

Math 120 QR

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Chapter 1

1.1 Day 1 notes

Definition 1.1.1: Distance Formula

Defintion:

$$|P_1P_2| = \sqrt{(x_2 - x_1)^2 + (y_2 - y_1)^2 + (z_2 - z_1)^2}$$



Definition 1.1.2: Equation of a sphere

Defintion: An equation of a sphere with center $C(h, k, l)$, and radius r is

$$(x - h)^2 + (y - k)^2 + (z - l)^2$$

In particular, if the center is the origin O , than an equation of the sphere is

$$x^2 + y^2 + z^2$$



1.2 Day 2 Notes

Definition 1.2.1: The lenght/magnitude of a vecotr

In 2D, $\vec{v} = \langle a, b \rangle$: $|\vec{v}| = \sqrt{a^2 + b^2}$

In 3D, $\vec{v} = \langle a, b, c \rangle$: $|\vec{v}| = \sqrt{a^2 + b^2 + c^2}$

A unit vector is a vector of length 1



Question 1

If \vec{v} is a vector and a is a scalar, then what is $|a\vec{v}|$

Solution:

$$|a\vec{v}| = |a||\vec{v}|$$

Definition 1.2.2: Vectors in \mathbf{R}^3

The standard basis vectors in \mathbf{R}^3 are

$$i = \langle 1, 0, 0 \rangle$$

$$j = \langle 0, 1, 0 \rangle$$

$$k = \langle 0, 0, 1 \rangle$$



Question 2

What is special about i, j, k ?

Solution:

- Cannot make any of them as a linear combination of the other three.
- Any vector $\vec{v} \in \mathbf{R}^3$ can be written uniquely as a linear combination of i, j, k

Example 1.2.1:

$$\vec{v} + \vec{u} = \begin{pmatrix} u_1 \\ u_2 \\ u_3 \end{pmatrix} + \begin{pmatrix} v_1 \\ v_2 \\ v_3 \end{pmatrix}$$

$$\vec{v} + \vec{u} = \begin{pmatrix} u_1 + v_1 \\ u_2 + v_2 \\ u_3 + v_3 \end{pmatrix}$$



Definition 1.2.3: Dot product

A dot product between v and w is:

In 2D: $v \cdot w = v_1 w_1 + v_2 w_2$

In 3D: $v \cdot w = v_1 w_1 + v_2 w_2 + v_3 w_3$

Geometric definition:

$|u \cdot w| = |u||w| \cos(\theta)$ where θ is the angle between v and w



Example 1.2.2: Why the 2 definitions are the same

$$v_1 w_1 + v_2 w_2 = |v||w| \cos(\theta) = p|v|$$

$$p = |w| \cos(\theta)$$

$$v_1 = |v| \cos(\theta)$$

$$v_2 = |v| \sin(\theta)$$

$$w_1 = |w| \cos(\theta)$$

$$w_2 = |w| \sin(\theta)$$

$$\text{LHS} = |v||w| (\cos(\alpha) \cos(\beta) + \sin(\alpha) \sin(\beta))$$

$$\text{LHS} = |v||w| \sin(\alpha + \beta)$$

$$\text{LHS} = |v||w| \cos(\theta) = \text{RHS}$$



Example 1.2.3: what does the def mean

How much effect of \vec{w} act along \vec{v}

Work: $w = \vec{F} \cdot \vec{S}$



Question 3

Find a relation between $|v|$ and $v \cdot v$

Solution: $|v|^2 = v \cdot v$

Question 4

v, w of fixed lengths when is $v \cdot w$ largest?

Solution: v parallel: $\theta = 0$
 $\cos(\theta) = 1$

Example 1.2.4: Projections

Given $\vec{v} \neq \vec{0}$

The project of w on v is $\text{proj } w = \left(\frac{\vec{w} \cdot \vec{v}}{|\vec{v}|} \right) \frac{\vec{v}}{|\vec{v}|}$

Direction of v is $\frac{\vec{v}}{|\vec{v}|}$

Dir project of w with direction is:

$$\vec{w} \cdot \frac{\vec{v}}{|\vec{v}|}$$



Question 5

TRUE or False:

u, v, w : vectors $(u \cdot v)w = u(v \cdot w)$

Solution: false

Question 6

TRUE or FALSE:

$|v - w| = |v| - |w|$ if $v \parallel w$

Solution: false

Question 7

When is this ideal square sum happening?

$$|v + w|^2 = |v|^2 + |w|^2$$

Solution: when $v \perp w$

Definition 1.2.4: Cross Product

The cross product of two vectors v and w , $v \times w$ is a vector u defined by $u \perp v$ and $u \perp w$.

Direction of u is given by the right hand rule

Magnitude: $|u| = \text{Area of the parallelogram spanned by } v \text{ and } w$.



1.3 Day 2 Reading notes

Definition 1.3.1: Vector Addition

If \mathbf{u} and \mathbf{v} are vectors positioned so the initial point of \mathbf{v} is at the terminal point of \mathbf{u} , then the **sum** $\mathbf{u} + \mathbf{v}$ is the vector from the initial point of \mathbf{u} to the terminal point of \mathbf{v} .



Definition 1.3.2: Scalar Multiplication

If c is a scalar and \mathbf{v} is a vector, then the **scalar multiple** $c\mathbf{v}$ is the vector whose length is $|c|$ times the length of \mathbf{v} and whose direction is the same as \mathbf{v} if $c > 0$ and is opposite to \mathbf{v} if $c < 0$ or $\mathbf{v} = \mathbf{0}$, then $c\mathbf{v} = \mathbf{0}$.



Example 1.3.1:

Given the points $A(x_1, y_1, z_1)$ and $B(x_2, y_2, z_2)$, the vector \mathbf{a} with representation \vec{AB} is:

$$\mathbf{a} = \langle x_2 - x_1, y_2 - y_1, z_2 - z_1 \rangle$$



Example 1.3.2:

If $\mathbf{a} = \langle a_1, a_2 \rangle$ and $\mathbf{b} = \langle b_1, b_2 \rangle$, then:

$$\mathbf{a} + \mathbf{b} = \langle a_1 + b_1, a_2 + b_2 \rangle$$

$$\mathbf{a} - \mathbf{b} = \langle a_1 - b_1, a_2 - b_2 \rangle$$

$$c\mathbf{a} = \langle ca_1, ca_2 \rangle$$

Similarly for three dimensional vectors

