Math 120 QR

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Chapter 1

1.1 12.1 Notes (Three Dimensional Coodinate Systems)

Definition 1.1.1: Distance Formula

Defintion:

$$|P_1P_2| = \sqrt{(x_2 - x_1)^2 + (y_2 - y_1)^2 + (z_2 - z_1)^2}$$

Definition 1.1.2: Equation of a sphere

Defintion: An equation of a sphere with center C(h, k, l), and radius r is

$$(x-h)^2 + (y-k)^2 + (z-l)^2$$

In particular, if the center is the origin O, than an equation of the sphere is

$$x^2 + y^2 + z^2$$



1.2 12.2 Notes (Vectors)

Definition 1.2.1: Vector Addition

If \mathbf{u} and \mathbf{v} are vectors positioned so the initial point of \mathbf{v} is at the terminal point of \mathbf{u} , then the $\mathbf{sum}\ \mathbf{u}$ is the vector from the initial point of \mathbf{u} to the terminal point of \mathbf{v} .

Definition 1.2.2: Scalar Multiplication

If c is a scalar and \mathbf{v} is a vector, then the **scalar multiple** $c\mathbf{v}$ is the vector whose length is |c| times the length of \mathbf{v} and whose direction is the same as \mathbf{v} if c > 0 and is opposite to \mathbf{v} if c = 0 or $\mathbf{v} = 0$, then $c\mathbf{v} = 0$

Example 1.2.1:

Given the points $A(x_1, y_1, z_1)$ and $B(x_2, y_2, z_2)$, the vector **a** with representation \overrightarrow{AB} is:

$$a = \langle x_2 - x_1, y_2 - y_1, z_2 - z_1 \rangle$$



Example 1.2.2:

If $\mathbf{a} = \langle a_1, a_2 \rangle$ and $\mathbf{b} = \langle b_1, b_2 \rangle$, then:

$$\mathbf{a} + \mathbf{b} = \langle a_1 + b_1, a_2 + b_2 \rangle$$

$$\mathbf{a} - \mathbf{b} = \langle a_1 - b_1, a_2 - b_2 \rangle$$

$$c\mathbf{a} = \langle ca_1, ca_2 \rangle$$

Similarly, for three demensional vectors,

$$\langle a_1,a_2,a_3\rangle + \langle b_1,b_2,b_3\rangle = \langle a_1+b_1,a_2+a_3+b_3\rangle$$

$$\langle a_1, a_2, a_3 \rangle - \langle b_1, b_2, b_3 \rangle = \langle a_1 - b_1, a_2 - a_3 - b_3 \rangle$$

$$c\langle a_1, a_2, a_3 \rangle = \langle ca_1, ca_2, ca_3 \rangle$$



Note:-

Properties of vectors: If \mathbf{a} , \mathbf{b} , and \mathbf{c} are vectors in V_n and c and d are scalars than

- $\bullet \ \mathbf{a} + \mathbf{b} = \mathbf{b} + \mathbf{a}$
- a + (b + c) = (a + b) + c
- $\mathbf{a} + 0 = \mathbf{a}$
- a + a + -a = 0
- $c(\mathbf{a} + \mathbf{b}) = c\mathbf{a} + c\mathbf{b}$
- $\bullet (c+d)a = c\mathbf{a} + d\mathbf{a}$
- $(cd)\mathbf{a} = c(d\mathbf{a})$
- $l\mathbf{a} = \mathbf{a}$



1.3 12.3 Notes (Dot Product)

Definition 1.3.1: Dot Product

If $\mathbf{a} = \langle a_1, a_2, a_3 \rangle$ and $\mathbf{b} = \langle b_1, b_2, b_3 \rangle$, then the **dot product** of **a** and **b** is the number $\mathbf{a} \cdot \mathbf{b}$ given by

$$\mathbf{a} \cdot \mathbf{b} = a_1 b_1 + a_2 b_2 + a_3 b_3$$

Properties of the Dot Product: If \mathbf{a}, \mathbf{b} , and \mathbf{c} are vectors in V_3 and \mathbf{c} is a scalar, then

- 1. $\mathbf{a} \cdot \mathbf{a} = |\mathbf{a}|^2$
- 2. $\mathbf{a} \cdot \mathbf{b} = \mathbf{b} \cdot \mathbf{a}$
- 3. $\mathbf{a} \cdot (\mathbf{b} + \mathbf{c}) = \mathbf{a} \cdot \mathbf{b} + \mathbf{a} \cdot \mathbf{c}$
- 4. $(c\mathbf{a}) \cdot \mathbf{b} = c(\mathbf{a} \cdot \mathbf{b}) = \mathbf{a} \cdot (c\mathbf{b})$
- 5. $\mathbf{0} \cdot \mathbf{a} = 0$

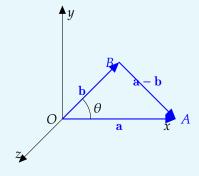


Definition 1.3.2: Geometric Definition of the Dot Product

If θ is the angle between vectors **a** and **b**, then

$$\mathbf{a} \cdot \mathbf{b} = |\mathbf{a}| |\mathbf{b}| \cos(\theta)$$

Proof:



$$|AB|^2 = |OA|^2 + |OB|^2 - 2|OA||OB|\cos\theta$$

Corollary: If θ is the angle between nonzero vectors **a** and **b**, then

$$\cos(\theta) = \frac{\mathbf{a} \cdot \mathbf{b}}{|\mathbf{a}||\mathbf{b}|}$$



Note:-

Two vectors \mathbf{a} and \mathbf{b} are orthogonal if an only if $\mathbf{a} \cdot \mathbf{b} = 0$



The direction angles of a nonzero vector **a** are the angles α , β , and γ (in the interval $[0,\pi]$) that **a** makes with the positive x-, y-, and z-axes, respectively .

The cosines of these direction angles, $\cos \alpha$, $\cos \beta$, and $\cos \gamma$, are called the **direction cosines** of the vector **a**. Using Corollary 6 with **b** replaced by **i**, we obtain:

$$\cos \alpha = \frac{\mathbf{a} \cdot \mathbf{i}}{|\mathbf{a}||\mathbf{i}|} = \frac{a_1}{|\mathbf{a}|} \tag{1}$$

Similarly, we also have:

$$\cos \beta = \frac{a_2}{|\mathbf{a}|} \quad \text{and} \quad \cos \gamma = \frac{a_3}{|\mathbf{a}|}$$
 (2)

By squaring the expressions in Equations 8 and 9 and adding, we see that:

$$\cos^2 \alpha + \cos^2 \beta + \cos^2 \gamma = 1 \tag{3}$$

We can also use Equations 8 and 9 to write:

$$\mathbf{a} = \langle a_1, a_2, a_3 \rangle = \langle |\mathbf{a}| \cos \alpha, |\mathbf{a}| \cos \beta, |\mathbf{a}| \cos \gamma \rangle = |\mathbf{a}| \langle \cos \alpha, \cos \beta, \cos \gamma \rangle$$

Therefore,

$$\frac{1}{|\mathbf{a}|}\mathbf{a} = \langle \cos \alpha, \cos \beta, \cos \gamma \rangle \tag{4}$$

which says that the direction cosines of a are the components of the unit vector in the direction of a.

Definition 1.3.3: Projections

The scalar projection of **b** onto **a** (also called the **component of b along a**) is defined to be the signed magnitude of the vector projection, which is the number $|\mathbf{b}| \cos \theta$, where θ is the angle between **a** and **b**. This is denoted by $\text{comp}_{\mathbf{a}}\mathbf{b}$. Observe that it is negative if $\pi/2 < \theta \leqslant \pi$. The equation

$$\mathbf{a} \cdot \mathbf{b} = |\mathbf{a}| |\mathbf{b}| \cos \theta = |\mathbf{a}| (|\mathbf{b}| \cos \theta)$$

shows that the dot product of a and b can be interpreted as the length of a times the scalar projection of b onto a. Since

$$|\mathbf{b}|\cos\theta = \frac{\mathbf{a}\cdot\mathbf{b}}{|\mathbf{a}|} = \frac{\mathbf{a}}{|\mathbf{a}|}\cdot\mathbf{b}$$

the component of \mathbf{b} along \mathbf{a} can be computed by taking the dot product of \mathbf{b} with the unit vector in the direction of \mathbf{a} . We summarize these ideas as follows.

Scalar projection of b onto a: $\operatorname{comp}_{\mathbf{a}} \mathbf{b} = \frac{\mathbf{a} \cdot \mathbf{b}}{|\mathbf{a}|}$

Vector projection of b onto a: $\operatorname{proj}_a b = \left(\frac{a \cdot b}{|a|^2}\right) a = \frac{a \cdot b}{|a|^2} a$



1.4 12.4 Notes (Cross Product)

Definition 1.4.1: Cross Product

Given two nonzero vectors $\mathbf{a} = \langle a_1, a_2, a_3 \rangle$ and $\mathbf{b} = \langle b_1, b_2, b_3 \rangle$, suppose that a nonzero vector $\mathbf{c} = \langle c_1, c_2, c_3 \rangle$ is perpendicular to both \mathbf{a} and \mathbf{b} . Then $\mathbf{a} \cdot \mathbf{c} = 0$ and $\mathbf{b} \cdot \mathbf{c} = 0$, and so:

$$a_1c_1 + a_2c_2 + a_3c_3 = 0 (1)$$

$$b_1c_1 + b_2c_2 + b_3c_3 = 0 (2)$$

To eliminate c_3 , we multiply (1) by b_3 and (2) by a_3 and subtract:

$$(a_1b_3 - a_3b_1)c_1 + (a_2b_3 - a_3b_2)c_2 = 0 (3)$$

Equation (3) has the form $pc_1 + qc_2 = 0$, for which an obvious solution is $c_1 = q$ and $c_2 = -p$. So, a solution of (3) is:

$$c_1 = a_2 b_3 - a_3 b_2$$

$$c_2 = a_3 b_1 - a_1 b_3$$

Substituting these values into (1) and (2), we then get:

$$c_3 = a_1 b_2 - a_2 b_1$$

This means that a vector perpendicular to both \mathbf{a} and \mathbf{b} is:

$$\langle c_1, c_2, c_3 \rangle = \langle a_2b_3 - a_3b_2, a_3b_1 - a_1b_3, a_1b_2 - a_2b_1 \rangle$$

The resulting vector is called the **cross product** of \mathbf{a} and \mathbf{b} and is denoted by $\mathbf{a} \times \mathbf{b}$.



Definition 1.4.2: Cross Product of two vectors

If $\mathbf{a} = \langle a_1, a_2, a_3 \rangle$ and $\mathbf{b} = \langle b_1, b_2, b_3 \rangle$ then the **cross product** of \mathbf{a} and \mathbf{b} is:

$$\mathbf{a} \times \mathbf{b} = \langle a_2 b_3 - a_3 b_2, a_3 b_1 - a_1 b_3, a_1 b_2 - a_2 b_1 \rangle$$



Note:-

Determinant of order 2:

$$\begin{vmatrix} a & b \\ c & d \end{vmatrix} = ad - bc$$



Note:-

Determinant of order 3:

$$\begin{vmatrix} a_1 & a_2 & a_3 \\ b_1 & b_2 & b_3 \\ c_1 & c_2 & c_3 \end{vmatrix} = a_1 \begin{vmatrix} b_2 & b_3 \\ c_2 & c_3 \end{vmatrix} - a_2 \begin{vmatrix} b_1 & b_3 \\ c_1 & c_3 \end{vmatrix} + a_3 \begin{vmatrix} b_1 & b_2 \\ c_1 & c_2 \end{vmatrix}$$



Definition 1.4.3: Second definition of cross product

Arithmetic Definition:

$$a \times b = \begin{bmatrix} i & j & k \\ a_1 & a_2 & a_3 \\ b_1 & b_2 & b_3 \end{bmatrix} = |a||b|\sin(\theta)$$
$$\begin{bmatrix} a_2 & a_3 \\ b_2 & b_3 \end{bmatrix} i - \begin{bmatrix} a_1 & a_3 \\ b_1 & b_3 \end{bmatrix} j + \begin{bmatrix} a_1 & a_2 \\ b_1 & b_2 k \end{bmatrix}$$
$$= (a_2b_3 - a_3b_2)i - (a_1b_3 - a_3b_1)j + (a_1b_2 - a_2b_1)k$$

The vector $\mathbf{a} \times \mathbf{b}$ is orthogonal to both \mathbf{a} and \mathbf{b}



Example 1.4.1: Proof that $\mathbf{a} \times \mathbf{b}$ is orthogonal to both a

$$(\mathbf{a} \times \mathbf{b}) \cdot \mathbf{a} = \begin{vmatrix} a_2 & a_3 \\ b_2 & b_3 \end{vmatrix} a_1 - \begin{vmatrix} a_1 & a_3 \\ b_1 & b_3 \end{vmatrix} a_2 + \begin{vmatrix} a_1 & a_2 \\ b_1 & b_2 \end{vmatrix} a_3$$

$$= a_1(a_2b_3 - a_3b_2) - a_2(a_1b_3 - a_3b_1) + a_3(a_1b_2 - a_2b_1)$$

$$= a_1a_2b_3 - a_1a_3b_2 - a_2a_1b_3 + a_2a_3b_1 + a_3a_1b_2 - a_3a_2b_1$$

$$= 0$$



Definition 1.4.4: sin definition of cross product

If θ is the angle between **a** and **b** (so $0 \le \theta \le \pi$), then the length of the cross product $\mathbf{a} \times \mathbf{b}$ is given by:

$$|\mathbf{a} \times \mathbf{b}| = |\mathbf{a}||\mathbf{b}|\sin(\theta)$$

Proof:

$$|\mathbf{a} \times \mathbf{b}|^{2} = (a_{2}b_{3} - a_{3}b_{2})^{2} + (a_{3}b_{1} - a_{1}b_{3})^{2} + (a_{1}b_{2} - a_{2}b_{1})^{2}$$

$$= a_{2}^{2}b_{3}^{2} - 2a_{2}a_{3}b_{2}b_{3} + a_{3}^{2}b_{2}^{2} + a_{3}^{2}b_{1}^{2} - 2a_{1}a_{3}b_{1}b_{3} + a_{1}^{2}b_{3}^{2} + a_{1}^{2}b_{2}^{2} - 2a_{1}a_{2}b_{1}b_{2} + a_{2}^{2}b_{1}^{2}$$

$$= (a_{1}^{2} + a_{2}^{2} + a_{3}^{2})(b_{1}^{2} + b_{2}^{2} + b_{3}^{2}) - (a_{1}b_{1} + a_{2}b_{2} + a_{3}b_{3})^{2}$$

$$= |\mathbf{a}|^{2}|\mathbf{b}|^{2} - (\mathbf{a} \cdot \mathbf{b})^{2}$$

$$= |\mathbf{a}|^{2}|\mathbf{b}|^{2} - |\mathbf{a}|^{2}|\mathbf{b}|^{2}\cos^{2}\theta \quad \text{(by Theorem 12.3.3)}$$

$$= |\mathbf{a}|^{2}|\mathbf{b}|^{2}(1 - \cos^{2}\theta)$$

$$= |\mathbf{a}|^{2}|\mathbf{b}|^{2}\sin^{2}\theta$$

Taking square roots and observing that $\sqrt{\sin^2 \theta} = \sin \theta$ because $\sin \theta \ge 0$ when $0 \le \theta \le \pi$, we have

$$|\mathbf{a} \times \mathbf{b}| = |\mathbf{a}||\mathbf{b}|\sin\theta$$



Note:-

Two nonzero vectors **a** and **b** are parallel if and only if

$$\mathbf{a} \times \mathbf{b} = 0$$

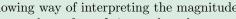
Example 1.4.2: Geometric interpretation of $|\mathbf{a} \times \mathbf{b}| = |\mathbf{a}| |\mathbf{b}| \sin \theta$

If a and b are represented by directed line segments with the same inital point, then they determine a parallelogram with base $|\mathbf{a}|$, altitude $\mathbf{b}\sin(\theta)$ and area

$$A = |\mathbf{a}|(|\mathbf{b}|\sin\theta) = |\mathbf{a} \times \mathbf{b}|$$

Thus we have the following way of interpreting the magnitude of a cross product:

The length of the cross product of $\mathbf{a} \times \mathbf{b}$ is equal to the area of the parallelogram determined by \mathbf{a} and \mathbf{b}



Note:-

If we apply the following theorem:

The vector $\mathbf{a} \times \mathbf{b}$ is orthogonal to both \mathbf{a} and \mathbf{b} , and

$$|\mathbf{a} \times \mathbf{b}| = |\mathbf{a}||\mathbf{b}|\sin\theta$$

to the standard basis vectors $\mathbf{i}, \mathbf{j}, \mathbf{k}$ using $\theta = \frac{\pi}{2}$, we obtain

$$\mathbf{i} \times \mathbf{j} = \mathbf{k}$$
 $\mathbf{j} \times \mathbf{k} = \mathbf{i}$ $\mathbf{k} \times \mathbf{i} = \mathbf{j}$

$$\mathbf{j} \times \mathbf{i} = -\mathbf{k}$$
 $\mathbf{k} \times \mathbf{j} = -\mathbf{i}$ $\mathbf{i} \times \mathbf{k} = -\mathbf{j}$



Note:-

If \mathbf{a} , \mathbf{b} , and \mathbf{c} are vectors and \mathbf{c} is a scalar, then

- 1. $\mathbf{a} \times \mathbf{b} = -\mathbf{b} \times \mathbf{a}$
- 2. $(c\mathbf{a}) \times \mathbf{b} = c(\mathbf{a} \times \mathbf{b}) = \mathbf{a} \times (c\mathbf{b})$
- 3. $\mathbf{a} \times (\mathbf{b} + \mathbf{c}) = \mathbf{a} \times \mathbf{b} + \mathbf{a} \times \mathbf{c}$
- 4. $(\mathbf{a} + \mathbf{b}) \times \mathbf{c} = \mathbf{a} \times \mathbf{c} + \mathbf{b} \times \mathbf{c}$
- 5. $\mathbf{a} \cdot (\mathbf{b} \times \mathbf{c}) = (\mathbf{a} \times \mathbf{b}) \cdot \mathbf{c}$
- 6. $\mathbf{a} \times (\mathbf{b} \times \mathbf{c}) = (\mathbf{a} \cdot \mathbf{c})\mathbf{b} (\mathbf{a} \cdot \mathbf{b})\mathbf{c}$



Example 1.4.3: Proof of property 5 of cross products

If $\mathbf{a} = \langle a_1, a_2, a_3 \rangle$, $\mathbf{b} = \langle b_1, b_2, b_3 \rangle$, and $\mathbf{c} = \langle c_1, c_2, c_3 \rangle$, then:

$$\mathbf{a} \cdot (\mathbf{b} \times \mathbf{c}) = a_1(b_2c_3 - b_3c_2) + a_2(b_3c_1 - b_1c_3) + a_3(b_1c_2 - b_2c_1)$$

$$=a_1b_2c_3-a_1b_3c_2+a_2b_3c_1-a_2b_1c_3+a_3b_1c_2-a_3b_2c_1$$

$$=(a_2b_3-a_3b_2)c_1+(a_3b_1-a_1b_3)c_2+(a_1b_2-a_2b_1)c_3$$

$$= (\mathbf{a} \times \mathbf{b}) \cdot \mathbf{c}$$



Definition 1.4.5: Triple Products

The product $\mathbf{a} \cdot (\mathbf{b} \times \mathbf{c})$ that occurs in Property 5 is called the *scalar triple product* of the vectors \mathbf{a} , \mathbf{b} , and \mathbf{c} .

$$\mathbf{a} \cdot (\mathbf{b} \times \mathbf{c}) = \begin{vmatrix} a_1 & a_2 & a_3 \\ b_1 & b_2 & b_3 \\ c_1 & c_2 & c_3 \end{vmatrix}$$

The geometric significance of the scalar triple product can be seen by considering the parallelepiped determined by the vectors \mathbf{a} , \mathbf{b} , and \mathbf{c} . The area of the base parallelegram is $A = |\mathbf{b} \times \mathbf{c}|$. If θ is the angle between \mathbf{a} and $\mathbf{b} \times \mathbf{c}$, then the height h of the parallelepiped is $h = |\mathbf{a}| |\cos \theta|$. (We must use $|\cos \theta|$ instead of $\cos \theta$ in case $\theta > \pi/2$.) Therefore, the volume of the parallelepiped is

$$V = Ah = |\mathbf{b} \times \mathbf{c}||\mathbf{a}||\cos\theta| = |\mathbf{a} \cdot (\mathbf{b} \times \mathbf{c})|$$

Thus, we have proved the following formula: The volume of the parallelepiped determined by the vectors \mathbf{a} , \mathbf{b} , and \mathbf{c} is the magnitude of their scalar triple product:

$$V = |\mathbf{a} \cdot (\mathbf{b} \times \mathbf{c})|$$



1.5 12.5 Notes (Equations of Lines and Planes)