

# Statistical Methods for Data Science: A Starter Kit

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## Statistical Data Type

**Categorical data:** labels or tags

- Nominal: unordered labels, e.g. species of ducks
- Ordinal: ordered labels, e.g. {"duckling", "teen duck", "adult duck"}

**Numerical data:**

- Discrete (interval): countable, e.g. integers; numbers of ducks
- Continuous (ratio): uncountable, e.g. real values; weights of ducks

## Data Container

**Array (tensor):**

- Scalar, vector, matrix, higher order array
- Same numerical data type
- Python library: numpy

**Table:**

- Described by columns and rows
- Mixed data types
- Python library: pandas

## Descriptive Statistics: numerical data

Data set (a sample): numerical data  $x_1, \dots, x_N$

**Centrality:**

- sample mean:  $\bar{x} = \frac{1}{N} \sum_{i=1}^N x_i$
- median: sort  $x_i$  and median is the value in the middle
- mode (discrete values): the most frequent value in a sample

**Dispersion:**

- min, max, range:  $\min\{x_i\}, \max\{x_i\}, \max\{x_i\} - \min\{x_i\}$
- quantiles/percentiles: given  $p \in (0, 1)$ ,  $q$  is a  $p$ -quantile of the data if  $p \times 100\%$  of the data are smaller than  $q$

- sample variance:  $s^2 = \frac{1}{N-1} \sum_{i=1}^N (x_i - \bar{x})^2$
- sample standard deviation:  $s$

**Dependence:** given a data set with two paired values:

$$\{(x_1, y_1), (x_2, y_2), \dots, (x_N, y_N)\}$$

- covariance:

$$\text{cov}(x, y) = \frac{1}{N-1} \sum_{i=1}^N (x_i - \bar{x})(y_i - \bar{y})$$

- correlation: measures how close data is to a linear relationship






$$\text{corr}(x, y) = \frac{\text{cov}(x, y)}{\sigma_x \sigma_y}, -1 \leq \text{corr}(x, y) \leq 1$$

## Descriptive Statistics: categorical data




Data set (a sample): categorical data  $x_1, \dots, x_N$

- Count/frequency
- Transformed into numerical, discrete data

## Visualization: numerical data

- Distribution:
  - Histogram/normalized histogram 
  - Kernel density estimator 
  - Box plot 
- Dependence (two variables):
  - Scatter plot 
  - Heat map for covariance/correlation 

## Visualization: categorical data






- Distribution
  - Bar chart 
  - Pie chart 
- Dependence
  - Mosaic plot 

## Probability distribution

- Experiment, sample space, event, probability distribution ( $P(\text{event})$ /PDF/PMF/CDF), random variable (discrete/continuous)
- Quantile function  $Q$ : the inverse CDF, i.e.  
 $F_X(Q(p)) = p$  and  $Q(F_X(q)) = q$
- Conditional probability
- Independent and identically distributed (i.i.d.) random variables

## Examples

Discrete/continuous, PMF/PDF, parameters, typical use cases (statistical data type, example scenarios)

- Bernoulli distribution 
- Categorical distribution 
- Binomial distribution 
- Discrete uniform 
- Gaussian distribution 

Generalize this learning routine to unknown distributions

## Properties of Gaussian distributions

- Let  $X \sim \mathcal{N}(\mu_X, \sigma_X^2)$  be a Gaussian random variable, then the following random variables are also Gaussian
  - Scaling:  $tX \sim \mathcal{N}(t\mu_X, t^2\sigma_X^2)$ ,  $t \neq 0$  is a constant
  - Translation:  $X + c \sim \mathcal{N}(\mu_X + c, \sigma_X^2)$ ,  $c$  is a constant
  - $tX + c \sim \mathcal{N}(t\mu_X + c, t^2\sigma_X^2)$
- Let  $X \sim \mathcal{N}(\mu_X, \sigma_X^2)$  and  $Y \sim \mathcal{N}(\mu_Y, \sigma_Y^2)$  be two **independent** Gaussian random variables, then the following random variables are also Gaussian
  - $X + Y \sim \mathcal{N}(\mu_X + \mu_Y, \sigma_X^2 + \sigma_Y^2)$
  - $X - Y \sim \mathcal{N}(\mu_X - \mu_Y, \sigma_X^2 + \sigma_Y^2)$

## Bayes' rule

- Parameter estimation:

$$f_{\Theta|data}(\theta | data) = \frac{\overbrace{f_{data|\Theta}(data | \theta)}^{\text{likelihood}} \overbrace{f_{\Theta}(\theta)}^{\text{prior}}}{f_{data}(data)}$$

where  $f(\cdot)$  is the PDF/PMF

- Multinomial naive Bayes classifier:

$$P(Y = y | X = x) = \frac{\overbrace{P(X = x | Y = y)}^{\text{likelihood}} \overbrace{P(Y = y)}^{\text{prior}}}{P(X = x)}$$

- Gaussian naive Bayes classifier/Gaussian mixture models:

$$P(Y = y | X = x) = \frac{\overbrace{f_{X|Y=y}(x | Y = y)}^{\text{likelihood}} \overbrace{P(Y = y)}^{\text{prior}}}{f_X(x)}$$

## Q-Q plot

- Use cases:
  - Compare a data distribution to a theoretical distribution (one sample test)
  - Compare two data distributions (two sample test)
- Steps:
  - Choose a set of  $m$  probabilities  $p_1, \dots, p_m \in [0, 1]$  (make sure they spread evenly between 0 and 1)
  - For  $i = 1, 2, \dots, m$ :
    - Compute the quantile  $q_i^1$  of the first distribution at  $p_i$
    - Compute the quantile  $q_i^2$  of the second distribution at  $p_i$
    - Make a scatter plot of the pair  $(q_i^1, q_i^2)$
- Interpretation
  - Case 1: if the two distributions are identical, the points in the Q-Q plot should follow a 45° straight line  $y = x$
  - Case 2: if the two distributions are linearly related, the points in the Q-Q plot follow a straight line that is not necessarily  $y = x$
  - Case 3: if the two distributions are from different families of distributions, the points in the Q-Q plot are not lying on a straight line.

## Mathematical Modeling

$$y = g(x; \theta | h)$$

- What do we want to predict, i.e. what is the target  $y$ ?
- What are the variables  $x$ ?
- What is the mathematical function  $g$  that relates variables  $x$  to the target  $y$ ?
- Are there any hyperparameters  $h$  in the function  $g$ ? How do we choose them?
- What are the unknown parameters  $\theta$  in  $g$ ? **How do we estimate them from data?**

## Parameter estimation for probabilistic models

- Maximum likelihood estimation: frequentist approach -  **$\theta$  is deterministic**
- Maximum A Posteriori estimation: Bayesian approach -  **$\theta$  is probabilistic**

## Maximum Likelihood Estimation

Given a model  $y = g(x; \mathcal{O} | h)$ , where  $\mathcal{O}$  is a set of parameters

- Describe the experiments
- Describe the data generated from the experiments
- Describe the random variables (typically with i.i.d. assumption)
- Choose a parameter of interest  $\theta \in \mathcal{O}$
- Choose the maximum likelihood estimation as the estimation method:  
Given data  $x_1, \dots, x_N$  and assume i.i.d. random variables  $X_i$  with PDF/PMF  $f(x_i)$ ,

$$L(\theta | x_1, \dots, x_N) = \prod_{i=1}^N f(x_i; \theta)$$

- Compute  $\hat{\theta}_{MLE}$  by maximizing the likelihood function:

$$\begin{aligned} \hat{\theta}_{MLE} &= \arg \max_{\theta} L(\theta | x_1, \dots, x_N) \\ &= \arg \max_{\theta} \prod_{i=1}^N f(x_i; \theta) \end{aligned}$$

or equivalently, minimizing the **negative log likelihood function**:

$$\hat{\theta}_{MLE} = \arg \min_{\theta} - \sum_{i=1}^N \log(f(x_i; \theta))$$

- Simple case, e.g. i.i.d. Gaussian, find the closed-form solution by:
  - Taking the partial derivative with respect to the parameter
  - Setting the derivative to zero
  - Solving for the parameter
- In general, the estimate needs to be found by iterative methods, e.g. gradient descent

## Maximum A Posteriori Estimation

Given a model  $y = g(x; \mathcal{O} \mid h)$ , where  $\mathcal{O}$  is a set of parameters

- a) Describe the experiments
- b) Describe the data generated from the experiments
- c) Describe the random variables (typically with i.i.d. assumption)
- d) Choose a parameter of interest  $\theta \in \mathcal{O}$
- e) Choose the maximum a posteriori estimation as the estimation method
  - **$\theta$  is assumed to be drawn from a random distribution**
  - Choose a prior distribution for  $\theta$  along with the hyperparameters:  $f_{\Theta}(\theta)$ 
    - \* Prior might be known by the problem setup
    - \* If prior unknown, conjugate priors are typically chosen for various reasons
  - Find the likelihood function:  $f_{X|\Theta}(\mathbf{x} \mid \theta)$  (same as in MLE)
  - Express the posterior distribution in terms of the prior and the likelihood function

$$f_{\Theta|X}(\theta \mid \mathbf{x}) = \frac{f_{X|\Theta}(\mathbf{x} \mid \theta)f_{\Theta}(\theta)}{f_X(\mathbf{x})}$$

- f) Compute  $\hat{\theta}_{MAP}$  by maximizing the posterior function (or equivalently, minimizing the negative log posterior function without the normalization constant). The optimal solution can be found by a closed-form expression or using iterative techniques.