

**ACADEMIC TRANSCRIPT**

**FAMILY NAME** ÇİMENÇİ  
**GIVEN NAME** KADİR  
**STUDENT ID** 1993971  
**GRADUATE SCHOOL PROGRAM** Natural and Applied Sciences  
Electrical and Electronics Engineering

**DATE OF ENTRY** September 11, 2013  
**DEGREES AWARDED** M.S.  
**DATE OF GRADUATION** June 27, 2016

<b>COURSE CODE</b>	<b>COURSE NAME</b>	<b>CREDITS</b>	<b>GRADE</b>	<b>POINTS</b>
<b>2013-2014 Fall</b>				
EE501	LINEAR SYSTEMS THEORY I	3,00	BA	10,50
EE587	INTRODUCTION TO ROBOTICS	3,00	AA	12,00
<b>CumGPA:</b> 3,75	<b>GPA:</b> 3,75 <b>STAN:</b> SATISFACTORY	<b>6,00</b>		<b>22,50</b>
<b>2013-2014 Spring</b>				
EE502	LINEAR SYSTEMS THEORY II	3,00	AA	12,00
<b>CumGPA:</b> 3,83	<b>GPA:</b> 4,00 <b>STAN:</b> SATISFACTORY	<b>3,00</b>		<b>12,00</b>
<b>2014-2015 Fall</b>				
EE583	PATTERN RECOGNITION	3,00	AA	12,00
EE500	M.S. THESIS	0,00	P	0,00
EE811	SPECIAL STUDIES	0,00	S	0,00
<b>CumGPA:</b> 3,88	<b>GPA:</b> 4,00 <b>STAN:</b> SATISFACTORY	<b>3,00</b>		<b>12,00</b>
<b>2014-2015 Spring</b>				
CENG580	MULTI AGENT SYSTEMS	3,00	AA	12,00
CENG773	COMPUTATIONAL GEOMETRY	3,00	BA	10,50
EE500	M.S. THESIS	0,00	P	0,00
EE811	SPECIAL STUDIES	0,00	S	0,00
<b>CumGPA:</b> 3,83	<b>GPA:</b> 3,75 <b>STAN:</b> PROBATION	<b>6,00</b>		<b>22,50</b>
<b>2015-2016 Fall</b>				
CENG786	ROBOT MOTION PLANNING AND CONTROL	3,00	AA	12,00
EE500	M.S. THESIS	0,00	P	0,00
EE590	SEMINAR	0,00	S	0,00
EE811	SPECIAL STUDIES	0,00	S	0,00
<b>CumGPA:</b> 3,86	<b>GPA:</b> 4,00 <b>STAN:</b> SATISFACTORY	<b>3,00</b>		<b>12,00</b>
<b>2015-2016 Spring</b>				
EE500	M.S. THESIS	0,00	S	0,00
EE811	SPECIAL STUDIES	0,00	S	0,00
<b>CumGPA:</b> 3,86	<b>GPA:</b> 0,00 <b>STAN:</b> SATISFACTORY	<b>0,00</b>		<b>0,00</b>
<b>CumGPA:</b> 3,86	<b>GRAND TOTALS:</b>	<b>21,00</b>		<b>81,00</b>

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