Lecture 2: Probability Distribution Statistical Methods for Data Science

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Today

- Probability distribution
 - Why probability distributions?
 - Terminology
 - Some probability distributions that you should know by heart
- 2 Demo
- Summary





Learning outcome

- Be able to explain the following concepts: experiment, event, random variable, probability distribution
- Given the PDF/PMF, be able to describe the probability distribution of a continuous/discrete random variable
- Be able to compute conditional probability
- Understand Gaussian distribution and Bernoulli distribution: 1)
 PDF/PMF; 2) what are the parameters? 3) what happens to the shape of the distribution if we change the parameters?
- Be able to apply the learning routine to study a new probability distribution yourself





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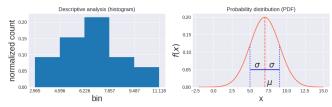
Why probability distributions?
Terminology

Why probability distributions?





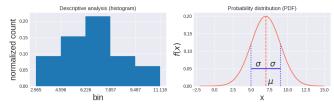
You need to predict the average weight of your 1000 ducks without weighing all of them. You weighed 20 ducks and you plotted the histogram of the weights. Your best friend Jack suggested that you should use a **Gaussian distribution** to make a better estimation of the average. For example, you can estimate a confidence interval for the mean value, Jack said.







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- Question 1: Why can't I just use descriptive analysis, like the histogram? Why should I use probability distributions?
- To address this question, let's describe the data using the histogram and a Gaussian distribution to see the difference.





Here are the weights of the 20 ducks in kg

| duck id | 1 | 2 | 3 | 4 | 19 | 20 |
|---------|------|------|------|------|----------|------|
| weight | 6.98 | 5.43 | 2.97 | 7.07 | 4.63 | 7.27 |

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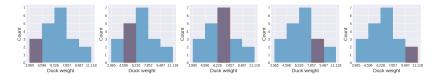


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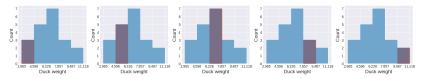


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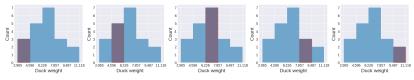


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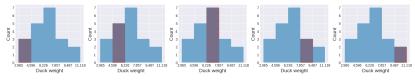


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• Resolution: the number of bins per kilogram

$$\frac{\text{number of bins}}{\textit{range}} = \frac{\text{number of bins}}{\text{max}(\textit{weights}) - \text{min}(\textit{weights})} = \frac{5}{11.118 - 2.965} = 0.61$$

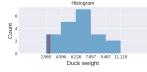


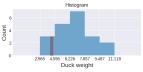


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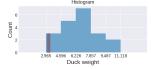


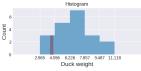


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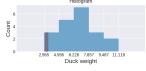


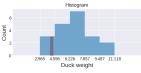
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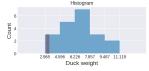
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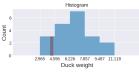


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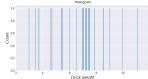
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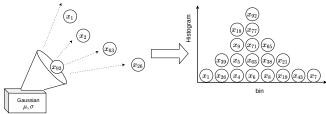


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- First, we assume that data is generated from a Gaussian distribution







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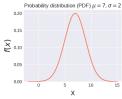
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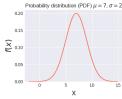




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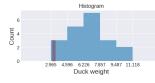
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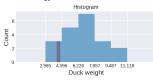


We will replace the histogram with this function.



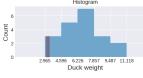
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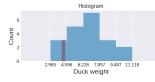






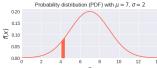
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- Gaussian distribution:
 - The chance of weight $\in [3.1, 3.4]$: $\int_{3.1}^{3.4} f(t) dt = 0.010$
 - The chance of weight $\in [4.1, 4.4]$: $\int_{4.1}^{4.4} f(t) dt = 0.023$









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| | Histogram | | Gaussian distribution | | |
|------------------------------------|-----------------------------|---|-------------------------------|---|--|
| Representation | M values | | mathematical function f | | |
| Number of parameters | М | - | $2 (\mu \text{ and } \sigma)$ | + | |
| Resolution | $\frac{M}{\max(x)-\min(x)}$ | - | infinity | + | |
| Analytical properties | No | - | Yes | + | |
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Disclaimer: we used a continuous distribution to illustrate the comparison between a histogram and a probability distribution.

A discrete probability distribution differs from a continuous distribution.





Choosing a probability distribution

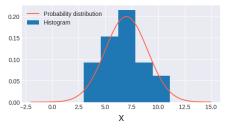
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 - Short answer: if the probability distribution looks like the histogram, then it's good enough.

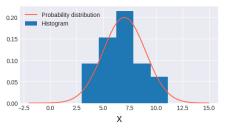






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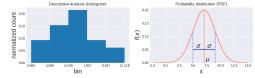
• Long answer will be given in lecture 3.





Parameter estimation and evaluation

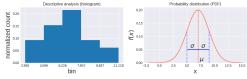
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This is done by parameter estimation. In this course (lecture 3 & 4), we will talk about the maximum likelihood estimation (MLE) and the maximum a posteriori estimation (MAP).



Why probability distributions? Terminology Some probability distributions that you should know by heart

Terminology





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- Random variable X:
 - Heuristically, X assigns a numerical value to each outcome of the experiment:

$$X: \mathsf{weight} o \mathbb{R}$$

- X follows some underlying probability distribution.
- Discrete random variable and continuous random variable: depends on the sample space of the
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- Data x: a value drawn from the underlying distribution of X.
 - We use a capital letter (e.g. X) to denote a random variable and the corresponding lower case letter (e.g. x) to denote the data generated from the underlying distribution of X.
 - Discrete random variable: categorical data or discrete numerical data
 - Continuous random variable: continuous numerical data





More precisely, the probability distribution can be described by a function f_X (also denoted as f if neglecting X does not cause confusion), where

• for discrete distribution, the probability mass function (PMF) is used, where

$$f_X(x_i) = P(X = x_i)$$

where $0 \le f_X(x_i) \le 1$ for all x_i .

 for continuous distribution, the probability density function (PDF) is used, where

$$P(a \le X \le b) = \int_a^b f_X(x) dx, \ \forall a, b \in \mathbb{R}, a \le b$$

where $f_X(x) \ge 0$ for all x.

where P(event) is the probability of the **event** occurring.

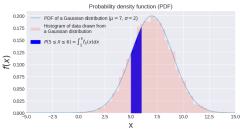




Example: continuous random variables and PDF

- Experiment: you weigh a duck and look at its weight
- Sample space: $0 < weight < \infty$
- Random variable X : weight $\to \mathbb{R}$
 - $\bullet \ \ X = x \ \text{if the duck weighs} \ x \ \text{kg for} \ 0 < x < \infty$
 - Assumption: X follows a Gaussian distribution with parameters μ and σ ; denoted as $X \sim \mathcal{N}(\mu, \sigma^2)$
- \bullet PDF: $f_X(x)$

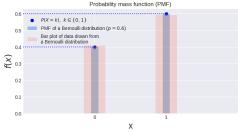
$$P(a \le X \le b) = \underbrace{\int_a^b f_X(x) dx}_{\text{Integral} = \text{area under the PDF curve}} \forall a, b \in \mathbb{R}, a \le b$$





Example: discrete random variables and PMF

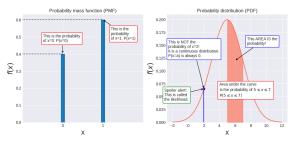
- Experiment: you measure the color of the duck.
- Sample space: the color can be only red or blue
- Random variable $X : color \rightarrow \mathbb{R}$
 - $X = \begin{cases} 0, & \text{if a duck is red} \\ 1, & \text{if a duck is blue} \end{cases}$
 - Assumption: X follows a Bernoulli with parameter p; denoted as $X \sim Bernoulli(p)$
- **PMF**: $f_X(x_i) = P(X = x_i)$





Differences between PMF and PDF

- Discrete distribution $f_X(x_i) = P(X = x_i)$:
 - · y-axis represents the probability itself
- Continuous distribution:
 - $P(a \le X \le b) = \int_a^b f_X(x) dx$: **y-axis** f(x) DOES NOT represent the probability itself.
 - For continuous distributions, the probability at any given value is always 0, i.e.
 P(X = a) = P(a ≤ X ≤ a) = ∫_a^a f_X(x)dx ≡ 0. Example: what is the probability of a duck weighing exactly 4.32028374... kg?







Conditional probability

Given events A and B,

$$P(A \mid B) = \frac{P(A \text{ and } B)}{P(B)} = \frac{P(A \cap B)}{P(B)}$$



- Experiment: You ask your ducks to stand in a row again and look at their colors and sizes.
- Sample space: The color can be either red or blue; the size can be either slim or chonker.
- Data:

| duck id | 1 | 2 | 3 | 4 | 5 | 6 |
|---------|---------|------|------|---------|---------|------|
| color | red | red | blue | blue | blue | red |
| size | chonker | slim | slim | chonker | chonker | slim |

- Event:
 - · A: a duck is blue
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· Conditional probability:

$$P(A \mid B) = \frac{P(A \text{ and } B)}{P(B)} = \frac{P(A \cap B)}{P(B)} = \frac{2/6}{3/6} = \frac{2}{3}$$





An alternative way to estimate $P(A \mid B)$:

- Count the chonkers: 3
- Count blue ducks within the chonker gang: 2
- $P(A \mid B) = \frac{2}{3}$



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Side note: from this calculation, can you make a bold statement of the probability distribution of all the ducks in the world? No. It is only an estimation based on the data you got.



As an exercise, let's define the random variables.

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Hint: $X : \mathsf{color} \to \mathbb{R}, \ Y : \mathsf{size} \to \mathbb{R} \ (\mathsf{10 \ secs})$





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Write the conditional probability in terms of the random variables X and Y (10 secs), i.e.

$$P(A \mid B) = \frac{P(A \text{ and } B)}{P(B)} =$$





Lecture 2: Probability Distribution

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Are they continuous or discrete? (2 secs) Discrete

Write the conditional probability in terms of the random variables X and Y (10 secs), i.e.

$$P(A \mid B) = \frac{P(A \text{ and } B)}{P(B)} = P(X = 1 \mid Y = 1) = \frac{P(X = 1 \text{ and } Y = 1)}{P(Y = 1)}$$





Independent events

Two events A and B are independent if and only if

$$P(A \text{ and } B) = P(A \cap B) = P(A)P(B)$$

$$\iff$$
 $P(A \mid B) = P(A), P(B \mid A) = P(B)$ (conditional probability)

$$\iff$$
 log $(P(A \text{ and } B) = \log(P(A \cap B)) = \log(P(A)) + \log(P(B))$





Bayes' rule

Given events A and B,

$$P(A \mid B) = \frac{P(B \mid A)P(A)}{P(B)}$$

Just a heads-up!





Summary: terminologies

- Experiment
- Sample space
- Event
- Random variable:
 - Discrete random variable
 - Continuous random variable
- Data
- Probability distribution:
 - Discrete distribution: P(event) is described by the probability mass function (PMF)
 - Continuous distribution: P(event) is described by the probability density function (PDF)

What are their differences?

- Conditional probability of events
- Independent events
- Bayes' rule





Terminology

Some probability distributions that you should know by heart

Some probability distributions that you should know by heart





| Probability distribution | Continuous/discrete | Apply to data type | | |
|--------------------------|---------------------|------------------------|--|--|
| Bernoulli distribution | Discrete | Categorical (nominal) | | |
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- how to estimate the parameters (next lecture)





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- Given *p* the probability of a duck being blue, we can express the probability distribution as follows:

$$P(a \text{ duck is red}) = P(X = 0) = 1 - p$$

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What is the PMF? Merge these two equations:

$$P(X=k) = f_X(k) \equiv f_X(k \mid p) = pk + (1-p)(1-k), \ k \in \{0,1\}, p \in [0,1]$$

Note: here we use a \mid to indicate that the parameter p is given.

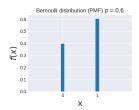




- Discrete distribution
- Applies to nominal data with 2 categories
- PMF:
 - Equation

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Shape



Parameters: p





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Why probability distributions?
Terminology
Some probability distributions that you should know by heart

Categorical distribution

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Given p₁ the probability of a duck being blue, p₂ the probability of a duck being red, p₃ the probability of a duck being green and p₄ the probability of a duck being gray. Note that p₁ + p₂ + p₃ + p₄ = 1.



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$$p_1 + p_2 + p_3 + p_4 = 1.$$

• Let
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• Now we can express the probability distribution as follows:

$$\begin{array}{l} P(\text{a duck is blue}) = P(X=1) = p_1 \\ P(\text{a duck is red}) = P(X=2) = p_2 \\ P(\text{a duck is green}) = P(X=3) = p_3 \\ P(\text{a duck is gray}) = P(X=4) = p_4 \end{array}$$



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Note: categorical distribution is also called multinoulli distribution. It is a generalization of the Bernoulli distribution.

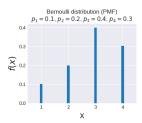




- Discrete distribution
- Applies to nominal data with n > 0 categories
- PMF:
 - Equation

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Shape



• Parameters: p_k , $k \in \{1, \dots, n\}$ for given n.





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- Given integers a and b with $a \le b$ (here we have a=1 and b=1000)
- Let X be a discrete random variable: X = k if a person has k ducks



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$$P(X = k) = f_X(k) \equiv f_X(k \mid a, b) = \frac{1}{b - a + 1}$$

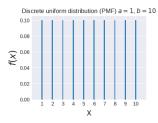




- Discrete distribution
- Applies to discrete numerical data
- PMF:
 - Equation

$$f_X(k \mid a, b) = \frac{1}{b-a+1}, \ a \le b, \ a, b \text{ integers}$$

Shape



Parameters: integers a, b





| Probability distribution | Continuous/discrete | Apply to data type |
|--------------------------|---------------------|------------------------|
| Bernoulli distribution | Discrete | Categorical (nominal) |
| Categorical distribution | Discrete | Categorical (nominal) |
| Discrete uniform | Discrete | Numerical (discrete) |
| Gaussian distribution | Continuous | Numerical (continuous) |





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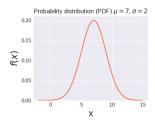
$$f_X(x \mid \mu, \sigma) = \frac{1}{\sqrt{2\pi\sigma^2}} e^{-\frac{1}{2}(\frac{x-\mu}{\sigma})^2} = \frac{1}{\sqrt{8\pi}} e^{-\frac{1}{2}(\frac{x-7}{2})^2}$$



- Continuous distribution
- Applies to continuous numerical data
- PDF:
 - Equation

$$f_X(x) = \frac{1}{\sqrt{2\pi\sigma^2}} e^{-\frac{1}{2}\left(\frac{x-\mu}{\sigma}\right)^2}, \ \mu \in \mathbb{R}, \ \sigma \in \mathbb{R}^+$$

Shape



• Parameters: $\mu, \ \sigma$





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Hooray!



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These probability distributions DO NOT ONLY apply to duck related applications!

Check out what data types they apply to!

We are going to talk about more applications in the future





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Check out what data types they apply to!

We are going to talk about more applications in the future (even though they won't be as important as ducks)





Today

- Probability distribution
- 2 Demo
- Summary





Demo

Code demo

- Image processing
- Natural language processing
- Table with numerical data
- Table with categorical data



Today

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Q-Q plot and mathematical modeling





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Before next lecture:

- Quantile
- Probability distributions from today and their parameters
- PMF and PDF





Stay safe!





