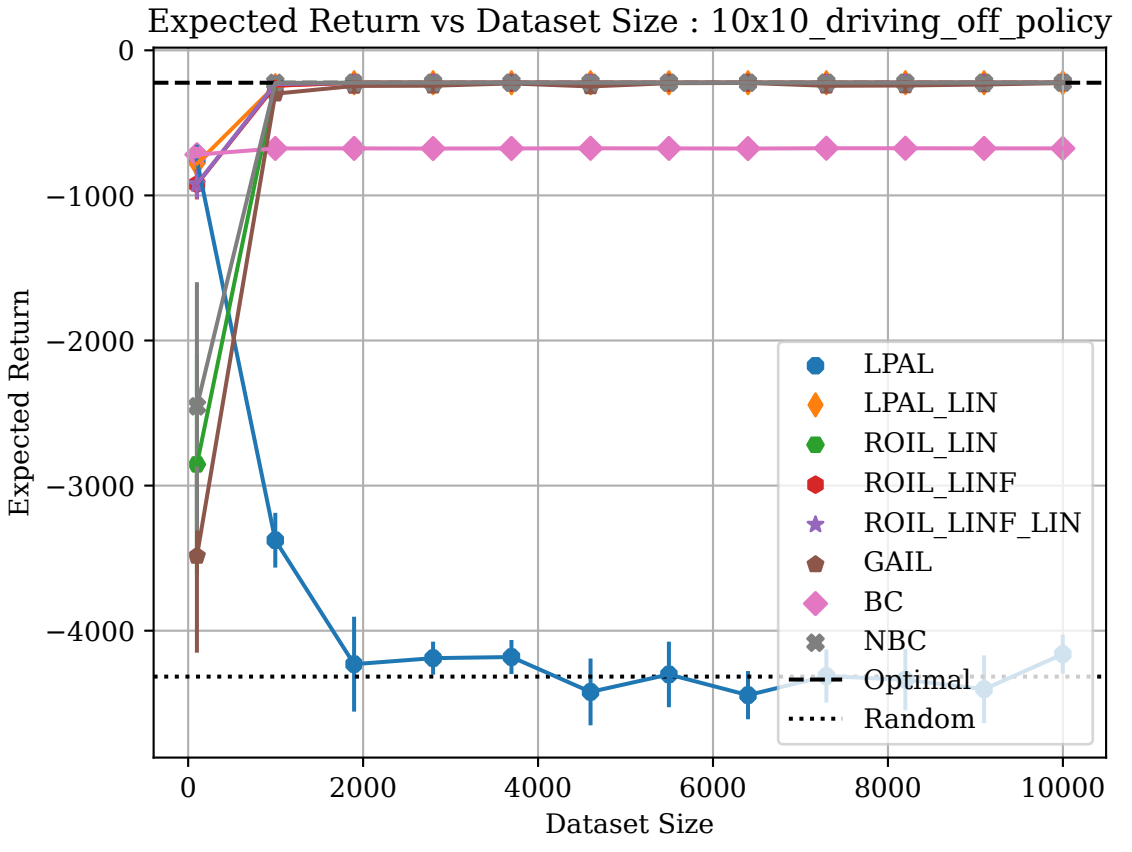
Expected Return vs Dataset Size : 10x10_driving_off_policy
Expected Return
Dataset Size
0
−1000
−2000
−3000
−4000
0
2000
4000
6000
8000
10000
LPAL
LPAL_LIN
ROIL_LIN
ROIL_LINF
ROIL_LINF_LIN
GAIL
BC
NBC
Optimal
Random