

# Lecture 10: Clustering Part II

## Statistical Methods for Data Science

**Yinan Yu**

Department of Computer Science and Engineering

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# Today

- 1 Clustering - recap
- 2 Centroid clustering
- 3 Distribution clustering
  - Gaussian Mixture Models (GMM)
  - One dimensional GMM
- 4 Summary

## Learning outcome

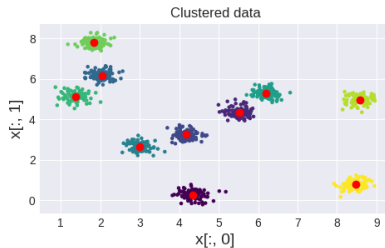
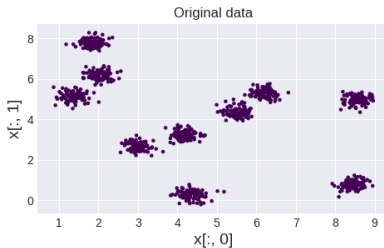
- Be able to explain the within-cluster sum of squared error (SSE) and the Silhouette score; be able to determine  $K$  and the best initial guesses using SSE and the Silhouette score
- Be able to explain the difference between Gaussian naive Bayes classifier and GMM in terms of parameter estimation
- Be able to explain the objective function  $Q(\theta)$  for GMM
- Understand what EM algorithm is used for and why we need it
- Be able to calculate AIC/BIC and use them to determine  $K$  for GMM

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## Recall: clustering

- We start with blobs of data



- We assign some semantics to each of these data points
- Each of these semantics is called a **cluster**
- The process of finding clusters is called **clustering**

## Recall: clustering (cont.)

Four categories of clustering models

- **Centroid clustering**
- **Distribution clustering**
- Hierarchical clustering
- Density clustering

## Recall: models in this course

In this course, we focus on two clustering models

- K-means
  - **Parameters:**  $K$  centroids
  - **Hyperparameters:**  $K$
  - **Parameter estimation:** an iterative method to update the centroids until convergence (simplified Expectation-Maximization algorithm)
- Gaussian mixture models
  - **Parameters:**  $K$  priors,  $K$  Gaussian likelihood (the big two!)
  - **Hyperparameters:**  $K$
  - **Parameter estimation:** the Expectation-Maximization algorithm

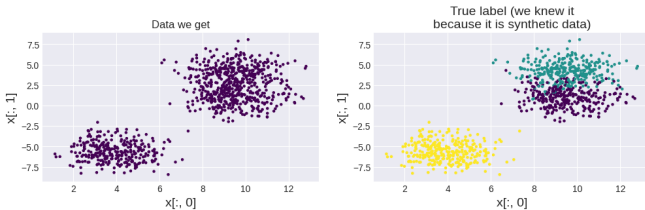
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# Recall: K-means

- **Data**  $\mathbf{x}$ :  $d$  dimensional feature vector  $\mathbf{x}$



- **Target**  $\mathbf{y}$ :

$$\mathbf{y} = \arg \min_{k \in \{1, \dots, K\}} \text{dist}(\mathbf{x}, \boldsymbol{\mu}_k)$$

where  $\text{dist}(\cdot, \cdot)$  is a distance measure; in this course, we use the Euclidean distance (cf. lecture 9)

- **Parameters**:  $K$  centroids  $\boldsymbol{\mu}_k$
- **Hyperparameters**:  $K$
- **Parameter estimation**: an iterative method to update the centroids until convergence
- It is a **hard clustering** technique - one data point is assigned to only one cluster

## Two challenges for K-means

- **Challenges:**

- How to choose the hyperparameter  $K$ ?
- K-means is sensitive to the initialization of  $\mu_k$  for  $k = 1, \dots, K$

- **Solution:**

- Choose a range of **candidate values**, e.g. for the first problem, we can choose  $K \in \{1, \dots, 10\}$ ; for the second problem, we can randomly select 100 different initial guesses for  $\mu_k$
- For each of these **candidate values**, we run the K-means algorithm to estimate the parameters and evaluate the **quality** of the clusters produced by these parameters
- Choose the **candidate value** that gives the best **quality**

- **Quality** evaluation criteria

- Within-cluster sum of squared errors (SSE)
- Silhouette score

# Cluster quality evaluation criteria 1: SSE

Two commonly used alternative evaluation criteria

1. **Within-cluster sum of squared errors (SSE)**: defined as the summation of the distances from all the data points to their closest centroid

$$SSE = \sum_{k=1}^K \sum_{\mathbf{x} \in C_k} dist(\mathbf{x}, \mu_k)^2 \quad (1)$$

where  $C_k$  denote cluster  $k$ ;  $dist(\cdot, \cdot)$  is a distance measure - in this course, we use the Euclidean distance

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- Note that  $SSE \rightarrow 0$  for  $K \rightarrow N$ , i.e. when every data point is their own centroid,  $SSE = 0$ , which is not optimal - we can't simply choose the  $K$  value that corresponds to the smallest  $SSE$

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- Instead, the best  $K$  is defined as the **elbow** point of the  $SSE$ , i.e. the point with the maximum curvature
- The elbow can be computed using, e.g. the kneed library in Python
- This method is also called the **elbow method**

## Cluster quality evaluation criteria 2: Silhouette score

2. **Silhouette score  $S$** : the idea is that a good clustering should end up with **compact clusters** with **large separation between different clusters**. This is characterized by the **within-cluster distance** and **between-cluster distance**

## Cluster quality evaluation criteria 2: Silhouette score (cont.)

2. **Silhouette score  $S$**  (cont.):

**Example:** given data  $x_1, x_2, x_3 \in \text{cluster 1}$ ,  $x_4, x_5 \in \text{cluster 2}$ ,  $x_6, x_7 \in \text{cluster 3}$ ;  $K = 3$



## Cluster quality evaluation criteria 2: Silhouette score (cont.)

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- **Within-cluster distance:** measures how data points scatter in relation to  $x_i$  within its own cluster; let  $x_i$  be a data point from cluster  $k$ ,

$$a_i = \frac{1}{|C_k| - 1} \sum_{x_j \in C_k \text{ and } j \neq i} \text{dist}(x_i, x_j)$$

In this example, let  $i = 1$ ,  $x_1 \in C_1$ ; there are  $|C_1| = 3$  data points in cluster 1

$$a_1 = \frac{1}{3 - 1} (\text{dist}(x_1, x_2) + \text{dist}(x_1, x_3))$$

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- **Between-cluster distance:** measures how data points scatter in relation to  $x_i$  when these data points are from other clusters

$$b_i = \min_{k' \neq k, k' \in \{1, \dots, K\}} \frac{1}{N_{k'}} \sum_{x_j \in C_{k'}} \text{dist}(x_i, x_j)$$

In the example,  $N_2 = N_3 = 2$

$$b_1 = \min \left( \frac{1}{2} (\text{dist}(x_1, x_4) + \text{dist}(x_1, x_5)), \frac{1}{2} (\text{dist}(x_1, x_6) + \text{dist}(x_1, x_7)) \right)$$

## Cluster quality evaluation criteria 2: Silhouette score (cont.)

### 2. Silhouette score $S$ (cont.):

- Silhouette score for one data point:

$$S_i = \begin{cases} \frac{b_i - a_i}{\max(a_i, b_i)}, & \text{if } |C_k| > 1 \\ 0, & \text{if } N = 1 \end{cases}$$

A large  $S_i$  indicates a compact cluster  $k$  in relation to  $\mathbf{x}_i$  and a large distance from  $\mathbf{x}_i$  to clusters other than  $k$

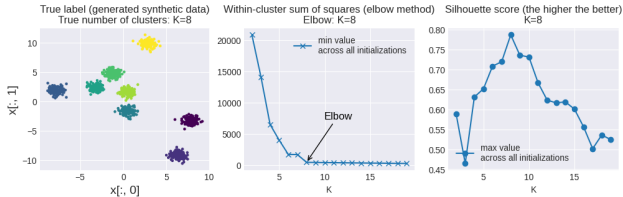
- Silhouette score for the data set

$$S = \frac{1}{N} \sum_{i=1}^N S_i, \quad S \in [-1, 1]$$

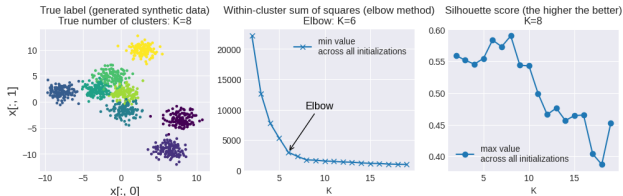
- A large Silhouette score indicates a good clustering quality

# Example - choose $K$

## Clusters with equal variance



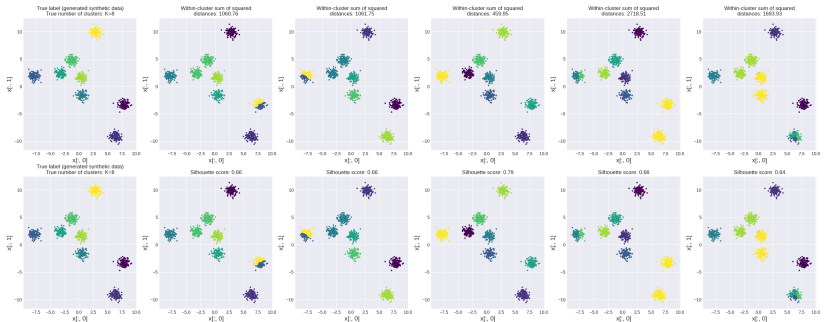
## Overlapping clusters with unequal variances



# Example - choose initial guess

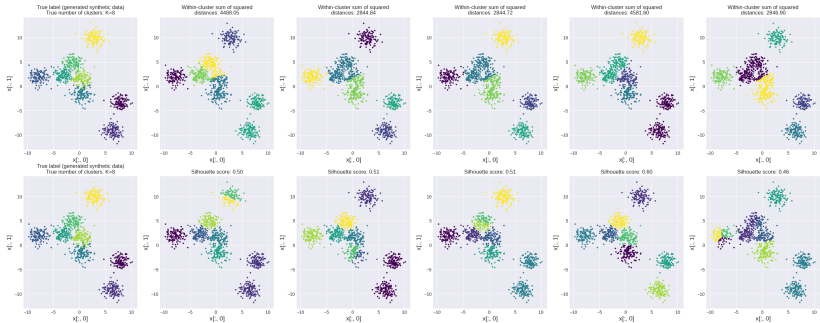
- Each column corresponds to a different initialization
- For a given  $K$ , choose the initialization that gives the smallest SSE or the largest Silhouette score

Clusters with equal variance



# Example - choose initial guess (cont.)

## Overlapping clusters with unequal variances



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# Gaussian Mixture Models (GMM)



# Gaussian Mixture Models (GMM) - overview

## Distribution clustering:

- Each cluster is modeled using a probability distribution
- Each data point is modeled using a combination of all clusters

## Gaussian Mixture Models:

- **Data  $\mathbf{x}$ :** a  $d$  dimensional feature vector  $\mathbf{x} = [x_1, \dots, x_d]$

$$f(\mathbf{x}) = \sum_{k=1}^K \pi_k f(\mathbf{x} | k)$$

where  $\pi_k = P(k) > 0$  and  $\sum_{k=1}^K \pi_k = 1$ ,  $k = 1, \dots, K$ ; each  $f(\mathbf{x} | k)$  is a  **$d$  dimensional multivariate Gaussian PDF** describing cluster  $k$

# Gaussian Mixture Models (GMM) - overview (cont.)

- Gaussian Mixture Model:

$$f(\mathbf{x}) = \sum_{k=1}^K \pi_k f(\mathbf{x} | k)$$

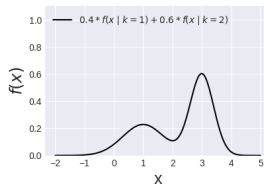
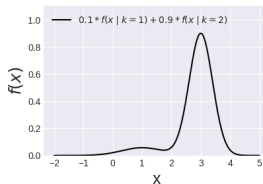
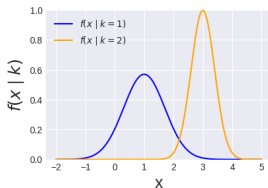
- Examples of the mixture distribution with  $d = 1$

- Example 1:  $\pi_1 = 0.1$ ,  $\pi_2 = 0.9$

$$f(\mathbf{x}) = 0.1 \times f(x | k = 1) + 0.9 \times f(x | k = 2) = 0.1 \times f(x | \mu_1, \sigma_1) + 0.9 \times f(x | \mu_2, \sigma_2)$$

- Example 2:  $\pi_1 = 0.4$ ,  $\pi_2 = 0.6$

$$f(\mathbf{x}) = 0.4 \times f(x | k = 1) + 0.6 \times f(x | k = 2) = 0.4 \times f(x | \mu_1, \sigma_1) + 0.6 \times f(x | \mu_2, \sigma_2)$$

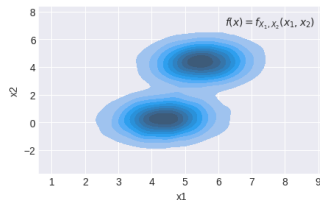


# Gaussian Mixture Models (GMM) - overview (cont.)

- Examples of the mixture distribution with  $d = 2$ :  $\pi_1 = 0.5$ ,  $\pi_2 = 0.5$

$$f(\mathbf{x}) = 0.5 \times f(\mathbf{x} \mid k = 1) + 0.5 \times f(\mathbf{x} \mid k = 2) = 0.5 \times f(\mathbf{x} \mid \boldsymbol{\mu}_1, \boldsymbol{\Sigma}_1) + 0.5 \times f(\mathbf{x} \mid \boldsymbol{\mu}_2, \boldsymbol{\Sigma}_2)$$

where  $\boldsymbol{\mu}_k \in \mathbb{R}^2$  is the mean and  $\boldsymbol{\Sigma}_k \in \mathbb{R}^{2 \times 2}$  is the covariance matrix



# Gaussian Mixture Models (GMM) - overview (cont.)

- **Data  $\mathbf{x}$** : a  $d$  dimensional feature vector  $\mathbf{x} = [x_1, \dots, x_d]$  with PDF  $f(\mathbf{x}) = \sum_{k=1}^K \pi_k f(\mathbf{x} | k)$
- **Target  $y$** :  $y$  is a set of  $K$  posterior probabilities; for  $k = 1, \dots, K$

$$\underbrace{P(k | \mathbf{x})}_{\text{posterior}} = \frac{\underbrace{P(k)}_{\text{prior}} \underbrace{f(\mathbf{x} | k)}_{\text{likelihood of } k}}{\underbrace{\sum_{c=1}^K P(c) f(\mathbf{x} | c)}_{\text{likelihood of the mixture distribution given data}}}$$

It is **soft clustering** -  $\mathbf{x}$  is assigned to **all clusters** with a probability - the posterior  $P(k | \mathbf{x})$ ; **alternatively**,  $y$  can be defined as the cluster index with the highest posterior probability, i.e.

$$y = \arg \max_{k \in \{1, \dots, K\}} P(k | \mathbf{x}) = \arg \max_{k \in \{1, \dots, K\}} P(k) f(\mathbf{x} | k)$$

- **Parameter**: the parameters of the mixture distribution  $f(\mathbf{x})$ 
  - The parameters for each Gaussian likelihood  $f(\mathbf{x} | k)$
  - The prior  $P(k)$ , typically denoted as  $\pi_k$

# Parameter estimation for GMM

- What's special about this? We know how to do it! It's almost the same as the **Gaussian naive Bayes classifier**!
- Let's discuss the key differences between these two algorithms
- **Set up**: given a data set  $\mathcal{X} = \{\mathbf{x}_1, \dots, \mathbf{x}_N\}$ , we need to estimate the parameter of interest from  $\mathcal{X}$

	Gaussian naive Bayes classifier	Gaussian Mixture Models
Parameter of interest	$P(k)$ , Gaussian PDF $f(\mathbf{x}   k)$ , for $k = 1, \dots, K$	
Labels for data set $\mathcal{X}$	known	unknown
	Hard assignment (one label for each $\mathbf{x}_i$ )	Soft assignment ( $K$ probabilities for each $\mathbf{x}_i$ )
Assumption	$\mathbf{x}_i$ and $\mathbf{x}_j$ independent for $i \neq j$ (i.i.d.)	
	$x_m^i$ and $x_n^i$ independent for $m \neq n$ ( <b>NAIVE!</b> )	$x_m^i$ and $x_n^i$ <b>NOT</b> independent for $m \neq n$

## Parameter estimation for GMM (cont.)

In summary, we have the following additional challenges compared to the Gaussian naive Bayes classifier:

1. We **do not have the labels** - we cannot easily estimate  $P(k)$  and  $f(\mathbf{x} | k)$
2. Now the distribution  $f(\mathbf{x} | k)$  is a **multivariate Gaussian PDF** and the features are **not necessarily independent** - now we need to explicitly work with **joint probability distributions**  $f_{X_1, \dots, X_d}(x_1, \dots, x_d | k)$  and **covariance matrices**; note: the subscripts here are the indices for the dimensions of the feature space; they are not the indices for the data points - data points are still i.i.d.!

## Parameter estimation for GMM (cont.)

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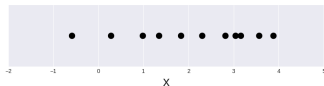
Let's focus on the first issue by working with one dimensional feature vectors so we don't get overwhelmed by dealing with all the problems at once

## One dimensional GMM



# Parameter estimation for one dimensional GMM

- **Data:**  $x_1, \dots, x_N$



- **Random variable:**  $X_1, \dots, X_N$  i.i.d. with PDF

$$f(x) = \sum_{k=1}^K \pi_k f(x | k)$$

The joint probability distribution of all data points is defined as

$$f_{X_1, \dots, X_N}(x_1, \dots, x_N) \stackrel{i.i.d.}{=} \prod_{i=1}^N f(x_i) = \prod_{i=1}^N \sum_{k=1}^K \pi_k f(x_i | k) \quad (2)$$

This is the **likelihood** of the **mixture distribution** given data  $x_1, \dots, x_N$ .

- **Parameter of interest:**  $\pi_k, \mu_k, \sigma_k$  for all  $k = 1, \dots, K$
- **Parameter estimation method:** maximum likelihood estimation

# Parameter estimation for one dimensional GMM (cont.)

- The **log likelihood** (cf. Eq. (2) on page 27) is defined as:

$$\begin{aligned} Q(\theta) &= \log L(\theta \mid x_1, \dots, x_N) = \log f_{X_1, \dots, X_N}(x_1, \dots, x_N) \\ &= \sum_{i=1}^N \log \left( \sum_{k=1}^K \pi_k f(x_i \mid k) \right) \end{aligned} \quad (3)$$

where  $\theta = (\mu_1, \dots, \mu_K, \sigma_1, \dots, \sigma_K, \pi_1, \dots, \pi_K)$

- The parameters are estimated by **maximizing the log likelihood**

$$\hat{\theta} = \arg \max_{\theta} Q(\theta)$$

- There is no closed-form solution due to the summation inside the log!
- We need to apply an iterative method to find the solution - the **EM algorithm** (explained in the next lecture)

## How to choose hyperparameter $K$

- For a given data set, we need to choose the number of clusters  $K$
- Similar to the K-means case, we first estimate  $\hat{\theta}$  and then we choose the  $K$  value that gives the best clustering quality
- Given an estimate  $\hat{\theta}$  for a given number of clusters  $K$ , we introduce two **alternative** criteria for this task: **Akaike Information Criterion (AIC)** and **Bayesian Information Criterion (BIC)**

# How to choose hyperparameter $K$ (cont.)

- Akaike Information Criterion (AIC)**

$$\begin{aligned} AIC(K) &= \overbrace{-\log(\text{likelihood})}^{\text{How well the model explains data}} + \overbrace{c_K}^{\text{Complexity of the model}} \\ &= -Q(\hat{\theta}) + c_K \end{aligned}$$

- Bayesian Information Criterion (BIC)**

$$\begin{aligned} BIC(K) &= \overbrace{-\log(\text{likelihood})}^{\text{How well the model explains data}} + \overbrace{\frac{1}{2}c_K \log N}^{\text{Complexity of the model}} \\ &= -Q(\hat{\theta}) + \frac{1}{2}c_K \log N \end{aligned}$$

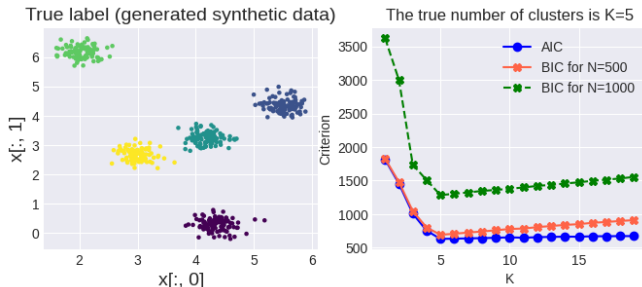
where  $c_K$  is the number of parameters to be estimated:

$$c_K = \overbrace{K \times d \times (d+1)/2}^{\text{covariancematrices}} + \overbrace{(K-1)}^{\text{priors}} + \overbrace{d \times K}^{\text{means}}$$

Note: an alternative definition is to multiply this definition of AIC and BIC by 2

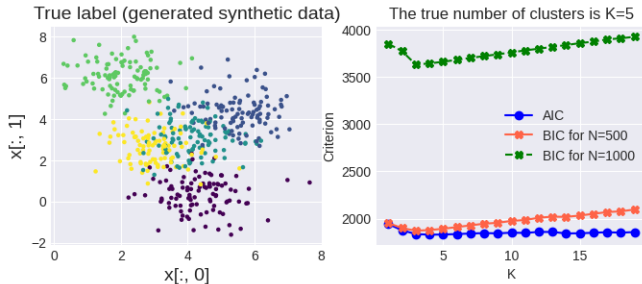
# AIC vs BIC

- The idea is that we want to find the best  $K$  that balances the “error” and the complexity of the model - **Occam’s Razor** (cf. lecture 5) - if two models explain the data equally well, we choose the simpler one!
- BIC penalizes the complexity more than AIC - BIC increases more as  $K$  gets larger
- Example 1: well separated clusters



# AIC vs BIC (cont.)

## • Example 2: overlapping clusters



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# Summary

So far:

- Data types and data containers
- Descriptive data analysis: descriptive statistics, visualization
- Probability distributions, events, random variables, PMF, PDF, parameters
- CDF, Q-Q plot, how to compare two distributions (data vs theoretical, data vs data)
- Modeling
- Parameter estimation: maximum likelihood estimation (MLE) and maximum a posteriori estimation (MAP)
- Classification, multinomial naive Bayes classifier, Gaussian naive Bayes classifier
- Central limit theorem, interval estimation
- Hypothesis tests, comparison of two classifiers
- Clustering, cluster tendency, k-means
- SSE and Silhouette score for cluster evaluation, one dimensional Gaussian Mixture Models, AIC/BIC



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Next:

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Before next lecture:

- GMM clustering model

