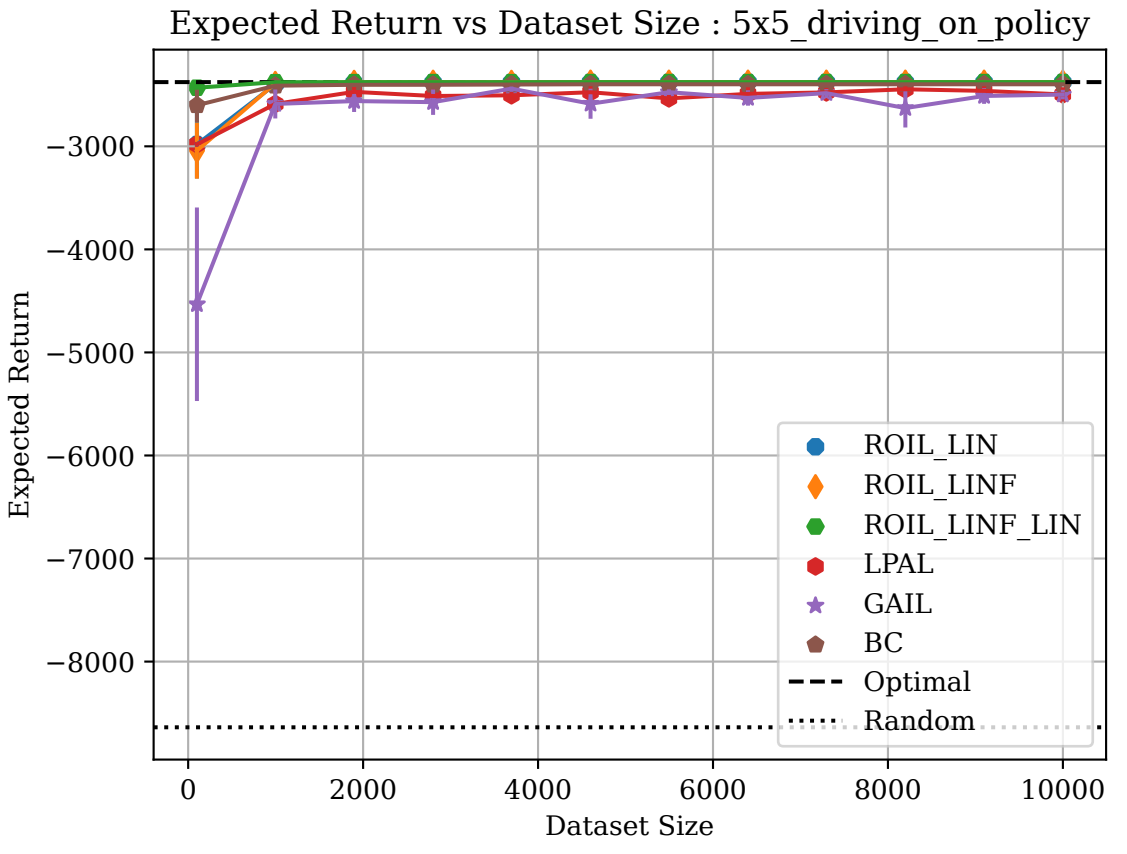
Expected Return vs Dataset Size : 5x5_driving_on_policy
Expected Return
−3000
−4000
−5000
−6000
−7000
−8000
0
2000
4000
6000
8000
10000
Dataset Size
ROIL_LIN
ROIL_LINF
ROIL_LINF_LIN
LPAL
GAIL
BC
Optimal
Random