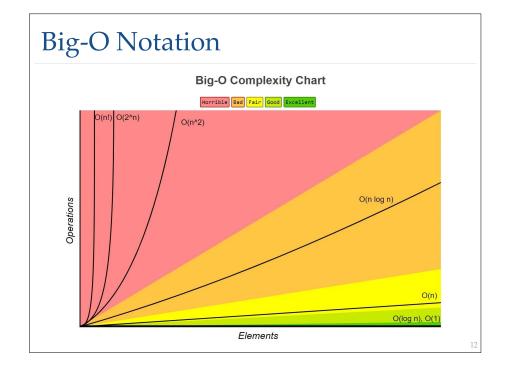
f(n)	Big-O
n	O(n)
32n + 23	O(n)
5n <sup>2</sup> + 6n - 8	O(n²)
18 log(n)	O(log n)

10

## **Big-O Notation**

- Unless specified otherwise, the Big-O of an algorithm refers to its worst case run time
- · "Asymptotic Complexity" of algorithm

f(n)	Big-O
n	O(n)
32n + 23	O(n)
5n² + 6n - 8	O(n²)
18 log(n)	O(log n)



#### **Bubble-Sort**

- Basic sorting algorithm
  - ✓ yet too slow in practice
- Scan the input sequence from left-to-right
  - compare all adjacent elements and swap them if they are in the wrong order
- Repeat the scan until the list is sorted

After every pass (iteration), the smaller/larger element bubbles up to the end of the sequence

# Bubble Sort in 2

14

## Implement Bubble Algorithm

```
BUBBLESORT(A)

1 for i=1 to A.length-1

2 for j=A.length downto i+1

3 if A[j] < A[j-1]

4 exchange A[j] with A[j-1]

void swap(int& v1, int& v2) {

int temp = v1;

v1 = v2;

v2 = temp;

}
```

#### Selection-Sort

- Basic sorting algorithm
  - ✓ yet too slow in practice
- ' Keep two parts: **left part** is already sorted and **right part** is to be sorted
  - initially, the sorted part is empty and the unsorted part is the input sequence
- At every iteration, find the smallest (or largest) element in the unsorted part and swap it with the leftmost unsorted element
  - ' then move the boundary between parts one element to the right

At every iteration we select the minimum/maximum

Selection Sort in 3

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## Implement Selection Algorithm

```
1: function SELECTION-SORT(A, n)
2: for i = 1 to n-1 do
3: min \leftarrow i
4: for j = i + 1 to n do
5: if A[j] < A[min] then
6: min \leftarrow j
7: end if
8: end for
9: swap A[i], A[min]
10: end function
```

```
void swap(int& v1, int& v2) {
    int temp = v1;
    v1 = v2;
    v2 = temp;
}

int find_min(int A[], int start, int last) {
    int min = start;
    for (int i = start + 1; i < last; i++) {
        if (A[i] < A[min]) {
            min = i;
        }
    }
    return min;
}

void selection(int A[], int n_elem) {
    for (int i = 0, j; i < (n_elem-1); i ++) {
        j = find_min(A, i, n_elem);
        swap(A[i], A[j]);
    }
}

int main() {
    int array[] = {15, 12, 13, 24, 5};
    selection(array, 5);
}</pre>
```

#### **Insertion-Sort**

- Basic sorting algorithm
  - ✓ slightly faster than bubble-sort and selection-sort
- Keep two parts: **left part** is already sorted and **right part** is to be sorted
  - ' initially, the sorted part contains the first element in the array and the unsorted part is the remaining elements
- At every iteration, the first element of the unsorted part is selected, and the algorithm finds the location it belongs within the sorted part, and inserts it there
  - ' then move the boundary between parts one element to the right
  - repeat until no elements remain in the unsorted part

Insertion Sort in 2

2

## Implement Insertion Algorithm

```
ALGORITHM InsertionSort(A[0..n-1])

//Sorts a given array by insertion sort

//Input: An array A[0..n-1] of n orderable elements

//Output: Array A[0..n-1] sorted in nondecreasing order

for i \leftarrow 1 to n-1 do

v \leftarrow A[i]
j \leftarrow i-1

while j \geq 0 and A[j] > v do

A[j+1] \leftarrow A[j]
j \leftarrow j-1
A[j+1] \leftarrow v
```

Binary Search

#### Linear search

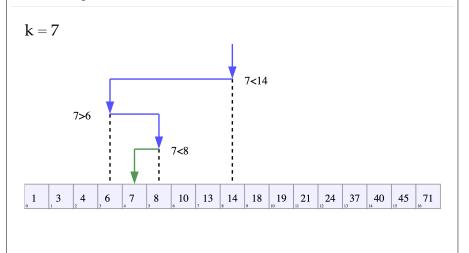
- Two fundamental problems in CS
  - √ Sorting and Searching
- Linear (sequential) search is a method for finding a value within a sequence
- A naive solution works by sequentially checking each element until a match is found
  - ✓ it also stops when there are no more elements to check
  - √ performs at most **n** comparisons for sequences of length **n**
  - ✓ considered slow for finding elements in collections of data

```
bool lin_search(int *A, int key, int len) {
    for (int i = 0 ; i < len; i++){
        if (A[i] == key){
            return true;
            }
        }
        return false;
}</pre>
```

## Binary search

- Search algorithm to find a given value within a sorted array
- The algorithm compares the value to the middle element
  - if they are not equal, one of the half is eliminated and the search continues on the other half
  - repeat until value is found or no more elements are left (value is not in the array)
- · Binary search is faster than linear search

## Binary search



## Binary Search

low high

k = 48?

## Binary Search

 1
 2
 3
 4
 5
 6
 7
 8
 9
 10
 11
 12

 1
 2
 5
 10
 15
 20
 22
 30
 35
 40
 43
 48
 51

low mid high

k = 48?

## Binary Search



low high

k = 48?

## Binary Search

 8
 1
 2
 3
 4
 5
 6
 7
 8
 9
 10
 11
 12

 1
 2
 5
 10
 15
 20
 22
 30
 35
 40
 43
 48
 51

low mid high

k = 48?

```
Binary Search
                     22
                         30
                            35
        5
           10
               15
                  20
                                40
                                   43
                                       48
                                          51
low
                                          high
k = 22?
k = 0?
k = 55?
```

```
// returns index of element k in A
// returns NOT_FOUND if element not in A
int bin_search(int *A, int lo, int hi, int k) {
    // base case
   if (hi < lo) {
        return NOT_FOUND;
    // calculate midpoint index
   int mid = lo + ((hi-lo)/2);
    // key found?
    if (A[mid] == k) {
        return mid;
    // key in upper subarray?
    if (A[mid] < k) {
        return bin_search(A, mid+1, hi, k);
    // key is in lower subarray?
    return bin_search(A, lo, mid-1, k);
```

```
Call stack
             2
                          10
                                 15
                                        20
                                               22
                                                       30
                                                              35
                                                                     40
#define NOT_FOUND -1
int bsch(int *A, int lo, int hi, int k) {
    if (hi < lo) {</pre>
        return NOT_FOUND;
    int mid = lo + ((hi-lo)/2);
    if (A[mid] == k) {
        return mid;
    if (A[mid] < k) {
        return bsch(A, mid+1, hi, k);
    return bsch(A, lo, mid-1, k);
int main() {
    int arr[] = \{1,2,5,10,15,20,22,30,35,40\};
    int idx = bsch(arr, 0, 9, 1);
}
                               https://bit.ly/36cEQWK
```



The latest news from Research at Google

"The version of binary search that I wrote for the JDK (java.util.Arrays) contained the same bug. It was reported to Sun recently when it broke someone's program, after lying in wait for nine years or so."

Extra, Extra - Read All About It: Nearly All Binary Searches and Mergesorts are Broken

Friday, June 02, 2006

Posted by Joshua Bloch, Software Engineer

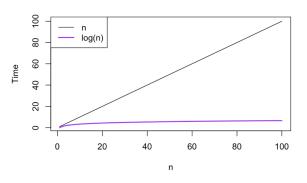
overflow

int mid = (low + high) / 2;

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## Big-O of Linear Search v. Binary Search

• Because runtime for linear search is proportional to the length of the list in the worst case, it is O(n). Every time we double the length of the list, binary search does just one more comparison; it is O(log n).



Unimodal arrays

 An array is (strongly) unimodal if it can be split into an increasing part followed by a decreasing part

1 2 5 16 20 18 17 16 15 12 10 8 5

 An array is (weakly) unimodal if it can be split into a nondecreasing part followed by a nonincreasing part



Find peak in unimodal arrays

#### Find the peak (strongly unimodal) 15 | 20 | 22 | 20 | **20 15 12** 15 | 20 | 15 | 20 | 22 20 22 20 20 22 20 15 | 20 | 22 20 15 20 22 20 15 20 22 20

