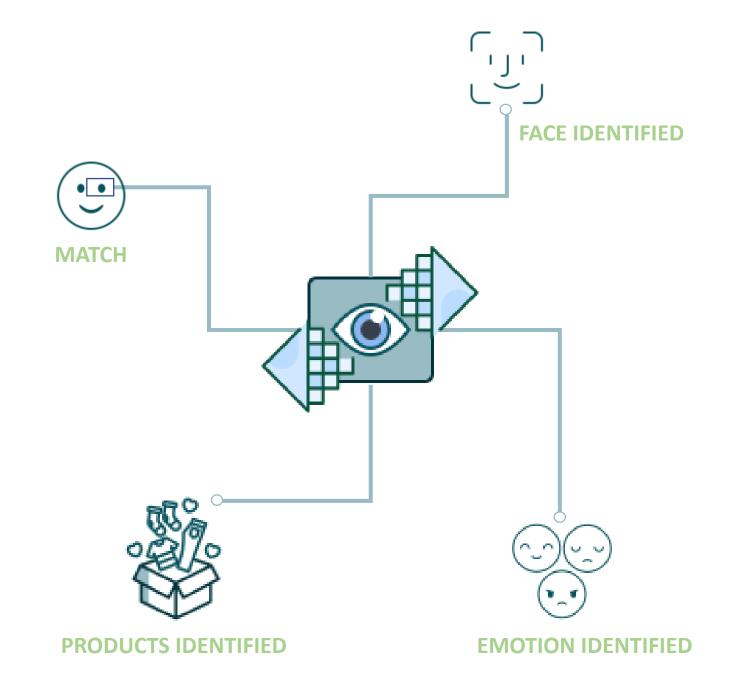
# Computer Vision Lecture-one Introduction



#### **Computer Vision**

Make computers understand images and video (extract information from an image that is necessary to solve task).

#### **Computer Vision vs Image Processing**

The methods that are used in Image Processing can alter images in a variety of ways, including sharpening, smoothing, filtering, enhancing, restoring, and blurring amongst others. Computer vision, on the other hand, is concerned with deciphering the meaning of what may be seen by computers

# **Computer Vision Levels**







Mid-Level Vision

**Low-Level Vision** 





# **Tools Requirements**

#### **Pycharm**



Python 3.6







**VSCode** 



Opency 3.4.1.15



#### **Basic operation on images**

- Read Images
- Gray and color Image in Read function
- Save Images

#### **Image Types and Color spaces**

- Binary Images
- Grayscale Images
- RGB Images
- Indexed Images
- Changing Color spaces

#### **2D** Transformations on images

- Scaling
- Translation
- Rotate
- Flip

#### **Basic operation on images**

Read Images

```
image = cv.imread('Home.jpg')
cv.imshow("img",image)
cv.waitKey(0)
```

Gray and color Image in Read function

```
#1 methode
image = cv.imread('Home.jpg',0)
cv.imshow("gray",image)
cv.waitKey(0)
```

Gray and color Image in Read function

```
#2 methode
image = cv.imread('Home.jpg')
gray = cv.cvtColor(image,
cv.COLOR_BGR2GRAY)
cv.imshow('gray',gray)
cv.waitKey(0)
```

Image Size and Shape

```
image = cv.imread('Home.jpg')
cv.imshow("img",image)
# size image
print( image.shape )
#(506, 760, 3)
# size image W*H*RGB
print( image.size )
# 1153680
```

#### **Basic operation on images**

Image Type and Channels

```
# image type
print( image.dtype )
# uint8
b,g,r = cv.split(image)
# cv.imshow("blue",b)
# or
cv.imshow("blue",image[:,:,1])
# merge 3 color
img = cv.merge((b,g,r))
cv.imshow("image",img)
cv.waitKey(∅)
```

Save Images

```
image = cv.imread('Home.jpg')
cv.imshow('image',image)
k = cv.waitKey(0)
if k == 27: # wait for ESC key to exit
cv.destroyAllWindows()
elif k == ord('s'): # wait for 's' key
to save and exit
cv.imwrite('messigray.png',image)
cv.destroyAllWindows()
```



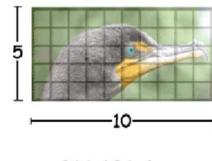
Image Types

#### **Binary and Grayscale Image**

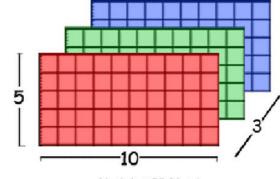




**RGB** Image

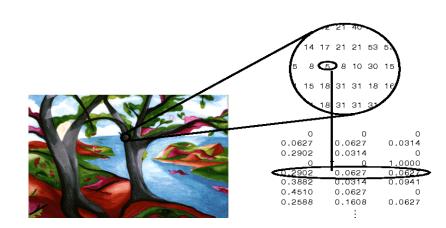


Original Color Image



Matlab RGB Matrix

**Indexed Image** 



# **Changing Color Spaces**

```
image = cv.imread('Home.jpg')
cv.imshow("img",image)
# Hsv
HSV=cv.cvtColor(image,cv.COLOR_BGR2HSV)
cv.imshow("HSV",HSV)
#gray
gray=cv.cvtColor(image,cv.COLOR_BGR2GRAY)
cv.imshow("gray",gray)
# BGR
gbr=cv.cvtColor(gray,cv.COLOR_GRAY2RGB)
cv.imshow("gbr",gbr)
cv.waitKey(∅)
```







Scaling

```
img = cv.imread('Home.jpg',0)
cv.imshow("img",img)
print(img.shape)
cv.waitKey(0)
# resize
dimentions=img.shape
res =cv.resize(img,(int(dimentions[1]/2),int(dimentions[0]/2)))
cv.imshow("res", res)
cv.waitKey(0)
```

#### Translation

```
img = cv2.imread('Images/Home.jpg')
rows,cols,depth = img.shape
cv2.imshow('img',img);
cv2.waitKey(0)
M = np.float32([[1,0,100],[0,1,50]])
dst = cv2.warpAffine(img,M,(cols,rows))
cv2.imshow('dst',dst);
cv2.waitKey(∅)
```





#### Rotate

```
img = cv2.imread('Images/Home.jpg',0)
rows,cols = img.shape
M=cv2.getRotationMatrix2D((cols/2,rows/2),
90,1)
dst = cv2.warpAffine(img,M,(cols,rows))
cv2.imshow('dst',dst);
cv2.waitKey(∅)
```





#### Rotate

```
img = cv2.imread('Images/Home.jpg')
img_rotate_90_clockwise =
cv2.rotate(img,cv2.ROTATE_90_CLOCKWISE)
img_rotate_90_counterclockwise
=cv2.rotate(img,cv2.ROTATE_90_COUNTERCLOCKWISE)
img_rotate_180 = cv2.rotate(img,cv2.ROTATE_180)
```



#### Flip









# That's All