

# GCS Mission Tracker

Menu

Plan

Upload Map

Upload WayPoints

Settings

From Base Point:

Distance: 0 m/s

Bearing: 0 deg

Login

Click to go to Mission Planner.

Click to upload waypoints from saved file(.pln).

Click to go to settings window. for trims adjustment and gain tuning and other settings of GCS.

This is the distance of current waypoint form basepoint.

This is the bearing of current waypoint form basepoint.

Waypoint Data

WayPoint 1

WayPoint 2

WayPoint 3

WayPoint 4

WayPoint 5

WayPoint 6

WayPoint 7

Next W.P 05

Alti. 1200

Lat. -4.2149

Long. 88.1250000

Fly To

Autopilot Mode

Manual OFF

Semi Auto OFF

Auto ON

GPS Status

UTC Time:

Latitude:

Longitude:

Mission Status

IAS:

SOG:

Heading:

Altitude:

A.O.A

Pitch Angle:

Roll Angle:

Yaw Angle:

Click to open widget setup, where you can select parameters and widgets you want to display.

Telemetry Status

DownLink: 36

UpLink: 12

W.P 01

W.P 02

W.P 03

W.P 04

W.P 05

W.P 06

W.P 07

Base Point

Designed By: Waqas Rauf Khattak

## 1. MissionTracker\_GCS

| # | Note  |
|---|---|
| 1 | Edit params. popup will only appear if you have saved the parameters before form prams window. If you click waypoint for the first time params. window will appear not the popup. |